XENIX® System V

Operating System

System Administrator’s Guide
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Introduction

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1.1 Overview

The XENIX operating system is a powerful system of programs that allows you to accomplish a full spectrum of tasks, from developing high-level and assembly language programs to creating, editing, and typesetting documents. To keep running smoothly, the powerful XENIX system requires careful control of its operation and a regular schedule of maintenance. This guide explains how to operate and maintain the XENIX operating system on your computer, ensuring maximum performance with the fewest system problems.

This guide also explains how to expand a XENIX system with remote and local networks. For local networking over serial lines, micnet can link XENIX systems in your work environment. For remote communications over phone lines, UUCP can be set up to communicate with XENIX/UNIX sites all over the world. (See “Building a Local Network with Micnet,” and “Building a Remote Network with UUCP” in this Guide for a complete explanation of network facilities available.)

1.2 The System Administrator

Every XENIX system should have one person in charge of system maintenance and operation. In this guide, that person is called the system administrator. It is the system administrator’s duty to ensure the smooth operation of the system and to perform tasks that require special privileges. These duties require that the system administrator become proficient with a wide variety of XENIX functions.

Depending on the size of the system and the number of users on it, a system administrator’s job can be anything from a once-a-day task to a full-time job. Even if the system is small, the system administrator should faithfully perform each required maintenance task, since sloppy maintenance can adversely affect XENIX performance.

The system administrator should keep a log of all system modifications and system events. Each event, message, backup, or modification should be logged with the date, time, and name of the person logging, and the circumstances surrounding the event. For example, if a new application is added to the system software, an entry should be placed in the log. This entry should include the time, date, and name of the person installing, and any notes about the software or installation that may be helpful. An accurate log helps in diagnosing system problems and charting the growth and use of a system.

All tasks in this guide are presented from the system administrator’s point of view, but many can also be accomplished by ordinary users. Since
some of the tasks dramatically change the system’s operation, we recom-
mend that, whenever possible, the system administrator perform these
tasks. However, no matter who performs an operation, it should be logged
in the system log. Following these rules can prevent unwanted or
unnecessary changes to the system.

The System Administrator has several tasks to perform, sometimes on a
daily basis:

- Making certain that adequate backups (regular copies of files on
the system) are made and stored for future use.
- Handling problems related to use of limited computer resources
(disk space, number of processes, etc.)
- Alleviating system communication (network) stoppages due to
failed connections.
- Applying operating system updates and maintenance fixes.
- Providing general support to users.

1.3 Making Administration Easier with the sysadm Shell

The *sysadmsh* is a menu interface designed to simplify the task of system
administration. The menus, submenus and screens allow you to simply
point and pick, or fill in blanks. The *sysadmsh* allows less-experienced
system administrators to use XENIX commands that would otherwise
require memorization and constant referring to manual pages. The
*sysadmsh* includes context-sensitive help; simply press the key from any
menu to display further explanations of the menu options.

If you are new to XENIX, we strongly recommend that you become fami-
liar with the concepts and tasks covered in the *XENIX Tutorial*, a tutorial
for new users. This guide assumes some familiarity with XENIX; after
studying the *XENIX Tutorial*, you should be able to perform the basic sys-
tem administrative tasks described here.

To aid users of the *sysadm* shell, the documentation of this guide is sup-
plemented by *sysadmsh* references that appear below XENIX command
line instructions.

For example, the following instructions refer to the *custom* utility, used
to add more software to your system. Below the actual command is a
sequence of *sysadmsh* menu selections.
Introduction

Enter the following command:

```
custom
A
sysadmsh
users select: System→Add→Software
```

This means that you can access the functions of the `custom` command by first selecting "System" at the main `sysadmsh` menu, followed by selecting "Addition" at the next lower level, and finally "Software" at the lowest level. Selections can be made from the menu in any of the following ways:

- Tab through the menu options using the TAB key and press RETURN on the option you want.
- Move left and right through the options using the arrow keys and press RETURN on the desired option.
- Press the first letter of the option desired. This is the quickest way. Using the example above, you would simply enter "sas" (without the RETURN key) to reach the `custom` menu.

For more instructions on using the `sysadmsh`, refer to the "sysadmsh: Using the System Administration Shell" chapter in this guide.

1.4 The Super User Account

The super user account is a special account for performing system maintenance tasks. It gives the system administrator unusual privileges that ordinary users do not have, such as accessing all files in the system, and executing privileged commands. Many of the tasks presented in this guide require that the system administrator be logged in as the super user. To do this, the system administrator must know the super user password created during the installation of the XENIX system. (See the `XENIX Installation Guide`.)

Log in as the super user only to perform system-maintenance tasks. Even if the system administrator is the only one using the system, that person should create a user account for day-to-day work, reserving the super user account for system-maintenance tasks only.

Few users should know the super user password. Misuse of the super user powers by naive users can result in a loss of data, programs, and even the XENIX system itself.
1.5 The Keyboard

Many keys and key combinations have special meanings in the XENIX system. These have names that are unique to the XENIX system, and may not correspond to the keytop labels on your keyboard. To help you find these keys, the following table shows which keys on a typical terminal correspond to those on the XENIX system. A list for your particular login device is in *keyboard(HW).*

In this table, a hyphen (-) between keys means "hold down the first key while pressing the second."

### Special Keys

<table>
<thead>
<tr>
<th>XENIX Name</th>
<th>Keytop</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>BREAK</td>
<td>Delete</td>
<td>Stops the current program, returning to the shell prompt. This key is also known as the INTERRUPT or DELETE key.</td>
</tr>
<tr>
<td>BACKSPACE</td>
<td>Backspace</td>
<td>Deletes the character to the left of the cursor.</td>
</tr>
<tr>
<td>Ctrl-d</td>
<td>Ctrl-d</td>
<td>Signals the end of input from the keyboard; exits current shell or initiates the &quot;logout&quot; procedure if the current shell is the login shell.</td>
</tr>
<tr>
<td>Ctrl-h</td>
<td>Erase</td>
<td>Deletes the first character to the left of the cursor. Also called the ERASE key.</td>
</tr>
<tr>
<td>Ctrl-q</td>
<td>Ctrl-q</td>
<td>Restarts printing after it has been stopped with Ctrl-s.</td>
</tr>
<tr>
<td>Ctrl-s</td>
<td>Ctrl-s</td>
<td>Stops printing at the standard output device, such as a terminal. Does not stop the program.</td>
</tr>
</tbody>
</table>
Introduction

Ctrl-u        Deletes all characters on
              the current line. Also
teached the KILL key.

Ctrl\         Quits current command
              and creates a core file.
              (Recommended for de-
              buggin only.) See
              core(F) for more infor-
              mation.

ESCAPE       Esc       Exits the current mode;
              for example, exits insert
              mode when in the editor
              vi.

RETURN       Return    Terminates a command
              line and initiates an
              action from the shell.

Many of these special function keys can be modified by the user. See
stty(C) for more information.

1.6 About This Guide

The tasks presented in this guide range from simple ones requiring very
little knowledge about XENIX, to complex tasks requiring extensive
knowledge about XENIX and your computer.

Each chapter explains the tools and knowledge you need to complete the
tasks described in that chapter. In some cases, you may be referred to
other manuals, such as the XENIX User's Guide or the XENIX User's
Reference.

This guide contains chapters about computer hardware you may wish to
use with XENIX. The use and interaction of various devices with XENIX
is described in a comprehensive fashion. For example, "Using Floppy
Disks and Tape Drives" discusses the use of magnetic storage media, and
covers the basics of preparing XENIX for such a device, installing it, and
how to use the drive once it has been installed.

In addition, there are chapters dealing with several other types of devices
you may wish to use, and there are many chapters to help you administer
your system. Some are designed to help you set up a network with other
computer systems and some help you maintain and understand your own
system.
Pay special attention to the chapters "Back up Filesystems" and "Solving System Problems." The latter is an excellent resource to help you keep your system running smoothly, and the chapter on backups discusses the most important aspect of system administration.
Chapter 2
sysadmsh: Using the System Administration Shell

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2.1 Introduction

The `sysadmsh` (system administration shell) is a menu interface designed to simplify the task of system administration. The `sysadmsh` allows you to run the scores of system administration commands with their numerous options without having to use the traditional XENIX command-line.

This chapter explains how to use the `sysadmsh` interface. In order to use `sysadmsh` effectively, you also need to know something about the XENIX commands called by `sysadmsh`. A list of these commands and their corresponding `sysadmsh` menu options is given at the end of this chapter. This list refers you to other sections of the XENIX documentation that contain detailed information on each command.

You will find it easier to learn the material in this chapter if you start the `sysadmsh` and actually run the examples as you get to them. The chapter assumes that you have some knowledge of the XENIX operating system. You should become familiar with the concepts covered in the XENIX Tutorial before using the `sysadmsh` menus.
2.2 Starting sysadmsh

There are two ways to start sysadmsh:

- Log in to the system as user sysadm, or
- While already logged in as root, enter the following command:
  
  \[
  \text{sysadmsh}
  \]

For the purposes of this tutorial, log in as root and enter the following commands:

\[
\begin{align*}
\text{cd /tmp} \\
\text{sysadmsh}
\end{align*}
\]

The main sysadmsh menu is displayed:
2.3 How the Screen is Organized

A schematic of the sysadmsh screen is given below. Areas shown between double lines appear on the screen as highlighted areas or bars of text. Each area is used to display specific types of information:

- The Context Indicator is the highlighted bar of text in the upper-right corner of your screen. It displays the name of the current menu. The Context Indicator for the sysadmsh opening screen shows SysAdmSh.

- The Menu Line displays the menu options that are currently available. The main sysadmsh menu consists of eight options: System, Filesystem, Dirs/Files, Backups, Users, Processes, Media, and Quit.

- The Description Line gives you a brief description of the currently highlighted menu option.

- The Status Line is the highlighted bar of text that separates the Menu and Description Lines from the Display Window. The Status Line in the sysadmsh opening screen contains the date, time, and current working directory. When a XENIX command is being executed, the name of the command and the options being used are displayed at the far right of the Status Line.
The Command/Form line displays a title for the contents of the Display Area. This can be either a XENIX command name, or the name of a sysadmsh form. When a command name is displayed, the location of the manual page associated with the command is appended in parentheses. For example, when the who command is being run, the Command Line displays "who(C)." This means that the command can be found in the (C) Section of the XENIX Reference.

- The Display Area is where sysadmsh forms and scan windows are displayed. Forms and scan windows are explained in detail later in this chapter.

- Error Messages and recovery instructions are displayed on the last line of the screen in highlighted text.

2.4 Selecting Menu Items

The keystrokes listed below are used to traverse the menus. Note that there are several ways to select options; if you have used menu-based programs before, use the method you are most familiar with.

<table>
<thead>
<tr>
<th>Basic sysadmsh Keystrokes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Action</td>
</tr>
<tr>
<td>---------------------------</td>
</tr>
<tr>
<td>Move to menu option</td>
</tr>
<tr>
<td>Select menu option</td>
</tr>
<tr>
<td>Retreat to previous menu</td>
</tr>
<tr>
<td>Get help</td>
</tr>
</tbody>
</table>

You can familiarize yourself with the menu options by using the Arrow keys or <SPACEBAR> to move the highlight from option to option. Each time you move the highlight to a new option, a description of that option appears on the Description Line.

sysadmsh has a hierarchical menu structure. Many of the menu options move you down to another menu. For example, when you select the Processes option from the main menu, a menu containing options that let you check on and manipulate your machine’s processes is displayed. The menu hierarchy makes it easy to find the command you need by moving down from one menu to the next. Eventually you get to a menu option that either executes a XENIX command or displays a form that you must
fill in with the details that the command needs. Note that typing the first letter of the option name is the quickest way to move through menu levels; in time you will be able to instantly reach the function you need by pressing three- and four-letter codes you have memorized.

The best way to learn how to use menus is to practice making menu selections with these keystrokes. If you select an option by mistake, you can always retreat to the previous menu by pressing the <ESC> key. If you are several levels deep, you can return to the Main menu by pressing the <F2> key and then typing n. <F2> takes you to the Quit option, and n returns you to the Main menu. To help you find your way through the sysadmsh menus, here is a chart of the second level menus:

<table>
<thead>
<tr>
<th>Dirs/Files</th>
<th>Processes</th>
<th>Users</th>
<th>Backups</th>
<th>System</th>
<th>Filesystems</th>
<th>Media</th>
</tr>
</thead>
<tbody>
<tr>
<td>↓</td>
<td>↓</td>
<td>↓</td>
<td>↓</td>
<td>↓</td>
<td>↓</td>
<td>↓</td>
</tr>
<tr>
<td>View</td>
<td>Terminate</td>
<td>Add Restore Halt Add</td>
<td>Execute Mount</td>
<td>Extract</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Copy</td>
<td>Delete Schedule</td>
<td>Modify Schedule Configure</td>
<td>Umount</td>
<td>Format</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Edit</td>
<td>Modify Communicate Add</td>
<td>Delete</td>
<td>Tapedump</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Modify</td>
<td>Print Archive Differences Remove UseDOS</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

This chapter uses a syntax convention for denoting a string of menu options. For example, to print a file you must select the Dirs/Files option from the main menu, and then select the Print option from the Dirs/files menu. This sequence is denoted by the shorthand notation Dirs/files → Print, and can be executed by typing dp.

When you select a menu option, one of three things happens:

- A lower lever menu is displayed,
- You are dropped into a form, or
- A XENIX command is executed and the result displayed in a scan window.

The next two sections explain the details of forms and scan windows.
2.5 Using Forms

Some menu options require additional information in order to perform the correct task. For example, the **Print** option cannot do anything until you tell it what you want to print and which printer to use. When you select an option of this sort, a form appears on the screen. By filling in the form, you give the command the information it needs.

The example below demonstrates how forms work by showing you how to print a file in your current directory. After the example, the keystrokes that allow you to move around the form, edit it, and select "Point and Pick" choices are listed.

To print a file, first select Dirs/Files→Print. The Print menu is displayed:

---

**Enter file or directory name**

24 May 1988  13:47  /usr/sysadm

---

**Print Files**

Enter the file(s) to print:

[ ? ]

Enter the name of the printer to send the files to:

[ ? ]
Notice that the highlight is on the first item in the form, and that a question mark (?) appears there. The question mark means that you can obtain a list of choices by pressing <F3>. You can enter the filename if you know it, but for the sake of this tutorial, assume you need to find the filename and press <F3> now. A window opens up overlapping part of the Print form:

```
Enter file or directory name
/usr/sysadm/*

24 May 1988 13:47 /usr/sysadm

Print Files

Enter the file(s) to print:

[ ? ]
```

The window contains a list of files that you can select. To select a file, "point" to it by moving the highlight to it, and "pick" it by pressing return. This is known as "Point and Pick," and is used whenever a range of choices is displayed. When you have made your selection, the window closes and you are returned to the Print form.

Note that the name of the file you selected is now displayed in the form. You can now change the name using the edit keys (listed later in this section), or press <RETURN> to move to the next field.
Note that a question mark appears here also. Now you should enter the name of the printer to be used. If you don’t know the printer name, press <F3> and another, smaller window is opened that contains a list of installed printers:

You can select the printer just as you did the name of the file. When you have selected a printer, you are returned to the Print menu. Press <RETURN> once more to exit the form and send the file to the printer. If you want to exit the form without executing it, press <ESC>.
The keystrokes listed in the following tables allow you to use forms easily:

## Movement, Quit, and Execute Keys

<table>
<thead>
<tr>
<th>Keystroke</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>&lt;ESC&gt;</strong></td>
<td>Tells the program that you have changed your mind and do not want to finish filling in this form. The form is removed, and no action performed. You are returned to the previous menu.</td>
</tr>
<tr>
<td>Up, Down Arrow</td>
<td>Moves to other fields in a form. Some fields are restricted and no input is allowed. The Arrow keys will skip over these. Other fields must be filled in. Pressing the Down Arrow key on the last item in a list brings you back to the first item.</td>
</tr>
<tr>
<td>Left, Right Arrow</td>
<td>Moves left and right in the current field. Allows changing of text without retyping the entire line.</td>
</tr>
<tr>
<td><strong>&lt;RETURN&gt;</strong></td>
<td>Pressing <strong>&lt;RETURN&gt;</strong> on a field completes the data entry to that field, and moves the cursor to the next field. In the last field, <strong>&lt;RETURN&gt;</strong> completes the entire form and tells the shell that the data is ready to use.</td>
</tr>
<tr>
<td><strong>&lt;CTL&gt;</strong> g</td>
<td>Exits and executes the form from wherever you are. Think g for go.</td>
</tr>
<tr>
<td>Other keys</td>
<td>You can use the spelling checker utility when you are in a form. If you think a word might be misspelled, press <strong>&lt;F4&gt;</strong> while the cursor is on the word and a list of possible correct spellings will appear in a Point and Pick list. The word you select replaces the misspelled word.</td>
</tr>
</tbody>
</table>
## Edit Keys

<table>
<thead>
<tr>
<th>Keystroke</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;CTL&gt;</code> x</td>
<td>Delete the current line, start over.</td>
</tr>
<tr>
<td><code>&lt;CTL&gt;</code> w</td>
<td>Delete the current word.</td>
</tr>
<tr>
<td><code>&lt;CTL&gt;</code> a</td>
<td>Move the cursor to the beginning of the line.</td>
</tr>
<tr>
<td><code>&lt;CTL&gt;</code> z</td>
<td>Move the cursor to the end of the line.</td>
</tr>
<tr>
<td><code>&lt;CTL&gt;</code> o</td>
<td>Toggle into or out of overstrike mode.</td>
</tr>
<tr>
<td><code>&lt;BACKSPACE&gt;</code></td>
<td>Back up and delete one character (left of cursor).</td>
</tr>
<tr>
<td>Left, Right Arrow</td>
<td>Move on the edit line.</td>
</tr>
</tbody>
</table>

## Point and Pick Keys

<table>
<thead>
<tr>
<th>Keystroke</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;RETURN&gt;</code></td>
<td>Pressing <code>&lt;RETURN&gt;</code> on a item name selects the item.</td>
</tr>
<tr>
<td><code>&lt;ESC&gt;</code></td>
<td>No item is desired, abort the selection process. The list is removed and no action performed.</td>
</tr>
<tr>
<td>Up, Down Arrow</td>
<td>Move to other items in a list.</td>
</tr>
<tr>
<td>Left, Right Arrow</td>
<td>Move across a multi-column display.</td>
</tr>
<tr>
<td><code>&lt;SPACEBAR&gt;</code></td>
<td>When the application will accept more than one item, the space bar is used to mark them. A marked item is indicated by a &quot;#&quot; character in the left column. It may be unmarked by pressing the space bar a second time while on the item. The entire collection of marked items is selected by pressing <code>&lt;RETURN&gt;</code>.</td>
</tr>
<tr>
<td><code>&lt;F5&gt;</code></td>
<td>The &quot;Search&quot; key is useful for finding items in long listings. A prompt appears and you enter the string to search for, and press <code>&lt;RETURN&gt;</code>. If the item is found, the highlight moves to that item, and another <code>&lt;RETURN&gt;</code> selects the item. If no match is found the highlight does not move.</td>
</tr>
</tbody>
</table>
sysadmsh: Using the System Administration Shell

First letter

The fastest method of selecting an item is by its first letter. Press the first letter of the item and the highlight moves to that item. Pressing <RETURN> then selects the item. If several items begin with the same letter, the cursor will move to the first occurrence in the list.

2.6 Using Scan Windows

When you execute a XENIX command by selecting a sysadmsh menu option, the result of the command is displayed in a Scan Window. Scan Windows are also used to display the contents of files and directory listings. To demonstrate the use of Scan Windows, let’s say you want to know who is currently logged on to the system. To do this, select Users→Report→Current. (This runs the XENIX who(C) command.)

When you select the Current option, a Scan Window that displays the output of the who(C) command appears in the Display Area:

```
<esc> to exit, movement keys are active


who(C)

NAME   LINE   TIME
root    tty01   24 May 10:23
faithz  tty02   24 May 11:03
faithz  tty05   24 May 10:55
karlc   tty07   24 May 07:03
teresaC tty08   24 May 08:21
barta   tty09   24 May 12:52
stevem  tty10   24 May 08:45
mattb   tty14   24 May 09:34
```
Note that the name of the command (who) and the XENIX reference section in which its description can be found (C) are displayed at the top of the window. Also note that the option given to the command (-H) is displayed in the right hand side of the Status Line. If you do not understand the information displayed, look up the command in the Xenix Reference for more information.

You can recognize a Scan Window by the vertical "scroll bar" that appears at the extreme right edge of the window. When the window is at the top of your text, the asterisk at the top of the Scroll Bar is visible. If it is at the bottom, the asterisk at the bottom of the Scroll Bar is visible. You can see both asterisks when the window contains all of the text.

The scroll bar also indicates where you are in the window. The highlighted portion of the bar represents the section of text that is currently displayed in the window. As you scroll up and down, the highlighted bar moves with you.

Use these keys when you are in a scan window:

<table>
<thead>
<tr>
<th>Action</th>
<th>Keystroke</th>
</tr>
</thead>
<tbody>
<tr>
<td>Exit the file</td>
<td>&lt;ESC&gt;</td>
</tr>
<tr>
<td>Move up one line</td>
<td>Up Arrow</td>
</tr>
<tr>
<td>Move down one line</td>
<td>Down Arrow, or &lt;RETURN&gt;</td>
</tr>
<tr>
<td>Move down a page</td>
<td>PgDn, or &lt;SPACEBAR&gt;</td>
</tr>
<tr>
<td>Move up a page</td>
<td>PgUp</td>
</tr>
<tr>
<td>Move to top of display</td>
<td>Home</td>
</tr>
<tr>
<td>Move to bottom of display</td>
<td>End</td>
</tr>
<tr>
<td>Search for a pattern in display</td>
<td>&lt;F5&gt;</td>
</tr>
<tr>
<td>Print the output of command or file currently in Scan Window</td>
<td>&lt;F7&gt;</td>
</tr>
</tbody>
</table>
2.7 Getting Help

You can press the <F1> key to display more information to help you with your selection. When you press the <F1> key, a Help window opens within your current screen. It looks like this:

```
-----------------------
Help Topic
-----------------------
```

This is how the first HELP window appears on your screen.

F1 again for more HELP

The window contains some basic information. If you need more help, you can press <F1> again and the complete Help menu is displayed:

```
F1 again for more HELP
Continue Back Index Related Search HELP Print Quit
Return to the application
```

```
sysadmsh Help Topic
```

This is what the HELP menu looks like.
From this menu you can select a variety of more detailed information. When you are finished, select Quit from the Help menu and you will be returned to your place in the sysadmsh menu proper.

Here are the menu options for Help:

<table>
<thead>
<tr>
<th>Option</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Continue</td>
<td>Continue on to the next page. All the vertical movement keys are active: Up and Down Arrows, Page Up and Down, Home and End. If there is no further information, the highlight moves to the Help menu Quit option and the Description Line reads &quot;Return to the application.&quot;</td>
</tr>
<tr>
<td>Back</td>
<td>Move back to topics that have been seen previously. There is no corresponding &quot;Forward.&quot; This is also used to back up to more general topics. You can go back until the top-level introductory topic is reached.</td>
</tr>
<tr>
<td>Index</td>
<td>Choose a new topic from a list of indexed topics.</td>
</tr>
<tr>
<td>Related</td>
<td>Choose a new topic related to the current one.</td>
</tr>
<tr>
<td>Search</td>
<td>Search for a new topic by matching a pattern. First, you specify where to look (the titles, the text lines or both), and then give the pattern. The pattern can be a simple keyword (like &quot;create&quot; or &quot;date&quot;) or a more complex &quot;regular expression.&quot; A list of topics containing the pattern is presented.</td>
</tr>
<tr>
<td>Help</td>
<td>How is the help facility itself used? A table similar to this one is displayed on the screen. If you need further information, look for your topic in Index, Related, or Search.</td>
</tr>
<tr>
<td>Print</td>
<td>Make a hardcopy printout of the current topic. First, you select which printer to use, then choose Go from the submenu to send the printout.</td>
</tr>
<tr>
<td>Quit</td>
<td>Exit Help and return to sysadmsh. &lt;F2&gt; or &lt;ESC&gt; are other ways to exit quickly.</td>
</tr>
</tbody>
</table>

Each Help screen has general information available, as well as specific information about each option listed on the menu from which Help was selected. Each descriptive passage is preceded by the associated Menu Line and followed by a reference to the XENIX Operating System.
documentation. Characters in parentheses following a command name indicate a section of the *XENIX Reference*. For example, vi(C) denotes that there is information about vi in the *XENIX Reference* (C) section.

**Note**

When you are within an actual XENIX command, you do not have access to the Help facility. For example, when you select: Dirs/Files→Edit, you are within the XENIX vi command, and the *sysadmsh* keys no longer function. When you exit the command and return to the *sysadmsh*, the keys will function as expected. If no element of the *sysadmsh* is visible on the screen (Menu Line, boxes, Context Indicator, etc.) then Help will probably not be available. If you need help, exit from the current process and press the <F1> key to view Help. In general, it is best to use Help prior to executing a menu selection.

### 2.8 Changing the Current Directory within *sysadmsh*

There are many occasions when it is necessary to change your current directory to use certain files and commands. You can move to another directory by pressing the <F6> key. The current directory is displayed at the top of the screen. You can use the <BACKSPACE> key to erase the name of the current directory (to start over), or you can add to or alter part of the current name. When you press <RETURN>, your directory change will be executed.

### 2.9 The Function Keys

The function keys give you access to several time-saving features.

<table>
<thead>
<tr>
<th>Key</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;F1&gt;</td>
<td>Help key - displays help for the current context within the application. Further information is available by pressing &lt;F1&gt; again.</td>
</tr>
</tbody>
</table>
<F2> Exit key - activates the Quit option on the top menu-level. This is an opportunity to return to the application. For some files, there is a choice of final status at this point.

<F3> List key (used within a form) - displays a list of items that are acceptable for the current field. This is similar to entering a "'?'" in a form entry.

<F4> Spell key (used within a form) - displays a list of words that are possible correct spellings of the word in the current field. Select a word from the list by pressing <RETURN>. The word is then placed in the field.

<F5> Search key (used within a window) - prompts for a string to search for. When you enter a string and press <RETURN>, the highlight moves to the item in the list that matches the pattern. If no match is found the search fails and the highlight does not move.

<F6> New directory - offers the opportunity to change your current working directory. Note that this will not change the directory you were in when you invoked sysadmsh.

<F7> Print key - prints the output of any command which is displayed in a Scan Window.

2.10 Using Shell Escapes to Access the XENIX Command Line

You can execute a XENIX command by typing the shell-escape character, an exclamation point (!). The menus are replaced by a subshell that displays a text-entry line and a prompt asking for a command. When you enter the command and press <RETURN>, the command is executed by XENIX. After the command is completed, the output is displayed on the screen and you are prompted to press any key to return to the shell.

2.11 XENIX Commands and sysadmsh Equivalents

The following table lists the XENIX commands that the various sysadmsh menu options execute. For more information on a particular command, see the manual page for the command. The reference section containing each command's manual page is given in parentheses after the command name. The C, M, and F reference sections are in the XENIX User's Reference; the ADM section is in the XENIX System Administrator's Guide.
### sysadmsh option  |  XENIX command

**Dirs/Files**
- **List:** `ls(C) -CF`
- **View:** `cat(C)`
- **Copy:** `copy(C)`
- **Edit:** `edit` (SCO Lyrix, `vi(C)`, `ed(C)` or definable via environment variable)

**Modify**
- **Permissions:** `chmod(C)`
- **Ownership:** `chown(C)`
- **Group:** `chgrp(C)`
- **Name:** `mv(C)`
- **Size:** `compress(C)`
- **Format:** `translate(C)`

**Print**
- `lp(C)` (definable via environment variable)

**Archive**
- `tar(C) -c`

**Differences**
- `dircmp(C)` or `diff(C)`

**Remove**
- `rm(C) -rf`

**UseDOS**
- **List:** `dos(C): dosdir or dosls`
- **Remove:** `dos(C): dosrdmdir or dosrm`
- **MakeDir:** `dos(C): dosmkdir`
- **Copy:** `dos(C): doscp`
- **View:** `dos(C): doscat`
- **Format:** `dos(C): dosformat`

**Processes**
- **Report:** `ps(C)`
- **Terminate:** `kill(C)`

**Users**
- **Report:** `who(C) -H`
- **Add**: similar to `mkuser(ADM)`
- **Delete**: similar to `rmuser(ADM)`
- **Modify**
  - **Username**: similar to `pwcheck(C)`
  - **Passwd**: `passwd(C)`
  - **Shell**: similar to `chsh(ADM)`
  - **Environment**: edit `.profile` or `.login`
  - **Group**: similar to `pwcheck(C)`
Communicate: mail(C) or SCO Portfolio email

Backups→
Create†: sysadmin(ADM), tar(C) -c, dd(C), or a utility similar to diskcp(C)
Restore: tar(C) -x or sysadmin(ADM)
Schedule: edit /usr/lib/sysadmin/schedule

System→
Report→
Activity: ps(C)
Users: who(C) -H
Printers: lpstat(C)
Disk: df(C) -v -i
Network→
Micnet: netutil(ADM)
UUCP: uustat(C)
Xnet: xnstatus
Messages→
Mail: mail(C) -u root
Console: tail(C) /usr/adm/messages
Software: custom(ADM)
Halt: shutdown(ADM)
Execute: run script in /usr/lib/sysadm/local
Configure→
Time: asktime(ADM)
Autologout: idleout(ADM)
Kernel: configure(ADM)
Network→
UUCP: uuinstall(ADM)
Defaults→
Message: edit motd
Checklist: edit /etc/checklist
Other: edit any file in /etc/default
International→
Individual: edit .profile or .login
System: edit /etc/default/lang
Display: mapchan(F)
Keyboard: modifies /usr/lib/keyboard/keys
Add→
HardDisk: mkdev(ADM) hd
Printer: mkdev(ADM) lp
### sysadmsh: Using the System Administration Shell

<table>
<thead>
<tr>
<th>Software</th>
<th>custom(ADM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Card_Serial</td>
<td>mkdev(ADM) serial</td>
</tr>
<tr>
<td>Delete→</td>
<td></td>
</tr>
<tr>
<td>HardDisk</td>
<td>mkdev(ADM) hd</td>
</tr>
<tr>
<td>Printer</td>
<td>mkdev(ADM) lp</td>
</tr>
<tr>
<td>Software</td>
<td>custom(ADM)</td>
</tr>
</tbody>
</table>

#### Filesystems→
- **Check**: fsck(ADM)
- **Add**: mkdev(ADM) fs
- **Mount**: mount(ADM)
- **Unmount**: umount(ADM)

#### Media→
- **List**: tar(C) -t
- **Extract**: tar(C) -x
- **Archive**: tar(C) -c
- **Format**: format(C) or dos(C): dosformat
- **Duplicate†**: similar to diskcp(C)
- **Tapedump**: tapedump(C)

†Calls a sysadmsh function that is similar to the named XENIX command.
Chapter 3
Starting and Stopping the System

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  3.2.1 Loading the Operating System 3-1
  3.2.2 Cleaning the File System 3-2
  3.2.3 Choosing the Mode of System Operation 3-2

3.3 Logging In As the Super User 3-3

3.4 Stopping the System 3-4
  3.4.1 Using the shutdown Command 3-4
  3.4.2 Using the haltsys Command 3-5
3.1 Introduction

This chapter explains how to start and stop the XENIX system. It also explains how to log in as the super user (root).

3.2 Starting the System

Starting a XENIX system requires more than just turning on the power. You must also perform a series of steps to initialize the system for operation. Starting the system requires:

- loading the operating system,
- cleaning the filesystem (if the system was improperly stopped), and
- choosing the mode of system operation.

The following sections describe each of these procedures.

3.2.1 Loading the Operating System

The first step in starting the system is to load the operating system from the computer's hard disk. Follow these steps:

1. Turn on power to the computer and hard disk. The computer loads the XENIX bootstrap program and displays the message:

   Boot:

2. Press the RETURN key. The bootstrap program loads the XENIX operating system.

When the system is loaded, it displays information about itself and checks to see if the "root filesystem" (i.e., all files and directories) is in order and not corrupted. If a filesystem is uncorrupted and in good order, it is called "clean." If the root filesystem is clean, you may choose the mode of operation. If not, the system requires you to clean the filesystem before choosing.
3.2.2 Cleaning the File System

You must clean the filesystem if the system displays the message:

```
Proceed with cleaning (y or n)?
```

This message is displayed only if the system was not stopped properly, as described in the section “Stopping the System” later in this chapter. The XENIX operating system requires a clean filesystem to work properly. If the above message does not appear, your filesystem is clean and ready to use.

To clean the filesystem, enter `y` (for “yes”) and press the RETURN key. The XENIX utility `fsck(ADM)` cleans the filesystem, repairing damaged files or deleting files that cannot be repaired. It reports on its progress as each step is completed. At some point, you may be asked if you wish to salvage a file. Always answer by entering “y” or “n” and pressing the RETURN key. For an explanation of how `fsck` works, see the “Filesystem Integrity” section of the “Using Filesystems” chapter in this guide.

When cleaning is complete, the system asks you to choose the mode of operation.

3.2.3 Choosing the Mode of System Operation

You may choose the mode of XENIX operation as soon as you see the message:

```
Type CONTROL-d to continue with normal startup,
(or give the root password for system maintenance):
```

The system has two modes: *normal operation* and *system maintenance* mode. Normal operation is for ordinary work on the system. This is the mode that allows multiple users to log in and begin work. System maintenance mode is reserved for work to be done by the system administrator. It does not allow multiple users.
Starting and Stopping the System

To choose normal operation, press Ctrl-d. The system displays a startup message and executes commands found in the command file `/etc/rc` described in the chapter "Solving System Problems." Next, the system displays the "login:" prompt. You may then log in as a normal user, as described in the "Logging In" chapter of the XENIX Tutorial, or as the super user, as described in the next section.

To choose system maintenance mode, enter the super user password (also called the "root password") and press RETURN. The system displays the message of the day and the super user prompt (#). The commands in the `/etc/rc` file are not executed. (Choose system maintenance mode only if you must do system maintenance work that requires all other users to be off the system.) When you log out of system maintenance mode using Ctrl-d, the system automatically enters normal operation.

To go from normal operation to system maintenance mode, log in as root and give the following command to shutdown the system, reboot and enter maintenance mode:

```
/etc/shutdown 2
```

Δ `sysadmsh` users select: System→Halt

3.3 Logging In As the Super User

Many system maintenance tasks, when performed during normal operation, require you to log in as the super user. For example, you must be logged in as the super user to stop the system.

In order to log in as the super user, you must know the super user password. You also need to see the "login:" message on your terminal’s screen. If you do not see this message, press Ctrl-d until it appears.

To log in as the super user, follow these steps:

1. When you see the "login:" message, enter the super user’s login name:

   `root`

   and press the RETURN key. The system prompts you for the super user’s password.

2. Enter the super user’s password and press the RETURN key. The system does not display the password as you enter it, so enter each keystroke carefully.
The system opens the super user account and displays the message of the day and the super user prompt (#).

Take special care when you are logged in as the super user. In particular, you should be careful when deleting or modifying files or directories. This is because the super user has unlimited access to all files; it is possible to remove or modify a file that is vital to the system. Avoid using wildcard designators in filenames and keep track of your current working directory.

You can leave the super user account at any time by pressing Ctrl-d.

3.4 Stopping the System

Stopping the XENIX system requires more than just turning off the computer. You must prepare the system for stopping by using either the shutdown or the haltsys command. The following sections describe each command.

3.4.1 Using the shutdown Command

The shutdown command is the normal way to stop the system and should be used whenever the system is in normal operation mode. It warns other users that the system is about to be stopped and gives them an opportunity to finish their work.

To stop the system with the shutdown command, follow these steps:

1. Log in as the super user. See the section “Logging in as Super User” in this chapter. The system opens the super user account and displays the message of the day and the super user prompt.

2. Enter:

   
   /etc/shutdown

   
   Δ sysadmsh users select: System→Halt

   
   and press the RETURN key. The system loads the command which in turn prompts you for the number of minutes you wish to have elapse before the computer stops:
3. Enter a number from 0 to 15 and press RETURN. The system displays a warning message at each terminal, asking logged-in users to finish their work and log out. As soon as all users are logged out or the specified time has elapsed, the system closes all accounts and displays the following message:

** Normal System Shutdown **
** Safe to Power Off **
-or-
** Press Any Key to Reboot **

4. Turn off the computer or press any key to reboot the system.

3.4.2 Using the haltsys Command

The `haltsys` command halts the system immediately. This command should be used only when no other users are on the system. If there are any users logged into the system when the `haltsys` command is given, they are logged out and their work in progress is lost.

To stop the system with the `haltsys` command, follow these steps:

1. Log in as the super user. The system opens the super user account and displays the message of the day and the super user prompt.
2. Enter:

/etc/haltsys

and press the RETURN key. The system displays the following message:

** Normal System Shutdown **
** Safe to Power Off **
-or-
** Press Any Key to Reboot **

3. Turn off the computer, or press any key to reboot the system.
Chapter 4
Using Filesystems

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4.1 Introduction

This chapter describes one of the most important responsibilities of a system administrator: creating and maintaining filesystems. Included is a procedure describing the most common filesystem addition: adding a second hard disk, including an option to relocate user accounts to the new filesystem. In addition, strategies for maintaining free space are discussed. The concept of "filesystem integrity" is introduced, and how XENIX repairs damaged filesystems. For information on file permissions and other security considerations, see the "Maintaining System Security" chapter in this Guide.

4.2 What is a Filesystem?

A filesystem is a distinct division of the operating system, consisting of files, directories and the information needed to locate and access them. A filesystem can be thought of as a structure that directories and files are constructed upon.

Each XENIX system has at least one filesystem on the primary hard disk. This filesystem is called "the root file system" and is represented by the symbol "/". The root filesystem contains the programs and directories that comprise the XENIX operating system. Typically, the root filesystem includes all the user directories as well. The primary hard disk can also be divided into more than one filesystem, as described in the "Installation Procedure" of the XENIX Installation Guide; one of the most common divisions is the /u filesystem, used to isolate user accounts from the root filesystem. (For more details on these filesystems, see "Planning Your Disk Layout" in the "Installation Procedure" chapter of the Installation Guide.

A XENIX system may also have other filesystems that contain special directories and application programs. Dividing the primary hard disk into multiple filesystems is done to protect the data and make maintenance easier. Adding still more filesystems by installing other hard disks expands the system storage space. New filesystems can be specifically created by the system administrator, then "attached" (mounted) and "detached" (unmounted) to the system when needed, the same way that a floppy disk is accessed. The next section describes how to add a new filesystem and, if desired, change the location of user accounts to the new disk. This is done without affecting the present configuration of the primary hard disk. (To change the current organization of filesystems on the primary hard disk, see "Changing/Adding Filesystems on the Primary Hard Disk."
4.3 Adding a Second Hard Disk

You can give the system extra room for storing user files and directories by adding a hard disk to the system. This is often the only remedy for a system that has one hard disk and suffers from chronic lack of space. See the Release Notes for a list of hard disks compatible with the current XENIX release.

You can only have one disk controller card. Software support is now provided for hard disks that do not have matching entries in the ROM tables. Switch settings on the disk controller card may need to be changed. Check your hardware manual for the hard disk drive and the computer for this information.

Before adding the new disk, you must know how to connect it to the computer. Connecting the hard disk is explained in the hardware manual provided with the disk.

Make sure the second drive is formatted and passes the manufacturer diagnostics before running XENIX. If it does not pass the diagnostic tests, you cannot use it with XENIX.

---

**Note**

In the steps outlined below, you are prompted to respond to a variety of prompts. Although it is not always designated in this documentation, remember to press RETURN (or ENTER) after you have typed each response. XENIX waits indefinitely until this is done.

---

These are the steps to add another hard disk with one XENIX filesystem and no DOS area:

1. Connect the hard disk, then boot the system and enter system maintenance mode.

2. When you are in system maintenance mode, enter:

```
/etc/mkdev hd
```

△ sysadmsh users select: System→Add→HardDisk
3. The first utility invoked by `hdinit` is `dkinit`, which sets parameters for non-standard hard disks. You see the menu:

```
Hard Disk Drive 1 Configuration
  1. Display current disk parameters
  2. Modify current disk parameters
  3. Select default disk parameters
```
Enter an option or 'q' to quit:

`dkinit` is primarily for unusual or non-standard disks. If you have a standard hard disk, one that is supported by your computer hardware or special mother board ROM, enter q followed by RETURN to continue the installation.

Entering q at this point selects the default parameters for your hard disk. Unless you know that your disk is non-standard, assume that it is standard and enter q to continue your installation with `fdisk(ADM)`. Skip to step 5.

If your disk is non-standard, you must enter in information that overrides the ROM disk configuration information, replacing it with the new information. If you are unsure of what parameters to enter for your non-standard disk, contact your disk manufacturer for this information.

4. If your disk is non-standard, `dkinit` operates as follows:

If you enter "1" or "2", you see the following display:

```
<table>
<thead>
<tr>
<th>Disk Parameters</th>
<th>Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Cylinders</td>
<td>value</td>
</tr>
<tr>
<td>2. Heads</td>
<td>value</td>
</tr>
<tr>
<td>3. Write Reduce</td>
<td>value</td>
</tr>
<tr>
<td>4. Write Precomp</td>
<td>value</td>
</tr>
<tr>
<td>5. Ecc</td>
<td>value</td>
</tr>
<tr>
<td>6. Control</td>
<td>value</td>
</tr>
<tr>
<td>7. Landing Zone</td>
<td>value</td>
</tr>
<tr>
<td>8. Sectors/track</td>
<td>value</td>
</tr>
</tbody>
</table>
```

When you see the display, "value" is replaced with the default value for that variable.
If you entered a "1", you now see the first menu again. If you entered a "2", you are now prompted:

Enter a parameter to modify or 'q' to return to the main menu:

Enter any of "1" - "8" to change the disk parameters, or q to return to the previous menu.

Enter the new value or <RETURN> to use the existing value:

If you wish to change the value, enter a new value now or press RETURN to use the existing value.

5. After you finish changing the disk parameters, enter q to return to the main menu. Next, enter q again to save the changes you made. Exiting from dkinit by entering q overwrites any parameters you have changed with the new values. If you wish to restore the default parameters after making modifications, enter "3" from the first menu.

As part of the initialization process, you may partition the hard disk, using the fdisk(ADM) utility, to support both DOS and XENIX on the same hard disk, or you can allow XENIX to use the whole disk.

6. After a moment, an fdisk menu appears on the screen. You see this option list:

1. Display Partition Table
2. Use Entire Disk for XENIX
3. Create XENIX Partition
4. Activate Partition
5. Delete Partition

Enter your choice or 'q' to quit:
Using Filesystems

If you would like XENIX to occupy the whole disk, select option "2". If your disk already has valid partitions, you will also see the following warning message:

```
Warning! All data on your disk will be lost!
Do you wish to continue? (y/n)
```

Enter y and press RETURN only if you want XENIX to occupy the whole disk. This ensures that fdisk partitions the whole disk for XENIX.

If no partitions were previously installed on your hard disk, fdisk will allocate the entire disk for XENIX without displaying the above warning.

Note that fdisk reserves the first track for masterboot and the last cylinder of the hard disk for disk diagnostics. Thus your partition begins on track 1 instead of track 0 and it ends on track 1219 instead of track 1223 in this example. Other hard disks will have different numbers.

You see the partition table again, with the following changes:

```
Current Hard Disk Drive: /dev/rhd10

<table>
<thead>
<tr>
<th>Partition</th>
<th>Status</th>
<th>Type</th>
<th>Start</th>
<th>End</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Active</td>
<td>XENIX</td>
<td>1</td>
<td>1219</td>
<td>1218</td>
</tr>
</tbody>
</table>

Total disk size: 1224 tracks (5 reserved for masterboot and diagnostics)
```

Press <RETURN> to continue.

After you press RETURN, you see the main fdisk menu, shown above. Note that the XENIX partition must be active before exiting fdisk. Type q to exit fdisk and continue with the installation.

For more information on having DOS and XENIX on your hard disk, see fdisk(ADM).
If you had a large portion of the disk already allocated to DOS, you must run DOS to deallocate this area. See \texttt{fdisk(ADM)} for more information on sharing disks between DOS and XENIX. No matter what configuration you produce with \texttt{fdisk}, the active partition must be the XENIX partition when you are through.

7. Now you see a menu from the program \texttt{badtrk(ADM)}. With the \texttt{badtrk} program, you can scan your hard disk for defective tracks. The program maps any flawed locations to good tracks elsewhere on the disk. It also creates a bad track table, which is a list of all the bad tracks on your hard disk.

The main \texttt{badtrk} menu looks like this:

\begin{verbatim}
1. Print Current Bad Track Table
2. Scan Disk (You may choose Read-Only or Destructive later)
3. Add Entries to Current Bad Track Table by Cylinder/Head Number
4. Add Entries to Current Bad Track Table by Sector Number
5. Delete Entries Individually from Current Bad Track Table
6. Delete All Entries from Bad Track Table

Please enter your choice or 'q' to quit:

Enter "2", then press RETURN.

8. You see the following submenu:

\begin{verbatim}
1. Scan entire XENIX partition
2. Scan a specified range of tracks
3. Scan a specified filesystem

Select option "1".
\end{verbatim}
9. After you select the area you want scanned, you are given the choice:

1. Quick scan (approximately 7 megabytes/min)
2. Thorough scan (approximately 1 megabyte/min)

Select option "2".

10. You are prompted:

Do you want this to be a destructive scan? (y/n)

Enter y. You are warned:

This will destroy the present contents of the region you are scanning. Do you wish to continue? (y/n)

Enter y and press RETURN. You see the following message:

Scanning in progress, press 'q' to interrupt at any time.

11. After you respond to the above prompts, the program scans the active partition of the new disk for flaws. The larger your disk, the longer the scanning process takes, so a very large disk may take a while.

As badtrk scans the disk, it displays the number of each track it examines, and the percentage of the disk already scanned. Pressing the q key at any time interrupts the scan. If you press q to interrupt the scan you do not need to press RETURN. You are then prompted to continue scanning or to return to the main menu.
Whenever badtrk finds a defective track, it lists the location of that track using both the sector number and cylinder/head conventions.

12. **If your disk comes with a flaw map**, you should enter any flaws from it into the bad track table.

Because most disk flaws are marginal or intermittent, your disk’s flaw map will probably list more bad tracks than the scanning process reveals. If so, you should now add these defective tracks to the bad track table.

Select either option ‘‘3’’ or option ‘‘4’’ depending upon the format of the flaw map furnished with your disk. Enter the defective tracks, one per line. If you make a mistake, enter q and press RETURN. When you see the main badtrk menu, select option ‘‘5’’ to delete a track.

13. **If your disk is not furnished with a flaw map, or you are finished making changes to the bad track table**, enter q and press RETURN.

14. The program displays the number of identified bad tracks. You are next prompted for the number of tracks to allocate as replacements for those tracks that are flawed. You should allocate at least as many as the recommended number. Enter the number or just press RETURN to use the recommended number that is displayed:

   Enter the number of bad tracks to allocate space for (or press return to use the recommended value of n):

If you press RETURN and do not enter an alternate value, badtrk allocates the recommended number of tracks as replacements. This number is based on the number of bad tracks currently in the table, plus an allowance for tracks that may go bad in the future. If you ever exceed the number of allocated bad tracks, you must reinstall XENIX.
15. **Next, badtrk prompts:**

   Do you want to update this device with the new table?

   Enter *y* and press RETURN to save the changes. To correct any mistakes or otherwise alter the bad track table, enter *n*. Modify the bad track table to contain the desired entries, enter *q* at the main menu to return to the prompt displayed above, then enter *y* to update the device with the new table.

16. **Next, you see:**

   Do you want to attempt to salvage any valid data on the bad tracks? [may take a long time] *(y/n)*

   Enter *n* and press RETURN.

17. **Next, you see a prompt from divvy. The divvy program divides a partition into filesystems. You can create up to seven divisions on a single partition, and name them anything you like.**

   If the hard disk you are installing is 20 megabytes or larger, you will be prompted for the number of filesystems you want to create. Press **RETURN** to use the default value of one filesystem. Smaller hard disks automatically default to creating one filesystem.

   You are next prompted for block control of your hard disk. You see:

   Do you require block by block control over the layout of the XENIX partition? *(y/n)*

   Enter ‘*y*’ and press RETURN. This allows you to create up to seven filesystems on a single XENIX partition, and assign specific names to whatever filesystems you create. You must enter ‘*y*’ if you prompted to create more than 1 filesystem in the previous prompt.
You see the main divvy menu and a display that shows you how your disk is divided:

<table>
<thead>
<tr>
<th>Name</th>
<th>New File System?</th>
<th>#</th>
<th>First Block</th>
<th>Last Block</th>
</tr>
</thead>
<tbody>
<tr>
<td>no</td>
<td>no</td>
<td>0</td>
<td>0</td>
<td>25302</td>
</tr>
<tr>
<td>no</td>
<td>1</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>no</td>
<td>2</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>no</td>
<td>3</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>no</td>
<td>4</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>no</td>
<td>5</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>no</td>
<td>6</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>hdal</td>
<td>no, exists</td>
<td>7</td>
<td>0</td>
<td>25546</td>
</tr>
</tbody>
</table>

25303 blocks for divisions, 244 blocks reserved for bad tracks

n[ame] Name or rename a division.

c[reate] Create a new filesystem on this division.
p[revent] Prevent a new filesystem from being created...

s[tart] Start a division on a different block.
e[nd] End a division on a different block.
r[estore] Restore the original division table.

Please enter your choice or 'q' to quit:

Each row in the divvy table corresponds to a filesystem. When you first see the table, there may be one or more filesystems created. If your disk is larger than 20 megabytes, you will see the number of filesystems that you specified at the first divvy prompt. You can change the default size of these filesystems by using the “start” and “end” options from the main divvy menu. Note that filesystem boundaries must not overlap. For example, filesystem 0 cannot end on the block number where filesystem 1 begins.

When you first see the main divvy menu, the filesystems are not named. Use option ‘n’ to change the name of a filesystem. Filesystems can have any name you choose. For example, you could name a filesystem u (for “user”).

Do not change the configuration of filesystem 7. It is reserved for internal use by XENIX.

Once you have defined the start and end points of your filesystems, be sure to use the “(c)reate” option for each filesystem to make the filesystems on the disk.
Exit from divvy by entering ‘q’. The program may prompt whether to install the new partition table, return to the main menu or exit the program without installing partition table. Select option ‘i’ to install the partition table.

If you have a large filesystem, you may be prompted if you want a scratch device to be created for you. You should answer yes as the scratch device is very useful for fsck.

For more information, see divvy(ADM) in this guide.

4.3.1 Mounting the New Filesystem

To use an additional disk, or create a second, mounted filesystem, you must make a new filesystem and mount it onto your system. The divvy n[ame] menu option created the device node /dev/u. The next step is to create the filesystem itself. Using the filesystem /u as an example, this is how the actual filesystem is created:

```
mkdev fs /dev/u /u
```

\[ sysadmsh users select: Filesystems → Add \]

This command does the following:

- Creates a directory /u (also known as the mountpoint).
- Creates the lost+found directory (used by fsck to recover files if the filesystem is corrupted).
- Mounts the device (/dev/u) on /u, cleans it, and unmounts it.
- Removes write permissions on the directory /u for group and all other users except root.
- Creates files in the /ulost+found directory, then removes them. This allocates inodes for the directory, so that if the filesystem is corrupted and runs out of inodes, fsck(ADM) is still able to recover files.
- Adds the following line to /etc/checklist:

```
/dev/u
```
- Prompts you to decide if the new filesystem is to be automatically mounted, checked, and cleaned at boot time or not.
Note

Note that your new filesystem does not have to be called /u. You can name your filesystems and mount points as you choose. It is recommended that mount points and filesystems have the same name to avoid confusion.

To mount or unmount /dev/u on /u, use the following two commands respectively:

```
mount /dev/u /u
```

```
unmount /dev/u
```

Only the super-user can use the `mount` command. The system administrator can permit users to mount specific filesystems (with or without password protection) by using the `mnt(C)` command. (For more information, refer to “Permitting Users to Mount Filesystems” in the “Maintaining System Security” in this guide.)

### 4.3.2 Moving User Accounts Off the Primary Hard Disk

You can access the files on your new filesystem by first mounting it in the appropriate directory (we used /u as an example in the preceding section). After you mount the filesystem, all directories and files on it are usable just as any others on the system.

Extending the example set forth in the previous sections, let’s assume that you want to move your user accounts to the new /u filesystem on your secondary hard disk. The first thing to do is to ensure that any new accounts you add to the system will be placed in the new location. The `mkuser(ADM)` command (used to create new user accounts) reads the default location for user accounts from the file `/etc/default/mkuser`. In particular, the variable ‘HOME’ must be changed to reflect the new location.
Edit the file `/etc/default/mkuser`. As distributed, the file has an entry that looks like this:

```
HOME=/usr
```

If you wish to use `/u`, change the entry accordingly to the name of the directory where you want to place user accounts. Now, whenever you run the `mkuser` command to add a new user, that user account will be in `/u`. Make certain that the `/u` filesystem is mounted before you run the `mkuser` script, or the new user’s directory will not be accessible when `/u` is mounted.

If there are already users on the system, and you want to move their accounts to the new filesystem, you can use the `cp(1)` command to copy their accounts to the new filesystem. You must also change the users’ entries in `/etc/passwd` to reflect the new pathnames of their home directories.

Follow these steps to move user accounts from one filesystem to another:

1. Make sure the new filesystem is mounted and the account in question is not being used. Also, be sure you are logged in as root.

2. Change directories to the top of the current user account directory. If, for example, the user accounts are in `/usr`, enter:

```
cd /usr
```

and press RETURN.

3. List the contents of this directory:

```
ls
```

You see a list of account names, for example:

```
alisonb  dean  jerrys  sams
blf  gregt  lost+found  tammyr
buckm  jeffj  pj  vicki
```
4. Enter:

```
copy -orm /usr /u
```

and press RETURN.

5. When the `copy` command has finished, enter:

```
cd /u
```

and press RETURN. List the new contents of `/u` to make sure all of the accounts have been copied correctly.

6. After you are sure that all of the accounts have been completely copied, you can remove the user accounts in the previous user filesystem by removing files, directories and aliases to that location.

7. Change the home directory for each user as listed in `/etc/passwd`. An example entry in `/etc/passwd` might be:

```
alb:CoHiKNs:271:104:Al Berry:/usr/alb:/bin/csh
```

You see one such line for every user on your system. Change the field:

```
:/usr/alb:
```

to match the user's new home directory:

```
:/u/alb:
```

Do this for every user whose home directory has changed.

4.4 Maintaining Free Space In Filesystems

Filesystem maintenance, an important task of the system administrator, keeps the XENIX system running smoothly, keeps the filesystems clean, and ensures adequate space for all users. To maintain the filesystems, the system administrator must monitor the free space in each filesystem, and take corrective action whenever it gets too low.

This chapter explains the filesystem maintenance commands. These commands report how much space is used, locate seldom-used files, and remove or repair damaged files.

The XENIX system operates best when at least 15% of the space in each filesystem is free. In any system, the amount of free space depends on the
Using Filesystems

size of the disk containing the filesystem and the number of files on the disk. Since every disk has a fixed amount of space, it is important to control the number of files stored on the disk.

If a filesystem has less than 15% free space, system operation usually becomes sluggish. If no free space is available, the system stops any attempts to write to the filesystem. This means that the user's normal work on the computer (creating new files and expanding existing ones) stops.

The only remedy for a filesystem which has less than 15% free space is to delete one or more files from the filesystem. The following sections describe strategies for keeping the free space available.

4.4.1 Strategies for Maintaining Free Space

The system administrator should regularly check the amount of free space on all mounted filesystems and remind users to keep their directories free of unused files. You can remind users by including a reminder in the message of the day file /etc/motd.

If the amount of free space slips below 15%, the system administrator should:

1. Send a system-wide message asking users to remove unused files.
2. Locate exceptionally large directories and files, and send mail to the owners asking them to remove unnecessary files.
3. Locate and remove temporary files and files named core.
4. Clear the contents of system log files.
5. Make a complete backup of the filesystem, remove all the files, and then restore them again from the backup.
6. If the system is chronically short of free space, it may be necessary to create and mount an additional filesystem.

The above suggestions are described in detail in the following sections.
4.4.2 Displaying Free Space

You can find out how much free space exists in a particular filesystem with the `df` (for "disk free") command. This command displays the number of "blocks" available on the specific filesystem. A block is 512 characters (or bytes) of data.

The `df` command has the form:

```
   df specialfile
```

`specialfile` can be the name of a XENIX special file corresponding to the disk drive containing the file system. If you do not give a special filename, then the free space of all normally mounted file systems is given.

For example, to display the free space of the root filesystem `/dev/root`, enter:

```
   df /dev/root
```

and press RETURN. The command displays the special filename and the number of free blocks. You can find the percentage of free space to total space on your system with the command:

```
   df -v
```

4.4.3 Sending a System-Wide Message

If free space is low, you may send a message to all users on the system with the `wall` (for "write to all") command. This command copies the messages you enter at your terminal to the terminals of all users currently logged in.

To send a message, enter:

```
   wall
```

and press RETURN. Enter the message, pressing RETURN to start a new line if necessary. After you have entered the message, press Ctrl-d. The command displays the message on all terminals in the system. To leave the `wall` command, press Ctrl-d. This removes the link to other terminals.
4.4.4 Displaying Disk Usage

You can display the number of blocks used within a directory by using the du command. This command is useful for finding excessively large directories and files.

The du command has the form:

```
   du  directory
```

The optional directory must be the name of a directory in a mounted filesystem. If you do not give a directory name, the command displays the number of blocks in the current directory.

For example, to display the number of blocks used in the directory /usr/johnd, enter:

```
   du /usr/johnd
```

and press RETURN. The command displays the name of each file and directory in the /usr/johnd directory and the number of blocks used.

4.4.5 Displaying Blocks by Owner

You can display a list of users and the number of blocks they own by using the quot (for “quota”) command. The command has the form:

```
   quot  specialfile
```

The specialfile must be the name of the special file corresponding to the disk drive containing the filesystem.

For example, to display the owners of files in the filesystem on the hard drive /dev/hd1, enter:

```
   quot /dev/hd1
```

and press RETURN. The command displays the users who have files in the filesystem and the numbers of blocks in these files.
4.4.6 Mailing a Message to a User

If a particular user has excessively large directories or files, you may send a personal message to the user with the `mail` command.

To begin sending a message through the `mail` command, enter:

```
mail login-name
```

and press RETURN. The `login-name` must be the login name of the recipient. To send a message, enter the message, press RETURN, and then press Ctrl-d. If the message has more than one line, press RETURN at the end of each line. The `mail` command copies the message to the user’s mailbox, where it may also be used via the `mail` command. See the XENIX User’s Guide for details.

4.4.7 Locating Files

You may locate all files with a specified name, size, date, owner, and/or last access date by using the `find` command. This command is useful for locating seldom-used and excessively large files.

The `find` command has the form:

```
find directory parameters
```

The `directory` must be the name of the first directory to be searched. (It will also search all directories within that directory.) The parameters are special names and values that tell the command what to search for. See `find (C)` in the XENIX User’s Reference for complete details. The most useful parameters are:

- `name file`
- `atime number`
- `print`

The `-name` parameter causes the command to look for the specified `file`. The `-atime` parameter causes the command to search for files which have not been accessed for the `number` of days. The `-print` parameter causes the command to display the locations of any files it finds.
For example, to locate all files named temp in the directory /usr, enter:

```
find /usr -name temp -print
```

and press RETURN. The command displays the locations of all files it finds.

### 4.4.8 Locating core and Temporary Files

You can locate core and temporary files with the `find` command.

A core file contains a copy of a terminated program. The XENIX system sometimes creates such a file when a program causes an error from which it cannot recover. A temporary file contains data created as an intermediate step during execution of a program. This file may be left behind if a program contained an error or was prematurely stopped by the user. The name of a temporary file depends on the program that created it.

In most cases, the user has no use for either core or temporary files, and they can be safely removed.

When searching for core or temporary files, it is a good idea to search for files which have not been accessed for a reasonable period of time. For example, to find all core files in the /usr directory that have not been accessed for a week, enter:

```
find /usr -name core -atime +7 -print
```

and press RETURN.

### 4.4.9 Clearing Log Files

The XENIX system maintains a number of files, called log files, that contain information about system usage. When new information is generated, the system automatically appends this information to the end of the corresponding file, preserving the file's previous contents. This means the size of each file grows as new information is appended. Since the log files can rapidly become quite large, it is important to clear the files periodically by deleting their contents.

You can clear a log file by entering:

```
cat < /dev/null > filename
```

where `filename` is the full pathname of the log file you wish to clear. A log file normally receives information to be used by one and only one program, so its
name usually refers to that program. Similarly, the format of a file depends on the program that uses it.

In some cases, clearing a file affects the subsequent output of the corresponding program. For example, clearing the file `/etc/ddate` forces the next backup to be a periodic backup.

### 4.4.10 Removing and Restoring a Filesystem

If your system has been in use for some time, the constant creation and removal of files creates a situation called *disk fragmentation*. This means that the files in the filesystem are written in small pieces on the hard disk. A small amount of disk space is used when a file is written across more than one portion of the disk. You can recover filesystem space (generally about 5 to 10 percent) by first making a complete backup of all the files in the filesystem and then removing all the files from the hard disk and restoring them from the backup. To make a complete backup of your system files, read the "Backing Up Filesystems" chapter in this guide for instructions on how to backup and restore a filesystem. (Disk fragmentation is a performance issue; for more information refer to the "Tuning System Performance" chapter in this guide.)

Since the files are completely rewritten on the disk, each file is written in one piece and fragmentation is reduced. A small amount of space will be recovered. It is a good idea to perform this action about once a year on a heavily used system and less often on a lightly used system. Be certain that you have complete, accurate, and readable backups before you begin or your files may be lost.

### 4.4.11 Expanding the Filesystem

If free space is chronically low, it may be to your advantage to expand the system's storage capacity by adding a second hard disk as described earlier in this chapter. Once it is mounted, you may use this new filesystem for your work, or even copy user or system directories to it.

A chronic shortage of space usually results from having more users on the system than the current hard disk can reasonably handle, or having too many directories or files. In either case, creating a new filesystem allows some of the users and directories to be transferred from the hard disk, freeing a significant amount of space on the existing filesystem and improving system operation.
4.5 Filesystems and Large Directories

It is wise to avoid directories that are larger than necessary. You should be aware of several special sizes. A directory that contains entries for up to 30 files (plus the required . and ..) fits in a single disk block and can be searched very efficiently. One that has up to 286 entries is still a small directory; anything larger is usually a disaster when used as a working directory. It is especially important to keep login directories small, preferably one block at most. Note that, as a rule, directories never shrink. This is very important to understand, because if your directory ever exceeds either the 30 or 286 thresholds, searches will be inefficient; furthermore, even if you delete files so that the number of files is less than either threshold, the system will still continue to treat the directory inefficiently.

4.6 Changing/Adding Filesystems on the Primary Hard Disk

It is always best to plan the layout of your hard disk in advance as described in the XENIX Installation Guide. If you decide to change the number of filesystems on your hard disk, then you must back up your system and reinstall as described in the "Reinstalling and Updating Your System" chapter of the XENIX Installation Guide. During the installation process, you will use "block-by-block" control to reapportion your disk space as desired. It is important to realize that you cannot use backups created by the backup(C) or sysadmin(ADM) utilities to restore your system. Backups created by these utilities cannot be used to restore filesystems that were larger than the filesystems you plan to restore them to. This is true even if the backed-up filesystem was not full. For example, if you backed up a twenty megabyte filesystem that was only 50 percent full, you still won't be able to restore the backup volumes on a fifteen megabyte filesystem. The reinstallation chapter explains that you must use tar(C) to back up your system.

4.7 Filesystem Integrity

We have explained that a filesystem is a distinct division of the XENIX operating system. It is part of the job of the operating system to maintain the integrity of filesystem data. Actual loss of data is a rare occurrence; XENIX filesystems are very resistant to corruption. This is because a certain amount of redundancy exists in special structures that are invisible to the user. It is these structures that ensure filesystem integrity. For example, when the system suffers a power outage, very little information is lost. Any damage usually affects one or two files, making them inaccessible. 99 percent of the time, XENIX can repair any damage done to files. In very rare cases, damage causes the entire filesystem to become inaccessible.
The XENIX system uses the \texttt{fsck} program to repair damaged filesystems. \texttt{fsck} (for "filesystem check") checks the consistency of filesystems. In cases where the contents of a file are lost (rare), the only way to restore lost data is from filesystem backups. \texttt{fsck} is run automatically on the root filesystem at boot time. The \texttt{fsck} status messages look like this:

\begin{quote}
** Phase 1 - Check Blocks and Sizes  
** Phase 2 - Pathnames  
** Phase 3 - Connectivity  
** Phase 4 - Reference Counts  
** Phase 5 - Check Free List
\end{quote}

If the system terminated abnormally (power outage) you see other messages that may seem alarming:

\begin{quote}
FREE INODE COUNT WRONG IN SUPERBLK (FIX?)
\end{quote}

In fact, this kind of message is routine when a system was not shut down properly, and you have only to enter \texttt{y} and \texttt{fsck} will continue its recovery work. This could be done without the system administrator’s intervention, but it is generally better to know what is happening to a filesystem after a problem has occurred.

In order to discuss the idea of filesystem integrity and how \texttt{fsck} functions, it is useful to explain the structure that underlies the simple idea of files, directories and filesystems. Although it is not necessarily vital to understand the principles of file storage, it is helpful to know what the messages like the one above refer to so they will seem less mysterious. After reading this section, you will understand some of the most basic principles of the XENIX operating system. The section "Repairing a Filesystem with \texttt{fsck}" explains the simple mechanics of using the \texttt{fsck} command. The subsections that follow explain the filesystem structures that \texttt{fsck} deals with.

### 4.7.1 How XENIX Maintains Files

Each filesystem contains special structures that allow the operating system to access and maintain the files and data stored on the filesystem. It is the disruption and repair of these structures that we are concerned with.

The structure of a filesystem is based on the way that hard disks store data. Although the hard disk contains all the data used by the system, it is not stored in neat little locations that correspond to individual files. It is unlikely that you could point to a spot on a hard disk and truthfully say: ‘‘My file is stored right there on this part of the disk.’’ In fact, the data is probably scattered across the disk, and a sophisticated addressing scheme is used by the
operating system so that it can access each of the pieces that a file is broken into and present it to the user as a unit.

The reason that data is spread around is because the operating system doesn’t really deal with files, but with units of data. To explain what this means, let’s assume that a file is created and is actually stored on one part of the disk. Now, suppose you edit that file, and delete a few sentences here and there. That means you are using a little bit less disk space then when you started. This space amounts to a series of gaps in the area where your file was stored. Disk space is a precious commodity and is not wasted. Those small amounts of memory are then allocated to other files. Picture this process on a scale of hundreds of files with a dozen users and you have an idea of how files are maintained in XENIX. Because of the effectiveness of the algorithms (formulas) that the operating system uses, this process is remarkably efficient and trustworthy.

4.7.2 How XENIX Maintains Filesystems

A filesystem contains files and directories, which are represented by special structures called “inodes” and “data blocks” that make it possible for the operating system to create and keep track of them:

- **Data blocks**: Blocks are units of data stored on the disk.
- **Inodes**: Inodes can be thought of as a card from a library card catalog. Each inode contains information about a file, just as a card contains information about a book, including its location and other important information. One important point to remember is that an inode does not contain the name of a file; directories contain the actual names. Inodes contain the locations of all the data that makes up a file so the operating system can collect it all when needed.

Blocks are not just stored on the hard disk. In order to minimize seeking data on the hard disk, recently-used data blocks are held in a cache of special memory structures called buffers. It is these structures that make the operating system more efficient. Some information is always lost when an outage occurs because recently-changed data that has not yet been written to the disk, but this is very minor.

With a hard disk filled with data, inodes, directories, files, and blocks cached in memory, how does the operating system keep track of them? The answer is that all these structures maintain sufficient connectivity between files and directories to allow severed connections to be reconstructed.
One special data block, the "super" block, contains overall information about the filesystem, rather than where a particular piece of a file is located. The super block contains the information necessary to mount a filesystem and access its data. It contains the size of the filesystem, the number of free inodes, and information about free space available.

In the case of the super block, the information is read when the filesystem is mounted, maintained in memory and written back to the disk every thirty seconds (the command `ps -ale` will show a process called "update." It is this process that writes to the super block.)

### 4.7.3 Causes of Filesystem Corruption

In the case of all the structures mentioned in this section, corruption can occur. This means that the data or the structures used to locate data can be damaged. This can occur for several reasons:

<table>
<thead>
<tr>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hardware Failure</td>
<td>Hardware failures are rare. The best way of dealing with it is to be sure that recommended diagnostic and maintenance procedures are followed conscientiously.</td>
</tr>
<tr>
<td>Program Interrupts</td>
<td>It is possible that errors that cause a program to fail might result in the loss of some data. It is not easy to generalize about this because the range of possibilities is so large.</td>
</tr>
<tr>
<td>Human Error</td>
<td>While it may be painful to admit it, probably the greatest cause of filesystem corruption falls under this heading. Here are three rules that should be followed when managing filesystems.</td>
</tr>
</tbody>
</table>

### 4.7.4 Rules For Checking Filesystems

1. **ALWAYS** check a filesystem before mounting it. Nothing complicates the problem of cleaning up a corrupt filesystem so much as allowing it to be used when it is bad.

2. **NEVER** remove a filesystem physically without first unmounting it.

3. **ALWAYS** use the `sync(C)` command before shutting the system down and before unmounting a filesystem. (The `sync` command writes data in the buffer cache back to the disk.)
Regular filesystem backups represent the best assurance of continued filesystem integrity.

4.7.5 Repairing a Filesystem with fsck

You can repair a filesystem with the fsck command. A filesystem must be unmounted before running fsck. (The root filesystem can’t be unmounted, so the system must be shut down first and brought up again in single-user (maintenance) mode.) fsck examines the various structures on the disk and attempts to reconcile them. Where possible, it reestablishes connections, resolves references, it "cleans" a filesystem.

The command has the form:

```
fsck specialfile
```

\[\text{△ sysadmsh users select: Filesystem→Check}\]

The specialfile must be the name of the special file corresponding to the device name of the filesystem.

For example, let’s assume that you have brought up your system after a power failure and are in single-user mode. To check the filesystem /u, which is represented by the device /dev/u, you would enter:

```
fsck /dev/u
```

and press RETURN. The program checks the filesystem and reports on its progress with the following messages:

```
** Phase 1 - Check Blocks and Sizes
** Phase 2 - Pathnames
** Phase 3 - Connectivity
** Phase 4 - Reference Counts
** Phase 5 - Check Free List
```

If a damaged file is found during any one of these phases, the command asks if it should be repaired or salvaged. Enter y to repair a damaged file. You should always allow the system to repair damaged files even if you have copies of the files elsewhere or intend to delete the damaged files.

Note that the fsck command deletes any file that it considers too damaged to be repaired. You may elect to have fsck either make the repair or not. The reason you might choose to have fsck ignore an inconsistency is that you judge the problem to be so severe that you want either to fix it yourself using
the `fsdb(ADM)` utility, or you plan to restore your system from backups. If you cannot use `fsdb`, you must allow `fsck` to resolve the inconsistencies or the filesystem may not be usable.

Note that you may need to run `fsck` several times before the entire filesystem is clean. For a complete list of error messages, see the `fsck(ADM)` manual page.

### 4.7.6 Summary of fsck Phases

`fsck` scans and examines each of the structures mentioned earlier. Each phase compares components and checks that the these components agree with each other.

Phase 1 checks the blocks and sizes. `fsck` reads the inode list to determine the sizes and locate the blocks used by each file. Inodes are checked for validity which includes checking inode type, zero link counts, inode sizes, and for bad or duplicate blocks. (Bad blocks are block values outside the boundary of a filesystem.) When `fsck` asks whether or not to clear an inode, this means to zero out the bad information in the node. This removes the file or directory that was associated with it. A duplicate block means that two files point to the same block on the disk. `fsck` attempts to find the original inode along with the duplicate for correction in Phase 2.

Phase 2 checks the path names. Files removed in Phase 1 must then have their directory entries removed. Phase 2 cleans up error conditions caused by improper inode status, out of range inode pointers, and directories that point to bad inodes as described earlier. For files with duplicate blocks found in Phase 1, `fsck` will want to remove both files (this is one of the few areas where system administrator intervention is useful).

Phase 3 checks for connectivity. Phase 2 removed directories that don’t point to valid files. Phase 3 reconnects files that have been severed from from the directory structure. Any files that are unreferenced but valid are placed in a special directory called `lost+found`. Because the directory has been severed, the name of the file is lost and a number is assigned to the file in `lost+found`.

Phase 4 checks the reference counts. `fsck` checks the link count of each entry that survives Phases 2 and 3. In some cases, files that were not pointed to under the directory structure but still have an inode can be relinked back to the file system in `lost+found`. 

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Phase 5 checks the free list. `fsck` examines the free-block list maintained by the filesystem and resolves the missing or unallocated blocks allocated or removed earlier. When an inconsistency is detected, `fsck` prompts to rebuild it.

Phase 6 salvages the free list. If specified in Phase 5, the system reconstructs a free block list from the altered filesystem.

### 4.7.7 Automatic Filesystem Check

The XENIX system sometimes requests a check of the filesystem when you first start it. This usually occurs after an improper shutdown (for example, after a power loss). The filesystem check repairs any files disrupted during the shutdown.
Chapter 5

Maintaining System Security

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5.1 Introduction

This chapter outlines XENIX facilities and strategies for maintaining system security. System security can be reduced to two major components:

- Prevention of theft; of data on a system and of the system itself.
- Prevention of tampering; with data on a system and to the system itself.

Both aspects of security are important. Thefts can be prevented and tampering eliminated by the following:

- user education
- administrator education
- management education
- hardware confinement
- software support

Notice that software and hardware are at the bottom of the list. This is because the best software in the world is essentially useless if users give away their passwords. (Basic security is discussed from a user standpoint in "Keeping Your Account Secure" in "Logging In" chapter of the XENIX Tutorial.)

Users must be trained not to do such things as revealing their passwords or writing them down. The same is true for system administrators. Management must not only agree that theft- and tamper-prevention are important, but must support appropriate efforts to provide such prevention if system security in to be reliable.

This chapter describes controlling and recording user access to the files and directories on the system. It also introduces system security, permissions, password protection on various facilities, and process accounting.

5.2 General Security Practices

Every system, no matter what its size, should have some form of protection from unauthorized access to the computer, disks, and system files. The following sections suggest ways for a system administrator to protect the system.
5.2.1 Physical Security

You can protect the physical components of the computer, especially system disks, by taking these steps:

1. Keep your hardware secure and locked when not in use.

2. Organize and lock up all floppy disks when not in use. They should not be stored with the computer itself.

3. Keep disks away from magnetism, direct sunlight, and severe changes in temperature.

4. Do not use ball point pens to write labels on disks.

5. Make backup copies of all floppy disks. See the section “Copying Floppy Disks” in the “Using Floppy Disks and Tape Drives” chapter.

6. Keep an accurate and complete system log.

5.2.2 Access Security

You can protect the system from access by unauthorized individuals by taking these steps:

1. Remind users to log out of their accounts before leaving the terminal.

2. Remind users to use the lock(C) utility if they leave their terminals even for a short time.

3. Force logouts on idle terminals with the idleout(ADM) command.

   △ sysadmsh users select: System→Configure→Autologout

4. Discourage users from choosing passwords that are easy to guess. Passwords should be at least six characters long and include letters, numerals, and punctuation marks.

5. Passwords should not be people's or pet names, place names, or any word that can be found in /usr/dict/words. Passwords should not be normal words spelled backwards or altered in any standard way. For example, “pig latin” forms of words should not be used. Passwords should never be normal words with an extra character or
numeral added. For example, "sally0" is a poor password choice.

6. Words from different languages or strings of short words make good password choices, provided they are not easily guessed. For example, a good password choice could be "gloCkenspiel." Note that one of the central characters is capitalized and there is a period at the end of the word. The word is unusual and long enough to prevent easy guessing or decoding using a password testing program.

7. Passwords should be kept secret at all times. Passwords should never be written down, sent over electronic mail, or verbally communicated.

8. Force users to change their passwords regularly with the `pwadmin(ADM)` command.

9. Keep the super-user password secret from all but necessary people and change it regularly.

10. Restrict access to the XENIX distribution floppies.

11. Maintain permissions on important directories such as `/etc`, `/bin`, `/usr`, and `/dev`. These directories should be readable and executable by all users but only the super user should have write permission. Incorrect permissions on these directories are a serious lapse in system security. In addition, maintain the permissions on important system utilities such as `mkuser`, `shutdown`, `haltsys`, `restore`, `setuid`, and other utilities reserved for the super user. XENIX is distributed with the correct permissions set on all files and directories. If these permissions are not changed, they will not present a system security problem.

### 5.2.3 Protecting Special Files

You can prevent ordinary users from gaining direct access to the data and program files on the system's hard and floppy disks by protecting the system's special files. The XENIX special files, in the `/dev` directory, are used primarily by the system to transfer data to and from the computer's hard and floppy disks, as well as other devices, but can also be used by ordinary users to gain direct access to these devices.

Since direct access bypasses the system's normal protection mechanisms and allows ordinary users to examine and change all files in the system, it is wise to protect the special files to ensure system security.
To protect the XENIX special files, log in as the super user and use the `chmod` command to set appropriate permissions. For example, to disallow any access by ordinary users, set the permissions of such special files as `/dev/mem`, `/dev/kmem`, `/dev/root`, and `/dev/usr` to read and write access for the user only. Note that you must not change the permissions for the `/dev/tty` files.

5.3 Permissions

Permissions control access to all the files and directories in a XENIX system. In XENIX, ordinary users may access those files and directories for which they have permission. All other files and directories are inaccessible.

There are three different levels of permissions: user, group, and other. User permissions apply to the owner of the file; group permissions apply to users who have the same group ID as the owner; and other (public) permissions apply to all other users.

5.3.1 Displaying Permissions

Any user can display the permission settings for all the files in a directory with the `l` (for “list directory”) command. This command lists the permissions along with the name of the file owner, the size (in bytes), and the date and time the file was last changed. The command display has the following format:

```
-rw-rw---- 1 johnd group 11515 Nov 17 14:21 file1
```

The permissions are shown as a sequence of ten characters at the beginning of the display. The sequence is divided into four fields. The first field (the “type” field) has a single character, the other fields (“user,” “group,” and “other”) have three characters each. The characters in the fields have the following meanings.

In the type field:

- `d` Indicates the item is a directory
Maintaining System Security

- Indicates the item is an ordinary file
b Indicates the item is a device special block I/O file
c Indicates the item is a device special character I/O file

In the "user," "group," and "other" fields:

r Indicates read permission. Read permission for a file means you may copy or display the file. Read permission for a directory means you may display the files in that directory.

w Indicates write permission. Write permission for a file means you may change or modify the file. Write permission for a directory means you may create files or subdirectories within that directory.

x Indicates execute permission (for ordinary files) or search permission (for directories). Execute permission for a file means you may invoke the file as you would a program. Execute permission for a directory means you may enter that directory with the `cd` command.

- Indicates no permission.

For example, the permissions:

```
-rwxrwxrwx
```

indicate an ordinary file with full read, write, and execute access for everyone (user, group, and other).

The permissions:

```
-rw-------
```

indicate an ordinary file with read and write access for the user only.

The permissions:

```
drwxr-x--x
```

indicate a directory with search access for everyone, read access for the user and group, and write access for only the user.
When you create a file, the XENIX system automatically assigns the following permissions:

- rw-r--r--

This means that everyone may read the file, but only the user may write to it.

When you create a directory, the system automatically assigns the default permissions:

drwxr-xr-x

This means everyone may search and read the directory, but only the user may create and remove files and directories within it.

5.3.2 Changing Permissions

Any user can change the permissions of a file or a directory that they own with the chmod (for "change mode") command. This command requires that you tell it how to change the permissions of a specific file or directory. You do so by indicating which levels of permissions you wish to change (user "u", group "g", or other "o"), how you wish to change them (add "+" or remove "-"), and which permissions you wish to change (read "r", write "w", or execute "x"). For example, the pattern:

u+x

adds execute permission for the user. The pattern:

go-w

removes write permission for group and other.

The chmod command has the form:

chmod pattern file ...

Δ sysadmsh users select: Dirs/File → Modify → Permissions
where file is the name of a file or directory. If more than one filename is given, they must be separated by spaces. For example, to change the permissions of the file "receivables" from "-rw-r--r--" to "-rw-------", enter:

```
chmod go-r receivables
```

Press the RETURN key.

After using chmod, use the l command to check the results. If you have made a mistake, use chmod again to correct the mistake.

### 5.3.3 Changing the File Creation Mask

The file creation mask is a special number, kept by the system, that defines the permissions given to every file and directory created by a user. Initially, the mask has the value "022" which means every file receives the permissions:

```
-rw-r--r--
```

Every directory receives the permissions:

```
drwxr-xr-x
```

You can change the mask and the initial permissions your files and directories receive by using the `umask` command. Although executable as a shell command, `umask` is most useful when inserted into the user's `.login` (for csh users) or `.profile` (for Bourne shell users) file. This establishes individual `umask` defaults for each user.

The `umask` command has the form:

```
umask value
```

where value is a three-digit number. The three digits represent user, group, and other permissions, respectively. The value of a digit defines which permission is given as shown by the following table:
For example, the command:

```
umask 177
```

sets the file creation mask so that all files and directories initially have read and write permission for the user, and no permissions for all others.

### 5.4 Managing File Ownership

Whenever a file is created by a user, the system automatically assigns “user ownership” of that file to that user. This allows the creator to access the file according to the “user” permissions. The system also assigns a “group ownership” to the file. The group ownership defines which group may access the file according to the “group” permissions. The file’s group is the same as the creator’s group.

Only one user and one group may have ownership of a file at any one time. (These are the owner and group displayed by the `I` command.) However, you may change the ownership of a file by using the `chown` and `chgrp` commands.

#### 5.4.1 Changing User Ownership

Any user can change the user ownership of a file they own with the `chown` command. The command has the form:

```
chown login-name file
```

![sysadmsh users select: Files/Dirs→Modify→Ownership](image)
where *login-name* is the name of the new user, and *file* is the name of the file or directory to be changed. For example, the command:

```
chown johnd projects.june
```

changes the current owner of the file *projects.june* to ‘‘johnd’’.

The *chown* command is especially useful after changing the user ID of a user account.

### 5.4.2 Changing Group Ownership

You can change the group ownership of a file with the *chgrp* command.

The command has the form:

```
chgrp group-name file
```

changes the group ownership of the file *projects.june* to the group named ‘‘shipping’’.

The *chgrp* command is especially useful if you have changed the login group of a user.

### 5.5 Changing a User's Password

Normally, ordinary users can change the password of their own accounts with the *passwd* command (see the ‘‘Logging In’’ chapter of the *XENIX Tutorial*). Sometimes, however, it may be necessary for the super-user to change the password for a user. For example, if a password has been forgotten, and the user and cannot get into the account to change it, it is necessary for the super-user to change the password. The super-user may change the password of any user (including the super-user account) with the *passwd* command.

To change a password, follow these steps:

1. Log in as the super-user.
2. Enter:
   \[\text{passwd login-name}\]
   (where \textit{login-name} is the user's login name) and press the \texttt{RETURN} key. The command displays the message:
   
   \begin{verbatim}
   New password:
   \end{verbatim}

3. Enter the new password and press the \texttt{RETURN} key. The command does not display the password as you type it, so type carefully. The command then prompts you to enter the password again:
   
   \begin{verbatim}
   Retype new password:
   \end{verbatim}

4. Enter the password again and press the \texttt{RETURN} key.

To see how an ordinary user can change their own password with the \texttt{passwd} command, see the "Logging In" chapter of the \textit{XENIX Tutorial}.

\section*{5.6 Forcing a New Password}

From time to time, a user account may need a higher level of security than ordinary. Since the security of any account depends its password, it is important to keep the password as secret as possible. One way to provide greater security is to force users to change their passwords on a regular basis.
You can force users to change their passwords by using the `pwadmin` command. This command automatically dates each password and requires the user to provide a new password when the specified number of weeks have passed. The command also requires users to wait a minimum number of weeks before allowing them to restore their previous password. To use the `pwadmin` command, you must log in as the super-user.

You can enable password aging for a specified user by using the `-a` option. Enter:

```
pwadmin -a login-name
```

where `login-name` is the login name of a user. The user will then be required to wait a minimum number of weeks before he can change his password, and will be forced to change his password after a maximum number of weeks have elapsed. The `-a` option uses the default minimum and maximum values found in the `/etc/default/passwd` file.

You can choose your own minimum and maximum number of weeks by using the `-min` and `-max` options. For example, a common pair of minimum and maximum values is 2 and 8. To set the minimum and maximum dates, enter:

```
pwadmin -min num -max num login-name
```

where `num` is a number in the range 0 to 63, and `login-name` is simply the login name of the user whose password you are administering. Note that the minimum and maximum cannot both be 0, and that the minimum must not be greater than the maximum.

If you are unsure of the current minimum and maximum values for a password, you can display them by entering:

```
pwadmin -d login-name
```

This command does not change the current values.

If you wish to force a user to change passwords immediately, enter:

```
pwadmin -f login-name
```

The user is prompted on his next login to supply a new password.
When a password no longer requires extra security, you can remove the current minimum and maximum values for the password by entering:

```
pwadmin -n login-name
```

The system will no longer prompt for changes.

For more information about password aging, see `pwadmin(ADM)` in this guide and `passwd(F)` in the `XENIX User's Reference`.

### 5.7 Adding Dial-in Password Protection

If desired, you can define special dial-in passwords on selected tty lines, requiring selected classes of users to input dial-in passwords. Logging information, including the last time of connection, can be stored for later use.

Specific dial-in lines that require passwords are defined in the file `/etc/dialups`. The format is one tty device name per line, for example:

```
/dev/tty1A
/dev/tty5C
```

The actual dialup passwords are kept in the file `/etc/d_yasswd`. The password format is the same used in `/etc/passwd`, except only the first two fields (user name and encrypted password) are meaningful. The remaining fields, if present, are ignored.

The first field ("user name") in `/etc/d_yasswd` is not a user name, but the name of a shell program (for example, `/bin/sh`) used in `/etc/passwd`. If the login shell of the user attempting to log in (on a tty line listed in `/etc/dialups`) is listed in `/etc/d_yasswd`, then the user is prompted for the dial-in password stored in `/etc/d_yasswd`. (A shell name of "*" in `/etc/d_yasswd` specifies the default dialup password.)

A sample `/etc/d_yasswd` file might be:

```
::<encrypted passwd>:Default dialup password
/usr/lib/uucp/uucico::UUCP dialup password (none)
/bin/rsh::<encrypted passwd>:Restricted shell user dialup password
```

The `<encrypted passwd>` cannot be a normal string. The following is the procedure for creating an encrypted password:
Maintaining System Security

- Create a dummy user in /etc/passwd (run mkuser(ADM) or edit the file directly).
- Run passwd(C) to set the password
- Edit the /etc/passwd file and move that line from /etc/d_passwd. (If you use mkuser, be sure to run rmuser(ADM) so that the home directory and system mailbox of this dummy user are removed from the system.)

To enable time-of-login recording (and reporting of the time of last login at each login), create the log file using the following command:

```
touch /usr/adm/lastlog
```

In addition, if this file exists and the user is not currently logged in, the finger(C) utility will report the time of last login.

To establish the proper ownership and permissions on these files, enter the following commands:

```
chmod 644 /etc/d_passwd /etc/dialups /usr/adm/lastlog
chown bin /etc/d_passwd /etc/dialups /usr/adm/lastlog
chgrp bin /etc/d_passwd /etc/dialups /usr/adm/lastlog
```

The two files in /etc can have greater restrictions if desired, but lastlog must be as specified above.

### 5.8 Permitting Users to Mount Filesystems

Only the super-user can use the mount command. However, the super-user can set up parameters to define which filesystems can be mounted by users with the mnt(C) command, including the use of an access password, if desired.

Each filesystem must have an entry in the file /etc/default/filesys. The following is a sample set of entries:

```
bdev=/dev/root cdev=/dev/rroot mountdir=/ \\ 
  desc="The Root Filesystem" rcmount=no mount=no

bdev=/dev/u cdev=/dev/ru mountdir=/u rcmount=yes \\ 
  fsckflags=-y desc="The User Filesystem"

bdev=/dev/x cdev=/dev/rx mountdir=/x mount=yes \\ 
  rcmount=yes fsckflags=-y desc="The Extra Filesystem"
```
In simple terms, the entries above determine the following:

<table>
<thead>
<tr>
<th>Filesystem</th>
<th>When Mounted</th>
<th>Can User Mount?</th>
</tr>
</thead>
<tbody>
<tr>
<td>root</td>
<td>boot time</td>
<td>no</td>
</tr>
<tr>
<td>/u</td>
<td>multiuser</td>
<td>no</td>
</tr>
<tr>
<td>/x</td>
<td>anytime</td>
<td>yes</td>
</tr>
</tbody>
</table>

If you wish to make any non-root filesystem mountable by users, simply add "mount=yes" to the entry for the given filesystem. In addition, when the \texttt{mnt} command is invoked without an argument (no filesystem name), the program will check all non-root filesystems to see if they can be mounted, and if so, mounts them. The option "mount=prompt" will ask the user if they want to mount each filesystem where a mount is permitted.

For more information on the \texttt{mnt} command, including a complete list of options, refer to the \texttt{mnt(C)} page in the \textit{XENIX User's Reference}.

\section*{5.9 Using XENIX Accounting Features}

The XENIX system provides a set of commands that allows the system administrator to perform process accounting. Process accounting is a simple way to keep track of the amount of time each user spends on the system. The process accounting commands keep a record of the number of processes (i.e., programs) started by a user, how long each process lasts, and other information such as how often the process accesses I/O devices, and how big the process is in bytes.

Process accounting is helpful on systems where users are being charged for their access time, but it may also be used to develop a detailed record of system, command, and system resource usage.

There are several commands which may be used to do process accounting. Of these, the most useful are \texttt{accton(ADM)} and \texttt{acctcom(ADM)}. The \texttt{accton} command starts and stops process accounting. When invoked, the command copies pertinent information about each process to the file named \texttt{/usr/adm/pacct}. The \texttt{acctcom} command is used to display this information. The command has several options for displaying different types of accounting information.
5.9.1 Starting Process Accounting

Process accounting can be started at any time, but is typically started when the system itself is started. You can start process accounting with the `accton` command. Enter:

```
accton /usr/adm/pacct
```

The command automatically creates a new file `/usr/adm/pacct` and begins to copy process-accounting information to it. If the `/usr/adm/pacct` file exists before starting `accton`, the file contents are deleted.

You can start process accounting automatically whenever you reboot the system. To do this, edit the system startup file `/etc/rc`. Among other commands, there are several that start up process accounting, as well as back up the accounting log file `/usr/adm/pacct`.

These commands are commented out but, if you remove the comment characters at the beginnings of those lines, the commands are executed every time you reboot the system. You must edit the following lines in `/etc/rc`:

```
# mv /usr/adm/pacct /usr/adm/opacct
# > /usr/adm/pacct ; chmod 644 /usr/adm/pacct
# [ -x /etc/accton ] && /etc/accton /usr/adm/pacct
```

The pound signs (#) in front of each line are comment symbols that cause the line to be ignored. Remove the pound signs from each line and close the file. Note that, when you start the system after editing `/etc/rc`, the contents of the `/usr/adm/pacct` file are saved in the file `/usr/adm/opacct`, overwriting the contents of `/usr/adm/opacct`.

5.9.2 Displaying Accounting Information

The `acctcom` command reads process-accounting information from the `/usr/adm/pacct` file by default, then displays selected information on your terminal screen. The command usually displays basic accounting information, such as the process’ program name, the name of the user who invoked the process, the start and stop times for the process, and the number of execution seconds in real time and CPU time. The command has several options that can be used to display selected information.

To display the average size of each process, enter:

```
acctcom
```
The command displays the basic information plus the average size of each process.

To display basic accounting information about a specific command, enter:

```
acctcom -n command
```

where `command` is the name of the command you are interested in. The command responds by displaying each entry for the specified `command`. For example, to display each entry for the system command `units`, enter:

```
acctcom -n units
```

To display information about the number and size of input and output counts, enter:

```
acctcom -i
```

The command displays basic program information plus the numbers of characters and blocks transferred or read by each program.

To display information about a program's use of system resources, enter:

```
acctcom -h
```

The command displays the basic information plus the "use factor." This is a number generated and used by the system to determine how each process should be scheduled for execution. Processes with high use factors use a high percentage of the system resources and are therefore scheduled after processes with lower factors.
Chapter 6

Backing Up Filesystems

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6.1 Introduction

The main task of a system administrator is to ensure the continued integrity of information stored on the system. Files and filesystems can be damaged and data lost in the following ways:

- Power interruptions (make certain you have a surge protector)
- Hardware failures (particularly the hard disk)
- User errors (accidental removal of important files).

The importance of having up-to-date backups cannot be overstated. If your system has a number of active users, backups require daily attention. It is difficult to estimate the magnitude of a simple loss of data until an accident occurs and several weeks or months of work is gone in an instant.

A filesystem backup is a copy, on storage media (floppy disks or tape) of the files in the root directory and other regularly mounted filesystems. (See the “Using Filesystems” chapter in this Guide for a discussion of filesystems.) A backup allows the system manager, when logged in as backup, to save a copy of the filesystem as it was at a specific time.

This chapter explains how use the sysadmin(ADM) utility to create backups of the root directory and other filesystems, and how to restore files from the backups. (Another utility used for simple backups, tar(C), is discussed extensively in “Making Backups” in the “Housekeeping” chapter of the XENIX Tutorial.)

The tools discussed in this chapter present menus with simple options instead of the complex command lines used with the utilities tar(C), backup(C) and restore(C). The key to efficient backups is to save only what has changed from day to day, which (when used with backup and restore) normally requires extra bookkeeping.

6.2 Strategies for Backups Using sysadmin

As system administrator, you should familiarize yourself with this chapter and create a schedule as instructed. When this schedule is complete, you have only to insert a media volume and respond to a series of prompts to perform your daily backups.
The primary purpose of the **sysadmin** Filesystem Maintenance Menu is to provide a dependable schedule of filesystem backups for systems with many users and large filesystems. The program automatically locates modified files and copies them to backup media. If your system has many users and a large number of files that are modified daily, the "scheduled" backup option uses a predefined schedule to make regular backups. When the Filesystem Maintenance Menu is invoked, the program presents each task as a menu option. To perform a task, simply choose the appropriate option from the menu and supply any required information.

For backups of a more informal nature, **sysadmin** includes an option for "unscheduled" backups. This allows the system administrator to perform a single, complete backup of a filesystem. (Note this type of backup covers the entire filesystem, not just modified files, and may require a number of storage media volumes.) If you intend to rely on unscheduled backups, be sure and perform one at least once a month.

### 6.2.1 Using the backup Account for Backups

Always use the **backup** account whenever you make or restore backups. (You must be **root** to restore an entire filesystem.) An ordinary user cannot make backups because they do not have access permissions for all files. If backups are made as **root**, files may be accidentally destroyed because **root** has unrestricted permissions on every file on the system. The **backup** account solves this dilemma by having restricted **root** permissions. Logging in as **backup** takes you directly to the Filesystem Maintenance Menu.

The **backup** account already exists on your system; you set the password when the BACKUP package was installed.

### 6.2.2 Floppy Drive Backups and Large Systems

If your system has only a floppy drive, backups for large systems with several users can be time-consuming and use a great deal of media. A complete backup of a 20 megabyte filesystem requires **fifteen** 1.2 MB 96tpi diskettes, whereas a single 450 foot cartridge tape can store more than twice that amount. More importantly, diskettes require the presence of the operator to keep feeding floppies, whereas a single cartridge tape can be inserted and the operator need not remain by the system. If your system has a large number of users and just a floppy drive, you are advised to install a cartridge tape drive, or make complete system backups once per week and warn your users to make individual backups of their own files on a regular basis.
6.2.3 Summary of Utilities Accessed

sysadmin accesses several utilities during this process. You need not be familiar with them. However, should you wish to use advanced options not discussed in this chapter, you will need to know how they are used and which XENIX Reference pages to read. sysadmin uses the Filesystem Maintenance menu to access the following utilities:

- **fsphoto(ADM)**: main utility that controls the automated backup facilities.
- **fsave(ADM)**: the program that interacts with the user to perform the backup.
- **schedule(ADM)**: the backup database.
- **backup** and **restore**(C): the actual backup utilities; each of the tools above (including sysadmsh and sysadmin) form the “user-friendly” layer that isolates the user from these programs.

6.3 Preparations for Scheduled Backups

The only mandatory requirement for scheduled backups is the creation of a backup schedule. In addition, it is recommended that the system administrator follow the optional procedures for labeling, storing and logging backups. A detailed explanation of backup levels is included at the end of this chapter in case it is necessary to design a more specialized schedule.

6.3.1 Creating a Backup Schedule

The first step is to create a timetable for backups using the **schedule** file. The file is located in /usr/lib/sysadmin. It contains all the data needed for the system to perform a system backup, including:

- The name of your site or machine
- The media type and drive to be used
- A precise schedule of filesystems to be backed up.

The sections that follow explain what changes should be made to the **schedule** file provided with your XENIX distribution.
Edit the schedule File

You can edit the schedule file with any text editor; make certain you are logged in as root. For example, if you use the vi(C) editor, you would enter the following command to edit the schedule file:

\texttt{vi /usr/lib/sysadmin/schedule}

\textbf{sysadmsh} users select: Backups\textbf{→}Schedule

The subsections that follow explain the exact changes you need to make to this file.
# SYSTEM BACKUP SCHEDULE

site mymachine

# Media Entries
# 48 tpi 360K floppy 0
# media /dev/rfd048ds9 k 360 format /dev/rfd048ds9
# 48 tpi 360K floppy 1
# media /dev/rfd148ds9 k 360 format /dev/rfd148ds9
# 96 tpi 720K floppy 0
# media /dev/rfd096ds9 k 720 format /dev/rfd096ds9
# 96 tpi 720K floppy 1
# media /dev/rfd196ds9 k 720 format /dev/rfd196ds9
# 96 tpi 1.2 MB floppy 0
# media /dev/rfd096ds15 k 1200 format /dev/rfd096ds15
# 96 tpi 1.2 MB floppy 1
# media /dev/rfd196ds15 k 1200 format /dev/rfd196ds15
# 135 tpi 1.44 MB floppy 0
# media /dev/rfd0135ds8 k 1440 format /dev/rfd0135ds8
# 135 tpi 1.44 MB floppy 1
# media /dev/rfd1135ds8 k 1440 format /dev/rfd1135ds8
# Cartridge tape 0
# media /dev/rct0 d 20000 300 450 600 tape erase
# Mini cartridge drive (10MB)
# media /dev/rctmini k 8800 format /dev/rctmini
# Mini cartridge drive (40MB)
# media /dev/rctmini k 37500 format /dev/rctmini
# 9-track tape drive
# media /dev/rmt0 d 1600 2400 1200 600

# Backup Descriptor Table

<table>
<thead>
<tr>
<th>level</th>
<th>size</th>
<th>how long</th>
<th>Vitality</th>
<th>Label</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>-</td>
<td>&quot;1 year&quot;</td>
<td>critical</td>
<td>&quot;a red sticker&quot;</td>
</tr>
<tr>
<td>1</td>
<td>-</td>
<td>&quot;4 months&quot;</td>
<td>necessary</td>
<td>&quot;a yellow sticker&quot;</td>
</tr>
<tr>
<td>8</td>
<td>-</td>
<td>&quot;3 weeks&quot;</td>
<td>useful</td>
<td>&quot;a blue sticker&quot;</td>
</tr>
<tr>
<td>9</td>
<td>-</td>
<td>&quot;1 week&quot;</td>
<td>precautionary</td>
<td>none</td>
</tr>
</tbody>
</table>

# Schedule Table

| Filesystem | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 |
| /dev/root  | M | T | W | T | F | M | T | W | T | F | M | T | W | T | F | M | T | W | T | F |
| /dev/ru    | 0 | 0 | 9 | 9 | 9 | 9 | 8 | 8 | 9 | 9 | 8 | 8 | 9 | 9 | 8 | 8 | 9 | 9 | 8 | 8 |

Figure 6-1: The schedule File
Add the Name of Your Site or Machine

Simply change the mymachine entry at the top of the file to the name used in your /etc/systemid file, or whatever name you wish.

Select the Media Device that Matches Your Configuration

The default schedule file appears as in Figure 6-1. The 96tpi 1.2 Megabyte floppy drive 0 is the default drive (reproduced below). The pound signs (#) are comment symbols used to “comment out” text so that it is ignored by the program. Note that the default drive is the only one without a comment symbol. If you plan to use a drive other than the default, put a comment symbol in front of the 96tpi drive and remove the comment symbol from in front of the drive you wish to use. The remaining drives should remain commented out.

```
# 96 tpi 720K floppy 1
# media /dev/rfdl96ds9 k 720 format /dev/rfdl96ds9
# 96 tpi 1.2 MB floppy 0
media /dev/rfd096ds15 k 1200 format /dev/rfd096ds15
# 96 tpi 1.2 MB floppy 1
# media /dev/rfdl96ds15 k 1200 format /dev/rfdl96ds15
```

Edit the Backup Descriptor Table

Directly below the media drive lines is the Backup Descriptor table. This table (below) describes each backup level in terms of volume size, how long it is to be stored, how important it is, and how it is marked. The default entries should prove useful, but the volume size entries must be edited according to the type of media you are using.

If you are using floppy disks, leave the dashes in the “Vol. size” column as they are. This causes the backup program to take the volume size from the media entry for that device.

If you are using tapes or tape cartridges, replace each dash in the “Vol. size” column with the size (in feet) of the tape volume. If you are using tapes that are all the same size for each backup level, replace each with the size of the tape you’re using.
Backing Up Filesystems

The last column contains label entries that are discussed in "Labeling Your Backups" later in this section.

<table>
<thead>
<tr>
<th>#</th>
<th>Backup level</th>
<th>Vol. size</th>
<th>Save for how long</th>
<th>Vitality (importance)</th>
<th>Marker label</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>-</td>
<td>&quot;1 year&quot;</td>
<td>critical</td>
<td>&quot;a red sticker&quot;</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>-</td>
<td>&quot;4 months&quot;</td>
<td>necessary</td>
<td>&quot;a yellow sticker&quot;</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>-</td>
<td>&quot;3 weeks&quot;</td>
<td>useful</td>
<td>&quot;a blue sticker&quot;</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>-</td>
<td>&quot;1 week&quot;</td>
<td>precautionary</td>
<td>none</td>
<td></td>
</tr>
</tbody>
</table>

Figure 6-3: Backup Descriptor Table

Edit the Backup Schedule Table

The default schedule assumes that daily backups will be done. A precise understanding of backup levels is not critical to using the schedule. Level 0 is the lowest level backup. It backs up everything on the filesystem, while 1, 8, and 9 each back up only the files that have changed relative to the last lower-level backup. (For a complete discussion, see "An Explanation of Backup Levels" at the end of this chapter.) Note that there is a level 0 done once per month for the root filesystem and twice per month for the /u filesystem. This is because the /u filesystem (user accounts) changes much more frequently than the root filesystem, which contains the system files.

If you do not have a /u filesystem, then your user accounts are located in the root filesystem (in /usr). If this is so, delete the entire line for /dev/rroot and change /dev/ru to /dev/rroot. This must be done so that the entire hard disk will be backed-up.

Figure 6-4: Backup Schedule Table

Note that the Monday-Friday notation can be misleading; if a backup is postponed or unsuccessful (because of bad media, for example) then that same level backup is attempted again at the next scheduled backup. This offsets the schedule, but does not alter the established sequence of backups. The numbered scale of 1-0 above M-F is more accurate, but less useful to people, who work in day and week units.
In addition, if you add lines for other filesystems, you should take care not to schedule two level 0 backups of large filesystems on the same day; the process will be lengthy and may slow your machine significantly.

6.3.2 Labeling Your Backups

It is important to label your backup tapes with meaningful and accurate information. If your backups consist of a pile of haphazardly labeled tapes, it will be difficult to locate data at a later date.

The following is a suggested format for media labels:

<table>
<thead>
<tr>
<th>Name of computer</th>
<th>Backup level</th>
<th>Date made</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Filesystem Name</td>
<td></td>
</tr>
<tr>
<td></td>
<td>save until date</td>
<td></td>
</tr>
<tr>
<td></td>
<td># of blocks on volume</td>
<td></td>
</tr>
<tr>
<td>Name of backup person</td>
<td></td>
<td>volume # of #</td>
</tr>
</tbody>
</table>

The date on the label, and the date from which you calculate the "save until" date, should be the date of the business day covered by the backup. This is to avoid confusion if it becomes necessary to restore information from this tape.

You may have noticed that the schedule file has a proposed color-coding scheme for easy reference:

<table>
<thead>
<tr>
<th># level size</th>
<th>how long</th>
<th>(importance)</th>
<th>Label</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>&quot;1 year&quot;</td>
<td>critical</td>
<td>&quot;a red sticker&quot;</td>
</tr>
<tr>
<td>1</td>
<td>&quot;4 months&quot;</td>
<td>necessary</td>
<td>&quot;a yellow sticker&quot;</td>
</tr>
<tr>
<td>8</td>
<td>&quot;3 weeks&quot;</td>
<td>useful</td>
<td>&quot;a blue sticker&quot;</td>
</tr>
<tr>
<td>9</td>
<td>&quot;1 week&quot;</td>
<td>precautionary</td>
<td>&quot;none&quot;</td>
</tr>
</tbody>
</table>

Figure 6-5: Backup Labeling Scheme

If there is more than one tape for a single backup, mark the date label on each volume to indicate the volume number and number of volumes, such as "1 of 2" and "2 of 2" for a two volume backup.

Finally, place a label on the side of the box or enclosure marked with the name of the computer, the filesystem, and the backup level completed.
6.3.3 Keeping a Log Book

It is recommended that a written log book be maintained for each computer. In addition to maintenance information (such as when breakdowns occur and what was done about it), you should record the following information:

<table>
<thead>
<tr>
<th>Date</th>
<th>Just as with the tape label, this date should be the last day covered by the backup.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Filesystem</td>
<td>The name of the device backed-up on the current tape.</td>
</tr>
<tr>
<td>Backup level</td>
<td>The backup level of the current tape.</td>
</tr>
<tr>
<td>#Vols</td>
<td>Number of tape volumes.</td>
</tr>
<tr>
<td>#Blocks</td>
<td>Number of tape blocks. This information is output when the backup is completed. (Pay attention to this figure; if the number of blocks for a level 9 backup consistently exceeds four digits for a particular filesystem, then you should probably increase the frequency of backups for that filesystem to lessen the burden.)</td>
</tr>
<tr>
<td>Start/finish time</td>
<td>(Optional.) The time from the start of a backup of a filesystem until the last error check is completed. The times are displayed after the backup is finished. The finish time will often be inaccurate, since you may be out of the room when the backup finishes, and the machine sits idle before you return.</td>
</tr>
</tbody>
</table>

If there are problems with the backup, record these in the log book as well, including any error messages that come to the screen.

6.4 Performing a Scheduled Backup

This section describes how to perform a backup using a defined schedule. Do not attempt this until you have edited (or at least examined) the schedule file to make certain that it suits your needs.

The system administrator should schedule backups at times when few (if any) users are on the system. This ensures that the most recent version of each file is copied correctly.
A regular schedule of backups requires a good supply of media and adequate storage for them. Level 0 backups should be saved indefinitely; lesser backups should be saved at least two weeks. Media volumes should be properly labeled with the date of the backup and the names of the files and directories contained in the backup. After a backup has expired, the media may be used to create new backups.

6.4.1 Using Formatted Media

If you use media that requires formatting, such as floppy disks or mini tape cartridges, you may wish to format several volumes before you begin. The exact number of volumes depends on the number and size of files to be backed up. For details on how to format your media, see the “Using Floppy Disks and Tape Drives” chapter in this guide. You also have the option to do formatting from the sysadmin program. (Note that rctmini tape cartridges take a very long time to format.)

6.4.2 Starting the Backup

To run your scheduled backup, follow these steps:

1. Log in as backup. After any login messages are displayed, you are taken directly to the Filesystem Maintenance Menu:

   1. Perform a scheduled backup
   2. Perform an unscheduled backup
   3. List the contents of an archive
   4. Restore backed up file(s)
   5. Restore an entire filesystem
   6. Check backup archive integrity

   Enter an option or enter q to quit:

2. Enter “1” for a daily backup and press RETURN.
3. A menu is displayed that looks like the following:

```
Level 0 backup of filesystem /dev/rroot, 22 Sep 1988
tape size: 450 feet [or Kb]
tape drive: /dev/rct0
This tape will be saved for 1 year, and is critical.
M)ounted volume, P)ostpone, C)heck or F)ormat volumes,
R)etension or H)elp:
```

The media type displayed is the one entered in the schedule file. Load a volume, tape or disk, into the selected drive. Enter "m" to tell the program the volume is mounted, and press RETURN.

4. The system displays the current date and the date of the last backup:

```
Backup date= the epoch
Backing up /dev/rroot to /dev/rct0
```

(If you have not performed a backup previously, the system has no last backup date recorded and "the epoch" is displayed as the previous backup date.) An estimate of the number of volumes necessary is displayed. The system then begins to copy files to the drive. If a volume runs out of space, the program displays the message:

```
Please insert new volume, then press <RETURN>
```
Note

If you are using 5.25-inch floppies for your backups, make certain you close the floppy door before pressing RETURN, or the entire backup will be aborted and you will have to start over.

Remove the present volume, insert a new volume, then press RETURN. The program continues to copy files to the new volume. Repeat this step until the program displays the message:

DONE

5. After the backup is complete, you are advised to select "c" from the main menu to perform a check of the format. This is not a check of the format used in formatted media, but a confirmation of the presence of header information that should be present on each volume of a backup. The following message is displayed:

Check critical volumes for format errors
M)ounted first volume, S)kip format check, or H)elp:

If you wish to have the volume checked, insert the first volume of the backup, select "m" and press RETURN. If you wish to skip checking the volume format, and continue on to the read error check, select "s" and press RETURN.

Note

During verification, you may see messages indicating that a file on the hard disk differs from the backup. This is because certain files can change during the short interval between backup and verification. These messages do not affect the backup and can be ignored.

6. Every volume should be checked for read errors, and they must be checked in first-to-last order. (The restore(C) utility is used to check for errors during reading.) If an error occurs, the backup is
declared unsuccessful and is retried from the beginning. The menu appears as follows:

```
M)oun ted which volume, E)rror on previ ous volume, D)one, S)kip checks, or H)elp:
```

7. If you wish to check each of the backup volumes, you should insert them in order, enter "m" and press RETURN. If you wish to skip the check, enter "s" and press RETURN.

8. If an error occurs on the last volume checked, discard the suspect volume and start the backup again by entering "e" and pressing RETURN.

9. When all volumes have been checked and no errors have occurred, enter "d" and press RETURN to exit the program.

After the backup has been successfully performed, instructions are given on how to label the volumes.

### 6.5 Performing an Unscheduled Backup

You can create backups on tape or disk. If you use media that requires formatting, such as floppy disks, you may wish to format several volumes before you begin. The exact number of volumes depends on the number and size of files to be backed up. For details on how to format media, see the "Using Floppy Disks and Tape Drives" chapter in this guide. You also have the option to do formatting from within the Filesystem Maintenance Menu.
To create a backup, follow these steps:

1. Log in as **backup**. The Filesystem Maintenance Menu is displayed:

   1. Perform a scheduled backup
   2. Perform an unscheduled backup
   3. List the contents of an archive
   4. Restore backed up file(s)
   5. Restore an entire filesystem
   6. Check backup archive integrity

   Enter an option or enter q to quit:

2. Enter "2" for an unscheduled backup and press **RETURN**.

3. You see the following menu:

   1. / - the root filesystem
   2. /u -
   3. Other

   Select a filesystem to backup
   or enter q to return to the main menu:

The menu lists all filesystems found in the file `/etc/default/filesys` (discussed later in “Editing `/etc/default/filesys` and `/etc/default/archive`”). Select the number of the filesystem you wish to back up and press **RETURN**. (If you wish to enter a filesystem that is not listed in `/etc/default/filesys`, select ‘Other’ and you will be prompted for the name.)
4. Next, you are asked to select the media device to be used:

1. Floppy Drive 0 (48dsdd)
2. Floppy Drive 1 (48dsdd)
3. Floppy Drive 0 (96dshd)
4. Floppy Drive 1 (96dshd)
5. Floppy Drive 0 (96dsdd)
6. Floppy Drive 1 (96dsdd)
7. Cartridge Drive (300 ft tape)
8. Cartridge Drive (450 ft tape)
9. Cartridge Drive (600 ft tape)
10. Mini-Cartridge Drive (10MB)
11. Mini-Cartridge Drive (40MB)
12. Other

Select an archive device, or enter q to return to the main menu:

Select the number that corresponds to the device you wish to use. The devices appearing in this menu are taken from /etc/default/archive; you can add entries or even simplify this menu by editing the this file (see "Editing /etc/default/filesys and /etc/default/archive" in this chapter).

Note

Take care when selecting the number of the media device. For example, make certain that you don’t select “Floppy Drive 1” when you want “Floppy Drive 0.” If you make this error, the backup is aborted and you must start over.

5. The following message is displayed:

It is important to have plenty of formatted media on hand. Do you wish to format any media at this time? (y/n)

You can format as many volumes as you wish by inserting them into the drive and pressing RETURN.
6. Next you see:

PERIODIC BACKUP (level 0) - /name FILESYSTEM

Load the first volume into the drive /dev/name, press <RETURN> when you are ready, or enter q to return to the main menu:

7. Load a volume, tape or disk, into the selected drive, and press RETURN. The system displays the current date and the date of the last backup. It displays “the epoch” if there has been no backup. The system then begins to copy files to the drive. If a volume runs out of space, the program displays the message:

Please insert new volume, then press <RETURN>

8. Remove the first volume, insert a new volume, then press RETURN. The program continues to copy files to the new volume. Repeat this step until the program displays the message:

DONE

If you are using floppies, you may need to repeat the last step several times before the backup is complete. You should label each volume as you remove it from the drive. For example, label the first volume “Volume 1,” the second “Volume 2,” and so on.

6.6 Getting a Backup Listing

You can keep a record of the files you have backed by selecting item 3: “List the contents of an archive” from the Filesystem Maintenance Menu. The program copies the names of all files from the backup disks to the temporary file /tmp/backup.list, or to another file of your choice. This listing is useful when you need to recover a file from a backup, and especially convenient if you wish to keep detailed records of the files copied in each backup.
Backing Up Filesystems

To get the listing, follow these steps:

1. Log in as backup
   \[ \text{sysadmsh users select: } \text{Backups} \rightarrow \text{Create} \]

2. The Filesystem Maintenance menu is displayed:

   1. Perform a scheduled backup
   2. Perform an unscheduled backup
   3. List the contents of an archive
   4. Restore backed up file(s)
   5. Restore an entire filesystem
   6. Check backup archive integrity

   Enter an option or enter q to quit:

3. Enter "3" and press RETURN. You are prompted for the name of the file in which to place the listing. Enter RETURN if you wish to use the default \(/	mp/backup.list\). The program prompts you to insert the first backup volume.

4. Load the first volume, then press RETURN. The program automatically reads the filenames off the backup volume and places them in the list file.

To print the backup list on a lineprinter, quit sysadmin and enter:

   \[ \text{lp } /\text{tmp}/\text{backup.list} \]

Δ sysadmsh users select: Dirs/Files → Print

and press RETURN. To save space after printing the file, you should remove it with the \text{rm}(C)\ command.

6.7 Restoring Individual Files or Directories From Backups

You can restore individual files or subdirectories from your filesystem backup volumes by invoking sysadmin and selecting the fourth item in the Filesystem Maintenance Menu. You will need the complete set of
backup volumes containing the latest version of the file or files you wish to restore. If you are restoring a file that has not been changed recently, use the last level 0 backup.

You must use the "full pathname" of the file or files you wish to restore. This pathname is given in the backup listing. If the files are not on the root filesystem, the name of the filesystem must be omitted from the pathname. For example, to restore the file /u/stellar/data from your /u backups, you would enter:

/stellar/data

To restore a file, follow these steps:

1. Log in as root and enter:

   sysadmin

   Δ sysadmsh users select: Backups→Create

   and press RETURN.

2. When the Filesystem Maintenance Menu appears enter "4" and press RETURN. You see:

   1. Floppy Drive 0 (48dsdd)
   2. Floppy Drive 1 (48dsdd)
   3. Floppy Drive 0 (96dshd)
   4. Floppy Drive 1 (96dshd)
   5. Floppy Drive 0 (96dsdd)
   6. Floppy Drive 1 (96dsdd)
   7. Cartridge Drive (300 ft tape)
   8. Cartridge Drive (450 ft tape)
   9. Cartridge Drive (600 ft tape)
   10. Mini-Cartridge Drive (10MB)
   11. Mini-Cartridge Drive (40MB)
   12. Other

   Select an archive device,
   or enter q to return to the main menu:

   Enter the number that corresponds to the drive used to create the backup originally.
3. Next, a message is displayed explaining that you can choose to restore the files to their original location (by providing the name of the top-level directory the filesystem is mounted on), or some other directory. This is followed by a prompt for the directory name:

```
Enter a directory name, enter <RETURN> to choose the current directory, or enter q to return to the main menu:
```

Note

If you respond with the pathname of the original location, the restored files will overwrite any files by the same names in that location. It is important to be sure that the files on the backup are the desired versions of these files. If you are not absolutely sure that your backup contains the preferred version of the files, you should restore them to a temporary location, such as /tmp, and compare them with your current files on disk using `diff(C)` or `cmp(C)`.

```
Enter the name of the directory you want the files restored to.
```

4. Next, you are prompted:

```
List the name of each file or directory to be restored. Do not include the destination (filesystem or directory) name, but use the rest of the full path name.

For example, if the destination is /usr, and the full path name is /usr/bin/lpr, then enter /bin/lpr.

Enter a file or directory and <RETURN>, enter <RETURN> if the list is complete, or enter q to return to the main menu:

Enter the full pathname of the files or directories you wish to restore and press RETURN to continue the program.
```
5. Next, you see:

```
RESTORE FILES - /file(s)
Mount desired dump volume:
```

Load volume 1 of the backup set into the drive, then press RETURN.

6. The program displays the inode numbers of the files you have given, then prompts for a volume number:

```
/file(s): inode nn
Specify volume #:
```

7. Remove the first volume and replace it with the last volume made of the backup set into the drive, enter its number and press RETURN. The program searches the volume for the specified files and places copies into the specified locations on your hard disk.

8. The program prompts for volume numbers until all of the files have been found. When each file is found, you see:

```
Extract file filename
```

Continue to feed volumes in reverse order until the first volume made has been loaded and you have returned to the main menu.

### 6.8 Restoring an Entire Filesystem

Restoring an entire filesystem is a last-resort option, used when a non-root filesystem has become corrupted or unreadable. Do not use this option carelessly; all information currently in the target filesystem will be overwritten. You cannot restore the root filesystem using this utility. If your root filesystem has been corrupted and is not bootable, you can
Backing Up Filesystems

restore it by referring to "Restoring a Corrupted Root Filesystem" in the "Solving System Problems" chapter of the XENIX System Administrator's Guide and using the Emergency Boot Floppy you created at installation time. If you did not create an Emergency Boot Floppy, you must reinstall XENIX as described in the "Reinstalling and Updating Your System" chapter of the Installation Guide.

To restore an entire non-root filesystem, you must first "remake" the filesystem using divvy. This will start you with a clear filesystem. Then you can invoke the "Restore entire filesystem" option.

To restore a filesystem, follow this procedure:

1. Log in as the super-user (root) and enter one of the following commands:

   If you are restoring a filesystem on the primary disk (/dev/hd00):

   \[ \text{divvy -b 1 -c 1 -p 0} \]

   If you are restoring a filesystem on the secondary disk (/dev/hd10):

   \[ \text{divvy -b 1 -c 1 -p 1} \]
2. You see a table similar to the following, plus the main *divvy* menu:

```
<table>
<thead>
<tr>
<th>Name</th>
<th>New File System?</th>
<th>#</th>
<th>First Block</th>
<th>Last Block</th>
</tr>
</thead>
<tbody>
<tr>
<td>root</td>
<td>no, exists</td>
<td>0</td>
<td>0</td>
<td>13754</td>
</tr>
<tr>
<td>swap</td>
<td>no, exists</td>
<td>1</td>
<td>13755</td>
<td>15135</td>
</tr>
<tr>
<td>u</td>
<td>no, exists</td>
<td>2</td>
<td>15136</td>
<td>25135</td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>3</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>4</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>recover</td>
<td>no, exists</td>
<td>6</td>
<td>25136</td>
<td>25145</td>
</tr>
<tr>
<td>d1057all</td>
<td>no</td>
<td>7</td>
<td>0</td>
<td>25546</td>
</tr>
</tbody>
</table>
```

*x blocks for divisions, y blocks reserved for the system*

n[ame] Name or rename a division.
c[reate] Create a new filesystem on this division.
p[revent] Prevent a new filesystem from being created...
s[tart] Start a division on a different block.
e[nd] End a division on a different block.
r[estore] Restore the original partition table.

Please enter your choice or ‘q’ to quit:

3. Enter “c” to recreate a filesystem. You are then prompted for a division number as displayed in column three:

```
which division? (0 through 6) --
```

Enter the number corresponding to the filesystem you wish to recreate.

*Note*

You should take extreme care when selecting the filesystem to recreate. However, after quitting out of *divvy*, you can undo any mistakes by selecting “e[xit]” as described in the next step.
4. The divvy menu is displayed again, but with "yes" in the "New File System?" column. Enter "q" to quit.

5. Next, you are given a final chance to undo your changes before leaving divvy:

   ![Menu Options]

   Please enter your choice:

   If you made a mistake, enter "e", otherwise enter "i" to use your changes. You can then quit out of divvy entirely. When you quit, your filesystem is rebuilt. You see the message:

   Making Filesystems

6. Next, while still logged in as root, enter the command:

   ```
   sysadmin
   Δ sysadmsih users select: Backups→Restore
   ```

   When the Filesystem Maintenance Menu is displayed, select option "5". You are warned:

   ![Warning]

   Respond "y" if you are certain that this is what you wish to do.
7. Next you are asked to select the filesystem that you wish to restore:

1. / - the root filesystem
2. /u -
3. Other

Select a filesystem to restore or enter q to return to the main menu:

If you select "Other", you are prompted for the device name of the filesystem that you wish to restore.

8. Next you see the archive menu. Select the medium on which your filesystem is backed up, for example, tape or floppy.

9. You are prompted to load the first volume of the backup into the selected drive:

```
RESTORE FILESYSTEM - /name
Load the first backup volume into drive /dev/devicename.
Press <RETURN> when you are ready, or enter q to return to the main menu:
```

Start with the last complete (level 0) backup, loading each volume in order as prompted.

10. You are first given another chance to stop:

```
Last chance before scribbling on /dev/name.
```

If you wish to continue, press RETURN.

11. The restoration process may take some time. When the restore phase of the operation is complete, you see:

```
End of backup
The restore of /name has been successful.
The filesystem will be checked to insure integrity.
```
Next, *sysadmin* runs a check on the filesystem using `fsck(ADM)`. You see a series of messages like this:

```
** Phase 1 - Check Blocks and Sizes
** Phase 2 - Check Pathnames
** Phase 3 - Check Connectivity
** Phase 4 - Check Reference Counts
** Phase 5 - Check Free List
***** FILE SYSTEM WAS MODIFIED *****
```

12. When the filesystem check is complete, you see:

You must remount `/dev/name` when ready to use the filesystem.

13. Now that the restore of your level 0 volumes is complete, you are returned to the Filesystem Maintenance Menu. Repeat steps 6-12 until each of your higher level backups (1, 8 and 9) have been restored that were done between the last level 0 and the date when your filesystem was damaged. Be sure and restore them in the order they were done, or you will overwrite recent versions of files with older ones.

Your filesystem is now completely restored. You need to mount the filesystem before you can use it. To mount it, enter the following command, substituting `name` for the name of your filesystem:

```
mount /dev/name /name
```

### 6.9 Editing `/etc/default/filesys` and `/etc/default/archive`

The files `/etc/default/filesys` and `/etc/default/archive` are used by *sysadmin* to create the filesystem and archive device menus. Even though each menu provides the option "Other" so that you can use filesystems and devices not described, you should keep these default files up to date as your system changes. These files are also used by other programs, and should be maintained as specified for these programs.
/etc/default/archive

The /etc/default/archive file contains a complete set of devices supported by XENIX. Each device, filesystem or drive, in these files is represented by a one line entry which consists of "name=value" pairs, separated by spaces or tabs. For example, the following is a possible entry in /etc/default/archive:

```
cdev=/dev/rfd048ds9 desc="Floppy Drive 0 (48dsdd)" \ 
   blocking=18 size=360 format="format -f /dev/rfd048ds9"
```

The value part of "name=value" pairs "desc="Floppy Drive 0 (48dsdd)"" and "format="format -f /dev/rfd048ds9"" contain spaces, therefore they must be surrounded by quotes in order to be interpreted correctly.

If your system does not use certain drives included in /etc/default/archive, or if you add an entry to either file, and then later decide that you don’t need it any longer, rather than deleting the entry, you can place a pound sign (#) at the beginning of the first line for that device, and it will be treated as a comment and ignored. Later, if you need the entry again, you can delete the #.

Entries commented out will not appear in the list of media devices displayed in the "Restore backup file(s)" option of the Filesystem Maintenance Menu.

/etc/default/filesys

The minimum necessary information about a filesystem is:

- A character device name, (cdev=), or a block device name, (bdev=).
- You may include a description, (desc=), which appears in the Filesystem Maintenance Menu.
- The mount directory, (mountdir=), which is also used by the mnt(C) utility, in addition to sysadmin. The name rcmount, in the example below is used exclusively by /etc/rc.

```
bdev=/dev/root cdev=/dev/rroot mountdir=/ \ 
desc="The Root Filesystem" rcmount=no mount=no
```

```
bdev=/dev/u cdev=/dev/ru mountdir=/u rcmount=yes fsckflags=-y desc="The User Filesystem"
```
6.10 An Explanation of Backup Levels

The most straightforward and dependable way to ensure the safety of data is to back up everything on a filesystem at one time. However, filesystems tend to be quite large (from 10 to 300 MB), and may take hours to backup. The concept of backup levels (or incremental backups) addresses this problem. The general idea of an incremental backup is to back up only those files that have changed since a previous backup. This can significantly reduce the size and duration of the backup. Consider the following scheme:

<table>
<thead>
<tr>
<th>Level</th>
<th>Files Saved</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>all files on the filesystem</td>
</tr>
<tr>
<td>1</td>
<td>files changed since last level 0 backup</td>
</tr>
<tr>
<td>2</td>
<td>files changed since last level 1 backup</td>
</tr>
<tr>
<td>3</td>
<td>files changed since last level 2 backup</td>
</tr>
<tr>
<td>4-9</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>files changed since last level 8 backup</td>
</tr>
</tbody>
</table>

This means that at the end of every month, the entire filesystem is backed-up. Each week, the files that have changed since last week are backed-up, and each day, any files that have changed since yesterday. If at some point a filesystem is damaged, you would simply restore the last full (monthly) backup, the last weekly backup, and any daily backups that happened just prior to the accident. Thus it is always possible to reconstruct a filesystem from a series of backups.

While this is a simple method to understand, the implementation using incremental backup levels is not.

6.10.1 Principles of Incremental Backup Levels

To make the business of backing up files more efficient, XENIX uses a progressive series of levels, each of which is based on the last occurrence of a lower level backup. The XENIX backup facility provides up to ten different levels of backups, giving the system administrator tremendous flexibility in organizing backups.

The full ten levels would be used to accommodate computers with massive filesystems; average systems will use only a few levels. The levels
serve to subdivide a backup into manageable units. It is important to realize that each backup level creates backups based on the previous (next lowest) level backup. This means that the order of the backups is not significant, but the level number is.

For example, let's assume that the following backups were done for a week:

<table>
<thead>
<tr>
<th>Day</th>
<th>Level</th>
<th>Files Backed Up</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mon</td>
<td>0</td>
<td>All files on filesystem</td>
</tr>
<tr>
<td>Tue</td>
<td>5</td>
<td>All files changed since Monday</td>
</tr>
<tr>
<td>Wed</td>
<td>2</td>
<td>All files changed since Monday</td>
</tr>
<tr>
<td>Thu</td>
<td>7</td>
<td>All files changed since Tuesday</td>
</tr>
<tr>
<td>Fri</td>
<td>5</td>
<td>All files changed since Wednesday</td>
</tr>
</tbody>
</table>

This example is illogical, but serves to demonstrate how the levels work. Remember that each of the backups saves the files changed since the next lower level backup, and that level 0 is the lowest. Therefore, the level 5 on Friday backs up all files changed since the next lowest number, level 2, on Wednesday. The level 5 on Monday saves only those files that have changed since the day before, since the only previous lower level backup is a 0. If all the backup levels except Monday were level 5, each would still backup all files that changed since the level 0 on Monday.

6.10.2 How the Default Schedule Works

The default schedule file provided with your distribution uses only four levels, and is optimized for use on systems under moderate use (7-10 terminals, 8-10 users):

```
#                      1 2 3 4 5 6 7 8 9 10 1 2 3 4 5 6 7 8 9 10
# Filesystem          M T W T F M T W T F M T W T F M T W T F
/dev/rroot            0 x 9 x 9 8 x 9 x 9 1 x 9 x 9 8 x 9 x 9 8 x 9 x 9
/dev/ru               9 0 9 9 9 9 8 9 9 9 9 1 9 9 9 9 8 9 9 9
```

Figure 6-6: The Default Schedule
The /u Filesystem

Filesystem /dev/ru is a heavily-used resource. Some level of backup is performed every day. This scheme is designed to minimize resources while maximizing safety; if one or more of the backups for that week is lost or goes bad, there is sufficient redundancy to minimize any loss of data.

According to the default schedule, a full (level 0) backup of /dev/ru occurs at the beginning of the month. (Because a level 0 is done on the root filesystem on Monday, the level 0 for /u is done on Tuesday.) Wednesday, a level 9 backup saves just those files on /dev/ru which have changed since the level 0 backup. By the end of the week far fewer floppies or tapes are used than the number needed for full backups each day. Time is substantially reduced as well. If it is necessary to restore the filesystem to the last recorded state, you would restore the last level 0 backup, followed by each of the lower-level backups that have been done since.

Note that each Tuesday, a lower level backup (0, 1 or 8) occurs that saves everything since the beginning of the month and causes each of the level 9 that follow it to be based on that week. This way the level 9 backups don't become too large and redundant.

The root Filesystem

The root filesystem contains the operating system and other system files. It changes less frequently, so it is not backed up every day. Each Monday, a lower level backup is done, and level 9 backups are done twice per week. Just as with the /u filesystem, the level 9 backups are restricted to cover only those files that have changed during that week.

6.10.3 How Backups are Used to Restore a Filesystem

Now, let's assume you have a hardware failure that ruins the information on the hard disk. Assume it happens on the last Thursday of the month, just before the backup was to be done that evening. You fix the hardware problem and reinstall your system, but how do you restore your backups? Restore the last occurrence of each backup level, in ascending order:

- level 0 (done on the first Tuesday of the month)
- level 1 (done on the third Tuesday)
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- level 8 (done on the fourth Tuesday)
- level 9 (done on Wednesday evening)

You wouldn't need to restore the level 8 that was done on the second Tuesday, because the level 1 that followed it covered the same files. The only information that is missing is what was changed during the day on Thursday, just before the crash. This is the primary reason for backups; recovery should be straightforward and with a minimum of loss.
Chapter 7

Adding Device Drivers
with the Link Kit

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7.1 Introduction

This chapter explains how to add device drivers to the XENIX kernel, a process known as "linking." To change any component of the XENIX kernel it is necessary to use the Link Kit to relink the kernel. The Link Kit consists of a set of kernel components in the form of relocatable object modules plus various programs and shell scripts used to link the components together.

The most common use for the Link Kit is to add device drivers to the system. A device driver is the software interface between a peripheral device and the operating system. Each device that can be used with XENIX must have a device driver. New drivers are generally supplied when adding a peripheral device to the system; they must be configured into XENIX before the device will function.

The Link Kit is also necessary to create new device drivers, and is used in conjunction with other tools that are included with the XENIX Development System. The device driver material in this chapter is intended for those who want to install an existing device driver. Driver writers should read the "Writing Device Drivers" chapter of the C User's Guide. Example device drivers are in the "Sample Device Drivers" chapter of the C User's Guide.

7.2 Device Drivers

A device driver is a set of routines that communicates with a hardware device, and provides a means by which XENIX can control the device in order to perform Input/Output (I/O) operations.

A device driver is usually supplied as a single software module. Installing this software into the kernel is as important as the actual hardware installation. It must be completed before the device can be used. A driver is usually accompanied by an auxiliary program or shell script that helps to form the links between driver and kernel.

To install a new device driver:

- Install the hardware device on the system according to the manufacturer's instructions.

- Boot the system and enter system maintenance mode. All the operations described as part of the installation process are carried out in this mode.
Make sure the Link Kit is installed. If it is not already installed, install it using the `custom(ADM)` command.

If the kernel has already been modified, copy the configuration files back from where they were previously stored. For example, enter:

```bash
cd /usr/sys/conf
cp ../io/master ../io/xenixconf ../io/link_xenix ../io/driver.o
```

where `driver.o` is the name of the driver installed earlier, if any.

### 7.2.1 Installing Device Drivers

The exact instructions for installing a new device driver are different for each type of device. This section contains example commands that may be slightly different than the actual commands. Read the specific installation instructions that are provided with the device driver software.

After the Link Kit is installed and the instructions read, the next step depends on how much of the work has already been done by the driver's vendors.

Many software vendors provide automatic driver installation utilities compatible with the standard System V installation utilities. If so, insert the vendor's floppy in the floppy drive and enter:

`custom`

Select the option to add a supported product, and follow the instructions that appear on the screen. `custom` should run any System V compatible, automatic installation software provided with the driver. This installs the device driver software and links a version of the kernel that contains the new device driver. After `custom` completes, the next step is usually to test the newly created kernel. See the device driver documentation for details.

If no mention is made of `custom` in the documentation for the individual driver, use the following procedure.
Move to the directory containing the Link Kit and copy the necessary files by entering:

```
    cd /usr/sys/conf
    cp master master.old
    cp xenixconf xenixconf.old
```

Some older installation sets contain their own versions of `master` and `xenixconf`. These files record the system configuration. If the installation floppy contains its own `master` and `xenixconf` files, an out-of-date and possibly obsolete kernel will be generated.

Insert the floppy containing the driver into the floppy drive and enter the following to extract the contents of the installation floppy:

```
    tar xvf /dev/install
```

Examine the names of the extracted files. If there are no files named `master`, `xenixconf`, `c.o`, or `c.c` on the driver installation floppy, the driver is `preconfigured`. Proceed to “Installing Preconfigured Drivers” in this chapter. Otherwise, proceed to “Installing Older Drivers and Drivers Without Configuration Shell Scripts” to determine the commands necessary to configure the driver.

### 7.2.2 Installing Preconfigured Drivers

The driver installation floppy may come with a shell script that edits the link command line to include the new driver. If such a script is present, run it by entering:

```
    ./scriptname
```

where `scriptname` is the name of the script. Most scripts also create all necessary device nodes; if this is the case, proceed to “Booting the New Kernel.” If your script does not create the proper nodes, you must create them with the `mknod(ADM)` command. For more information on making nodes, please refer to the `mknod(ADM)` manual page.
If no such script is present, edit the file `link_xenix` to include the names of all object files provided. The object files are the files on the distribution media whose names end in "o", as in `tape.o`. Add the names of any new modules to the `ld` command line, just before the pairs of arguments of the form `"-l lib_xxxx"`.

Enter:

```
/link_xenix
```

Linking can take as long as 10 minutes. Once a new XENIX kernel has been created, proceed to "Creating Special Device Files."

### 7.2.3 Installing Older Drivers and Drivers Without Shell Scripts

Any driver configuration shell script that neither installs a preconfigured driver nor calls `configure` dates from before the current release of XENIX. Many older drivers will work fine with the current XENIX release, but their shell scripts are no longer usable. If this is the case, the script must be ignored and the procedure is the same as for a driver unaccompanied by a configuration shell script.

**Note**

There is no warranty, expressed or implied, that any driver working with any earlier release will remain compatible with any subsequent kernel. Most drivers will continue to be compatible with new releases of XENIX. The following procedure will allow you to configure in an earlier driver. However, there are many reasons why an earlier driver may no longer function, few of them directly determinable.

Outdated drivers may simply malfunction when attempting to access their peripherals, or they may cause a system crash or even more insidious malfunctions. For this reason, make backup copies of all important files before attempting to reconfigure an older driver, and test drivers only in single user (maintenance mode).
1. Repeat the following procedure for each device driver. Enter:

```
rm c.o c.*.o space.o space.*.o
```

Ignore any error messages of the form "c.o non-existent" or "space.o non-existent."

2. If files named `master` and `xenixconf` were extracted when the `tar` command was entered, copy the old `master` and `xenixconf` files back to their original names. This will overwrite the versions of `master` and `xenixconf` that came with the driver. For example, use the commands:

```
cp master.old master
cp xenixconf.old xenixconf
```

3. Enter the following to obtain the `Major Device Number` (write it down for later use):

```
./configure -j NEXTMAJOR
```

4. The driver module is the remaining file or group of files from the installation media whose names end in "*.o". Enter:

```
./routines module1.o module2.o ...
```

where `module1.o module2.o ...` are the list of the driver modules provided. The list is most likely one module long, but if there is more than one, list them all.

This command can take as long as 5 minutes. Write down the names produced. Most of these names are either configurable driver routines or driver priority levels. Some names may be spurious.

5. Driver priority levels have names consisting of the string `spl` followed by a number between 0 and 7. If there are any strings beginning with `spl` present, write down the largest such number under the heading `Interrupt Priority Level`. Then cross all `spl` routines off the list. For example, if the string `spl6` is produced and it is the highest priority level produced, write it down under the heading `Interrupt Priority Level`.

6. Configurable driver routines all have a common prefix, such as `sio`. Each prefix is followed by one of a small group of suffixes: `open`, `close`, `read`, `write`, `ioctl`, `strategy`, `halt`, `poll`, `intr`, `init`, `tab`, `_tty`, or
stream. If there are files that do not fit this pattern, cross them out. For example, running routines on the sio.o driver reveals a long list of routines that begin with sio, and a single routine, ttinit. In this case you would cross out ttinit because it doesn’t begin with sio. There are a few other routines in the sio driver that would also be crossed out, such as siopinit, because of the extra “p.” sio is an extreme case: most drivers will not have spurious routine names scattered throughout the relevant ones.

7. If any routine ends with strategy or tab, the peripheral is a block device. If any routine ends with read, write, or ioctl, the device is a character device. A peripheral may be both a block and a character device. If none of these routines are present, consider the peripheral a character device.

8. If there is a routine containing the name intr, refer to the hardware manual to figure out which vector or vectors the device is capable of interrupting. To get a list of the vectors that are currently in use, enter:

```
./vectorsinuse
```

A few drivers are written to allow vector sharing, but it is better to give each device a unique vector whenever possible. Associate the peripheral with an appropriate vector or vectors. Write down the numbers chosen for the "Vectors".

9. The configure command has the following syntax and must be entered on a single line, without pressing RETURN until the entire command has been entered:

```
./configure -b -c -m Major_Device_Number -v Vector_or_Vector_List -a List_Of_Driver_Routines -l Interrupt_Priority_Level
```

The options have the following definitions and restrictions:

- **-b** Use if configuring a "block" device.
- **-c** Use if configuring a "character" device.
- **-m** Should be followed by the `Major_Device_Number` determined earlier.
- **-a** Should be followed by the list of driver routines determined by running routines and crossing out the extraneous entries.
Adding Device Drivers with the Link Kit

-v Use only if the device has an *intr* routine; should be followed by the list of vectors determined earlier.

-l Use only if *spl* routines appeared when *routines* was run earlier, followed by the *Interrupt_Priority_Level*.

For example, if you configure the serial I/O driver, use the following command:

```
./configure -c -m 5 -v 3 4 27 28 -a sioopen sioclose sioread sioclock siioctl siointer siopoll sioinit -l 7
```

The ramdisk driver is a simpler example; if it is not present, you can add it with the command:

```
./configure -b -m 31 -a ramopen ramclose ramstrategy ramtab
```

*configure* will produce new *c.o* and *space.o* files containing updated configuration information.

**Note**

If *routines* produces a long list containing a number of different prefixes, each with a healthy complement of configuration suffixes, this driver package contains not one driver but a driver suite made up of several drivers. Treat each prefix as an individual driver, and run *configure* once for each prefix.

10. After *configure* has been run once for each driver, edit the file *link_xenix* to include the names of all object files provided. The object files are the files on the distribution media whose names end in ‘*.o*’, as in *tape.o*. Add the names of any new modules to the *ld* command line, just before the pairs of arguments of the form ‘*-l lib_xxxx*’. Enter:

```
./link_xenix
```

Note that linking can take a while. Once a new XENIX kernel has been linked, proceed to ‘Creating Special Device Files.’
7.2.4 Troubleshooting

If the following ld error message appears on 286 machines:

Group 'DGROU P' larger than 64Kbytes

Reduce the size of some of the other kernel data structures to compensate for the extra room that the new driver is using. See “Freeing Kernel Space For Drivers” in this chapter for detailed instructions.

For hand-configured drivers: if the new kernel links without error, but on boot-up gets to the letter D and no farther (Ln on 386 machines, where n is a single digit), it is possible that an init routine produced when routines was run was never meant to be given on the configure command line. After rebooting the old XENIX kernel, enter the following commands:

```
 cd /usr/sys/conf
./configure -d XXinit -m Major_Device_Number -b -c
./link_xenix
```

where Major_Device_Number is the value determined earlier, and XXinit is the actual name of the initialization routine. Run link_xenix again, copy the kernel produced to the root directory, reboot, and try again.

7.2.5 Creating Special Device Files

For programs to gain access to the newly installed devices, they must also exist as files within the filesystem. These files are called special files and are usually located in the /dev directory. Once again, the specific installation instructions supplied with the device will give the precise details of the name to be used for the special file and the other parameters associated with it. To create a special file, use the mknod command. Supply the name of the special file, its type (which can be either “b” for a block device or “c” for a character device) and the major and minor device numbers associated with the device. For example, change directories to /dev and enter a command similar to one of these:

```
/etc/mknod hcd0 b 1 0
/etc/mknod rhcd0 c 1 0
/etc/mknod hqp c 7 0
```

Note the convention for setting up disk device names. A digit may be appended to the mnemonic to indicate the drive number. The “raw” device, or character special device, name has an “r” prefix.
Adding Device Drivers with the Link Kit

The major device number of the device can be found in the "master" file. Find a line in this file for an appropriate device. For example, a tape driver might be called "tape" at the beginning of the line, and "td" somewhat further down the same line. The name of the driver should also correspond to the name of the object module. For example, tape.o should be called "tape" inside the master file.

Next, find the columns at the top of the file marked "bmaj" and "cmaj". Search down these two columns until a line appears that describes the driver. Write down the block major device number (bmaj), and the character major device number (cmaj). If either bmaj or cmaj is "0", do not create any block or character nodes, respectively. Otherwise, these entries are the major device numbers for the driver.

7.3 Freeing Kernel Space for Drivers

If a driver is too large to be linked into the kernel, it may be possible to free sufficient kernel space by reducing certain resource allocations. Refer to "Reallocating Kernel Resources with configure" in the "Tuning System Performance" chapter.

This type of resource fine-tuning is similar to reconfiguring for performance. A reasonable first attempt would be to halve the allocations of each resource in configure's "Message Queue", "Shared Data", and "Semaphore" categories, except for the semaphore values SEMVMX, SEMAEM, and SEMOPM, which are not strictly resources and cause no space to be allocated. Halving the allocation of the other resources in these categories will free approximately 2.2K.

---

**Note**

No space will be freed by decreasing external buffers (NBUF), files (NFILE), inodes (NINODE) or multiscreens (NSCRN), as each of these resources is allocated out of user memory, not the precious near data that drivers must occupy.

---

After configure completes, the kernel is ready to link. Enter:

```
./link_xenix
```

Note that linking can take a while under XENIX-286. Reboot the system as described below to test the new kernel. Kernel space is generally not a
problem under XENIX-386. Kernels larger than 570K cannot boot under -286. If this is the case, reboot your previous kernel and unlink unused portions to reduce kernel size to less than 570K. You can use the size(C) utility to display the current size of your kernel.

7.4 Testing and Installing the New Kernel

7.4.1 Booting the New Kernel

Test the new kernel before installing it as /xenix. To do so, enter the following two command lines:

```
    cp /usr/sys/conf/xenix /xenix.new
    /etc/reboot
```

The system now reboots. A boot prompt appears:

```
    Boot
```

If you press RETURN, or do not enter anything for a time, the default operating system image /xenix is loaded and started. In order to test the newly installed device drivers, enter the name of the new kernel at the boot prompt:

```
    xenix.new
```

and press RETURN. The system is now running with the "new" kernel. Test the various devices (especially any that have been added).

Be aware that when an alternate kernel is used, ps(C) does not work correctly unless the -n flag and the pathname of the alternate XENIX kernel is specified. For example:

```
    ps -n /xenix.new
```

Whenever a different kernel is booted, remove /usr/adm/messages before switching to multi-user mode.
Note

Do not install xenix on the hard disk as /xenix until it is fully tested.

7.4.2 Creating A New /xenix

When the kernel is satisfactory, install the new kernel on the hard disk. Enter the following:

```
cd /usr/sys/conf
./hdinstall
```

hdinstall(ADM) moves the "old" /xenix to a file called /xenix.old and copies /usr/sys/conf/xenix to become /xenix.

7.4.3 Removing the Link Kit

Once the kernel is made, tested, and installed as /xenix, you can use custom to remove the Link Kit to save disk space. Before you do this, it is important to save the master, xenixconf, driver.o, and link xenix files. /usr/sys/io is one suitable place for them. These files are records of system changes. Unless these files are readily available, any further system configuration performed after removing and reinstalling the Link Kit will negate the work performed to reconfigure the system. Type:

```
cd /usr/sys/conf
cp master xenixconf link_xenix driver.o ./io
```

Where driver.o is the driver or list of drivers.

At the beginning of this chapter you were instructed to copy any previously created backup files into /usr/sys/conf if they existed. Now they exist. If these files are protected, an accurate picture of the system configuration can be maintained over any reconfigurations to come.
Chapter 8

Tuning System Performance

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8.1 Introduction

The Link Kit contains the configure(ADM) utility, which is used to alter a number of parameters that affect system performance. This chapter explains how to change these parameters to suit the needs of your system. In addition, general procedures are included that can improve resource usage and system performance.

Your XENIX system is optimized for use with a variety of hardware configurations and as a platform for many applications. The kernel, which lies at the heart of the operating system, controls a number of resources that are constantly being used, released and recycled. These resources include:

- **buffers**: A cache of in-memory storage units used to hold recently used data. (Buffers increase efficiency by keeping this data on hand and decrease reading from the disk.)

- **table entries**: A space in any of many tables that the kernel uses to keep track of the current tasks, resources and events.

- **other parameters**: Other definable values govern special resources (such as the number of multiscreens available or quantity of semaphores).

The use of these resources is defined by certain limits that can be decreased or extended, sometimes at the expense of other resources.

Performance tuning is an activity that may need your attention when you first set up your XENIX system. When you bring the system up for the first time, the system is automatically set to a basic configuration that is satisfactory for most applications. This configuration, however, cannot take into account the usage patterns and the behavior of your particular applications. For this reason, the structure of the system allows you to reconfigure it to enhance the performance for your particular application over that of the standard configuration.

There are several reasons for reallocating system resources:

- You install additional hardware memory and thus have greater memory resources to allocate.

- Persistent error messages are displayed indicating that certain resources are used up, such as inodes or table entries.
• The system response time is consistently slow, indicating that other resources are too constrained for the system to operate efficiently (as when too little hardware memory is installed.)

• Resource usage needs to be tailored to meet the needs of a particular application.

In addition, it is important to determine which resources are being wasted or have become inefficiently distributed due to the natural tendency for order to become chaos.

8.1.1 Examples of Specialized Resource Allocation

Specialized applications often require the reallocation of key system resources for optimum performance. For example, users with large databases may find that they need to lock more files simultaneously than the current allocation of file locks will permit. Users who have no need for specialized XENIX features such as message handling may find that they can get a slight performance boost by deallocating those features.

Deciding how to best optimize the use of these resources is known as performance or kernel tuning. Each resource or limit is represented by a separate kernel parameter. The actual values are altered using the configure utility.

8.2 Reallocating Kernel Resources with configure

The configure utility is an easy-to-use menu-driven program that presents each resource and prompts for modification. to set the allocation of the appropriate resources, relink the kernel by invoking the shell script link_xenix, copy the kernel to the root directory, reboot, and test the new kernel.

To change any kernel parameter, do the following:

1. If the Link Kit is not already installed, install it using the custom(ADM) command.

2. After making certain the Link Kit is installed, enter the following commands:

   cd /usr/sys/conf
   ./configure
3. The **configure** menu is displayed:

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>Disk Buffers</td>
</tr>
<tr>
<td>2.</td>
<td>Character Buffers</td>
</tr>
<tr>
<td>3.</td>
<td>Files, Inodes, and Filesystems</td>
</tr>
<tr>
<td>4.</td>
<td>Processes, Memory Management &amp; Swapping</td>
</tr>
<tr>
<td>5.</td>
<td>Clock</td>
</tr>
<tr>
<td>6.</td>
<td>MultiScreens</td>
</tr>
<tr>
<td>7.</td>
<td>Message Queues</td>
</tr>
<tr>
<td>8.</td>
<td>Semaphores</td>
</tr>
<tr>
<td>9.</td>
<td>Shared Data</td>
</tr>
<tr>
<td>10.</td>
<td>System Name</td>
</tr>
<tr>
<td>11.</td>
<td>Streams Data</td>
</tr>
<tr>
<td>12.</td>
<td>Event Queues and Devices</td>
</tr>
<tr>
<td>13.</td>
<td>Hardware Dependent Parameters</td>
</tr>
</tbody>
</table>

Select a parameter category to reconfigure by typing a number from 1 to 13, or type 'q' to quit.

Choose a category by entering the number preceding it. The resources in that category will be displayed, one by one, each with its current value. Enter a new value for the resource, or to retain the current value, simply press RETURN. After all the resources in the category have been displayed, **configure** will return to the category menu prompt. Choose another category to reconfigure or exit **configure** by entering q.

4. After you have finished changing parameters, you must link them into a new kernel. Enter the following command:

```
./link_xenix
```

This assembles each of the kernel modules into a new kernel, which must now be installed. Follow the instructions in the “Testing and Installing the New Kernel” section of the “Adding Device Drivers with the Link Kit” chapter.

### 8.2.1 Using the configure Command Line

**configure** also has a command-line interface suitable for use by application developers. For instance, a database developer who finds that 70 files rather than 50 files need to be locked simultaneously may provide a shell
script to perform the reconfiguration. To find the current value of any configurable resource using the command-line interface, enter:

```
./configure -y RESOURCE
```

Where `RESOURCE` is the name of the tunable parameter (in uppercase). To change the value of any resource from the command line, enter:

```
./configure RESOURCE=value
```

This interface is in addition to the interactive one; the same resources are configurable from both interfaces.

The sections that follow describe scenarios for reconfiguring the kernel resources.

### 8.3 Reconfiguring Because of Persistent Error Messages

The kernel should not be reconfigured because a kernel error message was received once, or even a couple of times, but when a single message persists. First try to increase a resource by a small amount, and if the problem persists, increase it by 50 or even 100 percent of its original value. If the problem is still not solved, more detailed research will be required to locate the exact program and sequence that causes the error.

**System Messages**

**Inode Table Overflow**

Increase `NINODE` in the “Files, Inodes, and Filesystems” category. `NFILE` and `NINODE` are usually set equal, but `NINODE` may be less in environments where many links are common. You can check these values with `pstat(C)`.

**no file**

Increase `NFILE` in the “Files, Inodes, and Filesystems” category. `NFILE` and `NINODE` are usually set equal, but `NINODE` may be less in environments where many links are common. You can check these values with `pstat(C)`.

**PANI C: Timeout table overflow**

Increase `NCALL` in the “Clock” category.

**out of text**

Increase `NTEXT` in the “Processes, Memory Management & Swapping” category. (Applies only to 80286-based machines.)
no more processes
Increase NPROC in the "Processes, Memory Management & Swapping" category.

map overflow \((n)\) shutdown and reboot
Increase CMAPSIZ and SMAPSIZ parameters in the "Processes, Memory Management and Swapping" category.
(Applies only to 80286-based machines.)

8.4 Reconfiguring for Performance

The system is configured such that greatest quantities of kernel resources are assigned to the most common tasks such as reading and writing from the disk, but performance of the more specialized features (such as interprocess communication) has not been ignored. This balance can be shifted to conform to individual requirements.

8.4.1 Deallocating Unused Resources

In order to save precious kernel space, it is possible to deallocate resources that your system does not use. By deallocating all semaphores, about 1.5K can be freed. By deallocating all message queue structures, about 3K can be freed. No standard utilities use either of these constructs, but they should only be entirely deallocated if no applications are present that might use these constructs. By deallocating all shared data segments, approximately 1.2K can be freed. Since shared data is used by applications such as spreadsheets and by the Cmerge compiler in some memory models, it is usually inappropriate to deallocate shared data entirely. In addition, if your system does not have programs that use file locking, you can decrease this resource (NFLOCKS) accordingly.

8.4.2 Improving Disk Utilization

Disk input/output may cause a bottleneck in system performance. There are three steps in tuning the disk subsystem for better utilization.

- Choosing the proper number of buffers.
- Setting the sticky-bit on selected programs.
- Organizing the filesystems to minimize disk activity.
Choosing Buffer Size

When the **configure** utility "Disk Buffer" category is selected, the buffer resources NBUF, NSABUF (XENIX-286 only), NHBUF and MAXBUF will be displayed in turn. (Buffer allocation differs in XENIX-286; refer to "Buffer Allocation on 80286-based Machines").

Use the number of buffers (NBUF and NHBUF) given in Table 8-1 as a starting point. These values come close to optimum for most system workloads.

The NBUF parameter controls the number of buffers in the system buffer cache used to reduce the need to access the disks. These buffers hold recently used data on the chance that it will be needed again. NHBUF specifies the number of hashing buckets in the buffer cache. The more buffers, the greater chance that needed data can be found in the buffers without the system having to do a time-consuming disk read. If the value for NBUF is left null, the system calculates the values shown in Table 8-1. The value for NHBUF is a power of 2 that is roughly one-quarter the value of NBUF.

When the number of buffers, NBUF, is nonzero, its value is the actual number of disk buffers. When NBUF is zero, the system will autoconfigure buffers based on the amount of memory available. To find out how many buffers have been autoconfigured, examine the value of "i/o bufs" displayed during system boot.

Increasing NBUF and NHBUF, up to a point, improves system performance. A system with two megabytes of memory can typically devote roughly 250K bytes of memory to buffers (250 buffers at approximately 1K bytes each) while a system with 4 megabytes of memory can devote 600K bytes of memory to buffers (more if there are few users). However, if too many buffers are allocated, there may not be enough memory space for efficient operation of user processes, and the amount of swapping done by the system will increase. The swapping activity usually costs more in system efficiency than is gained by having a large amount of buffer space.

After your XENIX system has run for a day or so, you will want to check for excessive swapping activity. If such activity is found, reduce the number of buffers (NBUF and NHBUF) or increase your system memory. (See the "Using vmstat to Diagnose System Inefficiency" section for more information.)
Buffer Allocation on 80286-based Machines

On 80286-based machines, there is a distinction made between near and far kernel data. NSABUF determines the number of near disk buffers and NBUF determines the number of far disk buffers. (This distinction is meaningless on 80386-based machines and the parameter NSABUF is not used.) The quantity of System Addressable Buffers (NSABUF), represents a tradeoff between buffers and other kernel resources.

A small amount of kernel resource space is available for additional device drivers, but it can be allocated to NSABUF, if desired. Beyond this, NSABUF should only be increased if other kernel resources are not being used.

The basic scheme is to deallocate any unused resources, set MAXBUF and NBUF to equal, large numbers, and after finding an appropriate tradeoff between user memory and external disk buffers, use any remaining near data space space for increasing NSABUF and the few extra buffer headers that the additional buffers will require.

Under XENIX-286, if combined allocated resources consume more than 64K of memory, the ld error message:

```
Group "DGROUP" larger than 64Kbytes
```

appears when the shell script `link_xenix` is run. This message does not apply to SCO XENIX-386. If you see this message, you should reduce some of the configurable kernel parameters discussed in this chapter.

Setting the "Sticky-Bit" (80286 Machines Only)

Setting the sticky bit can reduce the disk traffic of a select group of commands. The term "sticky" refers to making a program stay, or "stick" in memory. The text segments of selected sticky commands are kept in memory or contiguously in swap space, even when the process terminates.
Note

The sticky-bit is only useful on 80286-based machines. With 80386-based machines, recently used pages (with freshly initialized data) are held in the page cache, so there is no need to set the sticky bit. If the bit is set anyway, it is ignored.

The sticky bit is normally useful for very frequently used programs like ls, sh, and vi. Any program used often enough can have the sticky bit set for a significant performance boost. The sticky bit can be set by entering the following command:

```
chmod u+t filename
```

8.4.3 Filesystem Organization

This section describes several actions that can be taken to reduce the overhead of file access. As filesystems are used, the blocks of individual member files tend to become physically scattered around the disk(s) and I/O becomes less efficient. This scattering yields poor ordering of blocks with files and poor directory structure.

Organization of Filesystem Free List

Filesystems are set up to allocate free blocks in a manner that allows the files to be read or written with efficiency. A free list array is created when a filesystem is created with `mkfs(ADM)`. The free list is set up with the rotational gap specified by `mkfs` options. The difference between successive block numbers in the free list is the rotational gap. For example, a file created on a system with a rotational gap of 10 may consist of blocks 510, 520, and 530. When the file is read, I/O requests are sent to the disk drive to read blocks 510, 520, and 530. As soon as the drive finishes reading block 510 and has started to process the second request, block 520 will be moving over the read/write head just as the drive is ready to read that request. This method makes for efficient I/O operation.

However, as you start changing files (changing size or removing), the efficiency starts to decrease. When several files are being created at once, they will be contending for blocks from the free list. Some of the blocks allocated to the files will be out of sequence. As you can see, the free list also becomes scattered about the disk as blocks are allocated and freed.
Directory Organization

Directory organization also affects input/output performance. The problems show up when files are removed by users. When a file is removed from a directory, the i-node number is nulled out. This leaves an unused slot for that i-node; over time the number of empty slots may become quite large. If you have a directory with 100 files in it and you remove the first 99 files, the directory still contains the 99 empty slots, at 16 bytes per slot, preceding the active slot. In effect, unless a directory is reorganized on the disk, it will retain the largest size it has ever achieved.

Restoring Good Filesystem Organization

There is no automatic way to solve these problems; however, you can manually rearrange the filesystem. Here are a variety of ways to do this. Note that in all cases the filesystem(s) must be unmounted.

1. To reorganize the free list, run `fsck(ADM)` using the `-s` option.

2. To reorganize particular directory structures, use `cpio(C) -pdm` to copy them to a temporary location, remove the original structure, then use `cpio -pdm` to copy them back to their original location. Use the following command line:

   ```bash
   find sourcedir -print | cpio -pdm destdir
   ```

   `sourcedir` is the name of the original directory; `destdir` is the directory you are moving the structure to. After confirming that the entire structure has been copied over, remove the entire original directory. Finally, swap the source and destination directory names in the command line above, and execute the command again. After removing the superfluous directory, your original directory structure is reorganized.

3. To reorganize an entire filesystem, use the `sysadmin` utility to perform an unscheduled level 0 backup of the filesystem. (This is described in detail in the “Backing Up Filesystems” chapter in this Guide.) When the backup is complete, follow the instructions for restoring an entire filesystem.

4. If you have more than one disk, balance heavily-used filesystems across the disks.
8.5 Defining Efficient System Usage Patterns

After the kernel and the system activities are tuned, and the file systems organized, the next step for improving system performance is to perform some housekeeping activities and to check whether prime time load can be reduced. The person responsible for administering the system should check for:

- less important jobs interfering with more important jobs
- unnecessary activities being carried out
- scheduling of selected jobs for when the system is not so busy
- the efficiency of user-defined features, such as .profile and $PATH

8.5.1 ps

The ps(C) command is used to obtain information about active processes. The command gives a "snapshot" picture of what is going on, which is useful when you are trying to identify what processes are loading the system. Things will probably change by the time the output appears; however, the entries that you should be interested in are TIME (minutes and seconds of CPU time used by processes) and STIME (time when process first started).

When you spot a "runaway" process (one that uses progressively more system resources over a period of time while you are monitoring it), you should check with the owner. It is possible that such a process should be stopped immediately via the kill(C) command. When you have a real runaway, it continues to eat up system resources until everything grinds to a halt. For a process that proves "unkillable," rebooting is the only way to stop it.

When you spot processes that take a very long time to execute you should consider using cron(C) to execute the job during off-hours.

8.5.2 User $PATH Variables

$PATH is searched upon each command execution. Before displaying "not found," the system must search every directory in $PATH. These searches require both processor and disk time. If there is a disk or processor bottleneck, changes here can help performance.
Some things that you should check for in user $PATH variables are:

- **Path Efficiency**

  $PATH$ is read left to right, so the most likely places to find the command should be first in the path (/bin and /usr/bin). Make sure that a directory is not searched more than once for a command.

- **Convenience and Human Factors**

  Users may prefer to have the current directory listed first in the path (:/bin).

- **Path Length**

  In general, $PATH$ should have as few entries as possible.

- **Large Directory Searches**

  Searches of large directories should be avoided if possible. Put any large directories at the end of $PATH$.

### 8.6 Using vmstat to Diagnose System Inefficiency

The `vmstat` utility can be a useful tool for examining and tuning system performance. It cannot provide definitive answers on resource tuning issues, but can provide some insight into the internal workings of the system and help diagnose problems related to poor memory and CPU usage.

**Note**

The `vmstat` utility is only applicable to 80386-based machines and is not available for the 80286.

#### 8.6.1 Memory Usage: Buffers Versus Pages

Specifying the number of system disk buffers (either explicitly using `configure` or implicitly using the defaults), effectively divides the available memory between two pools: the disk buffer pool and the page pool. The page pool contains the programs being run and cached copies of
recently-used program pages. If the page pool is much too small for the load imposed on the system, the system will be constantly swapping pages in and out just to keep up with the current processes.

If the page pool is only slightly undersized, the effects will be seen not in swapping overhead but in reduced cache performance when running the same programs repeatedly. This means that sufficient pages are available to effectively handle current processes, but there are none to spare for keeping recently-used pages in memory for potential access savings.

By using `vmstat`, you can determine how many programs have been swapped in and out during a given interval. If excessive swapping is evident, you can redistribute memory allocation to increase the page pool. We also recommend adding as much RAM as practical; swapping is decreased and performance is improved.

### 8.6.2 The `vmstat` Display

`vmstat` is used to take a series of snapshots of how the system is performing, including:

- A summary of the number of processes in various states,
- Paging activity,
- System activity,
- CPU cycle consumption.

The `vmstat` display looks like this:

<table>
<thead>
<tr>
<th>procs</th>
<th>paging</th>
<th>system</th>
<th>cpu</th>
</tr>
</thead>
<tbody>
<tr>
<td>r b w</td>
<td>si so ch cm ffr swr sww rec shf shc cpy pf in sy cs us su id</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2 67 0</td>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 155 68 198 26 72 20 8</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

For the purposes of this procedure, the only categories you are interested in are as follows:

- `si` Number of processes swapped in.
- `so` Number of processes swapped out.
ch  Number of page cache hits; the number of pages that were re-used rather than retrieved from disk.

cm  Number of page cache misses; essentially the number of times the system had to retrieve a page from the hard disk.

id  The percentage of time the CPU spent doing nothing; idle time.

8.6.3 Checking Buffer and Page Cache Usage

To determine whether you have enough memory in the page pool for the page caching mechanism to work efficiently, do the following:

1. Run a small set of programs over and over in addition to your usual process and user load.

2. Start the `vmstat` command running at fifteen second intervals by entering the following:

   `vmstat 15`

Watch the columns "ch" (page cache hits) and "cm" (page cache misses) for a few minutes. If you see more misses than hits, you may find that a larger page pool will help performance. (However, an initially poor page cache hit-to-miss ratio is to be expected when running programs for the first time.) If the page pool is too small, the usual solution is to add more memory, but there may be application mixes for which shrinking the buffer cache will achieve the same result.

8.6.4 Checking CPU Usage

The "id" (percentage idle) column may also provide some insight into system performance. This figure is normally between 40 and 100 percent, even with a large number of active users. When this figure falls consistently below 30%, the chief competition for resources does not involve memory at all; the critical resource is raw processor power. (Run the `ps(C)` command to make certain that the excessive CPU usage is not due to a runaway process that is stealing every spare CPU cycle.)

If you are running a large number of users, it may help to switching to smart serial boards if you are using more common dumb cards. Smart cards take some of the burden off the CPU rather than adding to the amount of work it has to do.
In addition, you should examine `/usr/spool/crontab` to see if jobs are queued up for peak periods that might better be run at times when the system is idle. Use the `ps` command to determine what processes are heavily loading the system. Encourage users to run large, non-interactive commands (such as `nroff(C)` or `troff(C)`)) at off-peak hours. You may also want to run such commands with a low priority by using the `nice(C)` or `batch(C)` commands.

### 8.7 Summary of Tunable Parameters

Tunable system parameters are used to set various table sizes and system thresholds to handle the expected system load. Caution should be used when changing these variables since such changes can directly affect system performance. For the most part, the default tunable parameter values are acceptable for most configurations and applications. If your application has special performance needs, you may have to experiment with different combinations of parameter values to find an optimal set.

Table 8-1 shows the recommended tunable parameter values for a system equipped with different amounts of hardware memory (RAM) installed.

The following notes apply to the Tunable Parameters Table 8-1:

- The value of a few parameters are calculated each time a new kernel (/xenix) is generated, unless the value is manually overridden (see note below).
- The default value and the size in bytes for each entry are shown in the table.
- A dash (—) is used in the size information to indicate parameters that set flags in the kernel. Parameters that set flags do not affect the size of the kernel when their values are changed; only the values of the specific flags are changed.
- A dagger (†) indicates a parameter that applies only to 80386-based machines.
- An asterisk (*) indicates a parameter that applies only to 80286-based machines.
Note

Overriding the calculated value causes the parameter to be set to the new value each time a new kernel (/xenix) is generated. When calculated parameter values are overridden, however, any subsequent changes in the hardware configuration (adding new memory for example) require a change of the value that was manually set. This will allow you to optimize the performance of the new configuration.
<table>
<thead>
<tr>
<th>Parameter</th>
<th>RAM Installed</th>
<th>Default Value</th>
<th>Size per Entry in Bytes</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1 MEG</td>
<td>2 MEGS</td>
<td>3-5 MEGS</td>
</tr>
<tr>
<td>NDISK</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>NBUF</td>
<td>100</td>
<td>250</td>
<td>400</td>
</tr>
<tr>
<td>NSABUF*</td>
<td>4</td>
<td>16</td>
<td>40</td>
</tr>
<tr>
<td>NPBUF</td>
<td>32</td>
<td>64</td>
<td>128</td>
</tr>
<tr>
<td>NMBUF</td>
<td>100</td>
<td>100</td>
<td>160</td>
</tr>
<tr>
<td>NDISK</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>NBUF</td>
<td>10</td>
<td>24</td>
<td>—</td>
</tr>
<tr>
<td>NSABUF*</td>
<td>100</td>
<td>100</td>
<td>160</td>
</tr>
<tr>
<td>NPBUF</td>
<td>8</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>NMBUF</td>
<td>4</td>
<td>16</td>
<td>40</td>
</tr>
<tr>
<td>NDISK</td>
<td>60</td>
<td>70</td>
<td>80</td>
</tr>
<tr>
<td>NBUF</td>
<td>25</td>
<td>25</td>
<td>30</td>
</tr>
<tr>
<td>NSABUF*</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>NPBUF</td>
<td>8</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>NMBUF</td>
<td>4</td>
<td>16</td>
<td>40</td>
</tr>
<tr>
<td>NDISK</td>
<td>513</td>
<td>513</td>
<td>513</td>
</tr>
<tr>
<td>NBUF</td>
<td>8192</td>
<td>8192</td>
<td>8192</td>
</tr>
<tr>
<td>NSABUF*</td>
<td>8192</td>
<td>8192</td>
<td>8192</td>
</tr>
<tr>
<td>NPBUF</td>
<td>60</td>
<td>60</td>
<td>60</td>
</tr>
<tr>
<td>NMBUF</td>
<td>8</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>NDISK</td>
<td>21</td>
<td>21</td>
<td>21</td>
</tr>
<tr>
<td>NBUF</td>
<td>10</td>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>NSABUF*</td>
<td>20</td>
<td>20</td>
<td>20</td>
</tr>
<tr>
<td>NPBUF</td>
<td>10</td>
<td>10</td>
<td>10</td>
</tr>
</tbody>
</table>

Table 8-1: Configurable Kernel Parameters
# Tuning System Performance

## Table 8-1: Configurable Kernel Parameters (continued)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>RAM Installed</th>
<th>Default Value</th>
<th>Size per Entry</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1 MEG 2 MEGS 3-5 MEGS 6-15 MEGS</td>
<td></td>
<td>in Bytes</td>
</tr>
<tr>
<td>SEMOPM</td>
<td>5 5 5 5</td>
<td>5 5</td>
<td>8</td>
</tr>
<tr>
<td>SEMUME</td>
<td>5 5 5 5</td>
<td>5 5</td>
<td>8XSEMMNU</td>
</tr>
<tr>
<td>SEMVMX</td>
<td>32766 32766 32766 32766</td>
<td>32766</td>
<td></td>
</tr>
<tr>
<td>SEMAEM</td>
<td>16384 16384 16384 16384</td>
<td>16384</td>
<td></td>
</tr>
<tr>
<td>SEMMNS</td>
<td>40 40 40 40 40</td>
<td>40</td>
<td>8</td>
</tr>
<tr>
<td>NSDSEGS†</td>
<td>25 25 25 25 25</td>
<td>25</td>
<td></td>
</tr>
<tr>
<td>NSDSLOTS†</td>
<td>3 3 3 3 3</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>SHMMIN†</td>
<td>1 1 1 1 1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>SHMMNJ†</td>
<td>25 25 25 25 25</td>
<td>25</td>
<td>52</td>
</tr>
<tr>
<td>SHMSEG†</td>
<td>6 6 6 6 6</td>
<td>6</td>
<td>12XNPROC</td>
</tr>
<tr>
<td>SHMALL†</td>
<td>4096 4096 4096 4096 4096</td>
<td>4096</td>
<td></td>
</tr>
<tr>
<td>NODE</td>
<td>— — — — —</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>NQUEUE</td>
<td>— 256 384 384 128</td>
<td>128</td>
<td>36</td>
</tr>
<tr>
<td>NSTREAM</td>
<td>— 32 48 48 32</td>
<td>32</td>
<td>52</td>
</tr>
<tr>
<td>NBLK8192</td>
<td>— 0 0 0 0</td>
<td>0</td>
<td>4142</td>
</tr>
<tr>
<td>NBLK4096</td>
<td>— 0 0 0 0</td>
<td>0</td>
<td>4142</td>
</tr>
<tr>
<td>NBLK2048</td>
<td>— 20 40 40 5</td>
<td>5</td>
<td>2094</td>
</tr>
<tr>
<td>NBLK1024</td>
<td>— 12 32 32 10</td>
<td>10</td>
<td>1070</td>
</tr>
<tr>
<td>NBLK512</td>
<td>— 8 18 18 10</td>
<td>10</td>
<td>558</td>
</tr>
<tr>
<td>NBLK256</td>
<td>— 16 48 48 5</td>
<td>5</td>
<td>302</td>
</tr>
<tr>
<td>NBLK128</td>
<td>— 64 128 128 5</td>
<td>5</td>
<td>174</td>
</tr>
<tr>
<td>NBLK64</td>
<td>— 256 256 256 64</td>
<td>64</td>
<td>110</td>
</tr>
<tr>
<td>NBLK32</td>
<td>— 128 128 128 128</td>
<td>128</td>
<td>110</td>
</tr>
<tr>
<td>NBLK16</td>
<td>— 128 256 256 0</td>
<td>0</td>
<td>61</td>
</tr>
<tr>
<td>NBLK4</td>
<td>— 128 128 128 128</td>
<td>128</td>
<td>50</td>
</tr>
<tr>
<td>NMUXLINK</td>
<td>— 32 48 48 32</td>
<td>32</td>
<td>12</td>
</tr>
<tr>
<td>NSTREVENT</td>
<td>— 256 256 256 64</td>
<td>64</td>
<td>12</td>
</tr>
<tr>
<td>NSTRPUSH</td>
<td>— 9 9 9 9</td>
<td>9</td>
<td>16</td>
</tr>
<tr>
<td>MAXSEPCNT</td>
<td>— 1 2 2 1</td>
<td>1</td>
<td>2048</td>
</tr>
<tr>
<td>STRMSGSZ</td>
<td>— 4096 4096 4096 4096</td>
<td>4096</td>
<td></td>
</tr>
<tr>
<td>STRCTLSZ</td>
<td>— 1024 1024 1024 1024</td>
<td>1024</td>
<td>512</td>
</tr>
<tr>
<td>STRLOFRAC</td>
<td>— 80 80 80 80</td>
<td>80</td>
<td></td>
</tr>
<tr>
<td>STRMFRAC</td>
<td>— 90 90 90 90</td>
<td>90</td>
<td></td>
</tr>
<tr>
<td>EVQUEUES</td>
<td>1 3 6 40 8</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>EVDEVS</td>
<td>2 6 12 36 16</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>EVDEVSPerQ</td>
<td>2 3 3 32 3</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>DMAEXCL</td>
<td>— — — — —</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>KBTYPE</td>
<td>— — — — —</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>
The following is a complete list of configurable parameters, their purpose, and suggested tuning values.

### 8.7.1 Disk Buffers

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>NDISK</strong></td>
<td>The number of floppy drives attached to the system. This is set at boot time.</td>
</tr>
<tr>
<td><strong>NBUF</strong></td>
<td>Specifies how many system buffers to allocate. The XENIX system buffers form a data cache. The data cache is a memory array containing disk file information. Improvement in the hit rate of this cache increases with the number of buffers. Cache hits reduce the number of disk accesses and thus improve overall performance. The entries are normally in the range of 100 to 600. Each buffer contains 1076 bytes. Hash buffers (NHBUF) should be increased along with system buffers (NBUF) for optimal performance.</td>
</tr>
<tr>
<td><strong>NSABUF</strong></td>
<td>The number of buffer cache buffers in near kernel data on 286 kernels. Irrelevant on 386 machines since all data is near.</td>
</tr>
<tr>
<td><strong>NPBUF</strong></td>
<td>Specifies how many physical input/output buffers to allocate. Each entry contains 52 bytes. The default value is 8.</td>
</tr>
<tr>
<td><strong>NHBUF</strong></td>
<td>Specifies how many &quot;hash buckets&quot; to allocate. These are used to search for a buffer given a device number and block number rather than a linear search through the entire list of buffers. <strong>This value must be a power of 2.</strong> Each entry contains 12 bytes. The NHBUF value should be chosen so that the value NBUF divided by NHBUF is approximately equal to 4. While the value of NBUF is normally calculated by the system, that is not true for NHBUF.</td>
</tr>
<tr>
<td><strong>MAXBUF</strong></td>
<td>Maximum possible number of buffer cache buffers. This is the number of buffer description headers in the kernel. Fewer than this number of buffers may actually be autoconfigured by the kernel at boot time, depending on how much core is present. If NBUF is non-zero, then exactly NBUF buffers will</td>
</tr>
</tbody>
</table>
be configured, and there is no reason for MAXBUF to be larger than NBUF. If NBUF is 0, the kernel will configure at most MAXBUF buffers automatically.

8.7.2 Character Buffers

NCLIST
Clists, or character lists, are small buffers used to read from and write to serial devices. If NCLIST is insufficient, serial I/O performance may suffer. Each buffer contains up to 64 bytes. The buffers are dynamically linked to form input and output queues for the terminal lines and other slow speed devices. The average number of buffers needed per terminal is in the range of 5 to 10. No additional performance can possibly be achieved after there are 16 clists per character device, and most systems need far fewer. Each entry (buffer space plus header) contains 72 bytes. When the CLISTS are full, input and output characters dealing with terminals are lost, although echoing continues on the screen.

NEMAP
The number of 8-bit channel maps used for character set mapping. Each corresponds to one possible alternate character set.

NSXT
The number of shell-layer sessions.

8.7.3 Files, Inodes, and Filesystems

NINODE
Specifies how many inode table entries to allocate. Each table entry represents an in-core inode that is an active file. For example, an active file might be a current directory, an open file, or a mount point. The file control structure is modified when changing this variable. The number of entries used depends on the number of opened files. The entries are normally in the range of 100 to 400. The value for NINODE pertains directly to the NFILE value. Although these two resources are usually set equal, they sometimes diverge, for example:

The number of open files is greater than the number
of open inodes whenever two processes have the same file open. The number of open inodes is greater than the number of open files while a file is being opened.

When the inode table overflows, the following warning message is output on the system console:

```
inode table overflow
```

**NFILE**

Specifies how many open file table entries to allocate. Each entry represents an open file. The entry is normally in the range of 100 to 400. Each entry contains 12 bytes. The NFILE entry relates directly to the NINODE entry. The NFILE control structure operates in the same manner as the NINODE structure. When the file table overflows, the following warning message is output on the system console.

```
file table overflow
```

As a reminder, this parameter does not affect the number of open files per process.

**NMount**

Determines the maximum number of filesystems that can be mounted at one time. The root filesystem counts as a mounted filesystem in this calculation. If you configure this parameter, make sure to allow for an extra filesystem so that you can mount a filesystem floppy. When full, the `mount(S)` system call returns the error EBUSY. Since the mount table is searched linearly, this value should be as low as possible.

**NFLOCKS**

The number of files that can be locked at once. If you are not using an application that uses file locking, (none of the standard XENIX utilities do) this resource can be partially deallocated to save space. The default value is 50. Each entry contains 28 bytes.

**CMASK**

The mask used for file creation.
8.7.4 Processes, Memory Management & Swapping

NPROC The number of processes that can be active anywhere in the system. A process attempting to fork when there are already NPROC processes active will receive the error EAGAIN (see intro(5)). This error also generates the "no more processes" screen message. If any significant change is made to NPROC, CMAPSZ and SMAPSIZ (286 only) should also be changed (see below). The swapper is always the first process and /etc/init is always the second. The number of entries depends on the number of terminal lines available and the number of processes spawned by each user. The average number of processes per user is in the range of 2 to 5 (also see MAXUP, default value 30). The NPROC entry is in the range of 50 to 200.

MAXUPRC The number of processes that a single user can run simultaneously. A process attempting to fork when the user already has MAXUPRC processes active will receive the error EAGAIN. The entry is normally in the range of 15 to 30. This value should not exceed the value of NPROC (NPROC should be at least 10% more than MAXUP). This value is per user identification number, not per terminal. For example, if 12 people are logged in on the same user identification, the default limit would be reached very quickly.

MEMLIM A process may occupy up to this percent of user memory, plus the swap area it can occupy (which is constrained by SWPLIM). (This parameter is only valid on 80386-based machines.)

SWPLIM A process may occupy up to this percent of swap area, plus the memory area it can occupy (which is constrained by MEMLIM). (This parameter is only valid on 80386-based machines.)

CMAPSIZ Table used to hold list of program segments in memory. (This parameter is only valid on 80286-based machines.)

SMAPSIZ Table used to hold lists of program segments being swapped. While CMAPSZ and SMAPSIZ rarely
need to be changed themselves, they should vary with NPROC, each being NPROC * 2 by default. (This parameter is only valid on 80286-based machines.)

**NTEXT**
Maximum text segments (systemwide) (This parameter is only valid on 80286-based machines.)

### 8.7.5 Clock

**NCALL**
Specifies how many call-out table entries to allocate. Each entry represents a function to be invoked at a later time by the clock handler portion of the kernel. This value must be greater than 2 and is normally in the range of 10 to 70. The default value is 60. Each entry contains 16 bytes.

An example of callout table entry usage: Software drivers may use call entries to check hardware device status. When the call-out table overflows, the system crashes and outputs the following message on the system console:

```
PANIC: Timeout table overflow
```

**TIMEZONE**
Number of minutes west of Greenwich Mean Time.

**DSTFLAG**
This flag defines daylight savings time.

### 8.7.6 MultiScreens

**NSCRN**
The number of multiscreens that can be used on the console. The maximum is 12.

**SCRNMEM**
The number of 1024 byte blocks for console screen saves.
8.7.7 Message Queues

The following tunable parameters are associated with inter-process communication messages.

**MSGMAP**
Specifies the size of the control map used to manage message segments. Default value is 513. Each entry contains 8 bytes.

**MSGMAX**
Specifies the maximum size of a message in bytes. The default value is 8192. The maximum size is 64 kilobytes -1 byte.

**MSGMNB**
Specifies the maximum length of a message queue. The default value is 8192.

**MSGMNI**
Specifies the maximum number of message queues system-wide (id structure). The default value is 10.

**MSGTQL**
Specifies the number of message headers in the system and, thus, the number of outstanding messages. The default value is 60. Each entry contains 12 bytes.

**MSGSSZ**
Specifies the size, in bytes, of a message segment. Messages consist of a contiguous set of message segments large enough to fit the text. The default value is 8. The value of MSGSSZ times the value of MSGSEG must be less than or equal to 131,072 bytes (128 kilobytes).

**MSGSEG**
Specifies the number of message segments in the system. segments during system initialization. The default value is 1024. MSGSEG and MSGSSZ are multiplied to determine the number of bytes of memory to be allocated for messages. The value of MSGSEG * MSGSSZ is the number printed out in the XENIX boot message (e.g. “msg bufs = 8K”). Note that there is a flag IPC_NOWAIT that can be passed into many of the msg() system calls. If this flag is passed, the system calls will fail immediately if there is no space for a message. If this flag is not passed, then the system calls will sleep until there is room for the message. The value of MSGSSZ times the value of MSGSEG must be less than or equal to 131,072 bytes (128 kilobytes). If MSGSEG is zero, its value is set relative to the
amount of memory in the system at boot time. MSGSEG * MSGSSZ should be no more than MSGTQL * MSGMAX, but may be smaller to conserve user memory.

### 8.7.8 Semaphores

The following tunable parameters are associated with inter-process communication semaphores.

- **SEMMAP**: Specifies the size of the control map used to manage semaphore sets. The default value is 21. Each entry contains 8 bytes.
- **SEMMNI**: Specifies the number of semaphore identifiers in the kernel. This is the number of unique semaphore sets that can be active at any given time. The default value is 10. Each entry contains 32 bytes.
- **SEMMNS**: Specifies the number of semaphores in the system. The default value is 40. Each entry contains 8 bytes.
- **SEMMNU**: Specifies the number of undo structures in the system. The default value is 30. The size is equal to 8 x (SEMMUSE + 2) bytes.
- **SEMMSL**: Specifies the maximum number of semaphores per semaphore identifier. The default value is 10.
- **SEMOPM**: Specifies the maximum number of semaphore operations that can be executed per `semop(S)` system call. The default value is 5. Each entry contains 8 bytes.
- **SEMUME**: Specifies the maximum number of undo entries per undo structure. The default value is 5. The size is equal to 8*(SEMMNU) bytes.
- **SEMVX**: Specifies the maximum value a semaphore can have. The default value is 32767. The default value is the maximum value for this parameter.
- **SEMAEM**: Specifies the adjustment on exit for maximum value, alias `semadj`. This value is used when a semaphore value becomes greater than or equal to
8.7.9 Shared Data

The following tunable parameters are associated with inter-process communication shared memory. (These parameters are only valid on 80386-based machines.)

- **NSDSEGS**: The maximum number of shared memory segments allowed in the system.
- **NSDSLOTS**: NSDSLOTS * NSDSEGGGS is the maximum number of simultaneous attaches to shared memory segments for the entire system.
- **SHMMAX**: Specifies the maximum shared memory segment size. The default value is 131072.
- **SHMMIN**: Specifies the minimum shared memory segment size. The default value is 1.
- **SHMMNI**: Specifies the maximum number of shared memory identifiers system wide. The default value is 100. Each entry contains 52 bytes.
- **SHMSEG**: Specifies the number of attached shared memory segments per process. The default value is 6. The maximum value is 15.
- **SHMALL**: Specifies the maximum number of in-use shared memory text segments. The default value is 512.

8.7.10 System Name

- **NODE**: Specifies the node name of the system.
8.7.11 Streams Data

The following tunable parameters are associated with Streams processing. The values should be left at 0 unless the STREAMS package has been installed and you're planning on using STREAMS. Exception: STREVENT and NMUXLINK should be set to 1.

Note

STREAMS support requires installation of the XENIX STREAMS Runtime package; it is not included with the XENIX Operating System distribution.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>NQUEUE</td>
<td>The number of STREAMS queues to be configured. Queues are always allocated in pairs, so this number should be even. A minimal Stream contains four queues (two for the Stream head, two for the driver). Each module pushed on a Stream requires an additional two queues. A typical configuration value is 8*NSTREAM.</td>
</tr>
<tr>
<td>NSTREAM</td>
<td>The number of &quot;Stream-head&quot; (stdata) structures to be configured. One is needed for each Stream opened, including both Streams currently open from user processes and Streams linked under multiplexers. The recommended configuration value is highly application-dependent, but a value of 32-40 usually suffices on an 80386-based computer for running a single transport provider with moderate traffic.</td>
</tr>
<tr>
<td>NMUXLINK</td>
<td>The maximum number of multiplexer links to be configured. One link structure is required for each active multiplexor link (STREAMS I_LINK ioctl). This number is application dependent; the default allocation equal to the number of Streams (NSTREAM) guarantees availability of links.</td>
</tr>
<tr>
<td>NBLKn</td>
<td>The number of STREAMS data blocks and buffers to be allocated for each size class. Message block headers are also allocated based on</td>
</tr>
</tbody>
</table>
these numbers: the number of message blocks is 1.25 times the total of all data block allocations. This provides a message block for each data block, plus some extras for duplicating messages (kernel functions `dupb()`, `dupmsg()`). The optimal configuration depends on both the amount of primary memory available and the intended application.

**NSTREVENT**

The initial number of Stream event cells to be configured. Stream event cells are used for recording process-specific information in the `poll(S)` system call. They are also used in the implementation of the STREAMS `I_SETSIG ioctl` and in the kernel `bufcall()` mechanism. A rough minimum value to configure would be the expected number of processes to be simultaneously using `poll(S)` times the expected number of Streams being polled per process, plus the expected number of processes expected to be using STREAMS concurrently. The default is 256. Note that this number is not necessarily a hard upper limit on the number of event cells that will be available on the system (see MAXSEPGCNT).

**NSTRPUSH**

The maximum number of modules that may be pushed onto a Stream. This is used to prevent an errant user process from consuming all of the available queues on a single Stream.

**MAXSEPGCNT**

The number of additional pages of memory that can be dynamically allocated for event cells. If this value is 0, only the allocation defined by NSTREVENT is available for use. If the value is not 0 and if the kernel runs out of event cells, it will under some circumstances attempt to allocate an extra page of memory from which new event cells can be created. MAXSEPGCNT places a limit on the number of pages that can be allocated for this purpose. On a 80386-based computer, each new page can provide 340 event cells. Once a page has been allocated for event cells, however, it cannot be recovered later for use elsewhere. It is recommended that the NSTREVENT value be set to accommodate most load conditions, and that
MAXSEPGCNT be set to 1 to handle exceptional load cases should they arise.

**STRMSGSZ**

The maximum allowable size of the data portion of any STREAMS message. This should usually be set just large enough to accommodate the maximum packet size restrictions of the configured STREAMS modules. If it is larger than necessary, a single **write**(S) or **putmsg**(S) can consume an inordinate number of message blocks. The recommend value of 4096 is sufficient for existing applications.

**STRCTLSZ**

The maximum allowable size of the control portion of any STREAMS message. The control portion of a **putmsg**(S) message is not subject to the constraints of the min/max packet size, so the value entered here is the only way of providing a limit for the control part of a message. The recommended value of 1024 is more than sufficient for existing applications.

**STRLOFRAC**

The percentage of data blocks of a given class at which low-priority block allocation requests are automatically failed. For example, if STRLOFRAC is 80 and there are 48 256-byte blocks, a low-priority allocation request will fail when more than 38 256-byte blocks are already allocated. The parameter is used to help prevent deadlock situations by starving out low-priority activity. The recommended value of 80 works well for current applications. **STRLOFRAC** must always be in the range 0 <= **STRLOFRAC** <= **STRMEDFRAC**.

**STRMEDFRAC**

The percentage cutoff at which medium priority block allocations are failed (see **STRLOFRAC** discussion above). The recommended value of 90 works well for current applications. **STRMEDFRAC** must always be in the range **STRLOFRAC** <= **STRMEDFRAC** <= 100.
Tuning System Performance

Note

There is no cutoff fraction for high-priority allocation requests; it is effectively 100.

8.6.12 Event Queues and Devices

EVQUEUES Maximum number of open event queues systemwide.

EVDEVS Maximum number of devices attached to event queues systemwide.

EVDEVSPERQ Maximum devices per event queue.

8.6.13 Hardware Dependent Parameters

DMAEXCL This is set to 1 if only 1 DMA channel is usable at once, 0 otherwise.

KBTYPETE This is set to XT for XT-type keyboards and AT for AT-type keyboards.
Chapter 9

Using DOS and XENIX
On the Same Disk

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9.2 Partitioning the Hard Disk Using fdisk 9-1
9.3 Installing XENIX on a DOS System 9-4
9.4 Using XENIX and DOS With Two Hard Disks 9-6
9.5 Removing an Operating System From the Hard Disk 9-7
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9.7 XENIX and DOS On Non-Standard Disks 9-8
9.1 Introduction

Many users received the MS-DOS, or other closely compatible DOS, operating system with their computer. This chapter explains how you can still use DOS utilities, files, and applications after you install the XENIX operating system. You can even access DOS files and directories from XENIX. XENIX provides this facility so that you do not need to throw away your investment in DOS software, or buy another computer just to run XENIX.

Several programs make this coexistence possible. The dos(C) utilities allow access to DOS files on diskettes or on the DOS partition on the hard disk. These utilities are discussed later in this chapter. The utility which partitions the disk is called fdisk(ADM) and is available in DOS and XENIX versions. The next section explains how to use fdisk to run DOS and XENIX on the same hard disk. Another section discusses installing XENIX on the hard disk along with DOS. There is also a section explaining various booting configurations, for users who mostly use XENIX and for users who mostly use DOS.

9.2 Partitioning the Hard Disk Using fdisk

Each version of fdisk is documented in the respective operating system's manual. fdisk(ADM) is found in this guide. and, unless otherwise noted, this chapter refers to the XENIX fdisk.

fdisk is interactive, and uses a menu to display your options. Here is the main fdisk menu:

1. Display Partition Table
2. Use Entire Disk For XENIX
3. Create XENIX Partition
4. Activate Partition
5. Delete XENIX Partition

Enter your choice or 'q' to quit:

The fdisk utility allows you to set up separate areas (partitions) on your hard disk for your operating system. The hard disk is divided into tracks. The number of tracks depends upon the size of the hard disk.
A partition consists of a group of tracks. One hard disk may contain up to four partitions. Each partition can have a different operating system and associated directories and files.

The fdisk command allows you to specify a disk partition as "active". This means that when you turn on (boot) your computer, the operating system installed in the active partition will start running. The XENIX partition must be active when you intend to use the XENIX operating system.

The fdisk command allows you to specify the number of tracks assigned to each partition. The number of available tracks will vary according to the size of your hard disk. We recommend using at least a 30 megabyte hard disk to run XENIX. The size of the XENIX partition also depends on the number of software packages you want to install. Refer to the custom(ADM) manual page for information on how to install and remove packages from the three XENIX distribution Systems. You will generally need at least six megabytes for your XENIX partition. You can install the XENIX Operating System package in this space, and have space for user files.

The fdisk command allows you to specify where the partition begins. fdisk will not allow you to construct overlapping partitions. You do not need to install XENIX in the first partition.

You should always start your DOS partition at the beginning of the disk, starting at cylinder 1, not cylinder 0. Because DOS writes the boot block on cylinder 0 very close to the end of the Masterboot block, starting your DOS partition on cylinder 0 can cause the DOS partition to become inaccessible after installation.

If you install XENIX on the same disk after DOS, start the XENIX partition at the beginning of the next cylinder on the disk. To find the beginning of the next cylinder, note the ending track number of your DOS partition and start the XENIX partition on the next track number that is a multiple of the number of heads on your hard disk. For example, if you have five heads on your hard disk and your DOS partition ends at track 103, start your XENIX partition at track 105.

When you are running XENIX, the device name of the partition running XENIX is /dev/hd0a.

One option of fdisk tabulates the current state of the partitions (the Display Partition Table option). This option lists, for each partition, whether the partition is active, the first track, the last track, the number of tracks used, and the associated operating system.
If you enter the Display Partition Table option and press RETURN to see the partition table, the result will be similar to this:

<table>
<thead>
<tr>
<th>Partition</th>
<th>Status</th>
<th>Type</th>
<th>Start</th>
<th>End</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Inactive</td>
<td>DOS</td>
<td>005</td>
<td>398</td>
<td>393</td>
</tr>
<tr>
<td>2</td>
<td>Active</td>
<td>XENIX</td>
<td>400</td>
<td>1219</td>
<td>819</td>
</tr>
</tbody>
</table>

Total disk size: 1229 tracks (9 tracks reserved for masterboot and diagnostics).

There are two ways to switch operating systems once you have set up separate XENIX and DOS partitions:

- Use **fdisk** to change the current active partition.

  To use **fdisk**, enter:

  ```
  dos
  ```

  at the boot prompt:

  ```
  Boot :
  ```

- Use a floppy diskette with the files necessary to boot the DOS operating system

If you change operating systems frequently, you should use a bootable DOS diskette to switch between DOS and XENIX. Follow this procedure:

1. Make sure all users are logged off XENIX.
2. Run `shutdown(ADM)` to shut down the XENIX system. This command makes sure all users know the system is being shut down, terminates all processes, then halts the system.
3. Once XENIX has shut down, insert the bootable DOS diskette into the primary (boot) drive.
4. Boot DOS.

5. To get back to XENIX, remove any disks from the floppy drive(s) and press <CTRL><ALT><DEL> (or turn the computer off, then on). Since the XENIX partition is still active, the XENIX operating system boots.

We recommend that you use a boot floppy or enter dos at your boot prompt to boot the DOS operating system. Booting from a floppy or the boot prompt is generally easier, faster, and safer than constantly using fdisk to change active partitions.

The other way to change operating systems is to run fdisk and change the active partition from XENIX to DOS. Then, after you shut down XENIX (see the previous steps) DOS boots from the hard disk. You do not need a bootable DOS floppy disk.

To switch back to XENIX, run fdisk under DOS and make the XENIX partition active. Then press (or turn the computer off, then <CTRL><ALT><DEL> on) to reboot XENIX.

Because the XENIX partition must be active for XENIX to operate, you cannot use a bootable floppy to boot XENIX. This second method is appropriate for an occasional change of the active operating system.

The following hard disk device names:

/dev/hd0d
/dev/rhd0d
/dev/hd1d
/dev/rhd1d

are similar to /dev/hd0a (the active disk partition) in that the disk driver determines which partition is the DOS partition and uses that as hd?d. This means that software using the DOS partition does not need to know which partition is DOS (the disk driver determines that).

Remember that if you have an active XENIX partition and boot DOS from a floppy you can transfer to C: to work with the DOS files.

9.3 Installing XENIX on a DOS System

If you wish to set up XENIX on a hard disk which previously contained only DOS, follow these steps:
1. Copy (back up) all the DOS files and directories on the hard disk onto floppies, or whatever backup media you wish to use.

2. Run fdisk, under DOS. If there is enough free space (at least 15 megabytes) for XENIX on your hard disk, skip to step 4. Otherwise, delete the DOS partition, then recreate it, leaving enough room on the disk for XENIX. Allow at least 6 megabytes for XENIX.

3. Return the DOS files to the hard disk from the backup media. Keep the backups in case there is an error of some kind, so you will not lose any data.

4. Turn off your computer.

5. Follow the installation procedure outlined in the XENIX Installation Guide to install XENIX.

You will see a message warning that the contents of the hard disk will be destroyed. Don’t worry, you’ve backed up the DOS files and transferred them to the new DOS partition. The new partition being created will contain XENIX.

6. During the installation procedure fdisk is invoked to partition the hard disk. Use fdisk to assign a partition which is at least 15 megabytes to XENIX.

7. Designate “XENIX” as the active operating system.

8. Finish installing the XENIX operating system.

---

**Note**

XENIX fdisk displays DOS partitions as *DOS* while DOS fdisk displays XENIX partitions as *Other*.

You can only create DOS partitions using DOS fdisk, and only XENIX partitions using XENIX fdisk.

Be aware that DOS fdisk reports sizes in terms of cylinders, while XENIX fdisk reports sizes in terms of tracks. Check your hard disk manual for the number and size of cylinders on your hard disk.
9.4 Using XENIX and DOS With Two Hard Disks

Your computer always boots the operating system in the active partition on the first hard disk. XENIX must boot from the first hard disk. There are several ways to configure your system if you have two hard disks. Two ways are discussed here.

One configuration consists of designating the entire first disk as a XENIX partition. You then use a DOS boot floppy to start DOS and specify:

A> A: C:

to switch to the DOS area on the second hard disk, where C is the designation for the second hard disk. This strategy works for some versions of DOS. Early versions recognize only the first hard disk on the system.

Note

If you devote a hard disk for use with DOS, the disk must already be configured. See the "Adding A Second Hard Disk" section in the "Using Filesystems" chapter of this guide for details regarding hard disk configuration.

Another method is to maintain a small DOS partition on the first hard disk. The DOS partition is designated the active partition. In this configuration, the computer always boots DOS. This requires changing the active partition to boot the XENIX operating system from the hard disk.

If you use the entire second disk for DOS, you need only run mkdev hd to create device files for the second disk if you plan to use the XENIX DOS utilities (doscp, dosls, doscat, etc). If you do not wish to use those utilities to access DOS files on the second hard disk, there is no need to run mkdev hd.
Note

Be sure to make a backup copy of your boot floppies if you use them to boot your secondary operating system.

9.5 Removing an Operating System From the Hard Disk

You may find that you no longer need one of the operating systems installed on your hard disk. If you want to delete an operating system, use `fdisk` to delete the partition in question. Deleting the partition removes the contents of that partition and leaves unallocated space.

You can then reallocate that space by either adding another XENIX or DOS partition, or enlarging an existing partition. Enlarging a partition requires reinstalling the operating system and (for a XENIX partition) remaking the filesystem on the partition using `mkfs(ADM)`. Refer to the section on "Adding a Second Hard Disk" in the "Using Filesystems" chapter of this guide if you add a second XENIX partition and want to designate this partition as a mounted filesystem.

9.6 DOS Accessing Utilities

XENIX provides a set of utilities that help you bridge between the two operating systems. These are the XENIX commands, such as `dosls` and `doscat`, described in the XENIX manual page `dos(C)`. These programs allow you to access DOS files and directories which reside in a non-active DOS partition while running XENIX.

Note that you must have a bootable, although not active DOS partition on the hard disk or a DOS floppy in order to use these XENIX commands.

For example, you can only transfer a file from a XENIX partition on hard disk to a DOS floppy if either the DOS floppy is bootable or there is also a DOS partition on the hard disk.

Using these commands, you can list, copy, move and view the contents of DOS files and DOS directories. You may also be able to use the XENIX `dd(C)` and `diskcp(C)` commands to copy and compare DOS floppies. The XENIX `dtype(C)` command tells you what type of floppies you have (various DOS and XENIX types).
Also, the file /etc/default/msdos describes which DOS filesystems (e.g. A:, B:, C: ...) correspond to which XENIX devices.

---

**Note**

You cannot execute (run) DOS programs or applications under XENIX.

---

If you have the XENIX Development System, with the cmerge compiler, you can create and compile programs that can be run under DOS operating systems. Refer to the XENIX *C User's Guide* appendix entitled "XENIX to MS-DOS: A Cross Development System" and the *C Library Guide* Appendix entitled "A Common Library for XENIX and MS-DOS" for more on using XENIX to create DOS programs. Also, see the DOS section in the *Programmer's Reference*.

### 9.7 XENIX and DOS On Non-Standard Disks

XENIX provides support for "non-standard" hard disks. The term "non-standard" refers to hard disks for which there are no correct disk parameter entries in your computer's ROM.

The correct parameters you specify for your non-standard disk(s) are stored in the masterboot block, which is the first sector of your boot hard disk drive. You can specify the hard disk characteristics during XENIX installation and these characteristics are then written out with the rest of the masterboot block. The special masterboot block resets the disk parameters to the specified values no matter which operating system is "Active". This mechanism provides non-standard disk support for both XENIX and DOS.

Although the special masterboot supports non-standard disks under DOS, you cannot use XENIX to install DOS on your hard disk. If a non-standard disk is being used, it is assumed that you already have some method to transfer your DOS files to the hard disk.

You should only use the XENIX `fdisk` to manipulate your hard disk partition table. Using DOS `fdisk` or custom `fdisks` provided by hard disk manufacturers after XENIX has been installed may disable non-standard disk characteristics, rendering your disk unusable.
Chapter 10

Preparing XENIX for Users

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10.1 Introduction

User accounts help the XENIX system administrator keep track of the people using the system and control their access to system resources. Ideally, each user should have a user account. Each account has a unique "login name" and "password" with which the user enters the system, and a "home directory" where the user works.

It is the system administrator's job to create accounts for all users on the system, and maintain these accounts by changing user passwords, login groups, and user IDs when necessary.

This chapter explains how to:

- Add user accounts to the system
- Create a group
- Change an account's login group
- Change an account's user ID
- Remove user accounts from the system

The following sections describe each task in detail.

10.2 Adding a User Account

You can add a user account to the system with the `mkuser` program. The program creates a new entry in the XENIX system's `/etc/passwd` file. This entry contains information about the new user (such as login name and initial password) that the system uses to let the user log in and begin work. The program also creates a home directory for the user, a mailbox for use with the `mail` command, and an initialization file (for example, `.profile` for the Bourne shell or `login` for C-shell) containing XENIX commands that are executed when the user logs in.

To create a new user account, follow these steps:

1. Log in as the super user.
2. Enter:

\texttt{mkuser}

\textbf{Δ sysadms}h users select: Users→Add

and press the \textbf{RETURN} key. The system displays the following message:

\begin{verbatim}
Mkuser
Add a user to the system
Do you require detailed instructions? (y/n/q)
\end{verbatim}

3. Enter the letter \textit{y} (for "yes"), if you want information about the program, otherwise type the letter \textit{n} (for "no"). Enter \textit{q} (for "quit") only if you wish to stop the program and return to the system. If you type a "q" to any "(y/n)" prompt, the program will stop and no changes will be made.

4. When the program continues, you are prompted for user id:

\begin{verbatim}
Do you wish to use the next available user id? (y/n/q)
\end{verbatim}

If you enter \textit{n}, you are asked to specify the id number you wish to use.

5. Next, you are prompted for the login name:

\begin{verbatim}
Enter new user's login name, or enter q to quit:
\end{verbatim}

The login name is the name by which XENIX identifies the user. It is usually a short version of the user's actual name, typed in lower-case letters. For example, either "johnd" (a first name and last initial) or "jdoe" (a first initial and last name) is customary for the user John Doe.
6. Enter the new name, and press the RETURN key. The program now prompts you for information about the new user’s group name and group number.

A group name is the name of the group of users to which the new user will belong. Users in a group have access to a common set of files and directories. The group name is optional.

The program prompts:

```
Do you want to use the default group? (y/n):
```

If you enter ‘‘y’’, the user’s group name will be ‘‘group’’ and the group ID number will be 50.

If you enter ‘‘n’’, the program responds with a list of existing groups:

```
Existing groups are:

  Group ‘‘group’’ (50): demo vdemo cdemo

Do you want to use one of these groups? (y/n):
```

If you enter either ‘‘y’’ or ‘‘n’’, you are asked which group you want to use. Enter the name of the group. You may create a new group by entering in the new name.

Next, you are prompted for a group number. The group ID, or number, may be any number from 50 to 30000 that isn’t already used for another group.

7. After entering the group name and ID, you are prompted for the initial password.

```
Enter at least 5 characters for the password.
Enter password:
```

The initial password is the password you assign to the new user.
The user will use the initial password to enter the account for the first time. Once in the account, the user should create a new password for himself, one that is hard to guess. (See the section "Changing Your Password" in the "Logging In" chapter of the XENIX Tutorial.)

8. Enter the password, and press the RETURN key.

9. Next, you are prompted for a shell type. You see a list and brief explanation of the available shells (the menu selections depend on what packages and/or applications installed on your system) and the prompt:

```
ENTER Shell type (1, 2, 3,...) and press RETURN:
```

sh is the standard (Bourne) shell. vsh is the menu driven "visual" shell, csh is the C-shell, rsh is the restricted shell, and uucp login is an entry in /usr/lib/uucp/uucico enabling logging in to the system via uucp. For more information, see sh(C) and csh(C) in the XENIX User's Reference.

10. Enter the desired shell number and press RETURN. After you have entered the shell type, the program prompts you for a comment:

```
Please enter Comment >---------------------
```

A comment is information about the new user, such as a department name and phone extension. Although, the comment is optional, it is useful if the finger(C) command is often used to display information about users. If given, the comment must be no more than 20 characters long, including spaces. It must not contain any colons (:). The example

```
John Doe, 123
```

shows the recommended form for a comment.
11. Enter the comment. Make sure it is 20 characters or less. If you do not wish to enter a comment, just press RETURN.

The program now displays what you have entered and the special user entry that it has created for the new user. This entry is copied to the special system file `/etc/passwd`. The entry shows the login name, the encrypted password, the user ID, the group ID, the comment, the user's home directory, and the startup program. Fields in the entry are separated by colons (`:`). (For a full description of each field, see `passwd(F)` in the XENIX User's Reference.

The program then gives you an opportunity to change the user name, password, group, or comment:

Username is "johnd", user ID is 2001.
Group name is "group", group number is 50.
Comment field is: John Doe, 123
Shell is "/bin/csh"

Do you want to change anything? (y/n): 

12. Enter the letter y (for "yes") and press the RETURN key, if you wish to change something. Enter n (for "no") and skip to the next step if you wish to complete the new account. (Enter q, for "quit", only if you wish to leave the program and abort the new account.)

If you enter y, the program prompts for the field you wish to change:

Select an item to change, or enter q to quit:

1. User name
2. User id (uid)
3. Group
4. Shell
5. Password
6. Comment in /etc/passwd

Enter the name of the item (field) you wish to change and press RETURN. After you have changed a field, you see the complete list of fields and are asked if you wish to make other changes. When you are finished with any changes, the program adds the user.
13. The program displays the messages:

Password file updated.
Group file updated.
Home directory /x/name created.
/x/name/.shellfile created.
Test mail sent to user user.
User name added to this system.

The program then asks if you wish to add another user to the system.

14. Enter y if you wish to add another user. Otherwise, enter n to stop the program and return to the super user prompt.

A user can log into a new account as soon as it is created. For details see the "Logging In" chapter of the XENIX Tutorial.

10.3 Creating a Group

A group is a collection of users who share a common set of files and directories. The advantage of groups is that users who have a common interest in certain files and directories can share these files and directories without revealing them to others. Initially, all users belong to the common system group named "group", but you can create new groups by modifying the XENIX system file /etc/group using a XENIX text editor.

To create a new group, you need to choose a group name and a group identification number (group ID). You also need to make a list of the users in the new group. The group name may be any sequence of letters and numbers up to eight characters long, and the group ID may be any number in the range 50 to 30000. Both the group name and ID must be unique, i.e., they must not be the same as any existing group name or ID.

To create a new group, follow these steps:

1. Log in as the super user.

2. Display the contents of the /etc/group file by entering:

   cat /etc/group

   and pressing the RETURN key. The cat command displays the contents of the /etc/group file. The file contains several entries, each defining the group name, group ID, and users for a group.
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Each entry has the form:

```
group-name::group-ID:users
```

The users are shown as a list of login names separated by commas (,). For example, a typical file may look like this:

```
other:x:1:demo
sys:x:2:
group:50:johnd,suex
```

3. Check the `/etc/group` file entries to see that the group name and ID you have chosen are unique.

4. If the group name and ID are unique, invoke a XENIX text editor (see the XENIX User's Guide) and specify `/etc/group` as the file to edit.

5. Locate the last line in the file, then insert the new entry in the form given above. For example, if you wish to create a group named "shipping" with group ID "142" and users "johnd", "marym", and "suex", enter:

```
shipping:142:johnd,marym,suex
```

6. Exit the editor.

To make sure you have entered the group names correctly, use the `grpcheck(C)` command to check each entry in the `/etc/group` file. If the new entry is free of errors, no other changes to the file are required.

You can create any number of new groups. Each group may have any number of members. Furthermore, any user may be a member of any number of groups. Multiple group membership is especially convenient for users who have interests that span a variety of areas.

If a user is a member of several groups, they can gain access to each group by using the `newgrp(C)` command.

### 10.4 Changing a User's Login Group

When a user logs in, the system automatically places the user in the proper "login group". This is the group given by the group ID in the user's `/etc/passwd` file entry (see the section "Adding a User Account" in this chapter). You can change the user's login group by changing the group ID. To change the group ID you need the group ID of the new login
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group, and you need to know how to use a XENIX text editor (see the XENIX User's Guide).

To change the group ID, follow these steps:

1. Log in as the super user.

   `sysadmsh` users select: Users→Modify→Group

2. Use the `cd` command to change the current directory to the `/etc` directory. Enter:

   ```
cd /etc
   ```

3. Use the `cp` command to make a copy of the `/etc/passwd` file. Enter:

   ```
cp passwd passwd+
   ```

4. Invoke a text editor and specify `/etc/passwd+` as the file to edit.

5. Locate the desired user's password entry. Each entry begins with the user's login name.

6. Locate the user's group ID number in the user's password entry. It is the fourth field in the entry. Fields are separated by colons (:]. For example, the following entry has group ID "50":

   ```
marym:9iKlwp:205:50:Mary March,122:/usr/marym:/bin/sh
   ```

7. Delete the old group ID and insert the new one. Be sure you do not delete any other portion of the user's password entry.

8. Exit the editor.

9. Use the `mv` command to save the old `/etc/passwd` file. Enter:

   ```
   mv passwd passwd-
   ```

10. Use the `mv` command to make the edited file the new `/etc/password` file. Enter:

    ```
    mv passwd+ passwd
    ```

You can make sure you have entered the new login group correctly by using the `pwcheck(C)` command. If the new entry is correct, no other changes to the file are required.
You must not change the group IDs for system accounts such as "cron" and "root". System accounts are any accounts with user IDs less than 200. The user ID is the third field in the password entry.

Note that changing a user's login group does not change the "group ownership" of the files. Group ownership defines which group has access to a user's files. If users in the new group wish to access the user's files, you must change the group ownership with the `chgrp(C)` (for "change group") command. For details, see the section "Changing Group Ownership" in the "Using Filesystems" chapter.

10.5 Changing a User ID

Sometimes it is necessary to change the user ID in a user's account entry to allow a user to access files and directories transferred from other computers. In particular, if a user has different accounts on different computers and frequently transfers files and directories from one computer to another, the user IDs in each of the account entries must be made the same. You can make them the same by modifying the account entries in the `/etc/passwd` file.

To change a user ID, follow these steps at every computer for which the user has an account:

1. Log in as the super user.

2. Use the `cd` command to change the current directory to the `/etc` directory. Enter:

   ```bash
cd /etc
   ```

3. Use the `cp` command to make a copy of the `/etc/passwd` file. Enter:

   ```bash
cp passwd passwd+
   ```

4. Invoke a XENIX text editor and specify `/etc/passwd+` as the file to edit.

5. Locate the user's account entry. Each entry begins with the user's login name.
6. Locate the current user ID. The ID is the third field in the entry. For example, the following entry has a user ID of "205":

marym:9iKlwp:205:50:Mary March,122:/usr/marym:/bin/sh

Substitute the new user ID for the old one.

7. Exit the text editor.

8. Use the mv command to save the old /etc/passwd file. Enter:

   mv passwd passwd-

9. Use the mv command to make the edited file the new /etc/passwd file. Enter:

   mv passwd+ passwd

No other changes to the file are required.

In most cases, you can change the user ID to the same number as the user's most-used account. But the new number must be unique on every system for which the user has an account. If there is any conflict (for example, if the number already belongs to another user on one of the systems), you must choose a new number. You can choose any number greater than 200. Make certain it is unique, and that you copy it to all systems on which the user has an account.

Once a user's ID has been changed, you must change the "user ownership" of the user's files and directories from the old user ID to the new one. You can do this with the chown(C) (for "change owner") command described in the "Maintaining System Security" chapter.

For example, to change the ownership of johnd's home directory, enter:

   chown johnd /usr/johnd

Note that you may use the find(C) command described in "Finding Files" in the "Working with Files and Directories" chapter of the XENIX Tutorial to locate all files and directories with the user's old user ID.
10.6 Removing a User Account

It is sometimes necessary to remove a user account from the system. You can remove a user account with the \texttt{rmuser}(ADM) program. The program deletes the user's entry from the /\texttt{etc/passwd} file and removes the user's home directory and mailbox.

Before you can remove the user account, you must remove all files and directories from the user's home directory, or move them to other directories. If you wish to save the files, you can use the \texttt{tar}(C) command to copy the files to a floppy disk (see "Making Backups" in the "Housekeeping" chapter of the \textit{XENIX Tutorial}.)

To remove a user account, follow these steps:

1. Log in as the super user.

2. Enter:

   \texttt{cd /usr/login-name}

   and press the \texttt{RETURN} key to change to the user's home directory. The \texttt{login-name} must be the user's login name.

3. Make sure that you have made copies of all important files and directories in the user's home directory.

4. Use the \texttt{rm} (for "remove") command to remove all files and directories from the user's home directory. This includes any files that begin with a period (.). Directories can be removed by using the \texttt{-r} (for "recursive") option of the \texttt{rm} command. For example, the command:

   \texttt{rm -r bin}

   removes the directory named \textit{bin} and all files within this directory.

5. After removing all files and directories, make sure the user's mailbox is empty. Enter the following command, substituting the user's login name for \texttt{login-name}:

   \texttt{cat /usr/spool/mail/login-name}
If the mailbox contains text, enter:

```bash
cat /dev/null > /usr/spool/mail/login-name
```

and press the RETURN key.

6. When the user's home directory and mailbox are empty, enter:

```bash
cd /usr
```

and press the RETURN key. The user's home directory cannot be removed until you have moved to another directory.

7. Enter the following command, followed by RETURN:

```bash
rmuser
```

The program displays a message explaining how to remove a user:

```
rmuser
remove a user from the system
Press RETURN when you are ready.
```

The program then prompts you for the login name of the user you wish to remove:

```
Enter name of id to be removed.
```

8. Enter the user's login name. You should now see the message:

```
Removing user name from the system. CONFIRM? (y/n/q):
```
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9. Enter y (for "yes") to remove the user from the system. Otherwise enter n (for "no") to stop the removal, or q (for "quit") to stop the program. The program removes the user's entry from the /etc/passwd file, the user's mailbox, .profile file, and home directory. The program displays the message:

User name removed from the system

The program now gives you a chance to remove another user:

Do you want to remove another user? (y/n/q):

10. Enter y to remove another user. Otherwise, enter n or q to stop the program.

Note that the rmuser program will refuse to remove an account that has a system name, such as "root", "sys", "sysinfo", "cron", "uucp", or a system ID (user ID below 200). Also, the program cannot remove a user account if the user's mailbox still has mail in it, or if the user's home directory contains files other than .profile.

10.7 Changing XENIX Initialization

When your system is switched on and booted, the certain aspects of system operation are initialized, including the mounting of filesystems. You can adapt system initialization by modifying the system initialization files.

The XENIX initialization files contain XENIX commands and/or data which the system reads at system startup or whenever a user logs in. The files typically mount filesystems, start programs, and set home directories and terminal types. The initialization files are named /etc/rc, .profile, and /etc/motd.

The system administrator can modify these files to create any desired initial environment. The files are ordinary text files and may be modified
using a text editor such as \texttt{vi(C)} (see the \textit{XENIX User's Guide}). Note, however, that the \texttt{/etc/rc} and \texttt{.profile} files contain XENIX commands and comments, and have the command file format described in “The Shell,” chapter in the \textit{XENIX User's Guide}.

\textbf{10.7.1 Changing the /etc/rc File}

The \texttt{/etc/rc} file contains XENIX system initialization commands. The system executes the commands at system startup. The commands display a startup message, start various system daemons, and mount filesystems. You can display the contents of the file with the \texttt{more(C)} command. Enter:

\begin{verbatim}
more /etc/rc
\end{verbatim}

and press the \texttt{RETURN} key.

You may change the contents of the file so that the system executes any set of commands you wish. For example, if you want the system to automatically mount a new filesystem, simply append the appropriate \texttt{mount} command in the file. The system will execute the command on each startup.

To append a command to the file, follow these steps:

1. Log in as the super user.
2. Invoke a text editor and specify the \texttt{/etc/rc} as the file to be edited.
3. Locate the place in the file you wish to insert the command (e.g., if the command mounts a filesystem, insert it with other mounting commands).
4. Insert the command on a new line. Make sure you enter the command correctly. The system rejects any incorrect commands and the commands that follow it when the file is read at system startup.
5. Exit the editor.

No other changes to the file are required. Be careful not to delete any commands already in the file unless you are sure they are not needed.
10.7.2 Changing the .profile and .login Files

The .profile and .login files contain commands that initialize the environment for each user. If the user uses the standard command shell /bin/sh, they have the file .profile in their home directory. If the user uses the C-shell /bin/csh, they will have the file .login in their home directories. (Depending on the login shell, other files may apply.) The commands in these files are executed whenever the user logs in. The files usually contain commands that set various system variables (e.g., TERM, PATH, MAIL). These variables give the system information such as what terminal type is being used, where to look for programs the user runs, where to look for the user's mailbox, what keys to expect for the "kill" and "backspace" functions, and so on. (see the chapters about shell and C-shell in the XENIX User's Guide).

There is one .profile or .login file for each user account on the system. The files are placed in the user's home directory when the account is created. An ordinary user may modify their own .profile or .login file or allow the system manager to make modifications. In either case, the file can be edited like the /etc/rc file by using a text editor. Commands can be added or removed as desired.

10.7.3 Changing the /etc/motd File

The message of the day file, /etc/motd, contains the greeting displayed whenever a user logs in. Initially, this file contains the name and version number of the XENIX system. It can be modified to include messages such as a reminder to clean up directories, a notice of the next periodic backup, and so on.

The /etc/motd file is an ordinary text file, so you can change the message by editing the file with a text editor. One common change is to include a reminder to delete unused files in order to preserve disk space. In general, you should limit the size of the file to include no more than a screenful of information.
Chapter 11

Building a Remote Network

with UUCP

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11.1 Introduction

This chapter explains how to use the UUCP package to build a remote network system for your computer using a normal telephone line and a modem.

UUCP can also be used to physically connect dissimilar XENIX/UNIX systems (for example, two systems that lack a common local area network program, like micnet), using a direct serial line. In addition, the UUCP system is a practical solution to the problem of two micnet networks that cannot be connected because of distance or cost of cable (See the chapter on "Building a Local Network with Micnet" in this guide.)

11.1.1 What is UUCP?

The UUCP package permits XENIX/UNIX systems to communicate as part of a remote network. The name UUCP is an acronym for "UNIX-to-UNIX Copy." The UUCP package consists of a group of programs that provide the following capabilities:

- Remote file transfer (uucp)
- Remote command execution (uux)
- Delivery/forwarding of mail to remote sites (via mail)

Used primarily over phone lines, UUCP can be used to connect with specific remote machines on a demand or scheduled basis and by either dialing out, or allowing other machines to dial in.

UUCP uses a batch method to manage communication traffic, storing (or "spooling") requests for later execution when actual contact is made between systems. Thus, when UUCP commands are executed by the user, work files and any data files needed are created in /usr/spool/uucp. The program uucico scans this directory for the instructions contained in any work files and executes them. Although it is possible to execute commands immediately, most systems are set up to connect with other systems according to a daily schedule (usually during the evenings to reduce connection costs).
11.1.2 How to Use This Guide

This guide describes how to build a UUCP system and covers both hardware installation and software configuration. There are also sections on routine maintenance and troubleshooting.

The following is an outline of what must be done to set up your UUCP network:

1. Connect and configure a modem or direct wire.
2. Configure the UUCP software using uuinstall.
3. Create login accounts for any sites that will be calling your system.
4. Test your connections with each remote site.

The most important task of configuring UUCP is the editing of several control files that act as the database for UUCP. The next few sections describe the function of these files, and "Configuring UUCP on Your System" explains the information that these files contain. The uuinstall utility will edit these files for you and explain each entry. uuinstall also includes an extensive help facility. Read "Configuring UUCP on Your System" carefully before running uuinstall to understand the UUCP database.

11.1.3 What You Need

To install a direct wire communication system on your computer, you need

- At least one RS-232 serial line (or serial port) on your computer to use for UUCP.
- The UUCP programs and files extracted from your XENIX System distribution.

If you want to use your computer as a dial-in and/or dial-out site with a modem, you also need:

- A modem. Supported modems include models by Hayes, Penril, Ventel, Vadic, Rixon, AT&T, and Telebit; but you can supply Dialers entries or dialer programs for other modems. Instructions for the Hayes Smartmodem 1200 or 2400 and compatibles are given below.
- A standard telephone jack for access to the telephone system (touch tone line required for the Hayes).
- An RS-232 cable to connect the serial line to the modem.

11.1.4 UUCP Commands

UUCP programs are divided into two categories: user programs and administrative programs. The paragraphs that follow describe the programs in each category.

User Programs

The user programs for basic networking are in /usr/bin. No special permission is needed to use these programs. These commands are all described in the "Communicating with Other Sites" chapter of the XENIX User's Guide.

**cu**
Connects your computer to a remote computer so you can be logged in on both at the same time, allowing you to transfer files or execute commands on either computer without dropping the initial link.

**ct**
Connects your computer to a remote terminal so the user of the remote terminal can log in. The user of a remote terminal can call the computer and request that the computer call it back. In this case, the computer drops the initial link so that the remote terminal's modem will be available when it is called back.

**uucp**
Lets a user copy a file from one computer to another. It creates work files and data files, queues the job for transfer, and calls the uucico daemon, which in turn attempts to contact the remote computer.

**uuto**
Copies files from one computer to a public spool directory on another computer (/usr/spool/uucppublic/receive). Unlike uucp, which lets you copy a file to any accessible directory on the remote computer, uuto places the file in an appropriate spool directory and tells the remote user to pick it up with uupick.
uupick Retrieves the files placed under /usr/spool/uucppublic/receive when files are transferred to a computer using uuto.

uux Creates the work, data, and execute files needed to execute commands on a remote computer. The work file contains the same information as work files created by uucp and uuto. The execute files contain the command string to be executed on the remote computer and a list of the data files. The data files are those files required for the command execution.

uustat Displays the status of requested transfers (uucp, uuto, or uux). It also provides you with a means of controlling queued transfers.

Administrative Programs

Most of the administrative programs are in /usr/lib/uucp, along with the control files and shell scripts. The only exception is uulog, which is in /usr/bin. These commands are described in the (ADM) section of this Guide.

uulog Displays the contents of a specified computer’s log files. Log files are created for each remote computer your computer communicates with. The log files contain records of each use of uucp, uuto, and uux.

uucleanup Cleans up the spool directory. It is normally executed from a shell script called uudemon.clean, which is started by cron.

uutry Tests call processing capabilities and does a moderate amount of debugging. It invokes the uucico daemon to establish a communication link between your computer and the remote computer you specify.

uucheck Checks for the presence of basic networking directories, programs, and support files. It can also check certain parts of the Permissions file for obvious syntactic errors.
uuinstall  Allows the UUCP control files to be configured with a simple menu interface. Also configures ports and can be used to convert Version 2 UUCP control files to Honey DanBer format.

11.1.5 UUCP Directories

There are three directories associated with UUCP:

/usr/spool/uucp  This is the working directory for UUCP. Work files, log files and all UUCP communication traffic are stored here.

/ usr/spool/uucppublic  This is the publically-readable/writable target directory used for most file transfers.

/ usr/lib/uucp  Most of the UUCP programs are stored here, as well as the supporting database/control files. The main user programs, including uux and uucp, are found in /usr/bin.

In addition to programs, /usr/lib/uucp contains configurable data files for use by UUCP (easily distinguished by their capitalized names). Of these, the most important to understand are:

**Systems**  Contains information needed to establish a link to a remote computer. It contains information such as the name of the remote computer, the name of the connecting device associated with the remote computer, when the computer can be reached, telephone number, login ID, and password.

**Permissions**  This file defines the level of access that is granted to computers when they attempt to transfer files or remotely execute commands on your computer.

**Devices**  Contains information concerning the location, line speed, and type of the automatic call units, direct links, and network devices.
11.1.6 UUCP Background Programs

**uucp** traffic is managed by three *daemons*, or supervisory programs that run in the background, handling file transfers and command executions. (The daemons can also be executed manually as commands.)

- **uucico**
  Selects the device used for the link, establishes the link to the remote computer, performs the required login sequence and permission checks, transfers data and execute files, logs results, and notifies the user by *mail* of transfer completions. When the local **uucico** daemon calls a remote computer, it "talks" to the **uucico** daemon on the remote computer during the session.

- **uuxqt**
  Executes remote execution requests. It searches the spool directory for execute files (always named X.file) that have been sent from a remote computer. When an X.file file is found, **uuxqt** opens it to get the list of data files that are required for the execution. It then checks to see if the required data files are available and accessible. If the files are present and can be accessed, **uuxqt** also verifies that it has permission to execute the requested command.

- **uusched**
  Schedules the queued work in the spool directory. Before starting the **uucico** daemon, **uusched** randomizes the order in which remote computers will be called.

11.1.7 How UUCP Works

When you enter a UUCP command, the program creates a work file and usually a data file for the requested transfer. The work file contains information required for transferring the file(s). The data file is simply a copy of the specified source file. After these files are created in the spool directory, the **uucico** daemon is started.

The **uucico** daemon attempts to establish a connection to the remote computer that is to receive the file(s). It first gathers the information required for establishing a link to the remote computer from the *Systems* file. This is how **uucico** knows what type of device to use in establishing the link.
Then **uucico** searches the *Devices* file looking for the devices that match the requirements listed in the *Systems* file. After **uucico** finds an available device, it attempts to establish the link and log in on the remote computer.

When **uucico** logs in on the remote computer, it starts the **uucico** daemon on the remote computer. The two **uucico** daemons then negotiate the line protocol to be used in the file transfer(s). The local **uucico** daemon then transfers the file(s) that you are sending to the remote computer. The remote **uucico** places the file in the specified path name(s) on the remote computer. After your local computer completes the transfer(s), the remote computer may send files that are queued for your local computer. The remote computer can be denied permission to transfer these files with an entry in the *Permissions* file. If this is done, the remote computer must establish a link to your local computer to perform the transfers.

If the remote computer or the device selected to make the connection to the remote computer is unavailable, the request remains queued in the spool directory. Each hour (default), **uudemon.hour** is started by **cron** which in turn starts the **uusched** daemon. When the **uusched** daemon starts, it searches the spool directory for the remaining work files, generates the random order in which these requests are to be processed, and then starts the transfer process (**uucico**) described in the previous paragraphs.

### 11.1.8 A Sample UUCP Transaction

The following traces the execution of a **uucp** command:

1. A user on a system called “kilgore” wishes to send a copy of the file “minutes.01.10” to a remote system called “obie”. To accomplish this, the user enters the following command:

   ```
   uucp minutes.01.10 obie
   ```

   Note that the exclamation point need only be escaped (preceded by a “\”) if the **csh** is used; the Bourne shell (**sh**) doesn’t require this.

2. A work file is created in the `/usr/spool/uucp/obie` directory, c.obie/xxxx.

3. The **uusched** daemon schedules the request for execution by **uucico**.

4. When the execution time is reached, **uucico** first checks the *Systems* file and confirms that obie is a recognized system and that a call is permitted at this time.
5. Using the information in the *Systems* file, **uucico** next locates the modem device and tty port associated with it as stored in the *Devices* file.

6. Using the phone number in the *Systems* file and the modem type from the *Devices* file, **uucico** uses the appropriate modem commands from the *Dialers* file (or alternately runs a dialer program from the *lib* directory) to connect to the remote system.

<table>
<thead>
<tr>
<th>UUCP Control Files (sites: kilgore and obie)</th>
</tr>
</thead>
</table>
| **Systems:** obie Any ACU 2400 14081234567 \  
  oigin:--oigin: nuucp ssword: mavra |
| **Devices:** ACU tty11 - 2400 hayes2400 |
| **Permissions:** LOGNAME= ukilgore MACHINE= kilgore \  
  READ=/usr/spool/uucppublic:/usr/kilgore \  
  WRITE=/usr/spool/uucppublic:/usr/kilgore \  
  REQUEST=n SENDFILES=call |

7. **uucico** creates a lock file to lock the serial line in the directory `/usr/spool/uucp`.

8. **uucico** uses the login sequence and password defined in the *Systems* file to login to "obie", whose own **uucico** confirms that "kilgore" is recognized before beginning the actual transaction.

9. The calling system, "kilgore," (sometimes known as the *guest*) is said to be the "master" of the transaction; the called system, "obie," (also known as the *host*) is said be the "slave." The slave **uucico** checks the local *Permissions* file to confirm that the master is authorized to transfer the file.

10. The master ("kilgore") transmits the file in packets that are checked for errors and retransmitted if garbled. During reception, the file is stored in a temporary file in the `/usr/spool/uucp` directory. When the transfer is complete, the file is transferred to the proper destination, in this case `/usr/spool/uucppublic/minutes.01.10`. 

11-8
11. Each machine records its side of the transaction in logfiles. (For example, “obie” would have the exchange recorded in a file called `/usr/spool/uucp/.Log/uucp/kilgore`.)

12. Unless the slave system (“obie”) has requests of its own, a hangup request is sent, the connection is terminated, and the lock removed.

In the case of remote command execution (via `uux`), an execute x.file is created in the `/usr/spool/uucp` directory. The `uuxqt` daemon scans this directory for work, checks the `Permissions` file to confirm permission to execute the command, then executes it.

Having explained how UUCP functions, the next step is to set up the programs to work on your system.

11.2 Connecting Two Local Systems Using A Direct Wire

This section describes how to install a direct wire between two computers. If you are using UUCP to connect remote machines, you can skip this section. To connect two computers with a direct wire, you need to:

- Choose a serial line on each machine.
- Connect a serial wire (RS-232) between the two machines, using the chosen serial lines.
- Decide which machine is the dial-in site and which is the dial-out site. The dial-out site calls up and logs in to the dial-in site.

When you finish with these steps, you can proceed with the next sections to set up the sites.

11.2.1 Choose a Serial Line

On each machine, you must choose the RS-232 serial line you want to use. If there are no lines available, you must install a new serial line or make one available by removing any device connected to it. If you remove a terminal, make sure no one is logged in.
Once you have chosen a serial line, find the name of the device special file associated with the line by referring to the "XENIX Directories and Special Device Files" chapter in this guide. The filename should have the form

/dev/ttyn

where $nn$ is the number of the corresponding line. For example, /dev/tty1a usually corresponds to COM1. You need the name of the actual line for later steps.

The serial line you use for your communication system should be owned by uucp. To make sure the line is owned by uucp enter this command:

\texttt{chown uucp /dev/ttyn}$nn$

where $nn$ is the number of the corresponding line.

11.2.2 Connect a Serial Wire

You connect two computers together using an RS-232 cable. The actual pin configurations sometimes vary between machines.

Typically, the wire should connect pins 2, 3, and 7 (and/or 20) on one computer to the same pins on the second computer. Sometimes the cable must be \textit{nulled}, which means that pin 2 on one machine is connected to pin 3 on the other, and vice versa.

Since the connections can vary, you should check the hardware manuals for each computer to determine the proper pin connections.

Testing a Connection

For this section, tty2a is used as the example serial line for both machines.

To test the wire connection between two machines, follow these steps:

1. Disable the serial lines on each machine. On each computer, enter the command:

\texttt{disable /dev/tty2a}

Be sure to disable the modem control line as well:

\texttt{disable /dev/tty2A}
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2. Attach one end of the serial wire to one of the machines. Attach the other end to the standard data port of a terminal.

3. Enter this command at the computer:

(stty 9600; date ) < /dev/tty2a > /dev/tty2a

tty2a is our example serial line, and the date command provides sample output.

You should see the output of the date command appear on the terminal screen. Repeat this procedure on the other machine.

If this doesn’t work, check the following:

- The wire is plugged in properly at each end.
- The continuity of the wire.
- The terminal is configured correctly (baud rate, parity, etc.).
- The serial line is disabled.
- You are using the correct pin numbers.

Note

An unterminated serial line can cause serious system problems. Do not leave serial lines dangling.

11.3 Connecting Remote UUCP Systems with a Modem

With a modem, you can communicate with computers over standard phone lines. These are the steps to install a modem:

- Choose a serial line.
- Set the dialing configuration.
- Connect the modem.
- Test the connection.
The following sections explain each step in detail. Make sure you inform the telephone company of your intent to use a modem with your telephone line.

You should be particularly careful, since certain telephone services (such as "call waiting") can disrupt UUCP conversations.

11.3.1 Choose a Serial Line

Choose the RS-232 serial line you want to use with the system and connect to the modem. If there are no lines available, you must install a new serial line or make one available by removing any device connected to it. If you remove a terminal, make sure no one is logged in.

Once you have chosen a serial line, find the name of the device special file associated with the line by looking in the "XENIX Directories and Special Device Files" chapter of this Guide. The filename should have the form

```
/dev/ttynn
```

where *nn* is the number of the corresponding line. For example, `/dev/tty1A` usually corresponds to COM1. You need the name of the actual line for later steps.

---

**Note**

`/dev/tty1a` and `/dev/tty1A` correspond to the same physical line; `tty1a` should be used for a direct connection, but `tty1A` should be used for a modem connection.

---

The serial line you use for your communication system should be owned by `uucp`. To make sure the line is owned by `uucp` enter this command:

```
chown uucp /dev/ttynn
```

where *nn* is the number of the corresponding line.
11.3.2 Set the Dialing Configuration

In this communication system, your modem can be used to both send and receive calls. You must set the appropriate switches on the modem. The instructions that follow are specific to Hayes-compatible modems, but other modems are supported. You should refer to the modem manual for connection instructions and see the section "Adding Dial-out Entries to the Devices File" for a complete list of supported modems and dialer programs. (If you are setting up a Hayes Smartmodem 2400 or compatible, see the next section for configuration instructions.) Follow these steps to configure a Hayes Smartmodem 1200 or compatible modem:

1. Remove the front cover of the modem and locate the 8-pin configuration switch. (See the modem reference manual for instructions on how to locate the switch on your particular model.)

2. If the Devices file uses the dialer program dialHA12, set the pins on the configuration switch to the following positions:

<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>up</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
</tr>
<tr>
<td>down</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
<td>●</td>
</tr>
</tbody>
</table>

If the Devices file uses the alternative Dialers script hayes1200, set the pins as above, but set pin 6 in the "down" position, not "up."

3. Replace the front cover.

If you have a different modem, consult your reference manual for the proper switch settings to both send and receive calls.

11.3.3 Connect the Modem

Once your modem's dialing configuration is set, you are ready to connect the modem to your computer. For proper modem operation, the RS-232 cable must provide the pin connections shown below.

Note that the computer's serial connector must have a DTE (Data Terminal Equipment) configuration. The modem is assumed to have a DCE (Data Communications Equipment) configuration. If this is not the case, you will need to wire the cable from modem to computer with pins 2 and 3 transposed (pin 2 to pin 3, and pin 3 to pin 2).
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Pin Connections

<table>
<thead>
<tr>
<th>Name</th>
<th>Computer (DTE)</th>
<th>Modem (DCE)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protective ground</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>Transmit Data (TX)</td>
<td>2</td>
<td>2</td>
</tr>
<tr>
<td>Receive Data (RX)</td>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>Data Set Ready (DSR)</td>
<td>6</td>
<td>6</td>
</tr>
<tr>
<td>Signal Ground (GND)</td>
<td>7</td>
<td>7</td>
</tr>
<tr>
<td>Carrier Detect (CD)</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>Data Terminal Ready (DTR)</td>
<td>20</td>
<td>20</td>
</tr>
</tbody>
</table>

These connections are explained in the reference manual for your modem.

Review the installation instructions given in the your modem's manual, then follow these steps:

1. Connect the RS-232 serial cable to the serial line connector on the modem, then to the serial line connector on your computer. Make sure the cable is fully connected. (A 2-3-7 pin cable is not sufficient. We suggest a ribbon cable to connect all appropriate wires.)

2. Plug the telephone line cable into the telephone connector on the modem, then into the telephone wall jack.

3. Plug in the power cord of the modem.

11.3.4 Configuring a Hayes 2400 or Compatible Modem

Although most aspects of modem installation are similar, a Hayes 2400 Smartmodem or compatible modem requires on-line configuration if it is to be used as a dial-in line. Note that the Hayes 2400 will not answer the phone with a 2400 baud carrier if it was not set up with 2400 baud commands.

1. Make sure that the Devices file contains an entry for the line:

```
ACU ttynn - 2400 hayes2400
```

or

```
ACU ttynn - 2400 /usr/lib/uucp/dialHA24
```
2. You must then configure the modem by issuing set up commands via cu(C). Enter:

```
cu -s2400 -l ttynn dir
```

where nn is the "tty" number of the serial line. Press RETURN.

3. Next, enter the following commands to configure the modem. They will be saved in the modem's non-volatile memory. If you do not want to save the settings, do not enter the last command (at&w). Commands are in the left column and short descriptions of what they do are in the right column. Follow each command with a RETURN:

- `at&f` Fetch factory configuration.
- `att` Tone dialing.
- `atl0` Low speaker volume.
- `at&d2` Set dtr "2": go on hook when dtr drops.
- `at&c1` Set dcd "1": dcd tracks remote carrier.
- `ats0=1` Answer phone after 1 ring (AA light should come on).
- `ats2=128` Disable modem escape sequence.
- `ate0` No echo (modem will no longer echo what is sent to it).
- `atq1` Quiet mode (modem will not respond with "OK" after this command or any that follow).
- `at&w` Saves settings in non-volatile memory.

Exit from cu by entering a "tilde" and a "period", followed by RETURN:

(Sometimes it is necessary to press RETURN once before entering the tilde-period.)

The modem is now configured and ready for testing.
11.3.5 Variable Rate Modems

Some modems can determine the connection baud rate from the carrier sent by a remote system. These modems inform the local system of the connection baud rate before issuing the carrier detect signal. The Hayes 2400 dialer supplied with UUCP detects different connection baud rates and informs UUCP and cu when it exits with a successful connection.

The speed fields in Devices and Systems can specify a range of baud rates for a connection. If a dialer supports baud rates from 300 to 2400 baud, enter the baud rate range in the speed field of Devices as follows:

300-2400

If a dialer/modem does not allow variable baud rates, place a single baud in the speed field. If a remote system supports several different speeds, place the range of baud rates in the speed field of Systems. If the remote system connects at a single baud rate, place that number in Systems. UUCP passes the intersection of the Systems and Devices baud rate ranges to the dialer when connecting. If the dialer connects outside of the baud range, it returns a bad baud rate error. Otherwise, it returns the baud rate of the connection.

11.3.6 Test the Modem

As the last step of the modem installation, you should test the modem to make sure that it can send and receive calls. Once you have verified that the modem is working, you can begin to use the communication system.

To test the modem, follow these steps:

1. Start the computer and log in as the super user.
2. Disable the modem serial line by entering
   
   `disable /dev/ttynn`

   where `nn` is the ‘tty’ number of the serial line.
3. Turn on power to the modem.
4. If you are using a Hayes 1200 or compatible, make sure the volume switch on the modem is at an appropriate level. You must be able to hear the modem to carry out this test successfully. Refer to your modem reference manual for the location of this switch.
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5. Ensure that the Systems file has an entry for the system you intend to call, and that the Devices file has a matching entry for ttyyn.

6. Start the uutry program by entering:

   /usr/lib/uucp/uutry  sitename

7. Listen carefully to the modem. You should hear each digit as the number is dialed, then hear the busy signal when the telephone system tries to make connection with your modem.

8. If the busy signal is present, wait a few moments and listen carefully for the modem to hang up. The modem automatically discontinues any call that it cannot make a connection for.

9. If the busy signal is not present, make certain:
   
   • you have connected the modem to the telephone jack
   • the jack is connected to the phone system
   • you gave the correct phone number in the Systems file

10. If you do not hear the modem dial, make certain:

   • the volume switch is up
   • the modem is connected to the correct serial line and that the cable connection is tight
   • you gave the correct tty line in the Devices file
   • modem's power is on.

11.4 Configuring UUCP on Your System

In order to configure your UUCP system, you must edit a series of files which contain information about, and control the actions of the UUCP programs. The UUCP control files are in the /usr/lib/uucp directory. You can modify these files with a standard text editor, or use the uuninstall(ADM) program as described below. The descriptions in the latter part of this section provide details on the structure of these files so you can edit them manually.
11.4.1 An Important Consideration: Call or Be Called?

There are three ways to configure a UUCP site:

- As a dial-in only site.
- As a dial-out only site.
- As a dial-in/out site.

As a dial-in site, other computers call up and log in to your system. They can transfer files and execute certain commands.

As a dial-out site, your computer calls up other computers and logs in. Your computer initiates file transfers to and from the remote machine, as well as local and remote command execution.

Note

The terms dial-in, dial-out and call describe the communication process for both direct wire and modem/telephone sites.

11.4.2 Setting Up the Control Files with uuinstall

The rest of this section is concerned with the configuration or control files that act as the UUCP database. The uuinstall(ADM) utility provides a simple way to configure these files. Read the rest of the chapter to familiarize yourself with the descriptions of each file and the entries required. The uuinstall utility includes a complete series of help files (accessed by pressing ? while in the menus) so it will not be necessary to keep referring to the documentation. When you have some understanding of how each of the control files is used, follow this procedure:

1. Invoke uuinstall by logging in as root and entering the following command:

   /etc/uuinstall

   △ sysadmsh users select: System→Configure→Network→UUCP
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The main **uuninstall** menu is displayed:

```
UUCP Administration Utility
-----------------------------------
1. Display or update site or machine name (/etc/systemid)
2. Display or update list of remote sites (Systems)
3. Display or update direct- or dial-out lines (Devices)
4. Display or update direct- or dial-in lines (/etc/ttys)
5. Check consistency of UUCP files
6. Test connection with remote site
7. Convert old UUCP files to new format

Choose an option (1-7), or enter "q" to quit:
```

Use the **uuninstall** options as follows:

- Give your site a name in the `/etc/systemid` file using the "Display or update your sitename" option.

- Choose the devices to be used for dialing-in or out and enter them in the `Devices` file using the "Display or update dial-in or dial-out devices" option.

- Identify sites your system will have contact with by creating entries in the `Systems` file with the "Display or update list of remote sites" option.

- Add the tty lines to be used to the `/etc/ttys` file using the "Display or update line connections" option.

2. If other systems will be calling yours, create login accounts using the `mkuser(ADM)` program.

3. If other systems will be calling yours, define a security scheme that includes what commands and directories can be used in the `Permissions` file.

You will note that some files have many options; where possible, less commonly used options and control files are called out and discussed in the "Special UUCP Configuration Options" section.

When you install the UUCP system, or make any modifications, you should be logged in as super user (root). Virtually all of the UUCP files are writable only by the super user, and many of them are also readable and executable only by `root` and `uucp`. Make sure when you are done that all of the UUCP files are owned by `uucp` and not `root`. UUCP will not work correctly if it cannot read or execute its files.
Note

The files Systems and Permissions contain unencrypted passwords, and should therefore be readable only by uucp (and root). Note also that the program/usr/bin/ct must, exceptionally, be owned by root and not by uucp in order to work correctly.

11.4.3 Establish Your Site Name in the /etc/systemid File

In a UUCP system, every computer belongs to a site. A site is any computer or any micnet network that can communicate with the UUCP system.

To distinguish one site from another, every site must have a unique sitename. A sitename is any combination of letters and digits that begins with a letter and is no more than seven characters long. The UUCP and uux commands use the sitename to direct transmissions to the appropriate computer or micnet network.

The sitename should suggest some characteristic of the site, such as its location or affiliation. For example, a site in Chicago can be named chicago, or a site in the legal department can be named legal. The sitename must be unique. That is, no other computer that calls your computer or is called by your computer can have the same sitename.

Each site must have a /etc/systemid file. The file defines the sitename of the given site and associates the site with a micnet network, if any. The file has the following form:

sitename
[ machinename ]

where:

sitename is the name of the given site.
machinename is the micnet machine name for that computer. If the system is not connected to a micnet network, the machinename is optional.
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For example, the following entry defines a site named *chicago* whose *micnet* machine name is *brewster*:

```
  chicago
  brewster
```

Since UUCP systems are often created after a *micnet* network has been established, the *systemid* file often already exists on a given site. In this case, you must add the *sitename* to the beginning of each *systemid* file on each computer in the *micnet* network.

Note that you can list more than one machine name if desired, but each name must be on a separate line. For a full description, see *systemid(M)* in the *XENIX User's Reference*.

### 11.4.4 Selecting and Defining a UUCP port

As discussed earlier, you must select a serial line, disable it if it is to be used for dialing-out only or enable it for dialing-in, and edit the serial line entry in the `/etc/ttys` file.

1. Select the serial line. Use a line with modem control (for example, `/dev/tty1A`) for a dial-in or dial-out line, or a line without modem control (for example, `/dev/tty2a`) for a direct connection. For more information, see the section on "Choosing a Serial Line."

2. Disable the serial line. If you are using a modem, be sure it is installed and tested. If the serial line is to be a dial-in line, substitute `enable` for `disable` and enter the command:

   ```
   enable /dev/ttyyn
   ```

   where `nn` is the number of your serial line. If the line is already disabled/enabled, the command displays an error message that you can safely ignore.
3. Edit the /etc/ttys file. This file contains a list of possible login terminals. Enter the following command to display the current entries for the different serial lines:

```
cat /etc/ttys
```

tty entries have the following form:

```
xxttynn
```

where:

- `xy` is two digits. The first digit is either a one (1), which means the line is enabled; or a zero (0), which means the line is disabled. The second digit is a number or letter that defines the baud rate of the line.

- `nn` is the number of the tty.

If you need to change an entry, you can do so with a text editor. For more information on the /etc/ttys file and the various control codes, see getty(M) in the XENIX User's Reference.

For example, an entry for a dial-out line (connected to a modem) might look like this:

```
03tty2a
```

In this example, the first digit, 0, means the line is disabled, so that terminals or computers cannot log in on that line. That digit changes to a one when you use the enable command. The second digit, 3, means that the getty running on that line cycles the baud rate of that line between 1200 and 300 baud. The third digit, 2a, is the number of the serial line.

An example entry for a direct line between two computers might be:

```
06tty2a
```

If a line is to be used for dial-in, ensure that the baud rate code y for that line in /etc/ttys is correct. If the line is to be shared between dial-in and dial-out, ensure that it has an appropriate entry in /usr/lib/uucp/Devices and in /etc/ttys.

```
enable /dev/ttynn
```
11.4.5 Creating Login Accounts for Sites Dialing-in

A dial-in site must provide a login entry for the sites that call it. These entries are placed in the /etc/passwd file.

A UUCP login entry has the same form as an ordinary user login entry (see "Preparing XENIX for Users" in this guide), but has a special login directory and login program instead of the normal user directory and shell.

---

Note

"uucp" should not be used as the name of a uucp user; it is the name of the uucp owner/administrator.

---

To create a UUCP login entry, use the mkuser(ADM) program and follow these steps:

1. Choose a new username and a user ID (identification number) for the UUCP login. The name can be any combination of letters and digits that is no more than eight characters long. The user ID must be an integer in the range 50 to 65535.

   Make sure the name and ID are unique. A UUCP login entry must not have the same name or ID as any other login entry.

2. To invoke mkuser program, enter:

   
   /etc/mkuser

   Follow the program menus and prompts to add the account(s) you wish.

3. The mkuser program prompts you to enter a password for the new user. Passwords are optional for UUCP logins.

4. Choose option 5 (uucp) as the shell for a UUCP user; this gives uucico as a shell, and a home directory in /usr/spool/uucp.
11.4.6 Adding Entries for Remote Sites to the Systems File

The Systems file (/usr/lib/uucp/Systems) contains the information needed by the uucico daemon to establish a communication link to a remote computer. Each entry in the file represents a computer that can be called by your computer. In addition, the Systems file can be configured to prevent any computer that does not appear in this file from logging in on your computer. More than one entry may be present for a particular computer. The additional entries represent alternative communication paths that will be tried in sequential order.

Note

If you are setting up your system as a dial-in only (passive) site that never initiates calls, you only need add the names of the systems that will be calling you.

Each entry in the Systems file has the following format:

sitename schedule device speed phone login-script

sitename field contains the node name of the remote computer.

schedule field is a string that indicates the day-of-week and time-of-day when the remote computer can be called.

device is the device type that should be used to establish the communication link to the remote computer.

speed indicates the transfer speed of the device used in establishing the communication link.

phone provides the phone number of the remote computer for automatic dialers. If you wish to create a portable Systems file that can be used at a number of sites where the dialing prefixes differ (for internal phone systems), refer to "Using Dialcodes to Create a Portable Systems File" under "Special UUCP Configuration Options."

login-script contains login information (also known as a "chat script").
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The Schedule Field

The *schedule* consists of three subfields. The first, *day*, is required. The other two, *time* and *retry*, are optional. The syntax is as follows:

```
  day[time][;retry]
```

The *day* subfield can contain the following keywords:

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SuMoTuWeThFrSa</td>
<td>For individual days.</td>
</tr>
<tr>
<td>Wk</td>
<td>For any weekday (Mo Tu We Th Fr).</td>
</tr>
<tr>
<td>Any</td>
<td>For any day.</td>
</tr>
<tr>
<td>Never</td>
<td>For a passive arrangement with the remote computer. If the <em>schedule</em> field is <em>Never</em>, your computer will never initiate a call to the remote computer. The call must be initiated by the remote computer. In other words, your computer is in a passive mode in respect to the remote computer (see discussion of Permissions file).</td>
</tr>
</tbody>
</table>

The optional *time* subfield should be a range of times in 24-hour clock format, such as 0800-1230. If no *time* is specified, any time of day is assumed to be allowed for the call. A time range that spans 0000 is permitted. For example, *0800-0600* means all times are allowed other than times between 6 AM and 8 AM. For example, the following permits calls on Mondays, Wednesdays, and Fridays between the hours of 9 AM and Noon (the *schedule* field is in boldface for clarity):

```
grebe MoWeFr0900-1200 ACU,g D1200 14087672676 \ 
  ogin: nuucp sswor: Crested
```

You can also specify more than one set of *day* and *time* entries. This is useful for more complex specifications. The following example allows calls from 5:00 p.m. to 8:00 am, Monday through Thursday, and calls any time Saturday and Sunday. The example would be an effective way to call only when phone rates are low, if immediate transfer is not critical:

```
gorgon Wk1700-1800,SaSu ACU,g D1200 14087672676 \ 
  ogin: nuucp sswor: DontLook
```
The optional subfield, *retry*, is available to specify the minimum time (in minutes) before a retry, following a failed attempt. The subfield separator is a semicolon (;). For example, the following is interpreted as call any time, but wait at least 9 minutes before retrying after a failure occurs:

```
Any; 9
```

---

**Note**

By default UUCP uses an "exponential backoff" method to retry failed calls. After the initial failure, a second call is made in five minutes. This interval expands as the number of unsuccessful attempts increases. The retry field is used to override the default.

---

**The Device Field**

The *device* field selects the device type, in most cases an ACU (Automatic Calling Unit). For example, the keyword used in the following field is matched against the first field of *Devices* file entries:

```
Systems:  gorgon Any ACU, g D1200 14087672676 \
          oigin: nuucp ssword: DontLook

Devices:   ACU tty11 - D1200 hayes
```

**The Speed Field**

This field can contain a letter and speed (for example, C1200, D1200) to differentiate between classes of dialers (refer to the discussion on the *Devices* file, *speed* field). Some devices can be used at any speed, so the keyword *Any* may be used. However, we recommend that you specify the actual
range of speeds that can be used. (If \textbf{Any} is used in both \textit{Systems} and \textit{Devices} entries, 1200 is assumed.) For example, this field must match the \textit{speed} field in the associated \textit{Devices} file entry:

\begin{verbatim}
Systems:  gorgon Any ACU D2400-9600 14087672676 \ 
          oigin: nuucp ssword: DontLook

Devices:  ACU tty1l - D1200-2400 hayes2400
\end{verbatim}

If information is not required for this field, use a hyphen (-) as a place holder for the field.

\textbf{The Phone Field}

This field is used to provide the phone number used for the modem dialer. The phone number is made up of an optional alphabetic abbreviation and a numeric part. If an abbreviation is used, it must be one that is listed in the \textit{Dialcodes} file. (See the "Using Dialcodes to Create a Portable Systems File" section for details.) For example:

\begin{verbatim}
Systems:  gorgon Any ACU D1200 CA2676 \ 
          oigin: nuucp ssword: DontLook

Dialcodes:  CA 9=408767
\end{verbatim}

In this string, an equal sign (=) tells the ACU to wait for a secondary dial tone before dialing the remaining digits. A dash in the string (-) instructs the ACU to pause 4 seconds before dialing the next digit.

If your computer is connected to a LAN switch, you may access other computers that are connected to that switch. The \textit{Systems} file entries for these computers will not have a phone number in the \textit{phone} field. Instead, this field will contain the token that must be passed on to the switch so it will know which computer your computer wishes to communicate with. (This is usually just the system name.) The associated \textit{Devices} file entry should have a \texttt{\textbackslash D} at the end of the entry to ensure that this field is not translated using the \textit{Dialcodes} file.
The Login-Script Field

The login-script is used to open communications between modems, plus recognize and send proper login and password sequences. The script is given as a series of fields and subfields of the following format:

\[ expect \text{ send} \]

where \textit{expect} is the string that is received, and \textit{send} is the string that is sent when the \textit{expect} string is received.

The \textit{expect} field can be made up of subfields of the following form:

\[ expect[\text{-subsend-subexpect}]. . . \]

where the \textit{subsend} is sent if the prior \textit{expect} is not successfully read and the \textit{subexpect} following the \textit{subsend} is the next expected string. To make this distinction clear: the send-expect sequence sends a string if the expect string is received, the subsend-subexpect sends only if the prior expect string is not received.

For example, with "login--login", the UUCP program will expect "login". If a "login" is received, it will go on to the next field. If it does not get "login", it will send nothing followed by a carriage return, then look for "login" again. If no characters are initially expected from the remote computer, the characters " " (null string) should be used in the first \textit{expect} field. Note that all \textit{send} fields will be sent followed by a carriage return unless the \textit{send} string is terminated with a \textbackslash{c}.

The \textit{expect} string need not be complete; only the trailing characters must be specified, as in " \textbackslash{o} \textbackslash{g} \textbackslash{i} \textbackslash{n} : ". This avoids difficulties with login strings that use an uppercase letter as in "Login: " or "Password: ", and also difficulties when the line is shared by dial-in and dial-out.

Creating Login Scripts

This section explains in greater detail how to create a login (chat) script.

Consider the following sample \texttt{Systems} file entry:

\begin{verbatim}
terps Any ACU 1200 18005211980 "" \r o\textbackslash{g}i\textbackslash{n}:-\textbackslash{B}\textbackslash{R}\textbackslash{E}\textbackslash{A}\textbackslash{K}-\textbackslash{o}\textbackslash{g}i\textbackslash{n}: \textbackslash{u}\textbackslash{u}\textbackslash{c}\textbackslash{p}\textbackslash{x} \texttt{word}: ichore
\end{verbatim}
Building a Remote Network with UUCP

This is how this script would work during connection:

1. Nothing is expected initially.
2. A carriage return is sent and the script waits for the prompt "login:" (login:).
3. If it doesn't receive "login:", send a BREAK.
4. When "login:" is finally received, send the login name uucpx.
5. When the prompt, "password:" (for Password:) is received, send the password "ichore".

Login (chat) scripts will often require some experimentation. There will be cases where a modem will require one or more BREAK sequences before presenting a login (this is often true with variable speed modems). If you cannot obtain the necessary login sequence from the system administrator for a given site, it is a good idea to connect with the site manually. You can accomplish this using cu and find out what must be sent to generate a login prompt. (You can also connect with a system using a verbose option for debugging; see "Debugging Transmissions" for details.) There are several escape characters that cause specific actions when sent during the login sequence, some of which correspond to keystrokes; these should be included in the script where necessary:

Login (Chat) Script Escape Sequences

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\N</td>
<td>Sends or expects a null character (ASCII NUL).</td>
</tr>
<tr>
<td>\b</td>
<td>Sends or expects a backspace character.</td>
</tr>
<tr>
<td>\c</td>
<td>If at the end of a string, suppresses the carriage return that is normally sent. Ignored otherwise.</td>
</tr>
<tr>
<td>\d</td>
<td>Delays two seconds before sending or reading more characters.</td>
</tr>
<tr>
<td>\p</td>
<td>Pauses for approximately ¼ to ½ second.</td>
</tr>
<tr>
<td>\E</td>
<td>Starts echo checking. (From this point on, whenever a character is transmitted, it will wait for the character to be received before doing anything else.)</td>
</tr>
<tr>
<td>\e</td>
<td>Turns echo check off.</td>
</tr>
<tr>
<td>\n</td>
<td>Sends or expects a new-line character.</td>
</tr>
</tbody>
</table>
\r Sends or expects a carriage-return.
\s Sends or expects a space character.
\t Sends or expects a tab character.
\\ Sends or expects a \ character.
EOT Sends or expects EOT new-line twice.
BREAK Sends or expects a break character.
\K Same as BREAK.
\ddd Collapses the octal digits (ddd) into a single character.

11.4.7 Limiting Access with the Permissions File

If other machines will be dialing into your system, the Permissions file (/usr/lib/uucp/Permissions) specifies the permissions that remote computers have with respect to login, file access, and command execution. There are options that restrict the remote computer’s ability to request files and its ability to receive files queued by the local site. Other options specify the commands that a remote site can execute on the local computer.

Structuring Permissions File Entries

Each entry is a logical line with physical lines terminated by a \ to indicate continuation. Entries are made up of options delimited by white space. Each option is a name-value pair in the following format:

name=value

Note that no white space is allowed within an option assignment.

Comment lines begin with a pound sign (#) and they occupy the entire line up to a newline character. Blank lines are ignored (even within multi-line entries).

There are two types of Permissions file entries:

LOGNAME Specifies the permissions that take effect when a remote computer logs in on (calls) your computer.

MACHINE Specifies permissions that take effect when your computer logs in on (calls) a remote computer.
Considerations on Permissions File Restrictions

The following should be considered when using the Permissions file to restrict the level of access granted to remote computers:

- All login IDs used by remote computers to login for UUCP communications must appear in only one LOGNAME entry.

- Any site that is called whose name does not appear in a MACHINE entry, will have the following default permissions/restrictions:
  1. Local send and receive requests will be executed.
  2. The remote computer can send files to your computer's /usr/spool/uucppublic directory.
  3. The commands sent by the remote computer for execution on your computer must be one of the default commands, usually rmail.

Permissions Options

This section describes each option, specifies how they are used, and lists their default values.

REQUEST

Specifies whether the remote computer can request to set up file transfers from your computer. When a remote computer calls your computer and requests to receive a file, this request can be granted or denied. The following string specifies that the remote computer can request to transfer files from your computer:

REQUEST=yes

The following string specifies that the remote computer cannot request to receive files from your computer:

REQUEST=no

The no value is the default value. It will be used if the REQUEST option is not specified. The REQUEST option can appear in either a LOGNAME (remote calls you) entry or a MACHINE (you call remote) entry. A note on security: When a remote machine calls you, unless you have a unique login and password for that machine you don’t know if the machine is who it says it is.
SENDFILES
Specifies whether your computer can send the work queued for the remote computer. When a remote computer calls your computer and completes its work, it may attempt to take work your computer has queued for it.

The following string specifies that your computer can send the work that is queued for the remote computer as long as it logged in as one of the names in the LOGNAME option:

SENDFILES=yes

This string is mandatory if your computer is in a passive mode with respect to the remote computer.

The following string specifies that files queued in your computer be sent only when your computer calls the remote computer:

SENDFILES=call

The call value is the default for the SENDFILE option. This option is only significant in LOGNAME entries since MACHINE entries apply when calls are made out to remote computers. If this option is used with a MACHINE entry, it will be ignored.

READ and WRITE
Specify the various parts of the file system that uucico can read from or write to. The READ and WRITE options can be used with either MACHINE or LOGNAME entries.

The default for both the READ and WRITE options is the uucppublic directory as shown in the following strings:

READ=/usr/spool/uucppublic
WRITE=/usr/spool/uucppublic

The following strings specify permission to access any file that can be accessed by a local user with other permissions:

READ=/ WRITE=/

The value of these entries is a colon separated list of path names. The READ option is for requesting files, and the WRITE option for depositing files. One of the values must be the prefix of any full path name of a file coming in or going out.
Note

READ and WRITE options do not effect the actual permissions of a file or directory. For example, a directory with permissions of 700 will only permit the owner to access it, no matter what access options are defined in the Permissions file.

To grant permission to deposit files in /usr/news as well as the public directory, the following values would be used with the WRITE option:

```
WRITE=/usr/spool/uucppublic:/usr/news
```

It should be pointed out that if the READ and WRITE options are used, all path names must be specified because the path names are not added to the default list. For instance, if the /usr/news path name was the only one specified in a WRITE option, permission to deposit files in the public directory would be denied.

You should be careful what directories you make accessible for reading and writing by remote systems. For example, you probably wouldn't want remote computers to be able to write over your /etc/password file so /etc shouldn't be open to writes.

NO READ and NOWRITE

Specify exceptions to the READ and WRITE options or defaults. The following strings would permit reading any file except those in the /etc directory (and its subdirectories—remember, these are prefixes) and writing only to the default /usr/spool/uucppublic directory:

```
READ=/
WRITE=/usr/spool/uucppublic
NOREAD=/etc
NOWRITE=/etc
```

NOWRITE works in the same manner as the NOREAD option. The NOREAD and NOWRITE can be used in both LOGNAME and MACHINE entries.
CALLBACK

Specifies in LOGNAME entries that no transaction will take place until the calling system is called back. There are two examples of when you would use CALLBACK. From a security standpoint, if you call back a machine you can be sure it is the machine it says it is. If you are doing long data transmissions, you can choose the machine that will be billed for the longer call.

The following string specifies that your computer must call the remote computer back before any file transfers will take place:

```
CALLBACK=yes
```

The default for the COMMAND option is

```
CALLBACK=no
```

The CALLBACK option is very rarely used. Note that if two sites have this option set for each other, a conversation will never get started.

COMMANDS

Specifies the commands in MACHINE entries that a remote computer can execute on your computer. This affects the security of your system; use it with extreme care.

The uux program will generate remote execution requests and queue them to be transferred to the remote computer. Files and a command are sent to the target computer for remote execution. Note that COMMANDS is not used in a LOGNAME entry; COMMANDS in MACHINE entries define command permissions whether you call the remote system or it calls you.

The following string indicates the default commands that a remote computer can execute on your computer:

```
COMMANDS=rmail
```

If a command string is used in a MACHINE entry, the default commands are overridden. For instance, the following entry overrides the COMMAND default so that the computers owl, raven, hawk, and dove can now execute rmail, rnews, and lp on your computer:

```
MACHINE=owl:raven:hawk:dove \
COMMANDS=rmail:rnews:lp
```
In addition to the names as specified above, there can be full path names of commands. For example, the following command specifies that command `rmail` uses the default path:

```
COMMANDS=rmail:/usr/lbin/rnews:/usr/local/lp
```

The default paths for your computer are `/bin`, `/usr/bin` and `/usr/lbin`. When the remote computer specifies `lp`, `/usr/local/lp` is the command that will be executed.

Including the `ALL` value in the list means that any command from the remote computer specified in the entry will be executed. If you use this value, you give the remote computer full access to your computer. So, be careful; this allows far more access than normal users have.

The following string illustrates two points:

```
COMMANDS=/usr/local/bin/lc:ALL:/usr/local/lp
```

1. The `ALL` value can appear anywhere in the string; and the path names specified for `lc` and `lp` will be used (instead of the default) if the requested command does not contain the full path names for `lc` or `lp`.

2. The `VALIDATE` option should be used with the `COMMANDS` option whenever potentially dangerous commands like `cat` and `uucp` are specified with the `COMMANDS` option. Any command that reads or writes files is potentially dangerous to local security when executed by the UUCP remote execution daemon (`uuxqt`).

**VALIDATE**

Used in conjunction with the `COMMANDS` option when specifying commands that are potentially dangerous to your computer's security. It provides a certain degree of verification of the caller's identity. The use of the `VALIDATE` option requires that privileged computers have a unique login/password for UUCP transactions. An important aspect of this validation is that the login/password associated with this entry be protected. If an outsider gets that information, that particular `VALIDATE` option can no longer be considered secure. (`VALIDATE` is merely an added level of security to the `COMMANDS` option, though it is a more secure way to open command access than `ALL`.)
Careful consideration should be given to providing a remote computer with a privileged login and password for UUCP transactions. Giving a remote computer a special login and password with file access and remote execution capability is like giving anyone on that computer a normal login and password on your computer. Therefore, if you cannot trust someone on the remote computer, do not provide that computer with a privileged login and password.

The following LOGNAME entry specifies that if one of the remote computers that claims to be eagle, owl, or hawk logs in on your computer, it must have used the login uucpfriend:

```
LOGNAME=uucpfriend VALIDATE=eagle:owl:hawk
```

As can be seen, if an outsider gets the uucpfriend login/password, masquerading is trivial.

COMMAND options appearing in MACHINE entries define the commands available to the system, and to the machine's LOGNAME entry. Commands need to be defined in MACHINE entries in order to continue communication between the local and remote systems when the remote computer is logged on to the local system and the execution daemon is not running.

Each remote computer has its own spool directory on your computer. These spool directories have write permission given only to the UUCP programs. The execution files from the remote computer are put in its spool directory after being transferred to your computer. When the uuxqt daemon runs, it can use the spool directory name to find the MACHINE entry in the Permissions file and get the COMMANDS list. Or, if the computer name does not appear in the Permissions file, the default list will be used.

The following example shows the relationship between the MACHINE and LOGNAME entries:

```
MACHINE=eagle:owl:hawk REQUEST=yes \nCOMMANDS=rmail:/usr/local/bin/1c \nREAD=/ WRITE=/

LOGNAME=uucpz VALIDATE=eagle:owl:hawk \nREQUEST=yes SENDFILES=yes \nREAD=/ WRITE=/
```

The value in the COMMANDS option means that remote mail and /usr/local/bin/1c can be executed by remote users.
In the first entry, you must make the assumption that when you want to call one of the computers listed, you are really calling either eagle, owl, or hawk. Therefore, any files put into one of the eagle, owl, or hawk spool directories is put there by one of those computers. If a remote computer logs in and says that it is one of these three computers, its execution files will also be put in the privileged spool directory. You therefore have to validate that the computer has the privileged login uucpz.

**MACHINE** Entry for **OTHER** Systems
You may want to specify different option values for the computers your computer calls that are not mentioned in specific MACHINE entries. This may occur when there are many computers calling in, and the command set changes from time to time. The name **OTHER** for the computer name is used for this entry as follows:

```plaintext
MACHINE=OTHER \ COMMANDS=rmail:lc:/usr/local/bin/lc
```

All other options available for the MACHINE entry can also be set for the computers that are not mentioned in other MACHINE entries.

**Combining** **MACHINE** and **LOGNAME** Entries
It is possible to combine MACHINE and LOGNAME entries into a single entry where the common options are the same. For example, the following two entries share the same REQUEST, READ, and WRITE options:

```plaintext
MACHINE=eagle:owl:hawk REQUEST=yes \ READ=/ WRITE=/ LOGNAME=uucpz REQUEST=yes SENDFILES=yes \ READ=/ WRITE=/
```

These two entries can be merged as follows:

```plaintext
MACHINE=eagle:owl:hawk REQUEST=yes \ LOGNAME=uucpz SENDFILES=yes \ READ=/ WRITE=/
```
11.4.8 Adding Dial-out Entries to the Devices File

The Devices file (/usr/lib/uucp/Devices) contains information for all the devices that can be used to establish a link to a remote computer, devices such as automatic call units, direct links, and network connections. This file works closely with the Dialers, Systems, and Dialcodes files. Before you make changes in any of these files, you should be familiar with them all. Note that a change to an entry in one file may require a change to a related entry in another file.

Each entry in the Devices file has the following format:

\[ \text{type} \ \text{ttyline} \ \text{dialerline} \ \text{speed} \ \text{dialer-token} \]

where:

- **type** can contain one of two keywords (direct or ACU), the name of a Local Area Network switch, or a system name.
- **ttyline** contains the device name of the line (port) associated with the Devices entry. For example, if the Automatic Dial Modem for a particular entry was attached to the /dev/ttyll line, the name entered in this field would be ttyll.
- **dialerline** This option is useful only for 801 type dialers, which do not contain a modem and must use an additional line. Unless you have an 801 dialer, simply enter a hyphen (-) as a placeholder.
- **speed** is the speed or speed range of the device. Can also contain an indicator for distinguishing different dialer classes.
- **dialer-token** This field contains pairs of dialers and tokens, each representing a dialer and an argument to be passed to it. The dialer portion can be the name of an automatic dial modem, or it may be a direct for a direct link device.
The Type Field

This field can contain one of two keywords (direct or ACU), the name of a Local Area Network switch, or a system name:

Direct  This keyword indicates a direct link to another computer or a switch (for cu connections only).

ACU  This keyword indicates that the link to a remote computer is made through an automatic call unit (Automatic Dial Modem). This modem can be connected either directly to your computer or indirectly through a Local Area Network (LAN) switch.

LANswitch  can be replaced by the name of a LAN switch. micom and develcon are the only ones that have caller scripts in the Dialers file.

sysname  indicates a direct link to a particular computer. (sysname is replaced by the name of the computer.) This means that the line associated with this Devices entry is for a particular computer in the Systems file.

For example the keyword "gorgon" used in the Type field Devices is matched against the third field of Systems file entries:

<table>
<thead>
<tr>
<th>Devices:</th>
<th>gorgon tty11 - 1200 hayes1200</th>
</tr>
</thead>
<tbody>
<tr>
<td>Systems:</td>
<td>gorgon Any gorgon 1200 14087672676 ogin: nuucp \ssword: DontLook</td>
</tr>
</tbody>
</table>

The Speed Field

In most cases, this is simply the speed of the device, if the keyword ACU or Direct is used in the type field. However, speed may contain a letter and a speed (for example, C1200, D1200) to differentiate between classes of dialers (Centrex or Dimension PBX). This is necessary because many larger offices may have more than one type of telephone network: one network may be dedicated to serving only internal office communications, while another handles the external communications. In such a case, it becomes necessary
to distinguish which lines should be used for internal communications and which should be used for external communications. The keyword used in the speed field of the Devices file is matched against the fourth field of Systems file entries, for example:

<table>
<thead>
<tr>
<th>Devices:</th>
<th>ACU tty11 - D1200 hayes1200</th>
</tr>
</thead>
<tbody>
<tr>
<td>Systems:</td>
<td>gorgon Any ACU D1200 3251 ogin: nuucp \ ssword: Don'tLook</td>
</tr>
</tbody>
</table>

Some devices can be used at any speed, so the keyword Any can be used in the speed field. If Any is used, the line will match any speed requested in a Systems file entry. If this field is Any and the Systems file speed field is Any, the speed defaults to 1200 bps. If a device can be used at a range of speeds, then the speed field can specify this range (for example, 1200-9600 or D1200-9600). This is preferable to the use of Any.

**The Dialer-Token Field**

This field has the following format:

```
dialer [token dialer token ...]
```

For a direct line, this field contains simply the word direct, and no token is required.

For a simple connection to a dialer, this field contains the name of the dialer, and the token is omitted; by default it is taken from the phone number field of the Systems file entry.

For a dialer or a network dataswitch, this field contains the name of an entry found in the Dialers file (develcon and micom are examples of network data switches). Other dialer types are supported by binaries instead of Dialers entries. (Support for 801-type dialers is provided through use of separate lines for data and the dialer. See the Devices file for details.) UUCP recognizes a dialer as a binary if the name begins with a "/" or there is an executable file by that name in/usr/lib/uucp.
The following dialer types are available as *Dialers* entries:

<table>
<thead>
<tr>
<th>Dialer type</th>
<th>Modem or Data Switch</th>
</tr>
</thead>
<tbody>
<tr>
<td>Direct</td>
<td>Direct line; no dialer</td>
</tr>
<tr>
<td>Penril</td>
<td>Penril modem</td>
</tr>
<tr>
<td>Hayes</td>
<td>Hayes modem (or compatible)</td>
</tr>
<tr>
<td>Ventel</td>
<td>Ventel 212+ modem</td>
</tr>
<tr>
<td>Vadic</td>
<td>Racal Vadic 3451 modem</td>
</tr>
<tr>
<td>LANswitch</td>
<td>Network switch described in type field</td>
</tr>
<tr>
<td>Hayes1200</td>
<td>Hayes Smartmodem 1200</td>
</tr>
<tr>
<td>Hayes2400</td>
<td>Hayes Smartmodem 2400</td>
</tr>
<tr>
<td>Develcon</td>
<td>Develcon network dataswitch</td>
</tr>
<tr>
<td>Micom</td>
<td>Micom network dataswitch</td>
</tr>
<tr>
<td>Rixon</td>
<td>Rixon Intelligent Modem</td>
</tr>
<tr>
<td>ATT4000</td>
<td>AT&amp;T Programmable 300/1200 Modem Model 4000</td>
</tr>
<tr>
<td>ATT2212c</td>
<td>AT&amp;T DATAPHONE II 2212C Modem</td>
</tr>
<tr>
<td>ATT2224</td>
<td>AT&amp;T DATAPHONE II 2224 Modem</td>
</tr>
<tr>
<td>NLS</td>
<td>Network Listener Service</td>
</tr>
</tbody>
</table>

*Note*

The TLI and TLIS dialer types are currently not available with XENIX.

The following binary types are provided in *usr/lib/uucp*:

<table>
<thead>
<tr>
<th>Binary file</th>
<th>Modem</th>
</tr>
</thead>
<tbody>
<tr>
<td>dialHA12</td>
<td>Hayes Smartmodem 1200 or compatible</td>
</tr>
<tr>
<td>dialHA24</td>
<td>Hayes Smartmodem 2400 or compatible</td>
</tr>
<tr>
<td>dialVA3450</td>
<td>Racal Vadic 3451 modem</td>
</tr>
<tr>
<td>dialTBIT</td>
<td>Telebit Trailblazer Modem</td>
</tr>
</tbody>
</table>

(The source is also provided for these dialer binaries; you can adapt and compile your own dialers if desired. See the section "Dialing Out from Your Computer" in the "Using Terminals and Modems" chapter of this guide for details.)
Structuring Dialer-Token Entries

The \textit{dialer-token} can be structured four different ways, depending on the device associated with the entry:

1. **Simple modem connection.** If an automatic dialing modem is connected directly to a port on your computer, the \textit{dialer-token} field of the associated \textit{Devices} file entry will only have one pair. This pair would normally be the name of the modem. This name is used to match the particular \textit{Devices} file entry with an entry in the \textit{Dialers} file. Therefore, the \textit{dialer} field must match the first field of the following \textit{Dialers} file entry:

   \begin{verbatim}
   Devices:   ACU ttys11 - 1200 ventel
   Dialers:   ventel =\&-\% "" \r\p\r\c $<K\T\%\r>\c ONLINE!
   \end{verbatim}

   Notice that only the \textit{dialer} portion (ventel) is present in the \textit{dialer-token} field of the \textit{Devices} file entry. This means that the \textit{token} to be passed on to the dialer (in this case the phone number) is taken from the \textit{Phone} field of a \textit{Systems} file entry. (\text{T} is implied, see item 4 below.) Backslash sequences are described later.

2. **Direct links.** If a direct link is established to a particular computer, the \textit{dialer-token} field of the associated entry would contain the keyword \textit{direct}. This is true for both types of direct link entries, \textit{direct} and \textit{sysname} (refer to discussion on the \textit{type} field).

3. **Local network switches.** If a computer that you wish to communicate with is on the same local network switch as your computer, your computer must first access the switch and the switch can make the connection to the other computer. In this type of entry, there is only one pair. The \textit{dialer} portion is used to match a \textit{Dialers} file entry following:

   \begin{verbatim}
   Devices:   develcon ttys13 - 1200 develcon \D
   Dialers:   develcon "" "" \pr\ps\c est:007 \E\D\e \007
   \end{verbatim}

   As shown, the \textit{token} portion is \texttt{\D}, which indicates that it is retrieved from the \textit{Systems} file without translation. The \textit{Systems} file entry for this particular computer will contain the token in the \textit{phone} field; this...
is normally reserved for the phone number of the computer (refer to Systems file, phone field). The \D ensures that the contents of the phone field will not be interpreted as a valid entry in the Dialcodes file.

4. **Modems used with a local network switch.** If an automatic dialing modem is connected to a switch, your computer must first access the switch and the switch will make the connection to the automatic dialing modem. This type of entry requires two dialer-token-pairs. The following dialer portion of each pair (fifth and seventh fields of entry) will be used to match entries in the Dialers file:

```
Devices:   ACU tty14 - 1200 develcon vent ventel
Dialers:   develcon "" "" \pr\ps\c est:\007 \E\D\e \007
ventel = &-% "" \r\p\r\c $ <K\T%%\r> \c ONLINE!
```

In the first pair, **develcon** is the switch and **vent** is the token that is passed to the develcon switch to tell it which device to connect to your computer. This token would be unique for each LAN switch since each switch may be set up differently. Once the ventel modem has been connected, the second pair is accessed, where ventel is the dialer and the token is retrieved from the Systems file.

The following are two escape characters that can appear in the dialer-token field:

\T indicates that the Phone field should be translated at this stage, using the Dialcodes file. This escape character is normally placed in the Dialers file for each caller script associated with an automatic dial modem (penril, ventel, etc.). The translation will not take place until the caller script is accessed.

\D indicates that the Phone field should not be translated using the Dialcodes file. If no escape character is specified at the end of a Devices entry, \D is assumed by default when a Dialers script is to be used (which can itself contain a \T to translate the number). \T is assumed if a built-in or dialer binary is to be used (because there is then no later opportunity to translate the number).
11.4.9 Using the Same Port for Dialing In and Out

It is possible to dial in and out on the same line without enabling/disabling the line or running a special version of \texttt{getty}. All that is necessary is to first create an entry for a line in the \texttt{Devices} file (dial-out) and then an entry in /\texttt{etc/ttys} (dial-in) for the same line. When access to a dial-out line is requested on a shared port, \texttt{getty} runs a special program, \texttt{uuchat}, that automatically reinitializes the port when the call is complete. \texttt{uuchat} uses special dialer scripts found in the \texttt{Dialers} file that begin with an ampersand. This means there are actually two entries for some dialers. For example, the dialer for the Hayes Smartmodem 2400 (or compatible) consists of two entries: \texttt{hayes2400} and \texttt{\&hayes2400}, the latter of which is used when reinitializing a shared port to dial-in. In the case of the dialer binaries in /\texttt{usr/lib/uucp}, these programs are automatically invoked with the -\texttt{h} (hangup) switch that reinitializes the port to dial-in.

11.5 Special UUCP Configuration Options

This section contains several options that are used for special circumstances and can be ignored in most cases.

11.5.1 Adding Dialers to the Dialers File

The \texttt{Dialers} file (/\texttt{usr/lib/uucp/Dialers}) specifies the initial conversation that must take place on a line before it can be made available for transferring data. This conversation is usually a sequence of ASCII strings that is transmitted and expected, and it is often used to dial a phone number using an ASCII dialer (such as the Automatic Dial Modem).

A modem that is used for dialing in and out may require a second \texttt{Dialers} entry. This is to reinitialize the line to dial-in after it has been used for dial-out. The name of the dial-in version of a dialer must begin with an ampersand. For example, the \texttt{Dialers} file contains a \texttt{hayes2400} and a \texttt{\&hayes2400} entry.

As shown in the earlier examples, the fifth field in a \texttt{Devices} file entry is an index into the \texttt{Dialers} file or a special dialer type (801, for example). Here an attempt is made to match the fifth field in the \texttt{Devices} file with the first field of each \texttt{Dialers} file entry. In addition, each odd numbered \texttt{Devices} field starting with the seventh position is used as an index into the \texttt{Dialers} file. If the match succeeds, the \texttt{Dialers} entry is interpreted to perform the dialer negotiations. Each entry in the \texttt{Dialers} file has the following format:

\begin{verbatim}
    dialer substitutions expect-send ...
\end{verbatim}
The **dialer** field matches the fifth and additional odd numbered fields in the **Devices** file. The **substitutions** field is a translate string: the first of each pair of characters is mapped to the second character in the pair. This is usually used to translate '=' and '-' into whatever the dialer requires for "wait for dial-tone" and "pause."

The remaining **expect-send** fields are character strings. Below are some character strings distributed with the UUCP package in the **Dialers** file.

<table>
<thead>
<tr>
<th><strong>Dialers</strong> file entries</th>
</tr>
</thead>
<tbody>
<tr>
<td>penril =W-P &quot;&quot; \d &gt; s\p9\c ) - W\p</td>
</tr>
<tr>
<td>ventel =6-% &quot;&quot; \r\p\r\c $ &lt;\T%\r\c \c ONLINE!</td>
</tr>
<tr>
<td>hayes =-, &quot;&quot; \r\c OK \c \r \EATDT\T\c CONNECT</td>
</tr>
<tr>
<td>rixon =6-% &quot;&quot; \d\r\c s\c s9\c ) - W\r\ds9\c- s\c : \c T\r\c $ 9\c LINE</td>
</tr>
<tr>
<td>vadiac =K-K&quot; &quot;\005\p* -\005\p- D\p.BER? \c E\T\c e \c r\c LINE</td>
</tr>
<tr>
<td>develcon =, -, &quot;&quot; \d\AT\c OK \c EA'.ID\T\T\c CONNECT</td>
</tr>
<tr>
<td>micom =, &quot;&quot; \s\c NAME?: \c V\c r\c GO</td>
</tr>
<tr>
<td>direct =+-, &quot;&quot; \r\c ---: ato12=y,T\c r\c red</td>
</tr>
<tr>
<td>att4000 =+-, &quot;&quot; \033\r\c DEM: \033s0401\c \006\033s0901\c \c \006\033s1001\c \006\033s1102\c \006\033s\c T\c \006</td>
</tr>
<tr>
<td>att2224 =+-, &quot;&quot; \r\c ---: T\T\c r\c red</td>
</tr>
<tr>
<td>nls =+-, &quot;&quot; \NLPS: 000:001:1\N\c</td>
</tr>
</tbody>
</table>

The meaning of some of the escape characters (those beginning with "\") used in the **Dialers** file are listed below:

- \p pause (approximately ¼ to ½ second)
- \d delay (approximately 2 seconds)
- \D phone number or token without Dialcodes translation
- \T phone number or token with Dialcodes translation
- \K insert a BREAK
- \E enable echo checking (for slow devices)
- \e disable echo checking
- \r carriage return
- \c no new-line or carriage return
- \n send new-line
- \n send octal number.

Additional escape characters that may be used are listed in the section discussing the **Systems** file.
The penril entry in the *Dialers* file is executed as follows. First, the phone number argument is translated, replacing any = with a W (wait for dialtone) and replacing any - with a P (pause). The handshake given by the remainder of the line works as follows:

```
""                  Wait for nothing. (In other words, proceed to the next thing.)
\d                 Delay for 2 seconds.
>                  Wait for a >.
s\p9\c              Send an s, pause for 1/2 second, send a 9, send no terminating new-line
)-W\p|r\ds\p9\c-)   Wait for a ). If it is not received, process the string between the - characters as follows. Send a W, pause, send a carriage-return, delay, send an s, pause, send a 9, without a new-line, and then wait for the ).
\y\c                Send a y.
:\                 Wait for a :.
\E\TP               Enable echo checking. (From this point on, whenever a character is transmitted, it will wait for the character to be received before doing anything else.) Then, send the phone number. The \T means take the phone number passed as an argument and apply the *Dialcodes* translation and the modem function translation specified by field 2 of this entry. Then send a P.
>                  Wait for a >.
9\c                Send a 9 without a new-line.
OK                  Waiting for the string OK.
```

### 11.5.2 Using Dialcodes to Create a Portable Systems File

The *Dialcodes* file (/usr/lib/uucp/Dialcodes) contains the dial-code abbreviations that can be used in the *Phone* field of the *Systems* file. This feature is intended primarily for those who wish to create a standard *Systems* file for distribution among several sites that have different phone systems and area codes. As such, the *Dialcodes* file is probably not necessary for most sites.
Dial codes are used to phone system-specific parts of a dial string from the actual phone number. For example, if two remote sites in a network have the same sites to link with, but have different internal phone systems (one has to dial "9" and wait for a dial tone to dial outside the facility and the other does not) each site can share the same Systems file, but have different entries in a Dialcodes file. Each entry has the following format:

\[ abb \text{ dial-seq} \]

where:

- \( abb \) is the abbreviation used in the Systems file phone field
- \( \text{dial-seq} \) is the dial sequence that is passed to the dialer when that particular Systems file entry is accessed.

The following entry would be set up to work with a phone field in the Systems file such as \( \text{jt7867} \):

\[ \text{jt } 9=847- \]

When the entry containing \( \text{jt7867} \) is encountered, the following sequence would be sent to the dialer if the token in the dialer-token-pair is \( \backslash T \):

\[ 9=847-7867 \]

The phone number is made up of an optional alphabetic abbreviation and a numeric part. For example, if an abbreviation is used, it must be one that is listed in the Dialcodes file.

<table>
<thead>
<tr>
<th>Systems:</th>
<th>eagle Any ACU D1200 NY3251 ogn: nuucp \</th>
<th>ssword: Oakgrass</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dialcodes:</td>
<td>NY 9=1212555</td>
<td></td>
</tr>
</tbody>
</table>

In this string, an equal sign (=) tells the ACU to wait for a secondary dial tone before dialing the remaining digits. A hyphen in the string instructs the ACU to pause before dialing the next digit. The number of seconds may vary from dialer to dialer (for example, 2 seconds for Hayes, 5 seconds for Vadic).
11.5.3 Using a Streams-based Network: the Devconfig File

The /usr/lib/uucp/Devconfig file is used when your computer communicates over a Streams-based transport provider that conforms to the AT&T Transport Interface (TI).

**Note**

STREAMS support requires installation of the XENIX STREAMS Toolkit; it is not included with the XENIX Operating System distribution.

Devconfig entries define the STREAMS modules that are used for a particular TI device. Entries in the Devconfig file have the format:

```
service=x device=y push=z[:z...]
```

where x can be cu, uucico, or both separated by a colon; y is the name of a TI network and must match an entry in the Devices file; and z is replaced by the names of Streams modules in the order that they are to be pushed onto the Stream. Different modules and devices can be defined for cu and uucp services.

The following entries should most commonly be used in the file:

```
service=cu device=STARLAN push=ntty:ti rdwr:ld0
service=uucico device=STARLAN push=ntty:ti rdwr:ld0
```

This example pushes ntty, then ti rdwr, then ld0. The Devconfig file cannot be modified with the uuinstall utility. If you want to change the contents of this file, you must use one of the XENIX text editors, such as vi(C).

11.5.4 Creating Alternate Control Files with Sysfiles

The /usr/lib/uucp/Sysfiles file lets you assign different files to be used by uucp and cu as Systems, Devices, and Dialers files. Here are some cases where this optional file may be useful.

- You may want different Systems files so requests for login services can be made to different addresses than UUCP services.
- You may want different Dialers files to use different handshaking for cu and uucp.
• You may want to have multiple Systems, Dialers, and Devices files. The Systems file in particular may become large, making it more convenient to split it into several smaller files.

The format of the Sysfiles file is

\[ \text{service}=w \ \text{systems}=:x:x \ \text{dialers}=:y:y \ \text{devices}=:z:z \]

where \( w \) is replaced by uucico, cu, or both separated by a colon; \( x \) is one or more files to be used as the Systems file, with each file name separated by a colon and read in the order presented; \( y \) is one or more files to be used as the Dialers file; and \( z \) is one or more files to be used as the Devices file. Each file is assumed to be relative to the /usr/lib/uucp directory, unless a full path is given. A backslash-carriage return (\(<\text{CR}>\)) can be used to continue an entry on to the next line.

Here's an example of using a local Systems file in addition to the usual Systems file:

\[ \text{service}=\text{uucico}:\text{cu} \ \text{systems}=\text{Systems}:\text{Local\_Systems} \]

If this is in /usr/lib/uucp/Sysfiles, then both uucico and cu will first look in /usr/lib/uucp/Systems. If the system they're trying to call doesn’t have an entry in that file, or if the entries in the file fail, then they'll look in /usr/lib/uucp/Local_Systems.

When different Systems files are defined for uucico and cu services, your machine will store two different lists of Systems. You can print the uucico list using the uuname command or the cu list using the uuname -c command.

11.5.5 Preventing Unknown Sites from Logging in

The script remote.unknown is executed when a site whose name is not recognized dials in to your system. It will log the conversation attempt and fail to make a connection. If you wish to allow such “unknown” systems to log in to your system, you can change the permissions of this file so it cannot execute and your system will accept any communication requests. To do so, enter the following commands while logged-in as root:

\[ \text{cd} \ /\text{usr/lib/uucp} \]
\[ \text{chmod} \ 000 \ \text{remote.unknown} \]
11.5.6 Linking Micnet Sites with the UUCP Network

To use a UUCP system with your micnet network, follow these steps:

1. Add the following entry to the *maliases* file of the computer on which the UUCP system is installed:

   `uucp:`

2. For all other computers in your site, add the following entry to the *maliases* file:

   `uucp:machine-name:`

   where *machine-name* is the name of the computer on which the UUCP system is installed. This longer form of entry can also be used on the computer on which the UUCP system is installed.

You can test the UUCP system by mailing a short letter to yourself by means of another site. For example, if you are on the site *chicago*, and there is another micnet site named *seattle* in the system, then the following command sends mail to the *seattle* site, then back to your *chicago* site, and finally to the user *johnd* in your micnet network:

   `mail seattle!chicago!johnd`

Note that a UUCP system usually performs its communication tasks according to a fixed schedule and may not return mail immediately.

11.6 Administrating Your UUCP System

This section discusses the various shell scripts that are used to supervise and maintain UUCP. Consult the section on ‘‘Administration and Maintenance Commands’’ for details on all commands available to the system administrator. Included is an extended description of the /usr/spool/uucp work directory and a special subsection on troubleshooting.

11.6.1 Scheduling Communications with Other Systems

Scheduled UUCP communications are the result of the complex interaction of two shell scripts, *uudemon.hour* and *uudemon.poll*, and the programs
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**uusched** and **cron**. The following list isolates each of the relationships between these programs and explains how they work together to schedule jobs:

- **The uusched program** schedules the queued work in the spool directory, choosing at random the order in which remote computers will be called, before starting the **uucico** daemon.

- **The shell script uudemon.hour** executes **uusched** twice per hour to check for work files.

- **The uudemon.hour script** is in turn started by **cron**, which checks the file every two minutes to see if it is time.

- **In the case of polled sites (described below),** the script **uudemon.poll** is called by **cron** and sets up a work file started by **uudemon.hour**.

While in multi-user mode, **cron** scans files in **/usr/spool/cron/crontabs** once each minute for entries to execute at this time. As the system administrator, you should familiarize yourself with **cron**(C) and the two **uudemon** shell scripts discussed here and two others, **uudemon.admin** and **uudemon.clean**, that are discussed later.

An example crontabs file, **crontab.eg**, is provided to activate these daemons. The system administrator should copy these from **/usr/lib/uucp** to **/usr/spool/cron/crontabs/root**.

**How Often the UUCP Directory is Checked for Work**

The **uudemon.hour** shell script does the following:

- Calls the **uusched** program to search the spool directories for work files (C.) that have not been processed and schedules these files for transfer to a remote machine.

- Calls the **uuxqt** daemon to search the spool directories for execute files (X.) that have been transferred to your computer and were not processed at the time they were transferred.

The following is the default, root **crontab** entry for **uudemon.hour**:

```
39, 9 * * * * /usr/lib/uucp/uudemon.hour > /dev/null
```

This script runs twice per hour (at 39 and 9 minutes past). Thus, you may want to execute it more often if you expect higher failure rates.
Polling Remote Computers

As mentioned in the discussion of passive systems and the Systems file, it is possible to configure a site that originates no calls and the traffic flow is always one-way. Such sites require polling, where other sites periodically dial in (whether or not they have actual transactions logged) to check for jobs.

The Poll file (/usr/lib/uucp/Poll) contains information for polling remote computers. Each entry in the Poll file contains the name of a remote computer to call, followed by a tab character (a space won't work), and finally the hours the computer should be called. The hours must be integers in the range 0-23.

Poll file entries have the following format:

sysname<TAB>hour ...

For example, the following entry will provide polling of computer gorgon every four hours:

gorgon 0 4 8 12 16 20

The uudemon.poll script controls polling but does not actually perform the poll. It merely sets up a polling file (C.sysnxxxx) in the /usr/spool/uucp/nodename directory, where nodename is replaced by the name of the machine. This file will in turn be acted upon by the scheduler (started by uudemon.hour). The uudemon.poll script is scheduled to run twice an hour just before uudemon.hour so that the work files will be there when uudemon.hour is called. The default root crontab entry for uudemon.poll is as follows:

1,30 * * * "/usr/lib/uucp/uudemon.poll > /dev/null"

11.6.2 Automated Maintenance

The UUCP distribution includes predefined entries in the example file /usr/lib/uucp/crontab.eg, which can be copied to /usr/spool/cron/crontabs/root to enable these daemons. These entries will automatically perform some administrative tasks for you. The shell scripts are located in /usr/lib/uucp.

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uudemon.admin

The **uudemon.admin** shell script, as delivered, does the following:

- Runs the **uustat** command with `-p` and `-q` options. The `-q` reports on the status of work files (C.), data files (D.), and execute files (X.) that are queued. The `-p` prints process information for networking processes listed in the lock files (/usr/spool/locks).

- Sends resulting status information to the UUCP administrative login (**uucp**) via mail.

The default crontab entry for **uudemon.admin** is:

```
48 10,14 * * 1-5 /bin/su uucp -c \
"/usr/lib/uucp/uudemon.admin" > /dev/null
```

uudemon.clean

The **uudemon.clean** shell script, as delivered, does the following:

- Takes log files for individual machines from the /usr/spool/.Log directory, merges them, and places them in the /usr/spool/Old directory with other old log information. If log files get large, the ulimit may need to be increased.

- Removes work files (C.) 7 days or older, data files (D.) 7 days old or older, and execute files (X.) 2 days old or older from the spool files.

- Mails a summary of the status information gathered during the current day to the UUCP administrative login (uucp).

The default crontab entry for **uudemon.clean** is:

```
45 23 * * * ulimit 5000; /bin/su uucp -c \
"/usr/lib/uucp/uudemon.clean" > /dev/null
```
Some files may grow indirectly from UUCP and other networking activities. There are two files you should check and delete if they become too large:

- `/usr/adm/sulog`: This file keeps a history of all super user commands. Since `uudemon` entries in the `/usr/cron/root` file use the `su` command, the `sulog` will grow over time. You should delete this file if it becomes too large.

- `/usr/lib/cron/log`: This file is a log of `cron` activities. While it grows with use, it is automatically truncated when the system comes up multiuser.

### 11.6.3 Generating Log Reports on UUCP Usage: `uulog`

The `uulog` program displays log information on UUCP usage according to remote machine. All usage of the programs UUCP, `uuto`, and `uux` are logged in special log files, one per machine.

#### `uulog` Options

The `uulog` command has the following options:

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>-fsystem</code></td>
<td>Displays the last entry or entries of the <code>system</code> file transfer log.</td>
</tr>
<tr>
<td><code>-ssystem</code></td>
<td>Displays the <code>system</code> file transfer information.</td>
</tr>
<tr>
<td><code>-x</code></td>
<td>Displays the <code>uuxqt</code> log file for the given system.</td>
</tr>
<tr>
<td><code>-number</code></td>
<td>Specifies the <code>number</code> of lines displayed by the <code>-f</code> option.</td>
</tr>
</tbody>
</table>

For example, to print the last 10 lines of `chicago`'s file-transfer log, you would enter

```
uulog -fchicago -10
```
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Special uulog Files

During execution of the uulog program, the files from the following directories are examined:

<table>
<thead>
<tr>
<th>Directory</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>/usr/spool/uucp/.Log/uucico/*</td>
<td>Directory used for queries by the UUCP program.</td>
</tr>
<tr>
<td>/usr/spool/uucp/.Log/uuxqt/*</td>
<td>Directory used for queries by the uuxqt program.</td>
</tr>
</tbody>
</table>

11.6.4 The UUCP Spool Directory

The following is a comprehensive discussion of all files and subdirectories of the UUCP spool directory. These files are created in spool directories to lock devices, hold temporary data, or keep information about remote transfers or executions.

TM. (temporary data file)

These data files are created by UUCP processes under the spool directory (i.e., /usr/spool/uucp/system) when a file is received from another computer. The system directory has the same name as the remote computer that is sending the file. The names of the temporary data files have the format:

**TM.pid.ddd**

where *pid* is a process-ID and *ddd* is a sequential three digit number starting at 0.

When the entire file is received, the **TM.pid.ddd** file is moved to the path name specified in the C.sysnxxxx file (discussed below) that caused the transmission. If processing is abnormally terminated, the **TM.pid.ddd** file may remain in the system directory. These files should be automatically removed by uucleanup.
LCK. (lock file)

Lock files are created in the /usr/spool/uucp directory for each device in use. Lock files prevent duplicate conversations and multiple attempts to use the same calling device. The names of lock files have the format:

LCK..str

where str is either a device or computer name. These files may remain in the spool directory if the communications link is unexpectedly dropped (usually on computer crashes). The lock files will be ignored (removed) after the parent process is no longer active. The lock file contains the process ID of the process that created the lock. The lock file is always named using the "a" (non-modem control) suffix to avoid possible conflicts if the same line is specified both modem-control and non-modem-control. For example, the lock on /dev/tty1A is named LCK..tty1a.

C. (work file)

Work files are created in a spool directory when work (file transfers or remote command executions) has been queued for a remote computer. The names of work files have the format:

C.sysnxxxx

where sys is the name of the remote computer, n is the ASCII character representing the grade (priority) of the work, and xxxx is the four digit job sequence number assigned by UUCP. Work files contain the following information:

- Full pathname of the file to be sent or requested
- Full pathname of the destination or user/file name
- User login name
- List of options
- Name of associated data file in the spool directory. If the uucp -c or uuto -p option was specified, a dummy name (D.0) is used
- Mode bits of the source file
- Remote user's login name to be notified upon completion of the transfer
D. (data file)

Data files are created when it is specified in the command line to copy the source file to the spool directory. The names of data files have the following format:

\[ \text{D.systmxxxxyy} \]

where \textit{systm} is the first five characters in the name of the remote computer, \textit{xxxx} is a four-digit job sequence number assigned by \texttt{uucp}. The four digit job sequence number may be followed by a sub-sequence number, \textit{yyy} that is used when there are several D. files created for a work (C.) file.

X. (execute file)

Execute files are created in the spool directory prior to remote command executions. The names of execute files have the following format:

\[ \text{X.sysnxxxx} \]

where \textit{sys} is the name of the remote computer, \textit{n} is the character representing the grade (priority) of the work, and \textit{xxxx} is a four digit sequence number assigned by UUCP. Execute files contain the following information:

- Requester’s login and computer name.
- Name of file(s) required for execution.
- Input to be used as the standard input to the command string.
- Computer and file name to receive standard output from the command execution.
- Command string.
- Option lines for return status requests.

11.7 Troubleshooting

The procedures that follow describe how to solve common UUCP problems.
11.7.1 Check for Faulty ACU/Modem

There are two ways you can check if the automatic call units or modems are not working correctly:

- Run `uustat -q`. This command yields counts and reasons for contact failure.

- Run `cu -x9 -line dir`. This permits you to use a specific line and print debugging information during the attempt. Note that this command is only permitted for those who have write access to the `Devices` file, in order to protect the modem from interference from unqualified users.

11.7.2 Check the Systems File

If you are having trouble contacting a particular machine, ensure that the information in your `Systems` file is current. Some things that could be out of date are:

- Phone number
- Login
- Password

11.7.3 Debug Transmissions

If you are unable to contact a particular machine, you can check out communications to that machine using `uutry` and `uucp`. Do the following:

1. Make contact using this command line:

   `/usr/lib/uucp/uutry -r machine`

   where `machine` is the node name of the problem machine. This command does the following:

   - Starts the transfer daemon (`uucico`) with debugging. You will get more debugging information if you are `root`.
Building a Remote Network with UUCP

- Directs the debugging output to /tmp/machine.
- Prints the debugging output to your terminal (tail -f). Press the DEL key to end output.

You can copy the output from /tmp/machine if you wish to save it.

2. If `uutry` fails to isolate the problem, attempt to queue a job with the following command:

   `uucp -r file machine!/dir/file`

   where `file` is the file you want to transfer, and `machine` is the machine you want to copy to, and `dir/file` is the destination location on the other machine. The `-r` option will queue a job without starting a transfer.

3. Next, use `uutry` again. If you still cannot solve the problem, you may need to call support personnel. Save the debugging output; it will help diagnose the problem.

11.7.4 Check Basic Information

There are several commands you can use to check for basic communication information:

- `uname` Use this command to list the machines you are set up to contact.
- `uulog` Use this command to display the contents of the log directories for particular hosts.
- `uucheck -v` Run this command to check for the presence of files and directories needed by `uucp`. This command also checks the Permissions file and outputs information on the permissions you have set up.

11.8 Keeping Traffic and Congestion Under Control

The UUCP filesystem can be choked by traffic if a connection goes down, but unless your site is running a full USENET feed or your system connects with a number of systems, UUCP should prove self-sustaining. If UUCP is used more frequently on your system, this section discusses how to ensure that the system does not become stopped, congested, or affect the general performance of your system.
11.8.1 Crowded Directories and Lack of Space

The `uudemon.clean` script is the best way to prevent the UUCP spool directory from growing too large. To see how much disk storage is currently used by UUCP, use the `du(C)` command:

```
du /usr/spool/uucp /usr/spool/uucppublic
```

The current amount of disk space used in each directory is displayed in 512-byte blocks. Divide this number by two for the size in 1K bytes.

The `uudemon.admin` and `uudemon.clean` scripts will send great deal of mail to the `uucp` account. You should check and clear the mail file periodically.

11.8.2 Running out of Processes

On systems with a large amount of traffic, you may get error messages indicating that there are too many processes. If you use the `ps(C)` command, you may notice a number of uucico or uuxqt processes running. You can establish a new limit on the number of these processes running by editing the files `Maxuuscheds` and `Maxuxqts` in `/usr/lib/uucp`.

11.8.3 Evaluating Apparent Stoppages

If users complain that UUCP mail is not getting through and the spool directory is filled with old jobs, it is time to check for the source of the stoppage. UUCP provides an extensive set of error messages and log files that should allow you to trace the cause and remedy the situation.

- Use the `uulog(ADM)` command to study traffic on a per-system basis. Refer to “Generating Log Reports on UUCP Usage: uulog” for details. Error messages in the `Adminerrors` are called ASSERT errors. These usually involve filesystem problems.

- Find out the status of currently queued jobs using the `uustat -q` command. This command will also indicate the number of failed connection attempts.

Error messages are explained in “UUCP Error Messages” in this chapter. Each message is documented with a suggested remedy.
11.9 UUCP Error Messages

This section lists the error messages associated with UUCP. There are two types of error messages. ASSERT errors are recorded in the /usr/spool/uucp/Admin/errors file. STATUS errors are recorded in individual machine files found in the /usr/spool/uucp.Status directory.

11.9.1 ASSERT Error Messages

When a process is aborted, ASSERT error messages are recorded in /usr/spool/uucp/Admin/errors. These messages include the file name, scssid, line number, and the text listed below. In most cases, these errors are the result of filesystem problems. The "errno" (when present) should be used to investigate the problem. If "errno" is present in a message, it is shown as () in the following list.

<table>
<thead>
<tr>
<th>Error Message</th>
<th>Description/Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAN'T OPEN</td>
<td>An open() or fopen() failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T WRITE</td>
<td>A write(), fwrite(), fprintf(), etc. failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T READ</td>
<td>A read(), fgets(), etc. failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T CREATE</td>
<td>A create() call failed. Check permissions.</td>
</tr>
<tr>
<td>CAN'T ALLOCATE</td>
<td>A dynamic allocation failed.</td>
</tr>
<tr>
<td>CAN'T LOCK</td>
<td>An attempt to make a LCK (lock) file failed. In some cases, this is a fatal error.</td>
</tr>
<tr>
<td>CAN'T STAT</td>
<td>A stat() call failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T CHMOD</td>
<td>A chmod() call failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T LINK</td>
<td>A link() call failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>CAN'T CHDIR</td>
<td>A chdir() call failed. Check for the presence of the file and permissions.</td>
</tr>
<tr>
<td>Error Message</td>
<td>Description/Action</td>
</tr>
<tr>
<td>-----------------------------------</td>
<td>--------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CAN'T UNLINK</td>
<td>A unlink( ) call failed.</td>
</tr>
<tr>
<td>WRONG ROLE</td>
<td>This is an internal logic problem.</td>
</tr>
<tr>
<td>CAN'T MOVE TO CORRUPTDIR</td>
<td>An attempt to move some bad C. or X. files to the /usr/spool/uucp/Corrupt directory failed. The directory is probably missing or has wrong modes or owner.</td>
</tr>
<tr>
<td>CAN'T CLOSE</td>
<td>A close( ) or fclose( ) call failed.</td>
</tr>
<tr>
<td>FILE EXISTS</td>
<td>The creation of a C. or D. file is attempted, but the file exists. This occurs when there is a problem with the sequence file access. Usually indicates a software error.</td>
</tr>
<tr>
<td>No uucp server</td>
<td>A tcp/ip call is attempted, but there is no server for UUCP.</td>
</tr>
<tr>
<td>BAD UID</td>
<td>The uid cannot be found in the /etc/passwd file. The filesystem is in trouble, or the /etc/passwd file is inconsistent.</td>
</tr>
<tr>
<td>BAD LOGIN_UID</td>
<td>Same as previous.</td>
</tr>
<tr>
<td>ULIMIT TOO SMALL</td>
<td>The ulimit for the current user process is too small. File transfers may fail, so transfer is not attempted.</td>
</tr>
<tr>
<td>BAD LINE</td>
<td>There is a bad line in the Devices file; there are not enough arguments on one or more lines.</td>
</tr>
<tr>
<td>FSTAT FAILED IN EWRDATA</td>
<td>There is something wrong with the ethernet media.</td>
</tr>
<tr>
<td>SYSLST OVERFLOW</td>
<td>An internal table in genome.c overflowed. A big/strange request was attempted.</td>
</tr>
<tr>
<td>TOO MANY SAVED C FILES</td>
<td>Same as previous.</td>
</tr>
<tr>
<td>RETURN FROM fixline ioctl</td>
<td>An ioctl, which should never fail, failed. There is a system driver problem.</td>
</tr>
</tbody>
</table>
### Error Message

<table>
<thead>
<tr>
<th>Error Message</th>
<th>Description/Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>BAD SPEED</td>
<td>A bad line speed appears in the <em>Devices/Systems</em> files (Class field).</td>
</tr>
<tr>
<td>PERMISSIONS file: BAD OPTION</td>
<td>There is a bad line or option in the <em>Permissions</em> file.</td>
</tr>
<tr>
<td>PKGGET READ</td>
<td>The remote machine probably hung up. No action need be taken.</td>
</tr>
<tr>
<td>PKXSTART</td>
<td>The remote machine aborted in a non-recoverable way. This can generally be ignored.</td>
</tr>
<tr>
<td>SYSTAT OPEN FAIL</td>
<td>There is a problem with the modes of <code>/usr/lib/uucp/Status</code>, or there is a file with bad modes in the directory.</td>
</tr>
<tr>
<td>TOO MANY LOCKS</td>
<td>There is an internal problem!</td>
</tr>
<tr>
<td>XMV ERROR</td>
<td>There is a problem with some file or directory. It is likely the spool directory, since the modes of the destinations were suppose to be checked before this process was attempted.</td>
</tr>
<tr>
<td>CAN'T FORK</td>
<td>An attempt to fork and exec failed. The current job should not be lost, but will be attempted later (<em>uuxqt</em>). No action need be taken.</td>
</tr>
</tbody>
</table>

#### 11.9.2 UUCP STATUS Error Messages

Status error messages are messages that are stored in the `/usr/spool/uucp/Status` directory. This directory contains a separate file for each remote machine that your system attempts to communicate with. These individual machine files contain status information on the attempted communication, whether it was successful or not. What follows is a list of the most common error messages that may appear in these files.
<table>
<thead>
<tr>
<th>Error Message</th>
<th>Description/Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>OK</td>
<td>Things are OK.</td>
</tr>
<tr>
<td>NO DEVICES AVAILABLE</td>
<td>There is currently no device available for the call. Check to see that there is a valid device in the Devices file for the particular system. Check the Systems file for the device to be used to call the system.</td>
</tr>
<tr>
<td>WRONG TIME TO CALL</td>
<td>A call was placed to the system at a time other than what is specified in the Systems file.</td>
</tr>
<tr>
<td>TALKING</td>
<td>Self explanatory.</td>
</tr>
<tr>
<td>LOGIN FAILED</td>
<td>The login for the given machine failed. It could be a wrong login/password, wrong number, a very slow machine, or failure in getting through the dialer-token script.</td>
</tr>
<tr>
<td>CONVERSATION FAILED</td>
<td>The conversation failed after successful startup. This usually means that one side went down, the program aborted, or the line (link) was dropped.</td>
</tr>
<tr>
<td>DIAL FAILED</td>
<td>The remote machine never answered. It could be a bad dialer or the wrong phone number.</td>
</tr>
<tr>
<td>BAD LOGIN/MACHINE COMBINATION</td>
<td>The machine called us with a login/machine name that does not agree with the Permissions file. This could be an attempt to masquerade!</td>
</tr>
<tr>
<td>DEVICE LOCKED</td>
<td>The calling device to be used is currently locked and in use by another process.</td>
</tr>
<tr>
<td>ASSERT ERROR</td>
<td>An ASSERT error occurred. Check the /usr/spool/uucp/.Admin/errors file for the error message and refer to the section ASSERT Error Messages.</td>
</tr>
<tr>
<td>SYSTEM NOT IN Systems</td>
<td>The system is not in the Systems file.</td>
</tr>
</tbody>
</table>
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<table>
<thead>
<tr>
<th>Error Message</th>
<th>Description/Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAN'T ACCESS DEVICE</td>
<td>The device tried does not exist or the modes are wrong. Check the appropriate entries in the <em>Systems</em> and <em>Devices</em> files.</td>
</tr>
<tr>
<td>DEVICE FAILED</td>
<td>The open of the device failed.</td>
</tr>
<tr>
<td>WRONG MACHINE NAME</td>
<td>The called machine is reporting a different name than expected.</td>
</tr>
<tr>
<td>CALLBACK REQUIRED</td>
<td>The called machine requires that it calls your system.</td>
</tr>
<tr>
<td>REMOTE HAS A LCK FILE FOR ME</td>
<td>The remote site has a LCK file for your system. They could be trying to call your machine. If they have an older version of UUCP, the process that was talking to your machine may have failed leaving the LCK file. If they have the new version of UUCP, and they are not communicating with your system then the process that has a LCK file is hung.</td>
</tr>
<tr>
<td>REMOTE DOES NOT KNOW ME</td>
<td>The remote machine does not have the node name of your system in its <em>Systems</em> file.</td>
</tr>
<tr>
<td>REMOTE REJECT AFTER LOGIN</td>
<td>The login used by your system to login does not agree with what the remote machine was expecting.</td>
</tr>
<tr>
<td>REMOTE REJECT, UNKNOWN MESSAGE</td>
<td>The remote machine rejected the communication with your system for an unknown reason. The remote machine may not be running a standard version of UUCP.</td>
</tr>
<tr>
<td>STARTUP FAILED</td>
<td>Login succeeded, but initial handshake failed. Check communication parameters: data word size, parity, stop bits, etc.</td>
</tr>
<tr>
<td>CALLER SCRIPT FAILED</td>
<td>This is usually the same as DIAL FAILED. However, if it occurs often, suspect the caller script in the <em>dialers</em> file. Use <code>uutry</code> to check.</td>
</tr>
</tbody>
</table>
Chapter 12

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12.1 Introduction

A Micnet network allows communications between two or more independent XENIX systems. The network consists of computers connected by serial communication lines (that is, RS-232 ports connected by cable). Each computer in the network runs as an independent system, but allows users to communicate with the other computers in the network through the mail, rcp, and remote commands. These commands pass information such as mail, files, and even other commands, from one computer to another.

It is the system manager's task to build and maintain a Micnet network. The system manager decides how the computers are to be connected, makes the actual physical connections, then uses the netutil program to define and start the network.

This chapter explains how to plan a network and then build it with the netutil program. In particular, it describes:

- How to choose machine names and aliases
- How to draw the network topology map
- How to assign serial lines
- How to create the Micnet files
- How to distribute the Micnet files
- How to test the Micnet network

12.2 Planning a Network

To build a Micnet network, the netutil program requires that you provide the names of the computers that are to be in the network, a description of how the computers are to be connected, a list of the serial lines to be used, the names of the users who use the network, and what aliases (if any) they are known by.

To keep the task as simple as possible, you should take some time to plan the network and make lists of the information you are required to supply. To help you make these lists, the following sections suggest ways to plan a network.
12.2.1 Choosing Machine Names

A Micnet network requires that each computer in the network have a unique "machine name." A machine name helps distinguish each computer from other computers in the network. It is best to choose machine names as the first step in planning the network. This prevents confusion later on, when you build the network with the netutil program.

A machine name should suggest the location of the computer or the people who use it. You can also use any name you wish. The name must be unique and consist of letters and digits. The Micnet programs use only the first eight characters of each name, so be sure those characters are unique.

The netutil program saves the machine name of a computer in a /etc/systemid file. One file is created for each computer. After you have built and installed the network, you can find out the machine name of the computer you are using by displaying the contents of this file.

12.2.2 Choosing a Network Topology

The network topology is a description of how the computers in the network are connected. In any Micnet network, there are two general topologies from which all topologies can be constructed. These are "star" and "linear."

In a star topology, all computers are directly connected to a central computer. All communications pass through the central computer to the desired destination.

In a linear topology, the computers form a chain, with each computer directly connected to no more than two others. All communications pass down the chain to the desired destination.

A network may be strictly star, strictly linear, or a combination of star and linear topologies. The only restriction is that no network may form a ring. For example, you cannot close up a linear network by connecting the two computers at each end.

The kind of topology you choose depends on the number of computers you have to connect, how quickly you want communications to proceed, and how you want to distribute the task of passing along communications. A star topology provides fast communication between computers, but requires both a large portion of the central computer's total operation time and a large number of serial lines on the central computer. A linear topology distributes the communication burden evenly, requiring only two
Building a Local Network With Micnet

serial lines per computer, but is slow if the chain is very long (communication between computers can take several minutes). Often a combination of star and linear topologies makes the best network. In any case, make the choice you think is best. If you discover you have made a wrong choice, you may change the network at any time.

12.2.3 Drawing a Network Topology Map

A network topology map is a sketch of the connections between computers in the network. You use the map to plan the number and location of the serial lines used to make the network.

You can make the map while you work out the topology. Simply arrange the machine names of each computer in the network on paper, then mark each pair of computers you wish to connect with serial lines. For example, the topology map for a linear network of three computers might look like this:

```
a  -----------  b  -----------  c
```

As you draw, make sure that there is no more than one connection between any two computers in the network. Furthermore, make sure that no rings are formed (a ring is a series of connections that form a closed circle). Multiple connections and rings are not permitted.

12.2.4 Network Connection Strategy

Once you have made the topology map, you can decide which serial ports to use to connect the computers. Since every connection between computers in the network requires exactly two ports (one on each computer) and one serial wire, you need to be very careful about assigning the lines.

Make a list of the serial ports (also called TTY ports) available for use on each computer in the network. You can display a list of the serial ports on a computer by examining the file `/etc/ttys`. A port is available if it is not connected to any device such as a terminal or modem.

For example, in our above topology, computer \( b \) has two network connections, one to computer \( a \) and one to computer \( c \). You would need to allocate two tty ports on computer \( b \), one for computer \( a \) and one for computer \( c \).

There is a restriction on tty names that can be used with micnet. No tty port number may be duplicated across the network. Most computers have
similar tty numbering schemes (tty1a, tty2a, tty3a, etc.) This means that on every computer in your network, the serial ports have the same names. For example, if you connect tty1b on computer a to tty5d on computer b, you cannot then assign tty1b on computer c to any other machine on your network. The reason for this restriction is that micnet programs do not distinguish between different computers on the network and you must specify the ports used on each computer for communication. Therefore, if the program finds two ttys of the same name in the topology file, the network cannot operate correctly. We recommend a strategy to allow you to easily manipulate micnet connections.

We suggest that you choose a range of numbers that your system does not use and make those nonexistent tty ports into links for micnet. We recommend using tty numbers beginning with 40 or 50. There is no upper limit and you can have as many of these "virtual" ttys as you need in the topology file. For example, since no two computers can use the same tty name in the topology, state in the topology file that computer a uses tty50 to connect to tty51 on computer b. Since these ttys do not exist on any of your systems, you can be certain that the names are not duplicated across the network.

To make these new virtual tty names correspond to actual ttys on your computer, you use the ln(C) command to link the filenames you have given in your topology to real ttys on your system. When you use ln(C) to link the two filenames, you are telling XENIX that the actual tty is now also known by the new name you give it. When you list the contents of the /dev directory, you see both names, but both names access the same physical device.

For an example use of ln(C), the following command links tty50 on computer a to whatever physical tty you actually connect the wire. If you plug the wire into tty1a on computer a and the other end of the wire goes into tty5d on computer b, you give the following command on computer a:

```
ln /dev/ttyla /dev/tty50
```

Then, when micnet sends information to /dev/tty50, the information actually goes out through tty1a. Similarly, on computer b link /dev/tty5d, where you have actually connected the wire, to the virtual tty called tty51 as follows:

```
ln /dev/tty5d /dev/tty51
```

This allows you to physically connect the wires to whatever ports are available without concern for duplicating connections. For example, if the
only port available on computer c was /dev/tty1a, you would not have to change your system configuration to use that name in the network topology.

This strategy is also useful when a port fails for some reason. Instead of having to make and distribute a new network topology, you merely change the link from your virtual tty (tty50, 51, 52, etc.) to some other physical tty (tty2c for example) and your network will operate correctly.

12.2.5 Assigning Lines and Speeds

Follow these steps to create and assign your ttys and ports:

1. Using the topology map and the strategy outlined above, assign one (and only one) available tty to each network connection for each computer. List both the actual and the virtual ttys you plan to use. For example, if computer a has only one available serial line (tty1a) and you plan to use the virtual tty name tty50, then the entry in the topology map should look like this:

   a ----------- b ----------- c
   tty1b
   (tty50)

2. Repeat step 1 for all computers in the topology map. Make sure that each connection is assigned a line and a virtual tty and that no two connections on any given computer have the same virtual tty number. When finished, the map should look like this:

   a ----------- b ----------- c
   tty1b    tty2a    tty3a    tty1b
   (tty50)   (tty51)   (tty52)   (tty53)
Note

For an example of a star topology, imagine a cartwheel. One computer is the hub of the wheel and the spokes of the wheel are connections to the other network computers. The center machine in a star topology is often called the "hub" machine. The hub machine must have enough available serial ports to allow a connection to every machine on the network.

If a computer does not have enough available serial ports to meet its needs, you can make the lines available by removing the devices already connected to them. If you cannot remove devices, you must redraw your topology map.

3. Using the topology map, assign a serial line transmission speed for each computer pair. The speed must be within the normal range for XENIX serial lines (typically 110 to 9600). Transmission speeds are a matter of preference. In general, a higher speed means a smaller amount of time to complete a transmission, but a greater demand on system's input and output capabilities. In some cases, transmission speeds are a matter of hardware capabilities. Some hardware is not capable of transmission speeds greater than 1200 baud. For this reason, 1200 is the recommended speed when first installing Micnet. You may then increase the speed if you find the hardware can support it.

4. After the topology map is completely filled in, make a list of all computer pairs, showing their machine names, serial lines, and transmission speeds. You will use this list when installing the network. Here is the topology map showing the default transmission speeds:

```
computer     computer     computer
  a  ---1200---  b  ---1200---  c
tty1b  tty2a  tty3a  tty1b
(tty50)  (tty51)  (tty52)  (tty53)
```

Here is a sample list of computer pairs from the above topology:

- a (tty50) to b (tty51) at 1200 baud
- b (tty52) to c (tty53) at 1200 baud
5. Go to each computer on the network and give the commands to link each virtual tty to its physical counterpart on that machine. For example, the commands should have the form:

   `ln /dev/actual-tty /dev/virtual-tty`

12.2.6 Choosing Aliases

Once you have decided how to connect the computers in the network, you can choose aliases for users in the network. An alias is a simple name that represents both a location (computer) and a user. Aliases are used by the `mail` command to allow you to refer to specific computers and users in a network without giving the explicit machine and user names. Although not a required part of the network, aliases can make the network easier to use and maintain.

There are three kinds of aliases: standard, machine, and forward. A standard alias is a name for a single user or a group of users. A machine alias is a name for a computer or an entire network (called a site). A forward alias is a temporary alias for a single user or group of users. A forward alias allows users who normally receive network communications at one computer to receive them at another.

When you build a network with the `netutil` program, you are asked to provide standard aliases only. (You can incorporate machine and forward aliases into the network at your leisure.) Each standard alias must have a unique name and a list of the login names of the users it represents. You may choose any name you wish as long as it consists of letters and numbers, begins with a letter, and does not have the same spelling as the login names. The name should suggest the user or group of users it represents. The login names must be the valid login names of users in the network.

To help you prepare the aliases for entry during the `netutil` program, follow these steps:

1. Make a list of the user aliases (that is, the aliases that refer to just one user) and the corresponding login names of each user.

2. Make a separate list of the group aliases (that is, the aliases that refer to two or more users) and the login names or user aliases (from the first list) of the corresponding users. A group alias may have any number of corresponding users.
Note that there are a number of predefined group aliases. The name all is the predefined alias for all users in the network. The machine names of the computers in the network are predefined aliases for the users on each computer. Do not use these names when defining your own aliases.

12.3 Building a Network

You build a network with the netutil program. The program allows you to define the machines, users, and serial lines that make up the network.

To build a network, you must first create the Micnet files that define the network and then transfer these files to each computer in the network. After each computer receives the files, you may start the network and use it to communicate between computers.

The following sections describe how to build the network.

12.3.1 Creating the Micnet Files

The Micnet files are created with the install option of the netutil program. The install option asks for the names, aliases, and serial lines of each computer in the network. As you supply the information, it automatically creates the files needed for each computer. These files can then be transferred to the other computers in the network with the save and restore options of netutil. This means you can build the entire network from just one computer.

To use the install option, follow these steps:

1. Log in as the super user.

2. Enter:

   netutil

   and press the RETURN key. The program displays the network utility menu. The install option is the first item in the menu.
3. Enter "1", and press RETURN. The program displays the following message:

```
Compiling new network topology
Overwrite existing network files? (yes/no)?
```

Enter y and press the RETURN key to overwrite the files. The existing network files must be overwritten to create the new network. The first time you install the network, these files contain default information that need not be saved. If you install the system a second time or expand the system, it may be wise to save a copy of these files before starting the install option. The files can be saved on a floppy or a hard disk with the save option described later in this chapter.

Once you have entered y, the program displays the following message:

```
Enter the name of each machine
(or press RETURN to continue installation).
Machine name:
```

4. Enter the machine name and press the RETURN key. You may enter more than one name on a line by separating each with a comma or a space. After you have entered all the names, press the RETURN key to continue to the next step. The program displays the names you entered and asks if you wish to make changes.

5. Enter y (for "yes") if you wish to enter all the names again. Otherwise, enter n (for "no") or just press the RETURN key to move on to the next step. If you enter n, the program displays the message:

```
For each machine, enter the names of the machines to be connected with it
Machine a:
  Connect to:
```
6. Using the list of machine pairs you created when planning the network, enter the machine names of the computers connected to the given computer. You may enter more than one name on a line by separating each name with a comma (,) or a space. When you have entered the machine names of all computers connected to the given computer, press the RETURN key. The program prompts for the names of the computers connected to the next computer.

7. Repeat step 5 for all remaining computers. As the program prompts for each new set of connections, it shows a list of the machine names it already knows to be connected with the current computer. You need not enter these names. The program automatically checks for loops. If it finds one, it ignores the machine name that creates the loop and prompts for another.

Finally, when you have given the connections for all computers in the network, the program displays a list of the connections and asks if you wish to make corrections.

8. Enter y, if you wish to enter the connections again. Otherwise, enter n, to move to the next step. If you enter n, the program displays the message:

```
For each machine pair, enter the tty name and tty speeds
For the a <=> b machine pair.
  Tty on a:
```

9. Using the list of serial line assignments you created when planning the network, enter the serial line name or number (for example, tty03 or 3) for the first computer in the pair and press the RETURN key. The program displays the message:

```
Tty on b:
```
10. Enter the serial line name for the second computer in the pair and press the RETURN key. The program displays the message:

```
Speed:
```

11. Enter the speed (for example, 1200) and press the RETURN key. The program asks for the serial lines and transmission speed of the next pair.

12. Repeat step 8 for all remaining machine pairs. When you have given serial lines and speeds for all pairs, the program displays this information and asks if you wish to make corrections.

13. Enter y, if you wish to enter the serial lines and speeds again. Otherwise, enter n, to move to the next step.

The program displays the message:

```
Enter the names of users on each machine:
```

For machine a:
Users on a:

14. Enter the login name of a user on the given computer, then press the RETURN key. You may enter more than one name on a line by separating each name with a comma (,) or a space. When you have entered all names for the given computer, press the RETURN key. The program displays the names of the users on the computer and asks if you wish to make corrections.

15. Enter y, if you wish to enter the user names again. Otherwise, enter n. If you enter n, the program prompts you for the names of the users on the next computer.
16. Repeat steps 13 and 14 for all remaining computers. After you have entered the names of users for every computer, the program prompts you to enter any aliases:

Do you wish to enter any aliases? (yes/no)?

17. Enter y, if you wish to enter aliases. Otherwise, enter n, to complete the installation. If you enter y, the program displays the message:

Each alias consists of two parts, the first is the alias name, the second is a list of one or more of the following:
- valid user names
- previously defined aliases
- machine names

Aliases:

18. Using the list of aliases you created when planning the network, enter the name of an alias and press the RETURN key. The program displays the message:

Users/Aliases:

19. If the alias is to name a single user, enter the login name of that user and press the RETURN key. The program then prompts for another alias.

If, on the other hand, the alias is to name several users, enter the login names of the users. If one or more of the users to be named by the alias are already named by other aliases, enter the aliases instead of the login names. If all the users on one computer are to
be named by the alias, enter the machine name instead of the login names. In any case, make sure that each item entered on the line is separated from the next by a comma (,) or a space. If there are more items than can fit on the line, enter a comma after the last item on that line and press the RETURN key. You can then continue on the next line. After all names and aliases have been entered, press the RETURN key. The program then prompts you for another alias.

20. Repeat steps 17 and 18 for all remaining user aliases in your list. When you have given all aliases, press the RETURN key. The program displays a list of all aliases and their users and asks if you wish to make corrections.

21. Enter y, if you wish to enter all aliases again. Otherwise, enter n, to complete the installation.

Once you direct netutil to complete the installation, it copies the information you have supplied to the network files, displaying the name of each file as it is updated. Once the files are updated, you may use the save option to copy the Micnet files to floppy disk.

12.3.2 Saving the Micnet Files

You can save copies of the Micnet files on backup media (floppy disk) or hard disk with the save option of the netutil program. Saving the files allows you to transfer them to the other computers in the network. Before you can save the files to a floppy you need to format a floppy disk (see the section "Formatting Floppy Disks" in "Using Floppy Disks and Tape Drives"). Saving the files to the hard disk enables you to use uucp(C) to transfer the files to other machines.

To save the files, follow these steps:

1. Log in as the super user.

2. Enter:

   netutil

   Press the RETURN key. The program displays the network utility menu.
3. Enter "2", and press the RETURN key. The program displays the message:

```
Save to /dev/fdx (yes/no)?
```

where \( x \) is a drive number.

4. If you wish to use the specified disk drive, insert a blank, formatted floppy disk into the drive, wait for the drive to accept the disk, then enter "yes", and press the RETURN key. If you do not wish to use the drive, enter "no", and press the RETURN key. The program displays a prompt asking you for the filename of the disk drive (or file) you wish to use. Insert a blank, formatted disk into your chosen drive, wait for the drive to accept the disk, then enter the filename of the drive. The name of the default backup device (disk drive) is specified in the file /etc/default/micnet. This device can be changed depending on system configuration.

In either case, the program copies the Micnet files to the floppy disk.

5. Remove the floppy disk from the drive. Using a soft tip marker (do not use a ball point pen), label the disk "Micnet disk".

As soon as all files have been copied, you can transfer them to all computers in the network.

### 12.3.3 Restoring Micnet Files

The last step in building a Micnet network is to copy the Micnet files from the Micnet disk to all computers in the network. Do this with the restore option of the netutil program. For each computer in the network, follow these steps:

1. Log in as the super user.

2. Enter:

   ```
   netutil
   ```
Press the RETURN key. The program displays the network utility menu.

3. Enter the number 3, and press the RETURN key. The program displays the message:

   Restore from /dev/fdx (yes/no)?

where \( x \) is the number of a drive.

4. If you wish to use the specified disk drive, insert the Micnet disk into the drive, wait for the drive to accept the disk, then enter “yes” and press the RETURN key. If you do not wish to use the drive, enter “no” and press the RETURN key. The program displays a prompt asking you for the filename of the disk drive you wish to use. Insert the Micnet disk into your chosen drive, wait for the drive to accept the disk, then enter the filename of the drive.

In either case, the program copies the network files to the appropriate directories, displaying the name of each file as it is copied. Finally, the program displays the message:

Enter the name of this machine:

5. Enter the machine name of the computer you are using and press the RETURN key. The program copies this name to the new /etc/systemid file for the computer. If necessary, it also disables the serial lines to be used on the computer, preparing them for use with the network.

When the files have been copied, you may start the network with the start option.
12.4 Starting the Network

Once the Micnet files have been transferred to a computer, you can start the network with the **start** option of the **netutil** program. The **start** option starts the Micnet programs which perform the tasks needed to communicate between the computers in the network.

To start the network, follow these steps for each computer in the network:

1. Log in as the super user.

2. Enter:

    netutil

    Press the RETURN key. The system displays the network utility menu.

3. Enter "4", and press the RETURN key. The program searches for the `/etc/systemid` file. If it finds the file it starts the network. If it does not, it prompts you to enter the machine name of the computer and then creates the file. The program also asks if you wish to log errors and transmissions. In general, these are not required except when checking or testing the network. When starting the network for the first time, enter `n` in response to each question and press the RETURN key.

Once the network has started, you may move to the next computer and start the network there.

Note that, for convenience, you can let each computer start the network automatically whenever the system itself is started. Simply include the command:

    netutil start

in the system initialization file, `/etc/rc`, of each computer. To add this command, use a text editor as described in the section "Changing the `/etc/rc File" in the "Preparing XENIX for Users" chapter. You can add the `-x` or `-e` options to this command line if you wish to log transmissions or errors. Even if you do not use these options, Micnet copies a log in and log out message to the system *LOG* file each time you start and stop the network. This means you need to periodically clear the file. See the section "Clearing Log Files" in the "Using Filesystems" chapter.
12.5 Testing a Micnet Network

After you have started a network for the first time, you should test the network to see that it is properly installed. In particular, you must determine whether or not each computer is connected to the network.

To test the network, you need to know how to use the `mail(C)` command (see the "Mail" chapter in the XENIX User's Guide). The following sections explain how to test the network and how to correct the network if problems are discovered.

12.5.1 Checking the Network Connections

You can make sure that all computers are connected to the network by mailing a short message to `all` (the alias for all users in the network) with the `mail` command. Follow these steps:

1. Choose a computer.
2. Log in as the super user.
3. Use the `mail` command (see the XENIX User's Guide) and the `all` alias to mail the message:

   Micnet test

   to all users in the network.

4. Check the mailboxes of each user in the network to see if the message was received. To check the mailboxes, log in as the super user at each computer and use the `cat` command to display the contents of each user's mailbox.

   The name of each user's mailbox has the form:

   `/usr/spool/mail/login-name`

   where `login-name` is the user's login name.

The network is properly installed when all users have received the message. If the users at one or more computers fail to receive the message, the computers are not properly connected to the network. To fix the problem, you need to locate the computer which has failed to make a connection. The next section explains how to do this.
12.5.2 Using the LOG File to Locate a Problem

You can locate a problem with connections by examining the LOG files on each computer in the network. The LOG files contain records of the interaction between each pair of computers. There are two LOG files for each pair of computers (one file on each computer). The LOG files on any given computer are kept in subdirectories of the /usr/spool/micnet directory. Each subdirectory has as its name the machine-name of the other computer in the pair. You can examine the contents of a LOG file by entering:

```
cat /usr/spool/micnet/remote/machinename/LOG
```

and pressing the RETURN key. The machine-name must be the name of a computer that is paired with the computer you are using.

Each LOG file should contain a “startup message” which lists the name of each computer in the pair, and the serial line through which the pair is connected. It also shows the date and time at which the network was started. The message should look like:

```
daemon.mn: running as MASTER
Local system: a
Remote system: b, /dev/tty52
Tue Sep 24 22:30:35 1985
```

A startup message is added to the file each time the network starts successfully. If the message is not present, one or more of the network files and directories cannot be found. Make sure that you have used the restore option to transfer all the network files to the computer. Also, make sure that the /etc/systemid file contains the correct machine name for the given computer.

Each LOG file contains a “handshake” message if the connection between the computer pair has been established. The message:

```
first handshake complete
```

is added to the file on a successful connection. If the message is not present, make sure that the network has been started on the other computer in the pair. The network must be started on both computers before any connection can be made. If the network is started on both computers but the handshake message does not appear, then the serial line may be damaged or improperly connected. Check the serial line to make sure that the cable is firmly seated and attached to the correct RS-232
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connectors on both computers. If necessary, replace the cable with one known to work.

If both the startup and handshake messages appear in the LOG file but the network is still not working, then there is a problem in transmission. You can create a record of the transmissions and errors encountered while transmitting by restarting the network and requesting Micnet to log all transmissions and errors. Just enter y (for "yes") when the start option asks if you wish to log errors or transmissions.

Error entries contain the error messages generated during transmission. Each message lists the cause of the error and the subroutine which detected the error. For example, the message:

    rsync: bad Probe resp: 68

shows that the rsync subroutine received a bad response (character 68 hexadecimal) from the other computer. You may use this information to track down the cause of the problem. One common problem is stray information being passed down the serial line by electronic noise. Make sure that the serial line's cable is properly protected against noise (for example, that the cable does not lie near any electric motor, generator, or other source of electromagnetic radiation). Also make sure the cable is in good condition.

Transmission entries contain a record of normal transmissions between computers. Each entry lists the direction, byte count, elapsed time, and time of day of the transmission. For example, the entry:

    rx: 29349b 2:22 @16:22

shows that 29349 bytes were received (rx) at 16:22. The elapsed time for the transmission was 2 minutes and 22 second. You can use the records to see if messages are actually being transmitted.

12.5.3 Stopping the Network

You can stop the network with the stop option of the netutil program. This option stops the Micnet programs, stopping communication between computers in the network.

To stop the network, follow these steps on each computer in the network:
1. Log in as the super user.

2. Enter:

\texttt{netutil}

Press the RETURN key. The program displays the network utility menu.

3. Enter "5", and press the RETURN key. The program stops the network programs running on the computer.

\section*{12.5.4 Modifying the Micnet Network}

You can modify a Micnet network at any time by changing one or more of the Micnet files. You can reinstall the network with the \texttt{netutil} program. For very small changes (for example, correcting the spelling of an alias), you can modify the Micnet files directly with a text editor. The files and their contents are described in detail in the (M) section of the \textit{XENIX User's Reference}.

Before making any changes to a file, a copy should be made. You can make a copy with the \texttt{cp} command. You can replace an old file with the updated file using the \texttt{mv} command. Once one or more files have been changed on one computer, the files must be transferred to the other systems in the network using the \texttt{save} and \texttt{restore} options. These options can only be used after you have stopped the network.

Note that changes to the \texttt{aliases} file are not incorporated into the system until the \texttt{aliashash} program is executed. This program produces the \texttt{aliases.hash} file needed by the network to resolve aliases. See \texttt{aliashash(ADM)} in this guide for a description of this command.

\section*{12.6 Using a UUCP System}

You can send and receive mail from other Micnet sites by installing a UUCP system on one computer in your site. A UUCP system is a set of \textit{XENIX} programs that provide communication between computers using ordinary telephone lines.

To use a UUCP system with your Micnet network, follow these steps:

1. Install a UUCP system on one computer in the Micnet site. Installation of a uucp system requires a modem and the UUCP software
Building a Local Network With Micnet

provided with the XENIX Operating System. See the "Building a Remote Network with UUCP" chapter in this Guide for complete details.

2. Add the entry:

```
uucp:
```

to the *maliases* file of the computer on which the UUCP system is installed.

3. For all other computers in your site, add the entry:

```
uucp:machine-name:
```

to the *maliases* file. The *machine-name* must be the name of the computer on which the UUCP system is installed. One may also use the longer form of entry on the computer on which the uucp system is installed.

You can test the uucp system by mailing a short letter to yourself via another site. For example, if you are on the site "chicago", and there is another Micnet site named "seattle" in the system, then the command:

```
mail seattle!chicago!johnd
```

sends mail to the "seattle" site, then back to your "chicago" site, and finally to the user "johnd" in your Micnet network. Note that a UUCP system usually performs its communication tasks according to a fixed schedule, and may not return mail immediately.
Chapter 13

XENIX Directories

and Special Device Files

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13.1 Introduction

This chapter lists the most frequently used files and directories in the XENIX system. Many of these files and directories are required for proper XENIX operation and must not be removed or modified. The following sections briefly describe each directory.

This chapter also contains information needed to create device nodes relating to filesystems and terminals. For a full description of the special files mentioned here, see section (HW) of this guide.

13.2 XENIX Directories

The following subsections discuss each of the main directories of the XENIX Operating System.

13.2.1 The Root Directory

The root directory (/) contains the following system directories:

/bin  XENIX command directory
/dev  Device special directory
/etc  Additional program and data file directory
/lib  C program library directory
/mnt  Mount directory (reserved for mounted filesystems)
/usr  User service routines (may contain user home directories)
/tmp  Temporary directory (reserved for temporary files created by programs)

All of the above directories are required for system operation.

The root directory also contains a few ordinary files. Of these files, the most notable is the xenix file which contains the XENIX kernel image.

13.2.2 The /bin Directory

The /bin directory contains the most common XENIX commands, that is, the commands likely to be used by anyone on the system. The following is a list of a few of the commands:
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<table>
<thead>
<tr>
<th>basename</th>
<th>echo</th>
<th>passwd</th>
<th>su</th>
</tr>
</thead>
<tbody>
<tr>
<td>cp</td>
<td>expr</td>
<td>rm</td>
<td>sync</td>
</tr>
<tr>
<td>date</td>
<td>fsck</td>
<td>sh</td>
<td>tar</td>
</tr>
<tr>
<td>dump</td>
<td>login</td>
<td>sleep</td>
<td>restor</td>
</tr>
<tr>
<td>dumpdir</td>
<td>mv</td>
<td>stty</td>
<td>test</td>
</tr>
</tbody>
</table>

These commands and all others in the /bin directory are required.

### 13.2.3 The /dev Directory

The /dev directory contains special device files which control access to peripheral devices. All files in this directory are required, and must not be removed. There are several subdirectories to the /dev directory. Each of these subdirectories holds special device files related to a certain type of device. For example, the /dev/dsk directory contains device files for floppy and hard disks. The files in these directories are linked to the device files that exist in /dev. You can access the same device through the file in /dev or the file for the same device in a subdirectory of /dev.

The following is a list of the files:

- /dev/console: System console
- /dev/dsk/0s0: Entire disk on drive 0
- /dev/dsk/0s1: First disk partition on drive 0
- /dev/dsk/0s2: Second disk partition on drive 0
- /dev/dsk/1s0: Entire disk on drive 1
- /dev/dsk/1s1: First disk partition on drive 1
- /dev/dsk/1s2: Second disk partition on drive 0
- /dev/dsk/f0d9d: 48tpi floppy device
- /dev/dsk/f0d9dt: 48tpi entire disk floppy device
- /dev/dsk/f0q15d: 96tpi floppy device
- /dev/dsk/f0q15dt: 96tpi entire disk floppy device
- /dev/rdsk/f0d9d: raw 48tpi floppy device
- /dev/rdsk/f0d9dt: raw 48tpi entire disk floppy device
- /dev/rdsk/f0q15d: raw 96tpi floppy device
- /dev/rdsk/f0q15dt: raw 96tpi entire disk floppy device
- /dev/lp: Lineprinter
- /dev/kmem: Kernel virtual memory
- /dev/mem: Physical memory
- /dev/mt/0m: Magnetic tape device
- /dev/mt/0mn: Magnetic tape device (no rewind)
- /dev/null: Null device (used to redirect unwanted output)
XENIX Directories and Special Device Files

/dev/rmt0 Raw magnetic tape device (linked to /dev/rmt/Om)
/dev/rmt/0m Raw magnetic tape device
/dev/rmt/0mn Raw magnetic tape device (no rewind)
/dev/rnn Unbuffered interface to corresponding device name
/dev/root Root file structure
/dev/swap Swap area
/dev/ttynn Terminals
/dev/tty The terminal you are using

13.2.4 The /etc Directory

The /etc directory contains miscellaneous system program and data files. All files are required, but many may be modified.

The following program and data files must not be removed or modified:

/etc/mnttab Mounted device table
/etc/mount For mounting a file structure
/etc/mkfs For creating a file structure
/etc/init First process after boot

The following data files may be modified, if desired. No files may be removed.

/etc/passwd Password file
/etc/rc Bootup shell script
/etc/ttys Terminal set up
/etc/termcap Terminal capability map
/etc/motd Message of the day
The data files in the directory `/etc/default` contain default information which is used by system commands (see `default(F)`). The following data files may be modified. No files may be removed.

<table>
<thead>
<tr>
<th>File</th>
<th>Utility</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>/etc/default/archive</code></td>
<td><code>sysadmin(ADM) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/backup</code></td>
<td><code>backup(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/boot</code></td>
<td><code>autoboot(ADM) information</code></td>
</tr>
<tr>
<td><code>/etc/default/cron</code></td>
<td><code>cron(C) default logging information</code></td>
</tr>
<tr>
<td><code>/etc/default/dumpdir</code></td>
<td><code>dumpdir(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/format</code></td>
<td><code>format(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/filesys</code></td>
<td><code>sysadmin(ADM) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/login</code></td>
<td><code>login(M) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/lpd</code></td>
<td><code>lp(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/mapchan</code></td>
<td><code>mapchan(M) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/micnet</code></td>
<td><code>micnet(M) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/mkuser</code></td>
<td><code>mkuser(ADM) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/msdos</code></td>
<td>Location of DOS disks (A:, B:,....)</td>
</tr>
<tr>
<td><code>/etc/default/passwd</code></td>
<td><code>passwd(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/restor</code></td>
<td><code>restore(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/su</code></td>
<td><code>su(C) default information</code></td>
</tr>
<tr>
<td>(Note that you must create this file yourself.)</td>
<td></td>
</tr>
<tr>
<td><code>/etc/default/tar</code></td>
<td><code>tar(C) default information</code></td>
</tr>
<tr>
<td><code>/etc/default/usemouse</code></td>
<td><code>usemouse(C) default information</code></td>
</tr>
</tbody>
</table>

13.2.5 The `/lib` Directory

The `/lib` directory contains runtime library files for C and other language programs. The directory is required.
13.2.6 The /mnt Directory

The /mnt directory is an empty directory reserved for mounting removable filesystems.

13.2.7 The /tmp Directory

The /tmp directory contains temporary files created by XENIX programs. The files are normally present when the corresponding program is running, but may also be left in the directory if the program is prematurely stopped. You may remove any temporary file that does not belong to a running program.

13.2.8 The /usr Directory

The /usr directory contains the home directories of all users on the system. It also contains several other directories which provide additional XENIX commands and data files.

The /usr/bin directory contains more XENIX commands. These commands are less frequently used or considered nonessential to XENIX system operation.

The /usr/include directory contains header files for compiling C programs.

The /usr/lib directory contains more libraries and data files used by various XENIX commands.

The /usr/spool directory contains various directories for storing files to be printed, mailed, or passed through networks.

The /usr/tmp directory contains more temporary files.

The /usr/adm directory contains data files associated with system administration and accounting. In particular, the /usr/adm/messages file contains a record of all error messages sent to the system console. This file is especially useful for locating hardware problems. For example, an unusual number of disk errors on a drive indicates a defective or misaligned drive. Since messages in the file can accumulate rapidly, the file must be deleted periodically.
### 13.3 Log Files

A variety of directories contain log files that grow in size during the normal course of system operation. Many of these files must be periodically cleared to prevent them from taking up valuable disk space (see the section on “Clearing Log Files” in the “Using Filesystems” chapter). The following table lists the files (by full pathname) and their contents.

<table>
<thead>
<tr>
<th>Filename</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>/etc/ldate</td>
<td>Records date of each backup.</td>
</tr>
<tr>
<td>/usr/adm/pacct</td>
<td>Records accounting information; grows rapidly when process accounting is on. (See <code>accton(ADM)</code> and <code>acctcom(ADM)</code>.)</td>
</tr>
<tr>
<td>/usr/adm/messages</td>
<td>Records error messages generated by the system when started. (See <code>messages(M)</code>.)</td>
</tr>
<tr>
<td>/etc/wtmp</td>
<td>Records user logins and logouts. (See <code>login(M)</code>.)</td>
</tr>
<tr>
<td>/usr/adm/sulog</td>
<td>Records each use of the <code>su</code> command; grows only if option is set in the <code>/etc/default/su</code> file. You must create <code>/etc/default/su</code>. (See <code>su(C)</code>.)</td>
</tr>
<tr>
<td>/usr/lib/cron/cronlog</td>
<td>Records each use of the <code>at(C)</code> and <code>cron(C)</code> commands.</td>
</tr>
<tr>
<td>/usr/spool/micnet/remote/*/LOG</td>
<td>Records transmissions between machines in a Mic-net network. The (*) must be the name of a remote machine connected to the current machine.</td>
</tr>
</tbody>
</table>
13.4 Special Device Files

Many of the filesystem maintenance tasks described in this guide require the use of special filenames, block sizes, and gap and block numbers. The following sections describe each in detail.

13.4.1 Special Filenames

A special filename is the name of the device special block or character I/O file, which corresponds to a peripheral device, such as a hard or floppy disk drive. These names are required in such commands as `mkfs(ADM)`, `mount(ADM)`, and `df(C)` to specify the device containing the filesystem to be created, mounted, or searched.

The following table lists the special filenames and corresponding devices, for hard and floppy disk drives on a typical computer.

<table>
<thead>
<tr>
<th>Filename</th>
<th>Disk Drive</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/fd0</td>
<td>Floppy Drive 0</td>
</tr>
<tr>
<td>/dev/dsk/f0</td>
<td>Floppy Drive 0</td>
</tr>
<tr>
<td>/dev/fd1</td>
<td>Floppy Drive 1</td>
</tr>
<tr>
<td>/dev/dsk/f1</td>
<td>Floppy Drive 1</td>
</tr>
<tr>
<td>/dev/hd00</td>
<td>Entire hard disk</td>
</tr>
<tr>
<td>/dev/dsk/0s0</td>
<td>Entire hard disk</td>
</tr>
<tr>
<td>/dev/root</td>
<td>Root filesystem</td>
</tr>
<tr>
<td>/dev/usr</td>
<td>User filesystem</td>
</tr>
</tbody>
</table>

13.4.2 Block Sizes

The block size of a disk is the number of blocks of storage space available on the disk, where a block is typically 512 or 1024 bytes of storage. Refer to the `machine(HW)` manual page or use `cmchk(C)` to determine the size of blocks on your system. Many commands require input that defines the number of blocks to be operated on. Other commands report disk space in terms of 512 byte blocks, in particular `df(C)`, `du(C)`, `ls(C)`, `lc(C)`, and `find(C)`. A 500 byte file on a 1024 byte block filesystem is reported as using 2 blocks by these utilities, as the file uses one system block which is equivalent to two 512 byte blocks. The size of a 10 megabyte hard disk in
1024 byte blocks is 9792. Note that some of the blocks on the disk are reserved for system use and cannot be accessed by user programs. The block size of a typical floppy disk depends on the total storage capacity of the disk, as given by the manufacturer.

### 13.4.3 Gap and Block Numbers

The gap and block numbers are used by the `mkfs(ADM)`, and `fsck(ADM)`, commands to describe how the blocks are to be arranged on a disk. The following table lists the gap and block numbers for the floppy and hard disks used with a typical computer.

<table>
<thead>
<tr>
<th>Disks</th>
<th>Gap</th>
<th>Block</th>
</tr>
</thead>
<tbody>
<tr>
<td>Floppy Disk, 48ds9</td>
<td>1</td>
<td>9</td>
</tr>
<tr>
<td>Floppy Disk, 96ds15</td>
<td>1</td>
<td>15</td>
</tr>
<tr>
<td>Floppy Disk, 135ds9</td>
<td>1</td>
<td>9</td>
</tr>
<tr>
<td>Floppy Disk, 135ds18</td>
<td>1</td>
<td>18</td>
</tr>
<tr>
<td>Hard Disk</td>
<td>1</td>
<td>34</td>
</tr>
</tbody>
</table>

The number of blocks can also be determined by multiplying the number of sectors per track (usually 17) by the number of heads on the hard disk, dividing by 2 (since there are 2 blocks per sector), and rounding off to the nearest integer.

### 13.4.4 Terminal and Network Requirements

The `enable` and `disable` commands are used to add and remove terminals on a system. The `install` option of the `netutil` program is used to build a network. The preceding commands and option require the names of the serial lines through which a terminal or network is to be connected. The following table lists the device special filenames of the two serial lines (actually two serial ports either with or without modem control). The character I/O files corresponding to these serial lines can be found in the `/dev` directory. Note that the files `/dev/console` and `/dev/tty01` through `/dev/tty12` represent "hardwired" devices and are not available for connection to terminals or hardware. Also, refer to `serial(HW)` for more information on serial lines.
### XENIX Directories and Special Device Files

<table>
<thead>
<tr>
<th>Filename</th>
<th>Line</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/tty1a</td>
<td>main serial line (without modem control)</td>
</tr>
<tr>
<td>/dev/tty2a</td>
<td>alternate serial line (without modem control)</td>
</tr>
<tr>
<td>/dev/tty1A</td>
<td>main serial line (with modem control)</td>
</tr>
<tr>
<td>/dev/tty2A</td>
<td>alternate serial line (with modem control)</td>
</tr>
</tbody>
</table>
Chapter 14

Using Terminals and Modems

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14.1 Introduction

One important task of the system administrator is to add peripheral devices such as terminals and modems to the system. Adding these serial devices lets more users access the system and adds to overall system capabilities.

This chapter explains the following tasks:

- Physically connecting serial devices to your computer
- Enabling serial devices for operation
- Maintaining serial devices

Note that physical connections between a device and the system vary according to hardware configuration. For specific information about connecting your serial device, refer to the hardware manuals provided with the device and with your computer.

14.2 Using Multiscreen™

With Multiscreen, you can use your console as several terminals at one time. Pressing a simple key combination switches you from one screen to another, with each screen acting as an independent terminal.

Because each multiscreen is independent, you can log in and run programs on each screen. Because output from your programs is saved in a screen buffer, you see the most recent output for whichever screen you look at. If you stop output to one screen, as when you press the Ctrl-S key combination, only that screen is affected.

The amount of memory in your computer determines the number of multiscreens available on your system. When you boot your system, the number of automatically-enabled multiscreens is displayed. Most machines have between two and six multiscreens enabled, but your machine can have up to twelve if your system has sufficient memory. To increase the number of multiscreens on your system, add to your system’s memory; XENIX automatically enables more screens.

Although all of the multiscreens can be open and active at once, you see only one screen at a time. The selected multiscreen is like a terminal that is “connected” to the keyboard. Switching between screens is like moving to another terminal because each multiscreen has its own device file.
The multiple screen feature uses the /dev/tty[01...12] device files. These files provide character I/O between your system and your computer screen and keyboard.

To select any active screen, press alt-Fn, where Fn is one of the function keys on your keyboard. Function keys are generally located across the top or down the far left side of the keyboard. The tty01 is the ‘‘alt-f1’’ terminal, tty02 is the ‘‘alt-f2’’ terminal, tty03 is ‘‘alt-f3’’, etc. For example, this keystroke switches you to screen 6, corresponding to /dev/tty06:

alt-F6

You can also rotate through the screens by pressing the Control and Print Screen key combination, Ctrl-PrtSc (using the Ctrl key and the PrtSc key). Use this combination to access screens for which you do not have function keys: For example, if you have twelve multiscreens enabled, but your computer keyboard has only ten function keys, display screen eleven by pressing alt-F10 to get to screen 10, and then pressing Ctrl-PrtScr to rotate to screen 11. To access screen 12, press Ctrl-PrtScr again. Pressing Ctrl-PrtScr again rotate your back to the first multiscreen, tty01.

For more information, refer to multiscreen(M) and screen(HW).

14.3 Adding and Configuring Serial Ports

To add a multi-port expansion card, you must first determine whether the card is a ‘‘smart’’ serial card or a standard serial card. If the card is a ‘‘smart’’ card, the manufacturer will have supplied installation software and a driver. These should be all you need to add the card to your XENIX system.

Before installing your card, look through the ‘‘Using Bus Cards’’ chapter in this guide for information you might find helpful and check your XENIX Release Notes for information about hardware compatibility with XENIX. Follow the instructions for insertion furnished with your card, referring to your computer hardware manual if necessary.

If your card is a standard serial card, the following instructions explain how to create new device files for additional ports.

1. Boot the system and enter system maintenance mode.
2. When you are in system maintenance mode, enter:

```
/etc/mkdev serial
```

δ `sysadmsh` users select: System→Add→Card_Serial

3. This invokes `serinit`, which begins with the following display:

```
You would like to install a:
1. 1 port card
2. 4 port card
3. 8 port card

Select an option or enter 'q' to quit:
```

Enter the appropriate number and press RETURN.

4. The program responds with the following menu (only COM1 and COM2 appear on most systems):

```
The card is configured as:
1. COM1
2. COM2
3. COM3
4. COM4

Select an option or enter 'h' for help or 'q' to quit:
```

If you select "h", you see a table listing ports, card types, I/O addresses, and status addresses.

Enter a number and press RETURN. After `serinit` accepts the COM slot, you see a list giving the newly configured ports and their modem control counterparts. For example, tty2a and tty2A refer to the same serial port, but tty2A has modem control, whereas tty2a refers to the same port without modem control. You can access the port by only one name at a time, either with or without modem control.

Now that your serial ports are configured, make sure that they are also defined in the XENIX system hardware configuration.

Check your computer hardware manual to determine how your system is configured. If your system is configured using a CMOS database, the ports are defined in the database (see `cmos(HW)`).
If your system is configured with switch settings on the main system board, define the new ports by setting the proper switches (refer to your hardware manuals for the settings).

Note

An error message is displayed if you attempt to access a serial port that has not been installed and defined.

14.4 Setting Up a Serial Console

You can configure a serial device, rather than a display adapter, as your system console. The boot program sets the default console at boot time according to the following procedure:

1. The boot program looks for the entry SYSTTY=x (replace x with the name of the system console device) in the /etc/default/boot file.

2. If the SYSTTY entry is not found or the /etc/default/boot file is not readable, boot checks your system for a display adapter and designates it as your system console.

3. If no display adapter is found, boot looks for tty1a, sets the serial port to 9600 baud, 8 data bits, 1 stop bit, and no parity, and uses it as the system console.

To set up a serial console, create the following entry in your /etc/default/boot file (replace x with '0' for a display adapter or with '1' for a COM1 serial port):

SYSTTY=x

To change the system console device from the command line, enter systty=x at the boot prompt (replace x with '0' for a display adapter or with '1' for a COM1 serial port). This does not create or change a SYSTTY entry in the /etc/default/boot file.
14.5 Adding a Terminal

Before you add a terminal to your system, look in the hardware manual for your terminal for instructions on connecting the terminal to a serial line. Also, refer to the list of standard serial lines in the "XENIX Directories and Special Device Files" chapter to find the name of your serial line. (If you add a serial card, the possible names of the additional device files are listed in `serial(HW)` in this guide.)

To add a terminal to your system, connect it to an RS-232 serial line and enable it with the `enable(C)` command.

XENIX is compatible with many types of terminals. Look in the `terminals(M)` section of the `XENIX User's Reference` for a comprehensive list of terminals supported by XENIX. Support for terminals is provided through the `/etc/termcap` file, which contains the definitions and classifications of keystrokes and control sequences that vary from terminal to terminal. For a description of the `/etc/termcap` file, see `termcap(M)` in the `XENIX User's Reference`.

The following steps show how to install a terminal with the standard "COM" serial lines, or with serial expansion cards:

1. This step is for serial expansion cards. If you are adding a terminal directly to a COM port, skip to the next step.

   If you are using a supported 4 or 8-port expansion board, check to see if your board is recognized at bootup by checking the XENIX bootup message. If the boot process does not accurately report your board, then the switches on your card are not set properly. Check your board's hardware documentation for the proper switch settings and the XENIX `Release Notes` for the correct addresses. This applies to boards that are listed as supported in the `Release Notes`.

   Vendor-supplied drivers may not print a recognition message at boot time. If your serial expansion card is a "smart" card with a vendor-supplied driver, you should not need to run `mkdev serial` to install it. For your system to recognize the new card, run the vendor-supplied installation software.

   Configure the interrupts for the two standard COM ports - COM1 as interrupt 4 and COM2 as interrupt 3. Most serial cards use one interrupt per board, so two four-port boards can use COM1 and COM2. Be aware of the requirements of other products and hardware to avoid interrupt conflicts. See `serial(HW)` in this guide for more information on COM1 and COM2.
When a supported card is correctly configured for the desired COM port and recognized at bootup, run this command:

```
/etc/mkdev serial
```

\[ \text{sysadmsh users select: System→Add→Card_Serial} \]

This creates device files for your extra serial ports.

2. Make sure you are logged in as root in multi-user mode.

Plug in your terminal and turn it on. Set it for 9600 baud, 8 data bits, 1 stop bit, no parity, full duplex, and XON/XOFF handshaking. If your terminal does not work in this mode, look for advice on configuring your terminal in the section "Changing the gettydefs File" later in this chapter and in the \[\text{stty(C)}\] page in the \[\text{XENIX User’s Reference}\].

Some terminals connect with a straight cable directly to the computer. Other terminals connect to a modem. Terminals connected to a modem use a "null modem" or "modem connector," - a cable with pins 2 and 3 crossed. Connect the terminal so that Transmit Data on the serial port is connected to Receive Data on the terminal, and Transmit Data on the terminal is connected to Receive Data on the serial port. Signal Ground should be connected to Signal Ground. Other pins probably do not need to be connected. XENIX requires only that pins 2, 3, and 7 are connected.

For more information on your terminal, refer to your terminal manual or a reference on serial communication.

3. If the port is enabled, press the RETURN key a few times to see if a "login:" prompt appears. If so, you are ready to log in. If not, use the console or a working terminal to log in as the super-user (root), and disable the port with this command:

```
disable ttyname
```

In the previous command, \textit{ttyname} is the device special name of the port in question. Make sure you are using a non-modem control device, for example, /dev/tty1a, not /dev/tty1A. For more information on serial port names, see \textit{serial(HW)}, in this guide and the section "Adding and Configuring Serial Ports" in this chapter.
4. Check that the entry for this serial port in the /etc/ttys file looks like the following (ttyname is the name of the device file, for example /dev/tty1a):

0mttynamel

If the entry does not look like this example, edit the file to correct it. The first digit in each field is a 0 or a 1, depending on whether the device is disabled or enabled. A 0 means the device is disabled; a 1 means the device is enabled.

5. From the console, as root, see if you can redirect output to the terminal by entering:

```
date > /dev/ttyname
```

If you do not see the date printed on the terminal and you are not sure of the correct ttyname, try other ttynames on that serial port. If you still do not see the date printed on the terminal, there try the following:

- Make certain that the terminal is plugged in.
- Check that the cable is configured correctly. If the serial port you are using has a 25-pin connector (DB-25), read through Step 2 in the preceding set of instructions. Are pins 2, 3, and 7 connected correctly? (Note that pins other than 2, 3, and 7 are probably not used.)

If your system or expansion card has a 9-pin connector (DB-9), you must use a 9-pin to 25-pin connector. Look in your hardware manual for information on 9-pin to 25-pin connections.

- Check your terminal setup configuration. See Step 2 in the preceding set of instructions.
- Check the switches on your serial port. If you are using a multi-port card, try other lines on that card.
- Attach the terminal to a standard serial port (COM1 or COM2) to see if the terminal and cable are working correctly. If you are already using a COM port, try switching to another one.

If you have successfully installed another terminal, switch hardware between the working and the nonworking terminal one piece at a time. This may help you isolate a hardware
problem. Note that some faulty hardware may work under DOS but not under XENIX.

6. When you the date prints on your terminal, enable the port with the following command:

```
enable ttyname
```

The `enable` command starts a `getty` process that displays the following login prompt:

```
login:
```

If you do not see the "login:" prompt, enter the following command to verify that `getty` is running on the port and that the software is configured properly:

```
ps -t ttyname
```

Your screen should display a message similar to the one in the following example, with either "login" or "getty" listed in the "COMMAND" column:

```
PID    TTY  TIME  COMMAND
2557   la   0:06  getty
```

7. If you have typed the `enable` and `disable` commands many times, it is possible that a new `getty` cannot be spawned on that port. If so, shut the system down, reboot, login as "root" in multiuser mode, and try again.
14.6 Setting Terminal Lines

Your XENIX system can automatically adapt to several different terminal baud rates and settings. The same program that displays the login message, getty(M), reads these terminal line values from a table, trying each setting until one is successful, and the user can log in to the system. This table provides several default settings for different kinds of terminal lines.

On your XENIX system, getty automatically executes as part of the login process. The table of terminal settings is found in a file called /etc/gettydefs. You can edit gettydefs to add different sets of terminal characteristics or to change the existing ones.

14.6.1 The gettydefs File

The file /etc/gettydefs contains the information that getty uses to set up terminal line characteristics such as baud rate. The file is in the form of a table. Each table entry is divided into five fields. These fields include:

\[
\text{label} \# \text{initial-flags} \# \text{final-flags} \# \text{login-promp} \# \text{next-label} \# \text{login program}
\]

The fields are:

- **label**: Identifies the gettydefs entry to getty. This could be a number or a letter. label corresponds to the line mode field in /etc/ttyys. init passes the line mode to getty as an argument.

- **initial-flags**: Sets terminal line characteristics when getty first establishes the connection. getty recognizes the flags listed in termio(M), in the XENIX User's Reference. Often the only flag in this field is the one setting the baud rate. For example, B300 would set the speed to 300.

- **final-flags**: Sets the terminal line characteristics just before getty executes login. These flags describe the operating characteristics for the line. The baud rate (B) is set again. Other common flags include SANE (a composite flag that sets a number of terminal characteristics to reasonable values), TAB3 (expands tabs with spaces), IXANY (enables any character to restart output), and HUPCL (hangs up line on final close). Flags can be entered in any order.
**login-prompt**

Contains the login message that greets users. This field is printed exactly as it is entered, including spaces and tabs. An "@" symbol in the login-prompt field is expanded to the first line in the file `/etc/systemid` (unless the '@' is preceded by a '\').

Several character sequences are recognized, including:

- \n: Line feed
- \t: Tab
- \r: Carriage return
- \f: Form feed
- \v: Vertical tab
- \b: Backspace
- \nnn: (3 octal digits)

The specified ASCII characters

**next-label**

Identifies the next label in `gettydefs` for `getty` to try if the current one is not successful. `getty` tries the next label if a user presses the BREAK key while attempting to log in to the system. Groups of entries, such as dial-up or TTY lines, should form a closed set so that `getty` cycles back to the original entry if none of the entries is successful.

**login-program**

The name of the program which actually logs users onto XENIX. The default program is `/etc/login`. This field is optional and is specific to XENIX.

If preceded by the keyword "AUTO," `getty` does not prompt for a user name, but instead uses the device name (i.e. tty03) as the user name and immediately executes the `login-program`.

Each field is separated by a pound sign (#), and each entry in `gettydefs` is separated by a blank line.

An entry in `gettydefs` might look like the following:

```
4# B1200 # B1200 SANE TAB3 HUPCL #login: #2 #AUTO /etc/login.new
```

Here is a description of each part of this line:

- The number 4 identifies this entry to `getty`.
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- The next field sets the baud rate to 1200.
- The third field indicates the baud rate (B1200), SANE (a composite flag for a number of characteristics), and HUPCL (hangs up line on final close).
- login: appears as the login prompt. If this setting is not successful, getty proceeds to label 2 in gettydefs.
- AUTO attempts to log in the user by executing /etc/login.new.

If the last entry also contains a filename, that login program is executed. (Note that the filename and the corresponding login program are user created.) For example, including a file such as /etc/dial_login for a line connected to a modem can be used. It would set the user ID, acquire a password, validate the user, and then become the user. It could possibly require a password for the system in addition to an account password and even have a special set of login environment variables included in /etc/default/dial_login.

14.6.2 Changing the gettydefs File

The file /etc/gettydefs is on your XENIX system and has sets of entries for the dial-up lines and terminal lines. These different sets correspond to line mode settings in /etc/ttys. The init program passes the line mode as an argument to getty.

You can edit gettydefs to add new terminal settings or to change existing ones. For example, the settings for terminal lines on your XENIX system might look like the following:

```
4 # B2400 HUPCL # B2400 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 5
5 # B4800 HUPCL # B4800 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 6
6 # B9600 HUPCL # B9600 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 4
```
To change the sample `gettydefs` file so that the first baud rate `getty` attempts is 1200, do the following:

1. Enter a text editor to edit the first line of the file `gettydefs`.
2. Change the first and third fields from B2400 to B1200.
3. Save `gettydefs` and exit the editor.

The sample file should look like the next example:

```
4 # B1200 HUPCL # B1200 CS8 SANE HUPCL TAB3 ECHO IXANY #\n@!login: # 5
5 # B4800 HUPCL # B4800 CS8 SANE HUPCL TAB3 ECHO IXANY #\n@!login: # 6
6 # B9600 HUPCL # B9600 CS8 SANE HUPCL TAB3 ECHO IXANY #\n@!login: # 4
```

You can also add additional terminal line settings to `gettydefs`. Flags and permissible values for terminal settings are listed in `stty (C)`, in the *XENIX User's Reference*.

When you add a new entry, be sure that the groups of entries in `gettydefs` form a closed set, so the `next-label` field of the last entry directs `getty` back to the first entry in the group.

To add an entry for a baud rate of 300 to the preceding sample `gettydefs` file, follow these steps:

1. Enter a text editor to edit the file `/etc/gettydefs`.
2. Locate the point where you want to insert the new settings for `gettydefs`. The order of the entries does not matter; `getty` only looks for the label. In this example, the new entry is the last entry in the file.
3. Insert a carriage return after the last line in the file and enter the following on a new line:
   ```
   #B300 HUPCL # B300 CS8 SANE HUPCL TAB3 ECHO IXANY #\n@!login: # 4
   ```
4. To incorporate label 7 into the set of labels, change the `next label` field for entry 6 to 7:
   ```
   6 # B9600 HUPCL # B9600 CS8 SANE HUPCL TAB3 ECHO IXANY
   #\n@!login: # 7
   ```

   `getty` is now directed from label 6 to 7, and then back to 4.
Using Terminals and Modems

5. Exit the text editor, saving the revised `gettydefs` file.

The new `gettydefs` looks like the following:

4 # B1200 HUPCL # B1200 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 5
5 # B4800 HUPCL # B4800 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 6
6 # B9600 HUPCL # B9600 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 7
7 # B300 HUPCL # B300 CS8 SANE HUPCL TAB3 ECHOE IXANY #\n@!login: # 4

14.6.3 Checking the Terminal Settings

Each time you change the terminal line settings or add new entries to `gettydefs`, you should check to make sure that the new values make sense to `getty`. To do this you use the command `getty` with the check option, `-c`, and the filename.

For example, to check `gettydefs`, enter:

```
getty -c /etc/gettydefs
```

If any of the values and settings in `gettydefs` are not permitted, `getty -c` displays them on your terminal screen.

For more information on `getty` and `gettydefs`, see `getty(M)` and `gettydefs(F)`, in the `XENIX User's Reference`.

14.7 Changing Serial Line Operation

Whenever you enable a terminal with the `enable` command, the system automatically sets the operating characteristics of the serial line to a set of default values. Sometimes these values do not match the values used by the terminal and, therefore, must be changed to allow communication between the system and the terminal. You can display and change the operating characteristics of a serial line with the `stty` (for "setty") command.
You can display the current operating characteristics of a serial line by entering this command at the terminal connected to that line:

```
stty
```

If it is impossible to log in at that terminal, you can use another terminal to display the characteristics. Log in as the super-user at another terminal, and enter:

```
stty < ttyname
```

In the previous command, `specialfile` is the name of the device special file corresponding to the serial line (see the "XENIX Directories and Special Device Files" chapter). For example, this command displays the current characteristics of the serial line named `/dev/tty1a`:

```
stty < /dev/tty1a
```

The command displays the baud rate, the parity scheme, and other information about the serial line. This information is explained in the `stty(C)` in the XENIX User's Reference.

One common change to a serial line is changing the baud rate. This is usually done from a terminal connected to another serial line because changing the rate disrupts communication between the terminal and system. Before you can change the rate, you need to know the current baud rate of the terminal (review the terminal hardware manual to see how to determine the current baud rate). Once you have the baud rate, log in as the super-user at the other terminal, and enter:

```
stty baud-rate < specialfile
```

where `baud-rate` is the current baud rate of the terminal, and `specialfile` is the name of the device special file corresponding to the serial line you wish to change. The baud rate must be in the set 50, 75, 110, 134, 150, 200, 300, 600, 1200, 2400, 4800, and 9600. For example, the command:

```
stty 9600 < /dev/tty1a
```

changes the baud rate of the serial line `/dev/tty1a` to 9600. Note that the "less than" symbol (`<`) is used for both displaying and setting the serial line from another terminal.
Another common change is changing the way the system processes input and output through the serial line. Such changes are usually made from the terminal connected to the serial line. For example, the command:

```
stty tabs
```
causes the system to expand tabs with spaces (used with terminals which do not expand tabs on their own), and the command:

```
stty echo
```
causes the system to remove a deleted character from the terminal screen when you back over it with the BACKSPACE key.

Note that the `stty` command may also be used to adapt a serial line to an unusual terminal, to another type of serial device which requires parity generation and detection, or special input and output processing.

For a full description of this command, see `stty(C)` in the XENIX User's Reference.

### 14.8 Setting the Terminal Type

The XENIX system requires that the terminal type be clearly defined before any work is done at the terminal. The preferable method for setting your terminal type is to assign the type to the `TERM` variable, a special environment variable that associates the terminal you are using with a list of characteristics given in the `/etc/termcap` file. The characteristics tell the system how to interpret your terminal's keys and how to display data on your terminal screen.

If you are using the Bourne shell (sh), the `TERM` assignment has the form:

```
TERM=termtype; export TERM
```

If you are using the C-shell (csh), the `TERM` assignment has the form:

```
setenv TERM termtype
```

The `termtype` must be one of the names associated with one of the terminals defined in the `/etc/termcap` file. The assignment must be entered at the terminal whose type you are setting.
For example, to set the terminal type to "ansi" from Bourne shell, go to the terminal you wish to set, enter at the shell prompt ("$"):

```
TERM=ansi; export TERM
```

and press the RETURN key. From C-shell, enter at the shell prompt ("%"):

```
setenv TERM ansi
```

and press RETURN.

If you are not sure which name you may use for termtype, you can view the names by displaying the /etc/termcap file. To display the file, enter:

```
cat /etc/termcap
```

and press the RETURN key. Because the file is large, use Ctrl-s to stop the display at every full screen. You may view more of the file by pressing Ctrl-q or the SPACEBAR.

You can let the system define the terminal type automatically whenever you log in by including the TERM assignment in your .profile file (see "Changing the .profile and .login Files" in the "Preparing XENIX for Users" chapter).

For an alternate method of setting your terminal type see tset(C) in the XENIX User's Reference.

If you let the system set the terminal type, be careful when logging in on terminals that are not the same as your normal terminal. The XENIX system has no way of checking whether or not the terminal assignment is correct for the given terminal and assumes that it is the same as your normal terminal. If it is not, you must set the terminal type manually.

### 14.9 Setting the Terminal Type Automatically

If you want to have the terminal type set automatically at login time, follow this procedure:

1. Login on the terminal in question and determine which ttynname you're using by entering:

   ```
   tty
   ```

2. Login as root and edit the file /etc/ttytype with a text editor. Change the terminal type field for the line associated with the terminal in question to the terminal type you desire to use. Follow the model for
the console. If you want your terminal type to be set to ‘wy50’ for 
/dev/ttyla, edit /etc/ttytype as follows:

wy50 ttyla

3. Then the user’s start up file must be edited with the appropriate 
tset(C) command line to automatically set the terminal type. In each 
C-shell user’s .login file, add the following line:

tset -s -Q >/tmp/tset$ ; source /tmp/tset$ ; /bin/rm /tmp/tset$

Be sure the remove the default setenv(C) command line involving
TERM and TERMCAP from the .login file.

In each Bourne Shell user’s .profile, add the following line:

eval ‘tset -s’

Be sure to remove the existing tset command line from the .profile
file.

4. Have each user log out, then log in again to test the new terminal type
change. After they log in, have them verify the new termtype by
entering:

   env

14.10 Removing a Terminal

From time to time it may be necessary to remove a terminal from the system,
for example, if you wish to replace it with some other device. Before you can
remove a terminal, you must disable it with the disable(C) command.

To remove a terminal, follow these steps:

1. Turn off the power to the terminal.

2. Log in as the super-user at another terminal.

3. Use the disable command to disable the terminal. The command has
the form:

   disable ttyname

where special file is the name of the serial line to which the terminal is
attached. For example, the command:
disable /dev/tty1a

disables the terminal connected to serial line /dev/tty1a.

4. Disconnect the terminal from the system.

The serial line previously connected to the terminal is now free to accept another device.

When using the disable command, make sure that you wait a full minute between each use of the command. Failure to do so can cause a system crash.

14.11 Modem Usage under XENIX

14.11.1 Serial Lines

XENIX supports modem control on serial ports. The following device names refer to the serial ports with and without modem control.

<table>
<thead>
<tr>
<th>Device</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/tty1a</td>
<td>main serial adapter without modem control.</td>
</tr>
<tr>
<td>/dev/tty1A</td>
<td>main serial adapter with modem control.</td>
</tr>
<tr>
<td>/dev/tty2a</td>
<td>alternate serial adapter without modem control.</td>
</tr>
<tr>
<td>/dev/tty2A</td>
<td>alternate serial adapter with modem control.</td>
</tr>
</tbody>
</table>

/dev/tty1a and /dev/tty1A refer to the same serial port (likewise for /dev/tty2a and /dev/tty2A). The operating system uses different device-driver subroutines for each. Never attempt to use both modem and non-modem control ports at the same time or you will see the warning:

cannot open: device busy

For systems including multi-port serial cards, the devices /dev/tty[1,2][a-m] refer to use without modem control, and the devices /dev/tty[1,2][A-M] refer to use with modem control.
14.11.2 Dialing Out From Your Computer

The cu(C) and uucp(C) utilities are used to call remote systems and transfer data under XENIX. The file /usr/lib/uucp/Devices (referred to as Devices) contains information used by these programs to determine the characteristics of a particular serial line.

The Devices file contains lines which specify the device for the line, the call-unit associated with the line, and the baud rate, that are to be used by UUCP. (Modem control devices should be used with lines connected to modems.)

Using Dialer Programs

For dialing, both cu and UUCP use a common set of dialers, which can be standalone binaries (programs) like /usr/lib/uucp/dialHA12, or entries from the file /usr/lib/uucp/Dialers. (For more information on Dialers file entries, see the “Building a Remote Network with UUCP” chapter in this guide.)

The source for several dialer programs and a makefile for recompiling the source program are included in the directory /usr/lib/uucp. If you have any other kind of modem, you can modify any of the source files and create your own dialer program. Note that you must have the XENIX Development System installed to compile a program.

To make a new dial program, follow these steps:

1. Change directory to /usr/lib/uucp with the following command:
   
   cd /usr/lib/uucp

2. Edit the file makefile in the directory /usr/lib/uucp and find the line that reads:
   
   EXES= dialHA12 dialHA24 dialTBIT dialVA3450

   and add the name of the dialer program you wish to use. When this is done, exit the file, saving the changes you have made.

3. Next, enter the command:
   
   make

   to your shell prompt and press RETURN.
4. When the **make** command is finished, you have a new dialer program. This can be used in the fifth field of an entry in the *Devices* field.

When you are hooking up your modem, or any other device, make sure that serial wires connected to your computer are not left hanging. An unterminated line connected to your computer can considerably reduce system performance. Unplug a modem wire at the computer. Three-wire cables are not sufficient when using modems. Several other pins must be connected for the modem to operate properly. If you are unsure as to what to use, a ribbon cable that connects all pins will work correctly.

### 14.11.3 Installing a Dial-out Modem

1. Make sure the UUCP package is installed. Use **custom**(ADM) to install if necessary.

2. Make sure the serial port you have chosen for your dial-out modem is recognized at boot up and, if the modem is internal, make sure the COM port the internal modem is configured for does not conflict with any other device. Only serial devices attached to COM1 and COM2 are supported.

3. Make sure the port is disabled by entering:

   ```
   disable ttyname
   ```

4. Connect the modem to the machine using a straight-through cable (pins 2 & 3 not crossed). The cable must have at least pins 2, 3, 7, 8, and 20 connected.

   Most standard COM boards use straight through cables, but some hardware requires a null-modem cable (pins 2 & 3 crossed). A standard COM board is known as DTE, a board that needs a null-modem cable is known as DCE. Check your hardware documentation if you are not sure. If the COM board is a DCE, you will need a null-modem cable.

5. Add the correct entry to the `/usr/lib/uucp/Devices` file. This file has one line for each different dial-out port.
6. Enter the following command to establish UUCP as the owner of the port you have selected:

   `chown uucp /dev/ttynname`

7. Test the dial-out modem. To test the modem’s ability to dial correctly use the following command:

   `cu -s1200 -l ttynname dir`

where `ttynname` is the device name of the modem control port where you attached the modem. You should see a message indicating that you are connected. If you do not see such a message, either the `cu` command is incorrect, the `Devices` file is incorrect or the serial port is not operating correctly.

---

Note

The instructions that follow assume a Hayes-compatible command set and response codes. Other modems may use other conventions.

If you do see a message confirming your connection, enter

   `AT`

on your keyboard. “OK” should be echoed back onto your computer screen. If the modem is set to return result codes as numeric codes rather than text, you will see a 0. If this does not occur, check that the “send” light on the modem flashes when you press a key. This indicates the modem is receiving signals from the keyboard. If this light is not flashing, check your cable and modem switch settings. If the “send” light flashes, but you still don’t get an “OK” response from the modem, try entering

   `ATE1`

at your computer keyboard to enable the modem’s echo capability.

If you get the expected responses, you can dial out by entering

   `ATDT phonenumber`
or you can exit cu by entering:

and then press RETURN.

8. You are now ready to dial another XENIX/UNIX system. If you have any problems, refer to the next section on troubleshooting your dial-out modem. If the line is also to be used for dial-in, follow the additional steps specified in “Installing a Dial-in Modem” in this chapter.

14.11.4 Troubleshooting Your Dial-out Modem

The examples below assume a modem attached directly to COM1. Other serial ports are often used. If you have problems, first verify that the phone jack is plugged in and you have a dial tone on the phone line.

1. **Problem:** In testing the modem connection with the command:

   cu -s1200 -l tty1A dir

   I get a connected message but when I type “AT” there is no “OK” message.

   **Remedy A:** Check the cable and modem switch/software settings. If using a straight through cable try a null modem cable using at least pins 2, 3, 7, 8 and 20. If the “send” light flashes, try using ATE1 to turn on the modem’s echo capability.

   **Remedy B:** The modem may be defective. If this is the case, check your hardware documentation for an appropriate repair facility.

2. **Problem:** Modem dials but call never connects.

   **Remedy A:** The phone number may be incorrect or not operational. The phone line to which the modem is attached may be faulty.

   Try dialing the number from a telephone to make sure you get a modem on the other end of the line. Use the same phone line you are using for the modem.

   **Remedy B:** Try adding pauses to your telephone number. A hyphen is used to indicate a pause of two seconds, for example: “9----458--1234”.

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Listen carefully to the calling sequence to make sure the modem is pausing at the right moments. Check your hardware documentation to assure that you are using the right code to indicate a pause.

3. **Problem:** In dialing out you see the message:

   **Connect failed: NO DEVICES AVAILABLE**

   **Remedy A:** There is no entry in the *Devices* file for the modem port.

   **Remedy B:** The modem port in *Devices* does not have the correct baud rate associated with it.

4. **Problem:** Modem answers but I get garbage characters on my terminal.

   **Remedy A:** The remote computer is at a different baud rate. If you are dialing in to another XENIX system, send a break signal to cause the remote site to switch baud rates during the login sequence. Always have XENIX start at the highest baud rate and move down as necessary. Enter:

   \`
   ^%b
   \`

   **Remedy B:** The site you are calling may be set to different data bit and parity values than you are using. By default *cu* uses 8 data bits, and no parity. Use *cu -e* for 7 data bits, even parity, and *cu -o* for 7 data bits, odd parity.

   **Remedy C:** There may be noise on the line. This becomes more acute when operating at 2400 baud or higher. Check your phone line.

5. **Problem:** My modem does not hang up at the end of a call.

   **Remedy A:** A non-modem control port is being used. Change the non-modem control serial port you specify to the corresponding modem control port. For example, the modem control port associated with tty1a is ttylA.

   **Remedy B:** The modem is not lowering the CD line when the call is disconnected. Check the modem switches to verify that the modem is set to follow the incoming carrier or, if this is a Hayes 2400 or compatible modem, use the AT&C1 command.

   **Remedy C:** The modem is not set to watch DTR. Check the modem switches to verify that the modem is set to watch DTR or, if this is a Hayes 2400 modem, use the AT&D2 command.
14.11.5 Dialing Into Your Computer Under XENIX

To allow dialing into your computer, you must enable a serial line that recognizes modem control signals, with the `enable(C)` command. When using the `enable` command, make sure that you wait a full minute between each use of the command. Failure to do so may send too many signals to the `init(C)` program, which will then terminate. If `init` terminates, no new logins are possible.

To use the main serial adapter, enter:

```
disable tty1a
enable tty1A
```

Or, for the the alternate serial adapter, enter:

```
disable tty2a
enable tty2A
```

Note that tty1A and tty1a refer to the same (main) serial line, and tty2A and tty2a refer to the same (alternate) serial line. Do not use the same line in both its modem and non-modem modes at the same time as this will cause an error.

14.11.6 Installing a Dial-in Modem

The following procedure provides step by step instructions for installing a modem for dial-in operation. (Passwords are recommended for dial-in lines; refer to the section on "Adding Dial-in Password Protection" in the "Maintaining System Security" chapter for details.)

1. Follow the steps for installing a modem for dial-out. This ensures that you have a working hardware connection.

2. Some modems have switches or software commands for setting the modem configuration. If your modem has such settings, configure it as follows, following the instructions in your modem manual.
Using Terminals and Modems

Note

If the modem is to be shared between dial-in and dial-out, the next step can be omitted. Initialization to dial-in is performed whenever the system comes up, or a dial-out completes (getty runs the dialer program with the -h option, or uses an &chat entry from the Dialers file, to reinitialize the modem.

3. Set the modem to automatically answer the phone when a call comes in.

Most internal modems do not have auto-answer and some external modems do not have this setting. If this is the case, place the following line in your /etc/rc file.

(stty 1200; echo "ATS0=1\r" > /dev/ttyla) < /dev/ttyla

"tty1a" should be changed to match the non-modem control device the modem is connected to. "1200" should be changed to the highest baud rate used by the modem. "ATS0=1" is the command to put Hayes compatible modems into autoanswer mode. The "\r" is needed to send a carriage return signal to the modem to terminate the command line.

4. Set up your modem so that it does not answer when the DTR line is not active and it disconnects from the current connection when DTR goes from active to inactive.

5. The CD line should follow the incoming carrier, i.e. low when a carrier is present, high when a carrier is not present.

6. Set up your modem so that it does not echo commands or display responses.

7. Make sure the port is disabled by entering the command:

   disable ttyname

   Where ttyname is the non-modem control port.

8. Select the desired gettydefs entry in the /etc/ttys file. Entry "2" will select the 1200-2400-300 cycle.
9. Enable the port you are using for your modem with the following the command:

   \texttt{enable \texttt{ttyname}}

   Where \texttt{ttyname} is the modem control port.

10. Dial this modem from another modem.

11. If you are unable to successfully dial-in, see the next section on trouble shooting your dial-in modem.

### 14.11.7 Troubleshooting Your Dial-in Modem

The examples below assume that your modem is attached directly to the COM1 port. In practice, a modem may be attached to other serial ports.

1. **Problem:** Modem is not answering phone.

   **Remedy A:** The modem serial port is not enabled.

   Enter the following command:

   \texttt{enable /dev/tty1A}

   **Remedy B:** The modem is not configured to auto-answer.

   Check your modem switches or, if this is a Hayes 2400 modem, use the appropriate modem software command. Enter \texttt{“cu \texttt{-ltty1A dir}”} to the modem and use the command \texttt{“ATS0=1”} to set auto-answer.

   **Remedy C:** The DTR line is not connected from the computer to the modem.

   Check Pin 20 and make sure it is connected. Pins 2, 3, 7, 8, and 20 are used for modem hookup.

2. **Problem:** Modem answers, but hangs up immediately upon connection.

   **Remedy:** The modem is set to autoanswer and to watch the DTR line, but the DTR line is not asserted. Check the following possibilities:
a) The modem control port may not be enabled. Enter the command:

```
enable /dev/tty1A
```

b) The cable is incorrect.

If you are using a straight through cable with at least pins 2, 3, 7, 8 and 20 connected, check that pin 20 (DTR) is properly connected.

3. Problem: I see the error message “Garbage or loose cable on /dev/tty1A, port shut down” on my console when a call comes in to my modem.

Remedy: Your modem is set to echo back data or send responses to commands.

It is very likely that the modem is sending a “RING” signal to indicate that the phone you are calling is ringing. Since the CD signal is not active, getty interprets this as random data on the serial line. To correct this, set the modem to turn off echo and not to send command responses. The proper Hayes 2400 modem command is “ATE0Q1”.

4. Problem: The modem answers, but I get no login prompt.

Remedy A: The CD line is not being asserted by the modem after the modem has answered the phone.

Check the switches on your modem or, if this is a Hayes 2400 modem, use the appropriate modem software command.

Remedy B: The port is not enabled. Enter the command:

```
enable /dev/tty1A
```

Remedy C: An incorrect `/etc/gettydefs` entry is being used and is selecting the wrong baud rate.

Check the modem port device in the `/etc/ ttys` file. It will appear similar to the following example:

```
12tty1A
```

The first digit is a 0 or 1 depending on whether the device is disabled or enabled. A 0 means the device is disabled, and a 1 means the device is enabled. The second character is a pointer to an entry in the `/etc/gettydefs` file. Check the baud rate and serial line characteristics of this entry.
5. **Problem:** The screen scrolls when I log in.

**Remedy:** The modem and non-modem devices are both enabled.

Disable the non-modem device by entering the command:

`disable /dev/ttyla`

6. **Problem:** I get a login prompt but nothing coherent afterward.

**Remedy:** The line settings are incorrect.

Check the `/etc/ttys` file to verify that the "pointer" into the `gettydefs` file is correct. Chances are that the serial line characteristics don't match between the `stty` settings defined in the third field of the selected `gettydefs` entry. Try changing the terminal's setup to 8 data bits, one stop bit, and no parity.

### 14.11.8 Shared Dial-in/Dial-out

XENIX supports the use of dial-in and dial-out on the same modem line, without having to disable the login.

When a dial-out program is using the line, the login will be disabled. If someone is logged in on a line when a dial-out program attempts to use it, the dial-out program will fail to lock the device.

For this feature to work correctly, the modem control device must be used, and the modem must set CD to high when a carrier is present and low when a carrier is not present. (For information on using dial-in/dial-out in conjunction with `uucp`, refer to the "Building a Remote Network with UUCP" chapter in this guide.)

### 14.11.9 Installing A Shared Dial-in/Dial-out Modem

The following procedure allows you to install a shared dial-in/dial-out modem.

1. Perform the steps of installing a modem for dial-out, and those for installing a dial-in.

2. To dial out, simply invoke `cu`. The getty will automatically be suspended for the call out, and restarted when the call is completed.
14.11.10 Hayes Modem Settings

Proper modem configuration is necessary when using cu and uucp. Modem settings differ for each modem. Consult your modem manual for the proper switch settings.

Smartmodem 1200

If you have a Hayes Smartmodem 1200 or compatible, switches 3 and 8 should be down:

<table>
<thead>
<tr>
<th></th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>up</td>
<td></td>
<td></td>
<td>•</td>
<td>•</td>
<td>•</td>
<td>•</td>
<td>•</td>
<td></td>
</tr>
<tr>
<td>down</td>
<td></td>
<td>•</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>•</td>
</tr>
</tbody>
</table>

When switch 3 is down, the resulting codes will be sent to, (echoed by), the modem to the terminal or computer. When switch 8 is down, the modem is able to interpret the command being issued. This allows both the XENIX and DOS communications systems to work.

Smartmodem 2400

The Hayes 2400 Smartmodem or compatible modem requires on-line configuration if it is to be used as a dial-in line. Note that the Hayes 2400 does not answer the phone with a 2400 baud carrier if it is not set up with 2400 baud commands. You must configure the modem by issuing set up commands via cu(C). The form of the cu command is:

```
cu -s2400 -l ttyn dir
```

*nn* is the "tty" number of the serial line. To configure a modem on tty1A, enter this command and press RETURN:

```
cu -s2400 -l tty1A dir
```

Next, enter the following commands to configure the modem. They will be saved in the modem's non-volatile memory. If you do not want to save the settings, do not enter the last command (at&w). Commands are in the left column and short descriptions of what they do are in the right column. Follow each command with a RETURN:
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- AT&f Fetch factory configuration.

ATT Tone dialing.

ATI0 Low speaker volume.

AT&d2 Set dtr '"2': go on hook when dtr drops.

AT&c1 Set dcd '"1': dcd tracks remote carrier.

ATs0=1 Answer phone after 1 ring (AA light should come on).

- ATs2=128 Disable modem escape sequence.

ATE0 No echo (modem will no longer echo what is sent to it).

ATq1 Quiet mode (modem will not respond with 'OK' after this command or any that follow).

AT&w Saves settings in non-volatile memory.

Exit from cu by entering a 'tilde' and a 'period', followed by a RETURN:

The modem is now configured and ready for use.
Chapter 15
Using Printers

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15.1 Introduction

Printers are a highly important attachment to any computer system. Most systems require the ability to print out data on paper. XENIX supports a wide variety of printing hardware. Some lineprinters are parallel devices, but most will be connected as serial devices.

To add a printer, the system administrator must:

- Connect the physical hardware to the computer, then
- Use the correct system commands to enable the printer for operation.

This chapter explains how to do this and how to maintain printers once they are added.

Note that physical connections between a printer and the system vary depending on hardware configuration. This chapter provides some information about making the necessary physical connections, but for more information about these connections, see the hardware manuals provided with the printer and your computer.

XENIX supports serial printers that use the standard RS-232 interface. To find out if your printer uses this interface, check your hardware documentation. XENIX also supports RTS/CTS protocols.

15.2 The Printer Spooling System

The XENIX lineprinter spooling system is a collection of commands that help you, as system administrator, to efficiently install, monitor, and control the lineprinters serving your system. A request to print a file is "spooled" or queued with other printing jobs to be sent to the printer. Each print job is processed and waits its turn in line to be printed, thus the term "queue." When a user requests a file to be printed using the `lp(C)` command, the lineprinter system responds with a "request ID." This consists of the name of the printer on which the file will be printed and a unique number identifying the file. With this request ID, the user can find out the status of the print request or cancel it. The `lp` options help the user to easily control printer output.
There are several terms used to describe the line printer system:

**device**
The target for `lp` output. It can be a hard-wired printer, a terminal that is sometimes used as a printer, or a regular file. A device can be represented by a full XENIX path-name.

**printer**
The name assigned by the system administrator to represent a device. This name can have up to 14 characters. At different times, a printer may be associated with different devices.

**class**
An ordered list of printers. Print requests sent to a class of printers are printed by the first available member of that class.

**destination**
A destination is where print requests are sent. A destination can be a class or a printer.

Consult your computer and lineprinter hardware manuals for information on making the connection between your system and printing devices.

### 15.3 Installing a Printer

This section instructs you how to install new printing devices on your XENIX system. You must connect the printer to a proper port, (serial port for serial printers, parallel port for parallel printers) ensure that it works, and set up the XENIX printer spooling software using the `mkdev lp` command. Follow the steps below to install a printer:

1. Find a place for your printer and make sure that it is properly assembled and plugged in to a power outlet.

2. **If you are connecting a serial printer:** connect the RS-232 cable from your computer serial port to the port on your printer. Serial printers must be capable of supporting XON/XOFF or DTR protocols and must be configured for those protocols. Next, enter the following command substituting the correct port number for `nn`:

   ```
   disable /dev/tty\nn
   ```
and press **RETURN**. This disables logins on the port you have connected to your printer and allows the port to be used for serial communication.

3. **If you are connecting a parallel printer:** The printer must use a standard Centronics interface cable. The parallel port on a monochrome card should be configured for interrupt vector 7, and is recognized as **lp1** when booting up. The main parallel port should be configured for interrupt vector 7 and is recognized as **lp0**. So you must use either the main or the monochrome port - not both - to avoid a hardware conflict. The alternate/second parallel port should be configured for interrupt vector 5, and recognized as **lp2**. Make sure no other hardware is using these interrupts. (See your hardware manual for information on configuring your parallel ports.)

4. Verify that you have correctly hooked up the printer by sending data directly to the device. Enter one of the following commands:

   **For serial printers:**
   
   ```bash
   date > /dev/ttyyn
   ```
   
   where *nn* is the number of the serial port you are using (for example, `/dev/ttyla`).

   **For parallel printers:**
   
   ```bash
   date > /dev/lpn
   ```
   
   where *n* is the number of the parallel port you are using (for example `/dev/lp0`).

5. If you do not see the date printed on your printer, there is most likely some type of hardware malfunction, so verify the following:

   **For parallel printers:**
   
   - Make certain your cable is securely connected and all wires are good. Using the cable on a known good system, or printing under DOS are good ways to test this.
   - Re-check your printer configuration by verifying its switches in your printer hardware manual.
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- Re-check the switches on your parallel card. It must also be recognized at bootup. You can verify this by rebooting your system and looking for the following message:

  Parallel port lpn present

For serial printers:

- Make certain you are using the non-modem control device, for example: /dev/tty1a, not /dev/tty1A. (For more information on the naming convention for serial ports, see serial(HW) in this guide.) Try using a cable with only pins 2, 3 and 7 connected.

- Re-check your printer configuration by verifying its switches in your printer hardware manual.

- Re-check your switches on your serial port. If you are using a multi-port card, try other lines on that card and be sure it does not conflict with the standard COM ports.

- Try attaching the printer to a standard serial port, COM1 or COM2, to see if the printer and cabling is correct.

6. Once you have the printer correctly hooked up and responding, you are ready to run `mkdev lp`. You must know the port you are using or the XENIX pathname of the device (for example, /dev/tty1a) and the lineprinter interface program you are going to use. A model interface program is supplied with your XENIX system. For more information on printer interface programs, see "Printer Interface Programs."

7. `mkdev lp` prompts you with a series of questions. For most of them you need to supply your own answers, entering the information as you are prompted. When you are prompted for the printer name, however, you are given a default name option. If you wish to choose the default answer, simply press the RETURN key. If you make a mistake while responding to the questions, just press the DELETE key or the INTERRUPT key and start again.
Using Printers

Enter the following command:

\texttt{mkdev lp}

\texttt{\Delta sysadmsh} users select: System\rightarrow Add\rightarrow Printer

8. If the scheduler is running you are reminded that any jobs which are printing may be interrupted and you are prompted if you want to continue.

9. The following menu is displayed:

\begin{itemize}
  \item Do you wish to:
  \begin{itemize}
    \item 1 - Add a new printer.
    \item 2 - Remove a printer.
    \item 3 - Reconfigure an existing printer.
    \item 4 - Assign a default printer.
    \item 5 - Print lp status information.
  \end{itemize}
\end{itemize}

Select an option or enter q to quit:

Enter 1 and press \texttt{RETURN}.

10. Next you see the following menu:

\begin{itemize}
  \item 1. Parallel Printer
  \item 2. Serial Printer
  \item 3. Remote Printer
\end{itemize}

Select the type of printer you are adding or enter q to return to the previous menu:

11. A list of available parallel or serial devices is displayed.

Enter your choice and press \texttt{RETURN}.

12. The following message is displayed:

Enter a name for the printer, press \texttt{<RETURN>}
to use the default name (printer) or enter q to return to the previous menu.
Printer names can be up to 14 characters long and can be any combination of numbers, letters, or underscore characters. Enter the printer name and press the RETURN key.

13. If you specified that you are adding a remote printer, you now see the following messages and you are prompted to answer questions about the remote printer. If you specified Serial or Parallel you will not see these messages. For remote printers, you see:

```
Enter the node name of the remote computer to which your printer is connected or enter q to return to the previous menu:
```

Next you see:

```
Enter the name of the printer you wish to use on node_name or enter q to return to the previous menu:
```

Next you see the message:

```
Is node_name connected via (M)icnet or (U)ucp?
```

Enter "M" or "U" depending on the network your system uses. Next you see:

```
Is your remote printer an Imagen laser printer?
```

Once you have answered these questions for your remote printer, you see the "Printer enabled and accepting request" message described below. You do not see the other messages described here for serial and parallel printers. Note that this is to set up printing from a remote machine. You must also run `mkdev lp` for the printer locally on the machine where it is physically connected.
14. The following message is displayed:

If you have an unusual printer you must create an interface program in /usr/spool/lp/model. For a sample interface program look at /usr/spool/lp/model/dumb.

15. Now you are prompted for a printer type. The screen displays a numbered list of the available printer types on your system, followed by these instructions:

Enter one of the interface programs above or the full pathname of an interface program or enter q to return to the previous menu:

Enter one of the options, then press RETURN.

16. After you have finished responding to these questions, the following message is displayed:

destination printernamew now accepting requests
printer printernamenow enabled

printernamew is then automatically enabled and is ready accept print requests.

17. After enabling the printer, you are prompted to respond to one more question:

Is this the default printer? (y/n)

You can enter y (for yes) or n (for no) depending upon whether you want user print requests to be automatically routed to the printer.
18. One last message is displayed:

If you need to modify your interface program after installing it, the installed version is in /usr/spool/lp/interface/printername.

After you have responded to these questions, `lpsched'(ADM) is automatically started, and users can begin printing files on the new printer.

You can also add printers to your system using the `lpadmin'(ADM) command. However, you will need to give separate commands to stop `lpsched', to enable the printer, and to allow it to accept print requests. For more information on these programs and commands, see sections "Stopping the Print Spooling Daemon," "Controlling Print Requests," and "Enabling and Disabling Printers."

15.4 Stopping the Print Spooling Daemon: `lpsched'

The spooling daemon, `lpsched', routes print requests through the correct printer interface program and then to the lineprinter. No printing can be done on your system unless `lpsched' is running. The program `lpsched' starts automatically each time your XENIX system is restarted. Sometimes it is necessary to stop `lpsched', especially if you want to reconfigure printers or if you want to add new printers using the `lpadmin' command (`mkdev lp' automatically stops and restarts `lpsched').

This section explains how to find out whether or not `lpsched' is running, how to stop and restart it, and how to recreate it if necessary.

To find out whether or not `lpsched' is running, you use the `lpstat'(C) command:

`lpstat -r'

A `sysadmsh' users select: System→Report→Printers

The system responds with a message indicating whether `lpsched' is either running or not.
To shutdown the scheduler, `lpsched`, enter:

```
/usr/lib/lpshut
```

`lpsched` stops running and all printing stops as well. Printing requests stopped in the middle of printing reprint when `lpsched` starts again.

After you have finished configuring the printers, you should restart `lpsched`. To do this, enter:

```
/usr/lib/lpsched
```

`lpstat -r` should confirm that `lpsched` is running.

Each time `lpsched` sends a print request to an interface program, it records an entry in a log file, `/usr/spool/lp/log`. The entry includes the user name, the request ID, the name of the printer the request will be printed on, and the date and time requested. `lpsched` also records any error messages in this file. After you have stopped `lpsched`, the log file is renamed `/usr/spool/lp/oldlog` and `lpsched` starts a new log file. Requests waiting to be printed before `lpsched` was stopped may have an entry in both log files.

For more information on `lpsched`, see `lpsched(ADM)` in this guide.

### 15.5 Creating an Init Device File

The standard parallel printer devices (`/dev/lp`, `/dev/lp0`, `/dev/lp1`, and `/dev/lp2`) send a printer initialization string (`init`) the first time the device is opened after the system starts up. This is done on the first open only so that printers with large text buffers will not be flushed by the sending of another file.

Some parallel printers require initialization every time a file is received for printing. Others require an `init` if the printer is turned off and back on again (for example, after changing paper or ribbons). The symptom of this situation is that the printer works fine until it is turned off and then back on.

If you need to initialize the printer more often than the standard devices provide, you can create an additional device file for the parallel port in use. This “init device file” can be used when necessary to initialize the printer.

1. Log in as superuser.

2. Determine which device is the parallel port you are using. This example assumes the device is the main parallel port (`/dev/lp0`).
3. Use \texttt{mkdev lp} to associate one of the parallel \textit{init} devices (lp0i, lp1i, lp2i) with the printer (select option 3: "reconfiguring an existing printer").

If your printer needs an \textit{init} when it is turned off and on, use the following command line after the printer is turned on. Initialize the printer before the first file is sent to the printer (this example assumes the main parallel port):

\begin{verbatim}
> /dev/lp0i
\end{verbatim}

If your printer needs an \textit{init} every time a file is sent (and it doesn’t have a large internal text buffer) you can use the \texttt{/dev/lp0i} device all the time.

The \texttt{lp(C)} command now sends an \textit{init} every time a file is sent to the printer.

Some printers do not have newline/carriage return mapping. If your printer needs to have newlines mapped to newline/carriage returns, specify the \texttt{crnlmap} filter when you set up the printer using the \texttt{mkdev lp} command. When you are prompted for the type of printer (dumb printer, Imagen laser printer (parallel interface), Imagen laser printer (serial interface), or other), enter "other". You are then prompted for the pathname of the interface program. The printer filter file is found in \\
\begin{verbatim}
/usr/spool/lp/model/crnmap
\end{verbatim}

\subsection*{15.6 Moving Requests Between Printers: lpmove}

You can move print requests between printing destinations by using the command \texttt{lpmove}. This command does not move print requests while the scheduler, \texttt{lpsched}, is running. To stop \texttt{lpsched}, see "Stopping the Print Spooling Daemon." \texttt{lpmove} will move individual print requests by request ID, or all requests waiting to be printed on a particular printer.

For example, to move a request with a request ID of \texttt{quick-532} to a printer named \texttt{slow}, enter:

\begin{verbatim}
/usr/lib/lpmove quick-532 slow
\end{verbatim}

The print request now has a new request ID: \texttt{slow-532}.

To move all requests on a printer named \texttt{quick} to \texttt{slow}, enter:

\begin{verbatim}
/usr/lib/lpmove quick slow
\end{verbatim}

For more information on \texttt{lpmove}, see \texttt{lpsched} (ADM), in this guide.
15.7 Controlling Print Requests: accept

The accept command allows printers or classes of printers to accept print requests made with the lp command. You can allow a printer to accept requests after it has been properly configured. The printer, however, will not begin printing the requests until the enable command is given. If you added a printer to your system using the mkdev lp command, these steps were automatically performed. For information on enable, see "Enabling and Disabling Printers."

For example, to have print requests accepted for a class of printers named class1, enter:

```
/usr/lib/accept class1
```

If you want to prevent requests from being routed to a printer, you can use the reject command. The -r options allows you to send users a message explaining why a printer is out of service.

For example, to prevent printing requests, from being routed to a printer, printer4, because of repairs, enter:

```
/usr/lib/reject -r"printer4 needs repair" printer4
```

A user who requests a file to be printed on printer4 will receive the following message:

```
lp: can not accept requests for destination "printer4"
--printer printer4 needs repair
```

To find out the acceptance status of printing destinations, enter:

```
lpstat -a
```

For more information on lpstat, see "Finding Out the Status of a Print Request" in the "Working with Files and Directories" chapter of the XENIX Tutorial. For more information on accept/reject, see accept(C), in the XENIX User's Reference.
15.8 Canceling a Print Request

To cancel a printout you have requested, use the `cancel(C)` command. When you request a printout, XENIX responds and displays a request ID for your job. For example, if you send a job to printer "laser" on your system, XENIX will display the request ID as:

```
request id is laser-number
```

where `number` is the number assigned to your job. To cancel the job before it begins printing, use the following command:

```
cancel laser-number
```

and the printout will be canceled.

Most systems print quickly, so a `cancel` command must be used promptly to have any effect.

15.9 Enabling and Disabling Printers

The `enable` command allows `lpsched` to print files on printers. A printer can accept requests for printing after the `accept` command is given for it, but in order for the files to be printed, the `enable` command must be given as well.

For example, to enable a printer named `daisy`, enter:

```
enable daisy
```

You can disable printers with the `disable` command. The scheduler, `lpsched`, will not send printing requests to disabled printers regardless of their acceptance status. The `-r` options allows you to send a message to users explaining why a printer has been disabled.

For example, to disable a printer named "laser" because of a paper jam, enter:

```
disable -r"paper jam" laser
```
Users requesting the status of "laser" with the command `lpstat -plaser` will receive the following message:

```
printer laser disabled since Dec 5 10:15
paper jam
```

For more information on these two commands, see `enable(C)` and `disable(C)` in the XENIX User's Reference.

### 15.10 Printer Interface Programs

Each printer on your system must have a printer interface program. This can be a shell script, C program, or any other executable program. Your XENIX system provides a model interface program. It is written as a shell script and can be found in `/usr/spool/lp/model`. You can use this program as is, modify it, or write your own interface program.

If you want to write or modify a printer interface program, the following information may be helpful.

When `lpsched` routes a printing request to a printer `P`, `/usr/spool/lp` invokes the interface program for `P` as follows:

```
interface P id user title copies options file
```

These flags are:

- `interface` the directory which contains executable copies of interface programs
- `P` the interface program being executed
- `id` the request id returned by `lp`
- `user` the login name of the user who made the request
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title  an optional title given by the user

copies  the number of copies requested

options  a list of printer dependent options separated by blanks

file  the full pathname of a file to be printed

When the interface program is started, its standard input comes from /dev/null and both standard output and standard error output are directed to the printer's device. Devices are opened for reading as well as writing when file modes permit. If a device is a regular file, all output is appended to the end of that file.

Interface programs may format their output in any way. They must, however, ensure proper stty modes for terminal characteristics such as baud rate and output options. In a shell script interface, this means the printer device must be open for reading - take the standard input for the stty command from the device.

The file /etc/default/lpd contains a line "BANNERS=d" where d is the number of banner pages to be printed at the front of every printing request. If d is set to 0, no banner pages are printed. Interface programs should examine /etc/default/lpd and behave accordingly.

After printing is completed, the interface program should exit with a code showing that the print job was successful. Exit codes are interpreted by the printer scheduler, lpsched, as follows:

<table>
<thead>
<tr>
<th>Exit Code</th>
<th>Meaning to lpsched</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Print job was successful</td>
</tr>
<tr>
<td>1 to 127</td>
<td>lpsched found a problem while printing this particular request, for example, too many unprintable characters. This problem will not affect future printing requests. lpsched notifies users by mail that there was an error in printing the request.</td>
</tr>
<tr>
<td>greater than 127</td>
<td>These codes are reserved for internal use by lpsched. Interface programs must not exit with codes in this range.</td>
</tr>
</tbody>
</table>

Finally, when problems occur in printing that are likely to affect future
printing requests, the printer interface program should disable printers so that print requests are not lost. When a busy printer is disabled, the interface program will be terminated with a signal 15 so that print requests are not lost.

For more information on printer interface programs, see `lpadmin(ADM)`, in this guide.

15.11 Adding a Local Printer

XENIX supports the use of local printers attached to the AUX or PRINT port on the back of a normal serial terminal. These printers are connected via standard RS-232 connections and can significantly reduce the load on shared system resources. The `lprint` command is used to print files on a local printer, but the terminal must be properly configured for the command to work. To add a printer connected to the AUX or PRINT port on the back of a normal printer and use it for local printing, follow this procedure:

1. Connect your local serial printer to the AUX port on your terminal with a standard RS-232 cable with pins 1-8 and 20 connected. Make sure the printer is powered on and on-line.

2. Log in to XENIX on the terminal and verify that the terminal is working correctly.

3. Make sure that the AUX port on your terminal is configured with the same settings as your printer. (baud rate, parity, data bits, xon/xoff, etc.)

4. In order for the `lprint` command to work, `lprint` needs to know how to start and stop local printing for each specific terminal. `lprint` looks in the file `/etc/termcap` to find two terminal attributes: PN (start printing) and PS (stop printing). These are escape sequences that must be sent to the terminal to control local printing. Very few terminals have these attributes defined in their `termcap` entries. Use a text editor (such as `vi(C)`) to examine the file `/etc/termcap`. (`/etc/termcap` can also be an alternate file, as defined by the TERMCAP variable.) Search for the entry for your terminal. For example, if your terminal is a Wyse 60, you would search for "wyse60". The `termcap` entry looks like this:
The Wyse 60 does not have PN and PS defined. Just as with other terminals, you must add a line containing these two attributes to the /etc/termcap entry for your terminal. The line you will add has the form:

```
:PN=start sequence : PS=stop sequence :
```

5. Refer to your terminal manual to find the sequence of control characters used to switch the auxiliary port on and off. This is sometimes referred to as “passthrough” or “transparent” mode. For an example of the sequence to enable auxiliary printing, the code to switch the port on for a Wyse 60 terminal is:

```
ESC d#
```

And the code to turn it off again is:

```
Ctrl-T
```

6. These keystrokes must be translated into termcap format before inserting them into the termcap file. termcap uses the following codes to represent keystrokes:
To use a control sequence, use the caret (^) symbol, not the Ctrl key. For example, Ctrl-x would be represented by ^x. In addition, characters can be represented by their octal codes (see ascii(M), and the caret (^) and \ characters represented by \ and \, respectively. Entries for termcap attributes must be separated by a colon (:). (See termcap(M).) for more details.)

Recall that the termcap attributes for starting and ending printing are PN and PS. Using the table above termcap entry for the Wyse 60 keystrokes ESC # d (start printing, PN) and Ctrl-T (stop printing, PS) looks like this:

```
:PN=\Ed#:PS=^T:
```

7. For a Wyse 60 terminal, you would simply insert the above line into the termcap entry for the Wyse 60. (You must be certain to insert the line within the entry for your terminal; don’t add it as the first line or the last line.) For other terminals, check your owner’s manual and locate the proper sequences for turning the auxiliary print mode on and off and substitute the termcap sequences as in the example above. Some terminals (such as the Wyse 60) include a “transparent” mode, where the data is not displayed on the screen as it is printed. (This is the mode selected by the PN sequence in the example.)

Note

You must be logged in as root to edit /etc/termcap. We recommend that you copy the original file to another name in case you make an error. You can also extract the file again from your distribution using custom(ADM).
8. Once you have added the PN and PS entries, log out and back in again to activate the new termcap entry.

9. Use the following command will print the file filename on your local printer.

\texttt{lprint filename}

Do not touch your keyboard while local printing is taking place; you cannot perform other tasks on your terminal while printing.

10. If your file is printed on the screen instead of the printer, the PS and PN entries you created are incorrect. Revise the entries with the correct codes. If the file still does not print on the printer or the terminal, try crossing the Transmit and Receive Data pins in the cable connecting the terminal AUX port and the printer.
Chapter 16
Using Floppy Disks and Tape Drives

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16.1 Introduction

An important part of any computer system is the ability to offload files and restore them when needed. There are several types of media used to store and recall files. Among these are floppy disks and magnetic tape devices. This chapter explains how to install and use the above types of storage media with your system. Your system should come with at least a floppy disk drive already installed and ready to run. This chapter provides instructions on how to add tape drives and how to use floppy disks.

16.2 Using a Cartridge Tape Drive

A tape cartridge drive is a mass storage device that uses 1/4 inch tape cartridges to store data. It is also referred to as a QIC (quarter inch cartridge) tape drive. A tape cartridge can hold many times the data that can be stored on floppies, making it much more useful for large backup operations.

The drives that are supported under XENIX are listed in the Operating System Release Notes. For hardware-specific information, refer to the manual for your drive and tape(HW) in this guide.

16.2.1 Installation and Configuration

Read your tape drive hardware manual for physical installation instructions and general information.

You need to know the following technical information before you install your tape drive:

- The interrupt number. The default interrupt is set on your tape drive controller card. If this number conflicts with one that is already in use, you must change the setting on the card. Interrupts 0, 1, and 6 are always used by XENIX, even if no other devices are present. If you set the interrupt to anything other than the default, write down the setting you chose, as you need to specify it when you run the mkdev utility.

- The DMA Channel and base I/O address. There are also default settings on your tape drive controller card for DMA channel and base I/O address. If you need to change these because of a conflict with existing hardware, note the settings you select and specify them when you run mkdev(ADM).
Once it is connected to your computer, enter this command to configure the drive:

```
mkdev tape
```

`mkdev` runs an interactive program called `tapeinit` which explains the configuration process and prompts you for necessary input. If you are using the default settings on your controller card, select the option to "Install Cartridge Tape Driver" and then enter `q` at the second menu to use the default tape parameters.

If you modified the default settings on your controller card, first select option 1 to install the tape driver, then select the option to "Modify Current Tape Parameters" at the second menu. Next, you see a menu with the default tape parameters. Change any tape parameters here that you changed on your controller board. Note that if you changed the base address, you must enter an "H" after the number if it is a hexadecimal address. If you do not specify the "H", the system assumes that the address is decimal. Also, note that if you choose interrupt 2 on your controller, you must specify interrupt 25 when you modify your tape parameters. The software interrupt 25 corresponds to the hardware interrupt 2. All other interrupts use the same number in software as in the hardware.

When the tape initialization is done, reboot your system and check to assure that the tape device is recognized at boot time. The system should display a message that a "streaming cartridge tape" is present. See `mkdev(ADM)` for more information on installing tape drives.

### 16.2.2 Installing A Mini Tape Drive

Mini tape drives use the floppy disk drive controller and are significantly different from standard QIC tape drives. For one example, mini tapes must be formatted before they can be used. There are also some differences in the installation of mini tapes.

First make sure that your drive is correctly jumpered. The correct setting may be different for different brands of machines. See your hardware documentation and your XENIX Release Notes for more information.

When you run `mkdev tape`, choose the option to "Install A Mini Cartridge Tape Driver" and then choose "y" when you are prompted to link the driver into your kernel.

Note that mini tape drives are not explicitly recognized with a message at boot time.
Using Floppy Disks and Tape Drives

/etc/default/tar

After you install your mini tape drive, you must enter the correct size setting in the /etc/default/tar file. When you edit the file, you see several entries for various default devices. Here is the /etc/default/tar file provided with your distribution:

```
# device block size tape
archive0=/dev/rfd048ds9 18 360 n
archive1=/dev/rfd148ds9 18 360 n
archive2=/dev/rfd096ds15 10 1200 n
archive3=/dev/rfd196ds15 10 1200 n
archive4=/dev/rfd096ds9 18 720 n
archive5=/dev/rfd196ds9 18 720 n
archive6=/dev/rfd0135ds18 18 1440 n
archive7=/dev/rfd1135ds18 18 1440 n
archive8=/dev/rct0 20 0 y
archive9=/dev/rctmini 20 0 y
# The default device...
archive=/dev/rfd096ds15 10 1200 n
```

Find the entry in your /etc/default/tar file for /dev/rctmini. In the above sample file, this is archive7. Note that the size value for rctmini is 0. You must change this entry when you install your rctmini device. The correct number for your rctmini device varies with the size of the tape you use. Here are the correct size settings for rctmini devices:

<table>
<thead>
<tr>
<th>Tape Size</th>
<th>Entry in Size field</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 megabyte</td>
<td>8000</td>
</tr>
<tr>
<td>20 megabyte</td>
<td>18000</td>
</tr>
<tr>
<td>40 megabyte</td>
<td>39000</td>
</tr>
</tbody>
</table>

Note that you must include an even blocking factor (in this case "18") when you use tar on a mini tape drive. The utilities backup and restore have similar files and entries. For more information on default files, see default(M) in the XENIX User's Reference and the manual entry for the particular backup or restore command.
16.2.3 Using A Tape Drive

You use a QIC tape drive much like a floppy. You can use the standard commands such as \texttt{tar(C)}, \texttt{dd(C)}, \texttt{cpio(C)}, \texttt{backup(C)}, and \texttt{restore(C)}.

The \texttt{tar} Command

The \texttt{tar} command is useful for making a backup copy of entire directories. The command has the syntax:

\begin{verbatim}
  tar cvf devicefile files
\end{verbatim}

The \textit{devicefile} is the file name that corresponds to the cartridge drive. \textit{files} are the names of the files or directories to be copied. For example, to copy all the files in the directory \texttt{/ulbogart} to the cartridge drive \texttt{/dev/rct0}, enter:

\begin{verbatim}
  tar cvf /dev/rct0 /u/bogart
\end{verbatim}

\texttt{\textit{sysadmsh users select: Media\rightarrow Archive}}

To restore files stored on tape, insert the cartridge containing the files or directories you wish to restore and enter the following command:

\begin{verbatim}
  tar xvf devicefile
\end{verbatim}

\texttt{\textit{sysadmsh users select: Media\rightarrow Extract}}

\texttt{\textit{tar}} restores all the files on the tape to the original directory.

For detailed information on backup operations and other methods of copying files, refer to \texttt{tar(C)}, \texttt{cpio(C)}, \texttt{backup(C)}, and \texttt{restore(C)} in the \texttt{XENIX User's Reference}.

Tape Drive Maintenance

The \texttt{tape(C)} utility performs various tape maintenance operations on standard QIC tape drives. \texttt{tape(C)} does not work with mini tape drives. \texttt{tape} sends commands and receives status from the tape drive. The basic form of the command is:

\begin{verbatim}
  tape command [ devicefile ]
\end{verbatim}
Using Floppy Disks and Tape Drives

For example, to rewind the cartridge tape device /dev/rct0, enter:

```
tape rewind /dev/rct0
```

Other commands are:

- **erase**: Erase tape cartridge. Also re-tensions.
- **reset**: Reset tape controller and tape drive. Clears error conditions and returns tape subsystem to power up state.
- **reten**: Re-tension tape cartridge. Should be used periodically to remedy slack tape problems, generally resulting in an unusually large number of tape errors.

After certain tape operations are executed, the system returns a prompt before the tape controller has finished its operation. If you enter another tape command too quickly, the message "device busy" is displayed until the tape device is finished with its previous operation.

You should clean the tape drive heads and re-tension cartridges to keep it operating error-free.

**Tape Formatting**

Tape cartridges used with the mini tape drive (ctmini) must be formatted before use. Use the `format(C)` utility to format a cartridge tape. For example, this formats a ctmini tape cartridge:

```
format /dev/rctmini
```

`sysadmsh` users select: Media → Format

The -e option erases servo information on the 40 Megabyte cartridges:

```
format -e /dev/rctmini
```

Smaller cartridges must be bulk erased and reformatted. See also `tape(HW)` and `format(C)` for more information.
16.3 Using Floppy Disks

Floppy disks are the most convenient form of storage media. Depending on your floppy disk drive, you may be able to store from 360 kilobytes to 1.4 megabytes on a single disk. Floppy disks can be used for simple data storage in tar, cpio, dd or dump formats or you can make a mountable filesystem on a floppy disk. The following sections explain how to use floppys for data storage and as extra filesystem space.

16.3.1 Formatting Floppy Disks

Floppy disks must be formatted before they can be used. The XENIX command to format a floppy disk is:

```
format /dev/floppy-device
```

 yat sysadmsh users select: Media→Format

The floppy device you specify in the command relates to the type of disk drive and floppy you are using. For example, if you have a high density 5.25 inch floppy disk drive, you can use it in high density mode (96 tracks per inch) or in low density mode (48 tpi). If you have high density floppies to use with your drive, the floppy device to specify is:

```
/dev/rfd096
```

In the above example, rfd indicates the raw floppy device, 0 indicates that this is the primary floppy drive, and 96 indicates high density mode. Similarly, if you wish to use low density floppies and the low density mode of the floppy drive, the device name is:

```
/dev/rfd048
```

In the above example, 48 indicates the low density mode of floppy drive 0.
Using Floppy Disks and Tape Drives

/etc/default/format file

You can also define a default format device by adding an entry to the file /etc/default/format. For example:

DEVICE=/dev/rfd096ds15

After adding the above line, you no longer have to specify the device name. In addition, it is possible to define that all floppies be verified, which confirms that the data on the floppy is readable. (This can also be specified on the command line with the -y option.) Automatic verification can be specified by the following entry:

VERIFY=Y

If this entry is placed in /etc/default/format, all floppies formatted with the format command are verified. (To override verification, use the -n on the command line.)

For more information, refer to format(C) in the XENIX User's Reference.

16.3.2 Copying Floppy Disks

To ensure against the loss of data stored on floppy disks, any user can use the diskcp(C) command, or the dd(C) command to make copies of floppy disks on new, formatted disks.

diskcp makes use of dd and provides a simple interface to that program. dd is very powerful, and you can use it to perform many different kinds of copying.

You must copy information onto formatted disks. If you format floppies under XENIX, you can use them over again without reformatting.

If you have disks that have been formatted under another operating system, you must reformat them under XENIX before you can use them to make copies of XENIX disks. Be aware that floppies formatted under some operating systems cannot be used under other operating systems, even with reformatting.
You can use the `format` command to format floppies. This command is described in the section “Formatting Floppy Disks” in this chapter. The `diskcp` can also format floppies for you. This is accomplished by the following steps.

To copy a floppy disk using `diskcp`, do the following:

Δ `sysadmsh` users select: Media→Duplicate

1. Insert the disk you want to copy, also known as the *source* floppy, in drive 0, your primary floppy drive.
2. Insert another floppy in the other drive. This floppy is also known as the *target* disk. Note that any information already on the target disk will be destroyed.

   If you have only one disk drive, leave the source floppy in the drive. `diskcp` will prompt you to remove the source disk at the correct time.

3. To format the floppy disk before the image is copied, enter the command:

   ```
   diskcp -f
   ```

   and press RETURN.

   If your computer has dual floppy drives, enter the following command to copy the image directly on the target floppy:

   ```
   diskcp -d
   ```

   and press RETURN.

   If you do not need to format the target floppy, simply enter:

   ```
   diskcp
   ```

   and press RETURN.

4. Follow the instructions as they appear on your screen. Note that, with a single drive system, you are prompted to remove the source disk and insert the target disk.
Using Floppy Disks and Tape Drives

To copy a disk using `dd`, follow these steps:

1. Insert the disk to be copied into floppy drive 0.

2. Insert a formatted disk into drive 1. If necessary, you can format a disk with the `format` command described under "Formatting Floppy Disks" in this chapter.

3. Enter:

   ```
   dd if=/dev/fd0 of=/dev/fd1 count=blkcount
   ```

   and press RETURN. The `blkcount` is the number of blocks on the disk to be copied. If you do not know this number, leave the `count=blkcount` section out of the command.

This command copies the first disk to the second, then displays a record of the number of blocks copied.

16.3.3 Using Floppies for File Storage

To use a floppy for simple file storage, first, make sure that the floppy is formatted. Then, place the floppy in the floppy drive. You can use any of the standard XENIX file archiving utilities with floppy disks. These include `tar`, `cpio`, `dd` or `backup` formats.

`tar` is recommended for most file archiving tasks. For example, to place a copy of a file on a low density floppy disk in `tar` format, use the following command:

```
 tar cv filename
```

Δ `sysadmsh` users select: Media→Archive

For more information on `tar`, see the `tar(C)` manual page in the `XENIX User's Reference`. For more information on `cpio`, `dd` and `backup` formats, see the associated manual pages in the `XENIX User's Reference`. 
16.3.4 Making Filesystems on Floppy Disks

You can make a filesystem on a floppy disk much as you make one on a hard disk. Filesystems on floppy disks are portable and can be mounted on any XENIX system. XENIX provides a special directory called /mnt especially for mounting filesystems that do not have a specified mounting point. Note that for system security, you must be logged in as "root" to use floppy filesystems.

In the example below, a filesystem is created on a high density 96tpi 5.25 inch floppy and mounted on the XENIX system.

To make a portable filesystem on a floppy disk, use the following procedure:

1. Enter the command:

   mkdev fd

   $$\Delta$$ sysadmsh users select: Filesystems → Add

   You see the following menu:

   Choices for type of floppy filesystem.

   1. 48tpi, double sided, 9 sectors per track
   2. 96tpi, double sided, 15 sectors per track
   3. 135tpi, double sided, 9 sectors per track (3.5" diskette)

   Enter an option or enter q to quit:

   Enter 2 and press RETURN. You see the following prompt:

   Insert a 96ds15 floppy into drive 0.
   Press Return to continue or enter q to quit:
Press RETURN. Next you see:

Choices for contents of floppy filesystem.

1. Filesystem only
2. Bootable only
3. Root filesystem only
4. Root and Boot (only available for 96 tpi floppy)

Enter an option or enter q to quit:

Enter 1 and press RETURN. Next you see:

Would you like to format the floppy first? (y/n)

If you have already formatted the floppy, enter n and the filesystem is immediately created. If the floppy has not yet been formatted, enter y and you see:

formatting /dev/rfd096ds15 ...
track 00 head 0

The track and head numbers will count up as the floppy is formatted. When the formatting is finished, the word “done” is displayed. Next you see information about the filesystem as it is created. For a filesystem on a 96 tpi floppy, you see:

isize = 288
m/n = 1 15
filesystem creation complete.
Next you see this menu again:

Choices for contents of floppy filesystem.

1. Filesystem only
2. Bootable only
3. Root filesystem only
4. Root and Boot (only available for 96tpi floppy)

Enter an option or enter q to quit:

Now enter q and press RETURN to quit. Your floppy now contains a filesystem. To use this filesystem, you must mount it on your system. To do this for a 96tpi floppy, give the following command:

```
mount /dev/fd096 /mnt
```

△ sysadmsh users select: Filesystems → Mount

Note that you use the floppy device fd096 and not rf096. When you mount a floppy filesystem, you must use the name without the preceding ‘r’. For another example, if you choose to mount a filesystem on a 48tpi disk, use the following command:

```
mount /dev/fd048 /mnt
```

When you give the mount command, XENIX should return a prompt. This indicates that the filesystem has been successfully mounted. You can now use the cd command to move into the filesystem and create files there normally. When you are done and you wish to remove the floppy, give the following command:

```
umount /dev/fd096
```

△ sysadmsh users select: Filesystems → Unmount

and your filesystem is immediately unmounted. Your files are contained on the floppy and can be stored or transported easily.
16.3.5 Creating an Emergency Boot Floppy

`mkdev(ADM)` provides a utility to create an Emergency Boot Floppy to allow you to restore a corrupted root filesystem without reinstalling XENIX. If you have more than one system, you should make one Emergency Boot Floppy for each machine. Because each machine has a unique "Emergency" floppy, a reboot floppy made on one system will not work with any other system. Be sure to keep these diskettes separate; if you use an emergency floppy on the wrong machine, it will not work and further corruption may result.

To create the floppy, `mkdev` uses a menu-driven program to select the disk format and filesystem type. There are three basic types generated: boot and root on a single disk (96 tpi only), boot and root pair (48 tpi), or filesystem only (as described above). The formats supported are: 48 tpi, 96 tpi-15 sectors/track, and 135 tpi-9 sectors/track in the 3 1/2 inch format. To create the floppies, enter:

```
mkdev fd
```

Δ `sysadmsh` users select: Filesystems → Add

and you will see the following display:

```
Choices for type of floppy filesystem.

1. 48 tpi, double sided, 9 sectors per track
2. 96 tpi, double sided, 15 sectors per track
3. 135 tpi, double sided, 9 sectors per track (3.5" diskette)

Enter an option or enter q to quit:
```

Enter the correct type and press RETURN. You are then prompted for the disk:

```
Insert a xx tpi floppy into drive 0. Press Return to continue.
```
Insert your floppy and press RETURN. The program responds with another menu:

Choices for contents of floppy filesystem.

1. Filesystem only
2. Bootable only
3. Root filesystem only
4. Root and Boot (only available for 96tpi floppy)

Enter an option or enter q to quit:

Select the appropriate filesystem and press RETURN. fdinit generates the filesystem and displays the following message when complete:

xx tpi filesystem floppy complete.
Chapter 17

Using Bus Cards

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   17.2.1 Using the Manufacturer’s Setup Disk 17-2

17.3 Adding Additional Memory 17-3
17.1 Introduction

The bus (or "motherboard") of your computer is the center of your system. Every system administrator must deal with the bus and the hardware associated with it. To find the bus on your system, you must generally remove the shell from the main body of your computer. Generally, you find a large circuit board with expansion slots for extra boards. These boards are commonly known as Bus Cards.

Bus cards can be extra memory for your system, internal modems, multiport serial boards for extra terminals, controller boards for peripheral devices such as hard disks tape drives, control cards for monitors with color and graphics capabilities, mouse controllers, or other devices. In this chapter we explain a little about bus cards and how to install them with your XENIX system. Installation of most devices with bus cards is explained in detail in other chapters of this Guide, so we will deal only with the basics of bus cards in this chapter.

17.2 Installing Bus Cards

To install a bus card, you must first shut down XENIX and power down the system. Make sure that the computer is unplugged or you may injure yourself. Before you begin working on the computer, ground yourself by touching a metal object close at hand that is not the computer. Static electricity that builds up and jumps from your hand when you touch the hardware inside the computer can ruin your equipment.

Dip Switches and Jumpers

Before you plug your board into the bus, make sure that there are no settings on the board that must be changed. Again, your hardware documentation that comes with the board should list the default settings and how to change them. Generally, to change the settings of a board, there are dip switches and “jumpers.” Dip switches operate in “down” and “up” positions. Your hardware documentation should list the correct settings if your board has these switches. Jumpers are clips that slide over metal posts that stick out of the board to make a connection. You can change the settings on a board by moving the jumper to connect a different pair of posts. Again, your hardware documentation should provide you with specific instructions for jumper settings on your hardware.
Note

Note that XENIX is designed to work with most hardware using default settings. You will rarely have to change the settings on a board for it to work under XENIX.

Installing the Hardware

Carefully perform any steps necessary to expose the expansion slots on your computer. Your hardware documentation should explain this in detail. Once you can examine this area, note the number of available spaces for bus cards. A new system will have up to 8 or 10 available slots. Note that some slots are longer than others. There are both short and long cards. Short cards are about half as long as long cards. Generally there are 2 to 3 short slots and the rest are long slots. Find a slot that fits your board and gently but firmly plug the board into the slot in the bus. The board should have a tab on one side that fits into the slot on the bus. Bus cards only fit one way.

Some bus cards have a port that should face the outside of the computer. As stated before, bus cards only fit into the system one way. There may be a small plate covering an opening in the computer held on with a small screw. You can remove this cover plate if you need to. Boards such as modems, serial and parallel cards, and external device control cards will require this.

When you are done, replace the shell for your computer, and turn it on and boot. You may first need to use the manufacturer’s setup program as described below to change the system’s configuration before you can use the new hardware.

17.2.1 Using the Manufacturer’s Setup Disk

Your computer should come with a manufacturer’s setup program on a bootable floppy disk. Copy this disk for use and keep the original in a safe place. This disk is used to configure the permanent memory on your computer to describe the system hardware setup. Whenever you add a major device, like an extra hard disk or an extra serial card, you may need to run your setup program to tell your computer about the new hardware. Some
computers automatically recognize the presence of new hardware. Your manufacturer’s documentation should let you know if you need to run this software.

17.3 Adding Additional Memory

You can improve system performance and run larger programs by increasing the amount of internal memory.

To increase internal memory follow these steps:

1. Turn off your computer.

2. Install extended memory according to the manufacturer’s instructions. Make sure you have set all switches as noted in the instructions.

3. Boot XENIX. The boot screen details how the additional memory has affected your system.

4. Some features of XENIX may have been expanded. For example, you may have:
   - More multiscreens
   - More buffers
   - A larger maximum user process size

The number of multiscreens may be unchanged. Since the number of multiscreens can be set by the user, you may have already set a specific limit to the number of multiscreens available. If you have not set a limit to the number of multiscreens then you are already using the maximum number of multiscreens that XENIX allows.

The number of buffers may also be unchanged. Since the number of buffers can also be set by the user, you may have already set a specific limit to the number of buffers available. If you have not set a limit to the number of buffers then you are already using the maximum number of buffers that XENIX allows.
If the maximum user process size is unchanged, then it is now limited by the size of the swap filesystem instead of the amount of internal memory. You can:

- Reinstall XENIX and increase the size of the swap chapter of the Installation Guide for details on reinstallation.

- Change the process so that it runs without being swapped. Refer to proctl (S) for details.

You can follow the same procedure if you wish to remove internal memory from the system.

If the memory hardware reports an error to XENIX, the following message is displayed:

PANIC: parity

You then see the software reboot message:

** Normal System Shutdown **

** Safe to Power Off **

- or -

** Press Any Key to Reboot **

If the system repeatedly panics from parity errors, consider replacing the memory chips.

---

Note

Some machines have a hardware limitation on the maximum amount of memory that can be installed. Refer to your computer hardware manual to determine the maximum amount of memory you can install.
Chapter 18

Using a Mouse With XENIX

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18.1 Introduction

This chapter deals with the basics of installing any brand or type of mouse interface with your system. Using a mouse can be a great convenience for users and developers alike. For this reason, XENIX provides support for both serial and bus mouse hardware.

18.2 Installing the Hardware

Consult your hardware manufacturer’s documentation for specific instructions on hardware configuration. Note the brand and type of your mouse and whether it is attached to a serial port or directly to the system bus. For more information about the system bus, see the chapter in this Guide called “Using Bus Cards.” You will need to know this information when you configure your software to accept the mouse.

18.3 Installing A Mouse

To install a mouse on your system, you must perform the following steps:

1. Install the mouse according to the manufacturer’s instructions.

2. Make sure your link kit is installed and functioning correctly. The mouse drivers cannot be installed without the Link Kit.

3. Log in as root and input the following command:

   \[ \text{mkdev mouse} \]

   And you see the Mouse Initialization Menu:

   Mouse Initialization Program

   1. Display current configuration
   2. Add a mouse to the system
   3. Remove a mouse from the system
   4. Associate a terminal with an existing mouse
   5. Disassociate a terminal from an existing mouse
   6. Remove the mouse drivers from the kernel

   Select an option or enter q to quit:

To install a mouse, choose option 2. The other options allow you to change your mouse configuration at any time. For example, you
can add or remove additional mice on your system or change the terminals that are allowed to receive input from an existing mouse.

4. Choose option 2 to install a mouse and press **RETURN**. Next, you must specify the type of mouse you will use. All the mice currently supported under XENIX are listed. Enter the number corresponding to your type of mouse and press **RETURN**. You see the menu:

The following mouse devices are supported:

1. Logitech serial mouse
2. Microsoft Serial Mouse
3. Mouse Systems PC Mouse
4. Microsoft Busmouse or INport Bus mouse
5. Logitech Bus Mouse
6. Olivetti Bus Mouse

Select an option or press 'q' to return to the previous menu:

Enter the number corresponding to the mouse you wish to install and press **RETURN**.

5. If you choose a busmouse, you are asked to select the configuration for the busmouse card. If you choose a serial mouse, you skip this step and go directly to linking the mouse drivers into your kernel. If you choose a busmouse, you see the message:

```
Configuring driver...
```

and then you see the menu:

**Busmouse Configuration**

1. Display current busmouse parameters
2. Modify current busmouse parameters
3. Select previous busmouse parameters
4. Select default busmouse parameters

Enter an option or q to quit:
If you wish to use the default busmouse parameters, select option 4 and then press "q" to quit this menu. The default busmouse selection allows XENIX to auto-configure your busmouse. If you choose alternate parameters, be sure that you use interrupt vector 5 with your busmouse. Note that using interrupt vector 5 may conflict with a cartridge tape device if both devices are in use at the same time.

6. If you have previously installed a mouse of any sort on your system, the driver for the mouse devices should already be linked with your kernel. If you have never installed a mouse on your system, or the driver is not present in the kernel, you see the following messages. Note that these messages may take a few minutes to appear on your screen:

```
Updating system configuration...
Installing mouse drivers...
You must create a new kernel to effect the driver change you specified.
Do you wish to create a new kernel now? (y/n/q)
```

Answer "y" to add the mouse device driver to your kernel. As part of the linking process, you see the following messages:

```
Kernel with mouse driver modification is in
/usr/sys/conf/xenix
Do you want this kernel to boot by default? (y/n)
```

Answer "y" if you want this kernel to be used every time you boot XENIX. (Most systems will answer "y" to this prompt.) Next you see:

```
The new kernel is installed in /xenix.
After you finish configuring the mouse,
reboot your system to activate the new kernel.
```

You have now installed the mouse drivers in your kernel.

7. Next, you are asked to specify the terminals and multiscreens that will be allowed to accept input from the mouse. Do not attempt to allow mouse input on any tty where any mice are physically connected or you will receive an error message. You may choose to
allow any or all other terminals and video adapter monitor multiscreens to use the mouse. Entering the word "multiscreen" will associate all of the console multiscreens.

Note that only one mouse can be allowed for input on a given tty.

For more information on sharing the mouse between several terminals or multiscreens, see "Using the Mouse." You see:

Enter a list of terminals (e.g. ttyla, tty2a, multiscreen) or enter 'q' to quit. Press return when finished:

When you have pressed return, you see:

Do you want to use the <mouse_type> on any other terminals? (y/n/q)

Note that in above example, mouse_type will be replaced with the brand or type of mouse you specified earlier in the procedure.

8. Next you see:

Do you want to use the <mouse_type> on any other terminals? (y/n/q)

If you answer "n" no other terminals will be allowed to receive mouse input. If you answer "y" you are prompted to enter tty pathnames for terminals that are to be allowed to receive mouse input. You see:

Enter a list of terminals (e.g. ttyla tty1b). Press return when finished:
9. Next, if you are installing a serial mouse, you are asked to specify the tty port where you will physically attach the mouse. If you are installing a bus mouse, proceed to the following step, as the port is configured automatically. You see:

```
<mouse-type> is currently configured to attach to the
system on /dev/ttyla.

Do you wish to install this mouse on a different port? (y/n/q)
```

Note that you can choose any port on your system for your mouse, but that the default port is /dev/ttyla (COM 1). Otherwise, enter the serial tty name (for example, /dev/tty5a or /dev/tty2b) where you will attach your mouse. You see:

```
To which device (e.g. /dev/tty2a) do you want to attach the
<mouse_type> (or enter 'q' to quit):
```

10. Finally, you are returned to the main mouse menu again:

```
1. Display current configuration
2. Add a mouse to your system
3. Remove a mouse from your system
4. Associate a terminal with an existing mouse
5. Disassociate a terminal from an existing mouse

Select an option or enter 'q' to return to the previous menu:
```

If you have no changes to make to your mouse configuration at this time, enter "q" to quit and press RETURN.

Note that you can invoke `mkdev mouse` at any time to allow or prevent input on different terminals, remove mice or check your current configuration.
18.3.1 Removing a Mouse

Removal of any mouse or the mouse drivers on your system is an exact reversal of the process of installing a mouse. Choose the menu options to remove rather than to add a mouse.

18.4 Using the Mouse

Using the mouse under XENIX is automatic. If a program or utility accepts mouse input and the terminal is allowed to use the mouse, you simply invoke the program and the mouse works. If the terminal or multiscreen is not allowed to use the mouse, or the program is not configured to accept mouse input, using the mouse has no effect.

18.4.1 Using the Mouse With Multiscreens

Multiscreens (on monitors attached to video cards in the bus) provide the most convenient method for using the mouse. If a mouse is associated with the multiscreens on your main system console, (typically, a monitor attached to a video card in the system bus) the mouse input is associated with the current active multiscreen. For example, if your system has four multiscreens enabled on the main system console and all those screens are allowed to use the mouse, the input from the mouse goes to the program running on the active multiscreen.

Remember that programs that do not accept mouse input will be unaffected by moving the mouse, even on a mouse-allowed multiscreen.

Serial (or terminal) multiscreens and serial consoles can also be configured to use the mouse.

18.4.2 Using the Mouse on Serial Terminals

When you install the mouse, you are prompted to list the ttys that will be allowed to use mouse input. You can allow terminals on serial lines to use the mouse just as you allow multiscreens. Again, note that you cannot allow mouse input on a tty where a mouse is physically connected.
18.4.3 Sharing a Mouse With Several Terminals

When the mouse is shared among several terminals, the mouse is associated with a tty on a “first-come, first-served” basis. The first user to invoke a mouse enabled program has the mouse for the duration of that program. In order for another user to use the mouse, the first user must quit the program. (Thereby closing the input queue from the mouse.) Then, the next user for the mouse can invoke the program and open the line for input from the mouse.

Note that other users on mouse-allowed ttys can use programs that accept mouse input while the mouse is busy. If the mouse is busy, the programs will be unable to receive input from the mouse but should otherwise function normally.

18.4.4 Using a Mouse with Keyboard-based Programs

The usemouse(C) utility is used to map mouse movements and operations to keystrokes used by keyboard-based programs. Refer to the usemouse(C) manual page for complete information.
Chapter 19

Solving System Problems

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19.1 Introduction

This chapter explains how to solve problems that affect the operation of the system. The tasks range in complexity from how to fix a nonechoing terminal, to restoring lost system files.

19.2 Restoring a Nonechoing Terminal

A nonechoing terminal is a terminal that responds to keyboard input but does not display the display characters entered at the keyboard. (This is opposed to a “locked” terminal that does not respond to input at all; see “Restarting a Locked Terminal” for a solution to this problem.) This abnormal operation can occur whenever a program stops prematurely as a result of an error, or when the user presses the BREAK key.

To restore the terminal to normal operation, follow these steps:

1. Press Ctrl-j. The system may display an error message. If it does, ignore the message.

2. Enter:

   stty sane

   and press Ctrl-j. The terminal does not display what you enter, so be sure to enter it accurately.

After pressing Ctrl-j, the terminal should be restored and you may continue your work.

19.3 Restarting a Locked Terminal

One of the most frustrating problems faced by new users is a locked terminal. Terminals may lock for a variety of reasons, and the results range from momentary interruptions to lost work. When the problem occurs, the following steps should return the terminal to use with a minimum of lost time.

1. The first step is to wait. As your computer system becomes more heavily used, the “response time” will increase. During periods of peak activity, the terminal may accept keystrokes without “obeying” them, giving the impression that it has locked completely. Wait a minimum of 60 seconds before trying to resurrect the terminal.
2. Press Ctrl-q to re-enable transmission, in case a Ctrl-q (transmit off) signal, such as from a "No Scroll" key, has inadvertently been sent to the computer.

3. If the terminal remains unresponsive, it should be checked for hardware problems, such as a loose or disconnected power cord, keyboard cord, or communications cable. If everything is plugged in, and the communications cable is tight at both ends (and still intact in the middle), look for a software problem.

4. Sometimes the terminal's internal software may have become stuck in an unusual state. This can often be corrected by turning the terminal off and back on again. This will always result in a blank screen, so if there is information on the screen that you wish to save, you may want to copy it by hand, or save this step for last.

5. Having eliminated the wiring and the terminal itself, as sources of the problem, check the programs running on the terminal. The who command, typed on an operating terminal, will tell you which communication port each user is connected to, allowing you to identify the port of the locked terminal.

A useful hardware-communications test is redirecting some output from an operating terminal to the locked one. For a communication port named tty6c, a command such as:

```
date > /dev/tty6c
```

should produce some output on the screen of the locked terminal. If you get the message "permission denied," have the user log in on the operating terminal, and try the date command again. If there is still no output, go back and check the hardware again as described above.

To find out what programs the locked terminal is running, give the name of the port to the ps command, using the -t option. For the communication port tty6c, as above, the command:

```
ps -t tty6c
```

will list the programs being run by the terminal on that port. (Again, this must be typed on an operating terminal.) Also listed will be each program's PID (process identifier). Make a note of each program name and PID number.

Determining which program is currently running on the terminal may sometimes take a little guesswork. Often it will be the last
line of the `ps` list or the program with the highest PID. Other clues may be obtained by using the `-f` and `-l` options to `ps` (combined with `-t` as `-flt`) which will list the starting times (STIME) and the states (S), respectively, of the processes. (For more information see `ps(C)` in the XENIX User's Reference.)

You may find that the user is running a different program than they think. This can happen, for instance, when a user accidentally runs a program from a menu. In this case, the locked terminal may be freed by using the proper commands to exit the unwanted program.

If the currently-running program is the proper one, and the terminal will not respond to correct commands for that program, then the program must be "killed." Only the user who started the program or the super user (root) may kill a user's programs, so have the user log in on the operating terminal, if they have not already done so (or log in as root).

The `kill` command normally takes two arguments, a signal and a PID (see `kill(C)` for more details). For a currently-running program with a PID of 1234, the command

```
kill -15 1234
```

will send process 1234 a signal of 15, which asks the program to leave "politely," and will cause a minimum of problems (if it works).

Now use the `ps -t` command again to see if the program you "killed" has exited. If it has not stopped, issue the `kill` command again using `-9` instead of `-15`. This is a "sure kill," and may cause remnants of the program to be left behind, such as temporary files. You should check for these in the `/tmp` and `/usr/tmp` directories when you have finished, looking for files owned by the user, and remove them. Note that files belonging to programs which have not been killed may also be in these directories. If in doubt, leave it there and clean up later.

After each program is killed, the terminal may be tested. It may not respond. Many programs place the terminal in special modes when they run, and some of these modes will cause the terminal to seem to be locked. Applications may use what is called "raw" mode, in which characters typed at the terminal are not echoed to the screen. One problem with raw mode is that the RETURN or ENTER keys do not behave as expected.
XENIX expects a Ctrl-j (linefeed or newline) character at the end of each command, but most terminals send a Ctrl-m character when the RETURN key is pressed. Normally, the Ctrl-m is translated into Ctrl-j, but if the application has turned off this translation, and has then exited or been killed without turning the translation back on, you must type a true Ctrl-j character to end your commands.

On the locked terminal, type a Ctrl-j to start a new line, and then enter:

```
stty sane <Ctrl-j>
```

Be sure to use Ctrl-j instead of the RETURN or ENTER key to end the command. You may need to type this command twice before the terminal responds.

The kill-and-test sequence above may need to be used on each program listed on the output of the ps command. Many system administrators will simply kill all of the programs to save time. This choice is yours.

If the ps -t command shows only a program named getty, you have killed all the possible programs, and should have a login prompt on the terminal. If not, go back and check the hardware.

---

**Note**

Some programs cannot be killed. This is rare and there is only one solution: the computer must be shut down and restarted.

---

### 19.4 Loading adb(CP) Without the Development System

adb is provided as part of the Operating System distribution in order to apply kernel patches of the type described in "Fixing Console Keyboard Lockup." Apply patches only when they are recommended by the Release Notes or other documentation relating to your distribution. In addition, you should keep a record of all patches applied in your system log book.
To load `adb` on your system, enter the following command to determine which N volume of your XENIX distribution it is on:

```
grep adb /etc/perms/dsmd
```

This command displays the volume number in the last column; for example:

```
SOFT x711 bin/bin 1 ./bin/adb N01
```

In this case, `adb` is found on volume N1. Use the following key to determine whether the N volume must be mounted and `adb` copied off, or extracted from the volume using `tar`:

<table>
<thead>
<tr>
<th>Distribution</th>
<th>Type of Volumes</th>
</tr>
</thead>
<tbody>
<tr>
<td>48/135tpi</td>
<td>N1 and N2 mountable; all others are tar</td>
</tr>
<tr>
<td>96tpi</td>
<td>N1 is mountable; all others tar</td>
</tr>
</tbody>
</table>

6. Insert the proper N volume into your drive. Use one of the following commands to retrieve `adb` from your distribution. If the N volume is mountable, copy `adb` using the following commands:

```
mount -r /dev/install /mnt
cp /mnt/bin/adb /bin
umount /dev/install
```

If the N volume is a tar volume, enter the following commands:

```
    cd /
tar xv f /dev/install ./bin/adb
```

---

**Note**

`adb` is not supported for general programming and debugging unless you have purchased the Development System.
19.5 Fixing Console Keyboard Lock-up

A very small number of systems experience a problem known as "keyboard lockup," where the system does not respond to keyboard input from the console keyboard. This has been investigated thoroughly and should be quite rare. This particular condition only affects keyboards that are attached to the video display adapter, not standard terminals that are attached to serial lines.

Your keyboard may be "locked up" if:

- The system console keyboard cannot be used to enter data or perform any tasks
- You cannot flip Multiscreens and the CAPS LOCK key does not turn the caps lock light on or off
- Other terminals on the system continue to work
- Printers or other devices continue to work
- The system is still running.

Keyboard lockup is similar to other circumstances, so before trying to fix a "locked" keyboard, make sure that:

- You did not accidentally enter Ctrl-S
- The "Keyboard Lock" key is not in the lock position
- The keyboard is still plugged in
- The system itself is still running.

First, make sure you did not enter Ctrl-S accidentally. Press Ctrl-Q several times and check to see if you can enter characters on the screen. Press RETURN a few times, or enter DEL.

Next, check the Keyboard Lock key, if your computer has one. It should be turned to the "unlocked" position. Also, make sure the keyboard is still plugged in to the correct socket.

Make sure the system is still running. Check a terminal to see if it is still working and that you can perform system tasks, such as logging in and checking the date. If you do not have a terminal, watch the hard disk access light, if your computer has one. If it flashes periodically, at least once every thirty seconds or so, the system is still running and is using the
hard disk. Note that you cannot use other terminals and that the hard disk access light may not flash if you are in single user mode.

If you check all of the suggestions, but you still cannot use your console keyboard, try unplugging the console keyboard then plugging it in again. If this fixes the problem, it is definitely a case of keyboard lockup. If this last step does not fix the problem, you may still have keyboard lockup.

You can prevent keyboard lockup by applying a special "patch" that changes the operating system kernel. (The kernel is the main program of the operating system that is always running in memory.) Note that this patch disables the keyboard lights (LEDs), so you should do this only if you have tried all other approaches:

1. Get the system console working, if it is not. Reboot the system if you have to and bring it up to single-user mode.

2. If you didn't reboot, log in as root on the system console and shut the system down to single user mode with the `shutdown` command:

   `/etc/shutdown su`

   See `shutdown(ADM)` for more information.

3. Once the system is in single user mode, back up the kernel:

   ```
   cd /
   mv xenix xenix.00
   cp xenix.00 xenix
   ```

4. If you do not have the Development System installed on your system, load the `adb` program on your system as described in the section "Loading adb(CP) Without the Development System."

5. When you have `adb` installed, enter this command:

   ```
   adb -w /xenix
   ledspresent/w 0
   $q
   ```

   This patches your kernel with the necessary fix. Again, note that it permanently disables the console keyboard lights (LEDs).
6. Shut down the system:

```
# /etc/shutdown 0
```

7. When you see the "Normal System Shutdown" message, press any key to reboot the system. You have now fixed the keyboard lockup problem.

8. Finally, call your support center and report your problem.

19.6 Restarting a Stopped Printer Queue

No printing can be done on the lineprinter spooling system unless the print scheduler, `lpsched`, is running. To check the status of `lpsched`, enter:

```
lpstat -r
```

△ `sysadmsh` users select: System→Report→Printers

To restart `lpsched`, enter the following on two lines:

```
/usr/lib/lpshut
/usr/lib/lpsched
```

Calling the file `/usr/lib/lpshut` cleans the system and `/usr/lib/lpsched` starts it up again.

Access to files and directories in `/usr/spool/lp` by `lp` can be another source of spooling problems. You can check the `lpsched` log file, `/usr/spool/lp/log`. This is a record of the print scheduler's activity and errors. If `lpsched` refuses to run or a printer refuses to print, check to make sure that:

- The printer is enabled; see `lp(C)` in the `XENIX User's Reference`.
- The files and directories in `/usr/spool/lp` are readable and writable by `lp`.

For more information on the lineprinter spooling system, see the section "Installing A Lineprinter" in the "Using Printers" chapter.
19.7 Fixing a Slow Parallel Printer

If you have a parallel printer that prints abnormally slow, check your configuration according to the procedure described below. If it still prints slowly, you can switch to polling operation. Verify the following items, as it is important that your parallel ports be configured properly to work under XENIX:

1. The printer must be IBM compatible and should use a standard Centronics interface cable in order for it to work at all.

2. The IBM AT and compatibles only support up to 2 parallel ports. Deconfigure additional ports.

3. The parallel port on the monochrome card should be configured for interrupt vector 7, and is recognized as lp1 when booting up.

4. The main parallel port should be configured for interrupt vector 7 and is recognized as lp0. So you must use either the main or the monochrome's port - not both - to avoid a hardware conflict which would cause slow printing.

5. The alternate/second parallel port should be configured for interrupt vector 5, and recognized as lp2. Make sure no other hardware is using these interrupts. (See your hardware manual for information on configuring your parallel ports.)

6. Check to make sure your parallel card is recognized by XENIX by rebooting your system. Following the copyright information on the screen, you should see:

   Parallel port lpn present

where lpn is the device special filename of the port the printer is attached to (lp0, lp1 or lp2) as described above. If you do not see this message, check the switches and jumpers on your parallel card to make sure they are correct. Also try setting the card for a different configuration, if possible.

7. Be sure your printer is turned on and on-line, and the cable is properly attached to the computer and printer.

8. From the console, logged in as root, see if you can redirect output to your printer by entering:

   date > /dev/lpn
If you do not see the date printed on your printer, there is most likely some type of hardware malfunction, so verify the following:

- Your cable is securely connected and all wires are good. Using the cable on a known good system, or printing under DOS are good ways to test this.
- Re-check your printer configuration by verifying its switches in your printer hardware manual.
- Re-check the switches on your parallel card. It must be recognized at bootup, as described above in Step 6.

When you get the date printed on your printer, you should run `mkdev lp` to configure the spooler to support this printer. (See the “Using Printers” chapter of this guide for more information on `lpinit`, the script called by `mkdev lp`.)

### 19.7.1 Switching to Polling Operation

If your parallel ports are configured properly, as described in the previous section and you still get slow printing, your parallel port may not be capable of generating interrupts.

A solution is to alter the way that the hardware and the printer driver communicate. The parallel printer driver can be made to "poll" a parallel port. This way the driver does not rely on interrupts from the parallel port, but at the cost of a possible drain on system resources.

To set up polling for a parallel port/parallel printer, create what is known as a "special device node." Log in as `root` (super user) and enter one of the following sets of commands. (Note which printer ports are recognized during the boot up message.)

For `lp0`:

```
  mknod /dev/lp0p c 6 64
  chown bin /dev/lp0p
  chgrp bin /dev/lp0p
  chmod 222 /dev/lp0p
```
For lp1:

```bash
mknod /dev/lplp c 6 65
chown bin /dev/lplp
chgrp bin /dev/lplp
chmod 222 /dev/lplp
```

For lp2:

```bash
mknod /dev/lp2p c 6 66
chown bin /dev/lp2p
chgrp bin /dev/lp2p
chmod 222 /dev/lp2p
```

If you are using the print spooler, run `mkdev lp` to inform the spooler of the new parallel poll device. You can choose to add a new printer or reconfigure an existing printer. When you are asked to choose a device for the printer, do not use the standard parallel devices that are displayed. Instead, use: “/dev/lpl0p”, “/dev/lpl1p”, or “/dev/lpl2p”.

### 19.8 Stopping a Runaway Process

A runaway process is a program that cannot be stopped from the terminal at which it was invoked. This occurs whenever an error in the program “locks up” the terminal, that is, prevents anything you enter from reaching the system.

To stop a runaway process, follow these steps:

Δ **sysadms**h users select: Processes→Terminate

1. Go to a terminal that is not locked up.

2. Log in as the super user.

3. Enter:

```bash
ps -a
```

and press the RETURN key. The system displays all current processes and their process identification numbers (PIDs). Find the PID of the runaway program.
4. Enter:

```
kill  PID
```

and press the **RETURN** key. The *PID* is the process identification number of the runaway program. The program should stop in a few seconds. If the process does not stop, enter:

```
kill -9 PID
```

and press the **RETURN** key.

The last step is sure to stop the process, but may leave temporary files or a nonechoing terminal. To restore the terminal to normal operation, follow the instructions in the section “Restoring a Nonechoing Terminal” in this chapter.

**19.9 Replacing a Forgotten User Password**

The XENIX operating system does not provide a way to decipher an existing password. If a user forgets his password, the system manager must change the password to a new one. To change an ordinary user password, follow the instructions in the section “Changing a User’s Password” in the “Maintaining System Security” chapter.

**19.10 Removing Hidden Files**

A hidden file is any file whose name begins with a dot (.). You can list the hidden files in a directory by entering:

```
ls -a
```

and pressing the **RETURN** key.

You can remove most hidden files from a directory by entering:

```
rm .[a-z]*
```

and pressing the **RETURN** key. Remaining files can be removed individually.
19.11 Restoring Free Space

The system displays an "out of space" message whenever the root directory has little or no space left to work. To restore system operation, you must delete or reduce one or more files from the root directory. To delete and reduce files, follow the steps outlined in the section "Maintaining Free Space" in the "Using Filesystems" chapter of this guide.

19.12 Restoring Lost System Files

If a system program or data file is accidentally modified or removed from the filesystem, you can recover the file from the periodic backup disk with the sysadmin program. To restore the files, follow the instructions in the section "Restoring Individual Files or Directories from Backups" in the "Backing Up Filesystems" chapter of this guide.

19.13 Restoring a Corrupted root Filesystem

On very rare occasions, one or more of the critical XENIX system files may be accidentally modified or removed, preventing the system from operating. In such a case, you must restore your root filesystem from backups. To restore your root filesystem, you must first have made an Emergency Boot Floppy as you were directed in the XENIX Installation Guide. If you have not made this floppy, you must reinstall XENIX. Also, if you have no backups of your root filesystem, you must reinstall XENIX. To reinstall the system, follow the instructions in "Reinstalling and Updating Your System" in the XENIX Installation Guide.

To restore your root filesystem, perform the following steps exactly:

1. Power cycle your machine and boot the system using your Emergency Boot Floppy for that machine. (Note that you must have a separate Emergency Boot Floppy for each XENIX system or further corruption may result.)

2. At your system prompt, give the command:

   /bin/fsck -y /dev/hd0root
You should see messages indicating that `fsck` is proceeding through five or six phases of system cleaning. If the program exits within a few seconds or you see error messages that make no sense, such as:

```
UNKNOWN FILE SYSTEM VERSION 65535
CLEANING NON SYSTEM 3 FILESYSTEM
```

you must restore your entire root filesystem. If `fsck` appears to be successful, shut down your system using `/etc/haltsys` and attempt to boot from the hard disk. If this is not successful, you must continue this procedure.

3. If the above procedure does not correct your problem, you must restore your root filesystem. At your system prompt, enter the following command:

```
/etc/mount /dev/hd0root /mnt
```

4. Next, give the command,

```
restore fr /dev/devicename /dev/hd0root
```

Where `devicename` is the name of the device where you will read your backups. For example, a cartridge tape drive would be known as `/dev/rtc0` and a mini-tape drive would be `/dev/rtcmini`. A 96tpi floppy drive would be known as `/dev/floppy96`.

5. After the restoration is complete, halt the system using `/etc/haltsys` and reboot from the hard disk. You should now be able to restore other filesystems normally. If you cannot boot from your hard disk at this point, it is likely that you have serious hardware malfunctions.

### 19.14 Recovering from a System Crash

A system crash is a sudden and dramatic disruption of system operation that stops all work on the computer. System crashes occur very rarely. They are usually the result of hardware errors or damage to the root filesystem which the operating system cannot correct by itself. When a system crash occurs, the system usually displays a message explaining the cause of the error, then stops. This gives the system manager the chance to recover from the crash by correcting the error (if possible), and restarting the system.
Solving System Problems

A system crash has occurred if the system displays a message beginning with "panic:" on the system console, or the system refuses to process all input (including INTERRUPT and QUIT keys) from the system console and all other terminals.

To recover from a system crash, follow these steps:

1. Use the error message(s) displayed on the system console to determine the error that caused the crash. If there is no message, skip to step 3.

2. Correct the error, if possible. A complete list of error messages and descriptions for correcting the errors is given in messages(M) in the XENIX User's Reference. (Even if the problem cannot be located or corrected, it is generally worthwhile to try to restart the system at least once by completing the remaining steps in this procedure.)

3. Turn off the computer and follow the steps described in the "Starting the System" chapter, to restart the system.

4. If the system will not restart, or crashes each time it is started, the operating system is corrupted and must be restored or reinstalled. Follow the procedures described in the previous section to restore the system and in the "Backing Up Filesystems" chapter, to restore user files.

5. If the system cannot be started from the "Boot" disk in the distribution set for installation, the computer has a serious hardware malfunction. Contact a hardware service representative for help.

19.15 Fixing Bad HZ Value

If you see the message "Bad HZ Value" at any time during system operation, your system files may be incorrect or corrupted.

The HZ variable is used by XENIX to represent the system interrupt clock frequency. You must declare the HZ variable in three places; in the /etc/rc file, the /.profile or /.login file, and the /etc/default/login file. If the HZ variable is not correctly set in these files or one or more of these files is corrupted or missing, you will see the above error message. Also, if you verify that these files are correct, this message could indicate that your kernel is not properly serialized.
If you have an 80286 or 80386 system, the HZ value must be set to 50 cycles per second. If you have a 8086 system, the HZ value is set to 20 cycles per second.

If you verify that the value is set correctly in your system files, you can re-serialize your kernel. To re-serialize your kernel, enter the following commands:

```
   cd /
   cp /xenix xenix.bkp
   /etc/brand <serial#> <activationkey> /xenix
   /etc/shutdown
```

Now reboot your system. You should not see the error message.

19.16 Recovering from a General Protection Trap

Under XENIX the 80286 processor runs in "Protected" mode. If you have an 80286 based system and you see the error message:

```
panic: general protection trap
```

it means that the system loaded a segment register with an illegal value. This means that it is either a value not defined by the current descriptor table or the protection is such that the current user is not allowed to use that segment value or the code is trying to access out of the limits acceptable for that segment value as defined in the descriptor table.

If your system shuts down because of a general protection trap, reboot and note the time and circumstances, such as which users were logged on and what software they were using at the time of the error. If the error occurs repeatedly, it should be possible to locate the source of the problem and rectify the situation.
19.17 Mapping a Bad Track

Bad tracks on the hard disk are mapped during the XENIX installation procedure. This allows XENIX to avoid those areas of the disk that cannot be read or written. However, hard disks can develop bad tracks after XENIX is installed and running. If this occurs, the **badtrk**(ADM) utility should be run by the super user (root) enabling XENIX to avoid the new bad track(s). Be sure to run **badtrk** in non-destructive mode to save the data on your hard disk. **badtrk** must be run in single-user mode. Use `/etc/shutdown su` to enter single-user mode from multi-user mode (see **shutdown**(ADM)).

**badtrk** is a menu-driven utility for viewing, adding, or deleting entries to the bad track table. See **badtrk**(ADM) in this guide for more on its options and their use.
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acctcom  Searches for and prints process accounting files.
accton  Turns on accounting.
adfmt  Formats SCSI hard disks.
aliashash  Micnet alias hash table generator.
asktime  Prompts for the correct time of day.
autoboot  Automatically boot system.
badtrk  Disk flaws, scans for flaws and creates bad track table.
chroot  Changes root directory for command.
chsh  Changes a user's login shell entry in the password file.
clri  Clears inode.
configure  Configures a XENIX system.
consoleprint  Print /usr/adm/messages or any file to a serial printer attached to the printer port of a serial console.
custom  Installs specific portions of the XENIX System.
dial  Establish an outgoing terminal line connection.
divvy  Divides disk partitions.
dmesg  Displays the system messages on the console.
dparam  Displays/chances hard disk characteristics.
fdisk  Maintain disk partitions.
fdswap  Swaps default boot floppy drives.
fixperm  Correct or initialize file permissions and ownership.
fsave  Interactive, error-checking file system backup.
fsck  Checks and repairs file systems.
fsdb  File system debugger.
fsname  Prints or changes the name of a file system.
fsphoto  Performs periodic semi-automated system backups.
haltys, reboot  Closes out the file systems and shuts down the system.
hdinstall  Places newly-created kernel in default location.
idleout  Logs out idle users.
install  Installation shell script.
ipcsm  Removes a message queue, semaphore set or shared memory ID.
ipcs  Reports the status of inter-process communication.
ip, isbs, ipbs  IMAGEN protocol handlers.
kbmode  Tests or configures keyboard support.
lpadmin  Configures the lineprinter spooling system.
lpinit  Adds, reconfigures and maintains lineprinters.
lpsched, lpshut, lpmove  Starts/stops the lineprinter.
makekey  Generates an encryption key.
mkdev  Calls scripts to add peripheral devices.
mkfs  Constructs a file system.
mkuser  Adds a login ID to the system.
mount  Mounts a file structure.
mvdir  Moves a directory.
ncheck  Generates names from inode numbers.
netutil  Administers the XENIX network.
pwadmin  Performs password aging administration.
rmuser  Removes a user account from the system.
runbig  Runs a command that may require more memory than normal.
schedule  Database for automated system backups.
setclock  Sets system real time clock.
setmnt  Establishes /etc/mnttab table.
settime  Changes the access and modification dates of files.
shutdown  Terminates all processing.
sync  Updates the super-block.
sysadmin  Performs file system backups and restores files.
sysadmsh  Menu driven system administration utility.
telinit, mkinittab  Alternative method of turning terminals on and off.
umount  Dismounts a file structure.
uuchek  Checks the uucp directories and permissions file.
uucico  File transport program for the uucp system.
uuclean  UUCP spool directory clean-up.
uuinstall  Administers UUCP control files.
uusched  The scheduler for the uucp file transport program.
uutry  Tries to contact remote system with debugging on.
uuxqt  Executes remote command requests.
wall  Writes to all users.
Name

intro - Introduction to system administration commands.

Description

This section contains the commands that are used to administrate and maintain the XENIX operating system. These commands are largely root-only, meaning that they can only be executed by the super-user (root).
ACCTCOM (ADM)  ACCTCOM (ADM)

Name

acctcom - Searches for and prints process accounting files.

Syntax

acctcom [[options][file]]

Description

acctcom reads file, the standard input, or /usr/adm/pacct, in the form described by acct (F) and writes selected records to the standard output. Each record represents the execution of one process. The output shows the COMMAND NAME, USER, TTYNAME, START TIME, END TIME, REAL (SEC), CPU (SEC), MEAN SIZE (K), and optionally, F (the fork/exec flag: 1 for fork without exec) and STAT (the system exit status).

The command name is prepended with a # if it was executed with super-user privileges. If a process is not associated with a known terminal, a ? is printed in the TTYNAME field.

If no files are specified, and if the standard input is associated with a terminal or /dev/null (as is the case when using & in the shell), /usr/adm/pacct is read, otherwise the standard input is read.

If any file arguments are given, they are read in their respective order. Each file is normally read forward, i.e., in chronological order by process completion time. The file /usr/adm/pacct is usually the current file to be examined; a busy system may need several files, in which case all but the current file will be found in /usr/adm/pacct?. The options are:

- b  Reads backwards, showing latest commands first.

- f  Prints the fork/exec flag and system exit status columns in the output.

- h  Instead of showing mean memory size, it shows the fraction of total available CPU time consumed by the process during its execution. This "hog factor" is computed as:

        (total CPU time)/(elapsed time).

- i  Prints columns containing the I/O counts in the output.

- k  Instead of memory size, shows total kcore-minutes.
-m Shows mean core size (the default).

-r Shows CPU factor (user time/(system-time + user-time)).

-t Shows separate system and user CPU times.

-v Excludes column headings from the output.

-l line Shows only processes belonging to terminal /dev/line.

-u user Shows only processes belonging to user that may be specified by a user ID, a login name that is then converted to a user ID, a # which designates only those processes executed with super-user privileges, or ? which designates only those processes associated with unknown user IDs.

-g group Shows only processes belonging to group. The group may be designated by either the group ID or group name.

-d mm/dd Any time arguments following this flag are assumed to occur on the given month and day, rather than during the last 24 hours. This is needed for looking at old files.

-s time Shows only those processes that existed on or after time, given in the form hr:min:sec. The :sec or :min:sec may be omitted.

-e time Shows only those processes that existed on or before time. Using the same time for both -s and -e shows the processes that existed at time.

-n pattern Shows only commands matching pattern that may be a regular expression as in ed (C) except that + means one or more occurrences.

-H factor Shows only processes that exceed factor, where factor is the “hog factor” as explained in option -h above.

-I number Shows driver processes transferring more characters than the cutoff number.

-O time Shows only those processes with operating system CPU time that exceeds time.

-C time Shows only those processes that exceed time (the total CPU time).

Multiple options have the effect of a logical AND.
Files

/etc/passwd
/usr/adm/pacct
/etc/group

See Also

accton(ADM), ps(C), su(C), acct(S), acct(F), utmp(F)

Notes

acctcom only reports on processes that have terminated; use ps(C) for active processes.
Name

accton - Turns on accounting.

Syntax

accton [file]

Description

accton turns on and off process accounting. If no file is given then accounting is turned off. If file is given, the kernel appends process accounting records. (See acct (S) and acct (F)).

Files

/etc/passwd Used for login name to user ID conversions
/usr/adm/pacct Current process accounting file
/usr/adm/sulogin Super-user login history file
/etc/wtmp Login/logout history file

See Also

acctcom(ADM), acct(S), acct(F), su(C), utmp(F)
Name

adfmt - Formats SCSI hard disks.

Syntax

/etc/adfmt device_name

Description

The adfmt command issues a format command to the SCSI disk device_name. device_name should be the character-special device representing the whole SCSI disk, for example, /dev/rhd00.

Notes

This utility is not applicable to all hardware/software configurations and may not be included in your distribution.

SCSI disks with embedded controllers are formatted as part of the manufacturing test procedure. Using adfmt on these disks is unnecessary.

Files

/dev/rhd?0

See Also

scsi(HW)
hd(HW)
Name

aliashash - Micnet alias hash table generator.

Syntax

`aliashash [ -v ] [ -o output-file ] [ input-file ]`

Description

The `aliashash` command reads the `input-file` and generates an `output-file` containing a hash table of alias definitions for a Micnet network. The `input-file` must name a file containing alias definitions in the form described for the `aliases` file (see `aliases(M)`). If the `-o` option is not used to specify an `output-file`, the command creates a file with the same name as the `input-file` but with `.hash` appended to it. If no `input-file` is given, the command reads the file named `/usr/lib/mail/aliases` and creates the file named `/usr/lib/mail/aliases.hash`.

If invoked with the `-v` option, the command lists information about the hash table.

The `output-file` will contain both the alias definitions given in the `input-file` and the new hash table. The hash table appears at the beginning of the file and is separated from the alias definitions by a blank line. The hash table has three or more lines. The first line is:

```
#<hash>
```

The second line has 4 entries: the bytes per table entry, the maximum number of items per hash value, the number of entries in the table, and the offset (in bytes) from the beginning of the file to the beginning of the alias definitions.

The next lines (up to the end of the hash table) contain the hash table entries. Each line has 8 entries (separated by spaces) and each entry has 2 fields. The first field (1 byte) is a checksum (represented as a printable character); the second field is a pointer (in bytes) to the alias definition. The pointer is represented as a hexadecimal number with leading blanks if necessary and is always relative to the start of the definitions.

The `aliashash` command is normally invoked by the `install` option of the `netutil` command. If the alias definitions of a network must be changed, the definitions in the `aliases` file should be changed and a new `aliases.hash` file created using the `aliashash` command. The new `aliases.hash` file must then be copied to all other computers in the network.
Files

/usr/lib/mail/aliashash
/usr/lib/mail/aliases
/usr/lib/mail/aliases.hash
/usr/lib/mail/maliases.hash

See Also

aliases(M), netutil(ADM)

Warning

Do not use the aliashash command to create the aliases.hash file while the network is running. If necessary, create a temporary output file, aliases.hash-, using the -o option, then enter:

    mv aliases.hash- aliases.hash

This will prevent disruption of the network.
Name

asktime - Prompts for the correct time of day.

Syntax

/etc/asktime

Description

This command prompts for the time of day. You must enter a legal time according to the proper format as defined below:

```
[[yy]mmdd]hhmm
```

Here the first $mm$ is the month number; $dd$ is the day number in the month; $hh$ is the hour number (24-hour system); the second $mm$ is the minute number; $yy$ is the last 2 digits of the year number and is optional. The current year is the default if no year is mentioned.

Examples

This example sets the new time, date, and year to "11:29 April 20, 1985".

Current system time is Wed Nov 3 14:36:23 PST 1985
Enter time ([yy]mmdd]hhmm): 8504201129

Diagnostics

If you enter an illegal time, asktime prompts with:

Try again:

Notes

asktime is normally performed automatically by the system startup file /etc/rc immediately after the system is booted; however, it may be executed at any time. The command is privileged, and can only be executed by the super-user.
Systems which autoboot will invoke `asktime` automatically on reboot. On these systems, if you don’t enter a new time or press return within 1 minute of invoking `asktime`, the system will use the time value it has. If RETURN alone is entered, the time is unchanged.
autoboot - Automatically boots the system.

The system can be set up to go through the *boot* stages automatically (as defined in `/etc/default/boot` when the computer is turned on (booted), provided no key is pressed at the *boot(HW)* prompt.

If *boot* times out and *LOADXENIX= YES*, then *XENIX* is passed the word ‘*auto*’ in its boot string and *init(M)*, *fsck(ADM)*, and *asktime(ADM)* are passed an -a flag.

In addition, the *TIMEOUT* entry can be set to specify the number of seconds to wait before timing out.

The *autoboot* procedure checks the file `/etc/default/boot` for the following instructions on autobooting:

- **LOADXENIX= YES or NO**: Whether or not *boot(HW)* times out and loads XENIX. *boot* looks for this variable in the `/etc/default/boot` file on its default device.
- **FSCKFIX= YES or NO**: Whether or not *fsck(ADM)* fixes any root system problems by itself. If the variable is set at YES, then *fsck(ADM)* is run on the root file system with the -rr flag.
- **MULTIUSER= YES or NO**: Whether or not *init(M)* invokes *su*login or proceeds to multiuser mode.
- **PANICBOOT= YES or NO**: Whether or not the system reboots after a panic(). This variable is read from `/etc/default/boot` by *init*.
- **RONLYROOT= YES or NO**: Whether or not the root filesystem is mounted readonly. This must be used only during installation, and not for a normal boot. It will effectively prevent writing to the filesystem.
- **DEFBOOTSTR=bootstring**: Set default bootstring to *bootstring*. This is the string used by *boot* when the user presses `<RETURN>` only to the “Boot:” prompt, or when *boot* times out.
SYSTTY=x

If x is one (1), the system console device is set to the serial adapter at COM. If x is zero (0), the system console is set to the main display adapter.

TIMEOUT=n

where n is the number of seconds to timeout at the "Boot:" prompt before booting the kernel (if LOADXENIX=YES). If TIMEOUT is unspecified, defaults to one minute.

If either the /etc/default/boot file or the variable needed cannot be found, the variable is assumed to be NO. However, if the filesystem cannot be found, PANICBOOT is YES.

The /etc/default/boot file is shipped with the following default figura-tion:

- LOADXENIX=YES
- FSCKFIX=YES
- MULTIUSER=YES
- PANICBOOT=NO

A scratch file is needed by fsck to check large filesystems. The user is informed during the installation of XENIX if the system needs a scratch file to fsck the root filesystem. If necessary, the installation procedure creates the filesystem /dev/scratch to write the fsck temporary file. fsck uses the file named on the /etc/default/boot line:

```
SCRATCH=
```

as a scratch file. If the installation procedure creates the scratch filesystem, the entry in the /etc/default/boot is automatically made.

SCRATCH need only be specified if the root filesystem is large enough to need a temporary file. If a file is specified, it is always passed to fsck when checking the root filesystem, even if the system is booted manually. The only exception is the first time XENIX is booted from the hard disk, when the user must specify the scratch file. The file specified as SCRATCH must not be on the filesystem being checked by fsck. SCRATCH also can not be on an unmounted filesystem.

If the XENIX mail system, mail(C), is installed on the system, the output of the boot sequence is mailed to root. Otherwise, the system administrator should check the file /etc/bootlog for the boot sequence output. The output of fsck(ADM) is temporarily saved in the file /dev/recover before it is moved to /etc/bootlog and finally may be sent to the system administrator via mail.
Other boot options which take affect during autoboot are documented on the boot(HW) manual page.

Files

/etc/bootlog
boot output log for autobothing systems

/etc/default/boot
boot information file

/etc/rc
instructions for entering multi-user mode, includes mounting and checking additional file systems

/etc/sulogin
executed at start-up, prompts the user to press Ctrl-d for multiuser mode or to enter the root password for maintenance mode

/dev/recover
allows saving of fsck output

/dev/scratch
temporary fsck file for large filesystems

See Also

boot(HW), fsck(ADM), init(M)

Notes

The utilities invoked during the boot procedure are passed the -a flag and time out only when the system autoboots. For example, asktime(ADM) times out after 30 seconds when the system autoboots, but waits for a response from the user any other time it is invoked.

The previous boot modes of AUTO=CLEAN, DIRTY, NEVER have been retained for backwards compatibility, but are ignored if any of the newer modes are present.
Name

badtrk - Scans fixed disk for flaws and creates bad track table.

Syntax

    badtrk [-e] [-s qtdn] [-f /dev/rhd*]

Description

Used chiefly during system installation, badtrk scans the media surface for flaws, creates a new bad track table, prints the current table, and adds and deletes entries to the table.

**WARNING:** The `-e` flag should not be invoked by the user. It is called by `hdinit` during installation to change the space allocated for bad tracks. Use of the `-e` flag at any other time may restructure the hard disk, rendering much of the information stored on it unusable.

To use `badtrk`, you must be in single user mode. (See `shutdown(ADM)`). To address the active XENIX partition on your primary fixed disk, enter:

    badtrk -f /dev/rhd0a

To address the active XENIX partition on your secondary fixed disk, enter:

    badtrk -f /dev/rhd1a

Usage

When `badtrk` is executed, the program first displays the main menu:

1. Print Current Bad Track Table
2. Scan Disk (You may choose Read-Only or Destructive later)
3. Add Entries to Current Bad Track Table by Cylinder/Head Number
4. Add Entries to Current Bad Track Table by Sector Number
5. Delete Entries Individually From Current Bad Track Table
6. Delete All Entries From Bad Track Table

Enter your choice or ‘q’ to quit:

You are prompted for option numbers, and, depending upon the option, more information may be queried for later.
A bad track table (option '1') might look like this:

<table>
<thead>
<tr>
<th>Cylinder</th>
<th>Head</th>
<th>Sector Number(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>190</td>
<td>3 12971-12987</td>
</tr>
</tbody>
</table>

Press <RETURN> to continue.

Option "2" scans the disk for flaws. If badtrak thinks changes may have been made to your bad track table since entering badtrak or updating your table, you will be asked if you want to update the device with the new table before scanning. You should answer "y" to save your changes, 'n' if you don't want to save changes made up to this point. Next you are prompted for more information. After you respond to these prompts, badtrak begins its scan. You can interrupt a scan by typing "q" at any time. You are then prompted to continue the scan or return to the main menu.

As the program finds flawed tracks, it displays the location of each bad track. An example error message might be:

wd: ERROR : on fixed disk ctrl=0 dev=0/47 block=31434 cmd=00000020 status=00005180, sector = 62899, cylinder/head = 483/4

(You may see this kind of message if there is a read or write error during the scanning procedure.)

When the scan is complete, the main menu reappears. The program automatically enters any detected flaws in the bad track table.

If there are no entries in your bad track table and a scan does not reveal any flaws, but your disk is furnished with a flaw map, you should enter these flaws into the bad track table. Select either option "3" or '4' to add the entries. (See next paragraph.)

To add flaw locations to an existing bad track table, select either option "3" or option "4", depending upon the format of the flaw map furnished with your disk. Enter the defective tracks, one per line.

When you are satisfied that badtrak contains a table of the desired flaws, quit the badtrak program by entering "q" at the main menu.

If badtrak was invoked with the -e option (which should only occur when called by hdinit, during the XENIX installation procedure), if you are reinstalling and you have a valid disk division table, the following message is displayed prior to the badtrak menu:
This device contains a valid division table. Additional (non-root) filesystems can be preserved across this reinstallation. If you wish to be able to preserve these file systems later, you must not change the current limit of the bad track table, which is \( n \) bad tracks. Do you wish to leave it unchanged? \(<y/n>:s+1\)

If you respond "y", you will not be prompted later to enter a new limit for the size of your bad track table. You can add or delete entries, but you will not be allowed to increase the maximum number of bad tracks allocated. If you respond "n" and the size of your bad track table is changed, your disk division table will be destroyed.

If you do not have a valid disk table or you selected "n" when prompted, you are prompted for the number of bad tracks to allocate. There will be a recommended number of replacement tracks to allocate based on the number of known bad tracks plus an allowance for tracks that will go bad in the future. You should choose to allocate at least as many as the recommended number of replacement tracks. Make your choice carefully, because if you want to change this amount later, you will have to reinstall XENIX.

At this point, you are asked if you want to "update". This is badtrk's way of asking if any changes which were made should be saved. You should answer "y" to save your changes, "n" to leave the bad track table as it was when last updated.

**Arguments**

- **-f name**
  
  Opens the partition name and reads the bad track table associated with that partition. The default is /dev/rhd0a.

- **-s options**
  
  Invokes badtrk non-interactively. Valid options for this flag are:

  - [q]uick
  - [t]horough
  - [d]estructive
  - [n]on-destructive

  The -s flag takes two options at a time. Choose quick or thorough scan, and destructive or non-destructive scan.

**Notes**

This utility can only be used in single-user mode.

If a bad spot develops in the boot blocks or system tables at the very beginning of the fdisk partition, reinstallation is required.
Files

/etc/badtrak
Name

chroot - Changes root directory for command.

Syntax

chroot newroot command

Description

The given command is executed relative to the new root. The meaning of any initial slashes (/) in pathnames is changed for a command and any of its children to newroot. Furthermore, the initial working directory is newroot.

Notice that:

chroot newroot command >x

creates the file x relative to the original root, not the new one.

This command is restricted to the super-user.

The new root pathname is always relative to the current root even if a chroot is currently in effect. The newroot argument is relative to the current root of the running process. Note that it is not possible to change directories to what was formerly the parent of the new root directory; i.e., the chroot command supports the new root as an absolute root for the duration of the command. This means that ‘‘../’’ is always equivalent to ‘‘/’’.

See Also

chdir(S)

Notes

Exercise extreme caution when referencing special files in the new root file system.

command must be under newroot or command is reported:
command: not found
Name

chsh - Changes a user's login shell entry in the password file.

Syntax

chsh

Description

chsh is used to modify the login shell entry in /etc/passwd. chsh prompts for a login name, confirms the entry, and prompts before making the actual change to /etc/passwd.

Files

/etc/passwd

See Also

passwd(C), passwd(F)

Notes

Only the super user can invoke chsh.
Name

clri - Clears inode.

Syntax

/etc/clri file-system i-number ...

Description

clri writes zeros on the 64 bytes occupied by the inode numbered i-number. File-system must be a special filename referring to a device containing a file system. After clri is executed, any blocks in the affected file will show up as "missing" if the file system is checked with fsck(ADM). Use clri only in emergencies and exercise extreme care.

Read and write permission is required on the specified file-system device. The inode becomes allocatable.

The primary purpose of this routine is to remove a file which, for some reason, does not appear in a directory. If you use clri to destroy an inode which does appear in a directory, track down the entry and remove it. Otherwise, when the inode is reallocated to some new file, the old entry will still point to this file. At that point removing the old entry will destroy the new file. The new entry will again point to an unallocated inode, so the whole cycle is likely to be repeated again and again.

See Also

fsck(ADM), ncheck(ADM)

Notes

If the file is open, clri is likely to be ineffective.
Name

config - Configures a XENIX system.

Syntax

/config [-i] [-c file] [-s] -m master dfile

description

/config takes a description of a XENIX system and generates compilable files that define the configuration tables for the various devices on the system.

Options include:

-m Specifies the name of the file that contains all the information regarding supported devices; /usr/sys/conf/master is the standard name. This file is supplied with the XENIX system and should not be modified by the user. The configure(ADM) utility should be used to update /usr/sys/conf/master and dfile.

-i Requests assembly-language output, instead of the default C language output.

-c Specifies the name of the configuration table file. c.c is the default names unless the -i option is given, in which case the default name is c.asm.

-s Specifies the name of the parameters file. space.c is the default name; if the -i option is used, the default name is space.inc.

dfile contains system device information and is divided into two parts. The first contains physical device specifications. The second contains system-dependent information. Any line with an asterisk (*) in column 1 is a comment. A standard dfile is provided as /usr/sys/conf/xenixconf. The configure(ADM) utility should also be used to update /usr/sys/conf/xenixconf.

All configurations are assumed to have a set of required devices, such as the system clock, which must be present to run XENIX. These devices must not be specified in dfile.

First Part of dfile

Each line contains two fields, delimited by spaces and/or tabs in the following format:
devname number

where devname is the name of the device, and number is the number (decimal) of devices associated with the corresponding controller. The device name can be any name given in part 1 of the /usr/sys/conf/master file, or any alias given in part 3 of the same file; number is optional, and if omitted, a default value which is the maximum value for that controller is used.

There are certain drivers that may be provided with the system that are actually pseudo-device drivers; that is, there is no real hardware associated with the driver. If the system has such drivers, they are described in section M of the XENIX User's Reference.

Second Part of dfile

The second part contains three different types of lines. Note that all specifications of this part are required, although their order is arbitrary.

1. root/pipe device specification

Two lines, each having three fields:

    root   devname   minor
    pipe   devname   minor

where devname is the name of the device, and minor is the minor device number (in octal). The device name can be any name given in part 1 of the /usr/sys/conf/master file, or any alias given in part 3 of the same file.

2. swap device specification

One line that contains five fields as follows:

    swap  devname   minor  swplo  nswap

where devname is the name of the device, minor is the minor device number (in octal), swplo is the lowest disk block (decimal) in the swap area, and nswap is the number of disk blocks (decimal) in the swap area. The device name can be any name given in part 1 of the /usr/sys/conf/master file, or any alias given in part 3 of the same file.

3. Parameter specification

One or more lines, each having two fields as follows:

    name   number
where name is a tunable parameter name, and number is the desired value (in decimal) for the given parameter. Only names that have been defined in part 4 of the /usr/sys/conf/master file can be used; number overrides the default value for the given parameter. The following is a list of the available parameters:

- **buffers**: Maximum number of external (mapped-out) buffers available to the kernel. If set to 0, config computes the optimum number for the system.
- **sabufs**: Maximum number of internal (non-mapped) buffers available.
- **hashbuf**: Maximum number of hash buffers.
- **inodes**: Maximum number of inodes per file system.
- **files**: Maximum number of open files per file system.
- **mounts**: Maximum number of mounted file systems.
- **coremap**: Maximum number of core map elements.
- **swapmap**: Maximum number of swap map elements.
- **pages**: Number of memory pages. On segmented systems such as the 286, this value should be 0.
- **calls**: Maximum number of entries in the system timeout table.
- **procs**: Maximum number of processes per system.
- **maxproc**: Maximum number of processes per user.
- **texts**: Maximum number of text segments per system.
- **clists**: Maximum number of clists per system.
- **locks**: Maximum number of file locks per system.
- **shdata**: Maximum number of shared data segments per system.
- **timezone**: Number of minutes difference between the local timezone and Greenwich Mean Time.
- **daylight**: Daylight savings time in effect (1) or not in effect (0).
- **msgmap**: Number of entries in message map.
- **msgmax**: Maximum message size.
- **msgmnb**: Maximum number of bytes in a message queue.
- **msgmni**: Number of message queue identifiers.
- **msgtql**: Number of message headers in the system.
- **msgssz**: Number of bytes in message segments.
- **msgseg**: Number of message segments.
- **semmap**: Number of entries in semaphore map.
- **semnmi**: Number of semaphore identifiers.
- **semnmu**: Number of undo structures in the system.
- **semmsm**: Maximum number of semaphores per identifier.
CONFIG (ADM)

semopm Maximum number of operations per `semop'(S) call.
semume Maximum number of undo entries per process.
semvmx Maximum semaphore value.
semaem Maximum value for "adjust on exit'.
semmns Number of semaphores in the system.
cmask Default file creation mask for process 0.
maxprocmem Maximum amount of memory available per process.
screens Number of Multiscreens for the systems.
emaps Maximum number of distinct eight-bit channel maps in the system.
nodename The nodename of the system (as used by `uucp'(C) and other programs).
npbuf The number of physical input/output buffers to allocate.
dmaexcl This is set to 1 if only 1 DMA channel is usable at once, 0 otherwise.

sdslots `sdslots * shdata` is the maximum number of simultaneous attaches to shared memory segments for the entire system.
memlim A process may occupy up to this percent of user memory, plus the swap area it can occupy (which is constrained by `swplim`). This parameter is only valid on 80286-based machines.
swplim A process may occupy up to this percent of swap area, plus the memory area it can occupy (which is constrained by `memlim`). This parameter is only valid on 80286-based machines.
maxbuf Maximum possible number of buffer cache buffers.
shless The number of shell-layer sessions.
shmmmax Specifies the maximum shared memory segment size. The default value is 131072.
shmmin Specifies the minimum shared memory segment size. The default value is 1.
shmmni Specifies the maximum number of shared memory identifiers system wide.
shmseg Specifies the number of attached shared memory segments per process.
shmmax Specifies the maximum number of in-use shared memory text segments.
nqueue The number of STREAMS queues to be configured.
**Examples**

Suppose you wish to configure a system with the following devices:

One HD disk drive controller with 1 drive  
One FD floppy disk drive controller with 1 drive

You must also specify the following parameter information:

- root device is an HD (pseudo disk 3)  
- pipe device is an HD (pseudo disk 3)  
- swap device is an HD (pseudo disk 2)  
  with a swplo of 0 and a nswap of 2300  
- number of buffers is 50  
- number of processes is 50  
- maximum number of processes per user ID is 15  
- number of mounts is 8  
- number of inodes is 120
number of files is 120
number of calls is 30
number of texts is 35
number of character buffers is 150
number of swapmap entries is 50
number of memory pages is 512
number of file locks is 100
timezone is pacific time
daylight time is in effect
number of entries in message map is 513
maximum message size is 8192
maximum number of bytes in a message queue is 16384
number of message queue identifiers is 10
number of message headers in the system is 40
message segment size is 8
number of message segments is 1024
number of entries in semaphore map is 21
number of semaphore identifiers is 10
number of undo structures in the system is 60
maximum number of semaphores per identifiers is 10
maximum number of operations per semop call is 5
maximum number of undo entries per process is 5
maximum semaphore value is 32767
maximum value for "adjust on exit" is 16384
number of semaphores in the system is 40

The actual system configuration would be specified as follows:

hd 1
fd 1
root hd 3
pipe hd 3
swap hd 2 0 2300
* Comments may be inserted in this manner
buffers 50
procs 150
maxproc 15
mounts 8
inodes 120
files 120
calls 30
texts 35
clists 150
swapmap 50
pages (1024/2);
locks 100
timezone (8*60)
daylight 1
msgmap (MSGSEG/2+1)
msgmax 8192
msgmnb 8192
msgmni 10

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msgql 40
msgsz 8
msgseg 1024
semmap (SEMMNS/2+1)
semni 10
semmnu 20
semmx 10
semopm 5
semume 5
semvmx 32767
semaem 16384
semmns 40

Files

/usr/sys/conf/master default input master device table
c.c default output driver configuration table file
space.c default output resource configuration table file
c.asm default driver configuration in assembly language
space.inc default resource configuration in assembly language

See Also

configure(ADM), master(F)

Diagnostics

Diagnostics are routed to the standard output and are self-explanatory.

Notes

The value on the right-hand side of a parameter specification must be a double-quoted character string, an integer, the name of another parameter defined within the master(F) file, or some arithmetical combination of integers and defined parameter names. Only the "+", "-", "*", and "/" operators can be used in an arithmetical expression. Expressions are interpreted left-to-right: if operator precedence is in doubt, parenthesize.
Name

configure - xenix configuration program.

Syntax

configure [options] [parm=val ... ]

Description

The configure program determines and alters different kernel resources. For end users, configure is easier than modifying the system configuration files directly. For device driver writers, configure avoids the difficulties of editing configuration files that have already been edited by an earlier driver configuration script.

Resources are modified interactively or with command-line arguments. Adding or deleting device driver components requires the command line options.

The next paragraphs discuss how to use configure interactively. Command line options are discussed in the “Options” section.

Interactive Usage

configure functions interactively when no options are given, or when -f is the only option specified on the command line.

When you invoke configure interactively, you first see a category menu that looks something like this:

1. Disk Buffers
2. Character Buffers
3. Files, Inodes, and Filesystems
4. Processes, Memory Management & Swapping
5. Clock
6. MultiScreens
7. Message Queues
8. Semaphores
9. Shared Data
10. System Name
11. Streams Data
12. Event Queues and Devices
13. Hardware Dependent Parameters

Select a parameter category to reconfigure by typing a number from 1 to 13, or type ‘q’ to quit:
To choose a category, enter its number, (e.g. "1" for "Disk Buffers") then press RETURN.

Each category contains a number of configurable resources. Each resource is presented by displaying its true name, a short description, and its current value. For example, for the "Disk Buffers" category you might see:

NBUF: total disk buffers. Currently determined at system start up:
NSABUF: system-addressable (near) disk buffers. Currently 10:
NHBUF: hash buffers (for disk block sorting). Currently 128:

To keep the current value, simply press RETURN. Otherwise, enter an appropriate value for the resource, then press RETURN. configure checks each value to make sure that it is within an appropriate range. If not, configure will warn you that the value is inappropriate and confirm that you wish to override the recommended value.

To exit from configure enter 'q' at the category menu prompt. If any changes are made, configure asks if it should update the configuration files with the changes. To keep the old configuration values, enter 'n' at this prompt, and no changes are made. Otherwise, enter 'y' and configure updates the required system configuration files. After configure has completed, the kernel is ready for linking.

To link the kernel, enter:

link xenix

Linking may take a few minutes. After the kernel is linked, enter the following commands to place a copy of the new kernel (xenix.new) in the root directory and reboot the system:

cp /usr/sys/conf/xenix /xenix.new
/etc/shutdown

Next, you see the boot prompt:

Boot :

To test the new kernel, enter the following at the boot prompt:

xenix.new

The system is now running the new kernel. When you are satisfied with the performance of the new kernel, enter the following command to install the new kernel on the hard disk:
/usr/sys/conf/hdinstall

The hdinstall(ADM) program backs up the old /xenix and copies /usr/sys/conf/xenix to /xenix.

Remove xenix.new by entering the following command:

    rm /xenix.new

Reboot the system to run the new kernel.

Options

The command line options are designed for writers of driver-installation shell scripts. You can configure drivers, remove driver definitions from the configuration files, and modify some driver attributes, all from the command line. There are also options for querying the current driver configuration.

configure uses the following options:

- a [ func1 func2 ... ]
- d [ func1 func2 ... ]
- b
- c
- d [ func1 func2 ... ]
- f master_file [ dfile ]
- g dev_name handler | dev_name
- j [ prefix ] [ NEXTMAJOR ]
- l priority_level
- m major
- n
- q
- r
- t
- v interrupt_vector [ interrupt_vector2... ]
- w
- x
- y resource

-m, -b, and -c
These options are used to define which driver is being referenced. Following -m must be the major device number of the driver. If you are configuring a block driver, -b must appear; if you are configuring a character driver, -c must appear. Both are used when configuring a driver with both kinds of interfaces.

-a and -d
Each option is followed by a list of functions to add or delete, respectively. These are the names of the functions that appear within bdevsw[] or cdevsw[], as appropriate, plus the names of the
initialization, clock poll, halt and interrupt routines, if present, plus
the names of the tty, stream, and tab structure pointers. configure
enforces the rules that all of a driver's routines must have a com-
mon prefix, and that the prefix be 2-4 characters long.

-j When followed by a prefix used by a driver, the major device
number is displayed. When followed by NEXTMAJOR, the smal-
lest major device number is displayed.

-r This option forces a rewrite of the configuration files regardless of
whether or not the command changed the configuration.

-v This option modifies the system notion of the vectors on which this
device can interrupt. A device may interrupt on up to 4 vectors.

-l This sets the interrupt priority level of the device, which is almost
always the same as the type of spl() call used: a driver that inter-
locks using spl5() almost always has an interrupt priority level of
5.

-q If the -q option is given, no qswtch() is possible after returning
from the device interrupt. Use of this option in new drivers is not
recommended.

-f The configuration is maintained in two data files, whose default
names are master and xenixconf. The -f option can be used to
specify alternate names. Note that if -f is the only option present,
the program is still interactive.

-n If -n is present, the two configuration data files are modified, but no
'.o' files are produced. This option is useful when configuring a
driver package containing multiple drivers.

-w This option suppresses warning messages.

-x This dumps all the resource prompts known to configure. These
reveal the name, description and current value of each parameter
capable of being reconfigured. Category prompts are not dumped.

-y The -y option prints out the current value of the requested resource.

-t This option prints out nothing (except possibly error messages).
However, it has a return value of 1 if a driver corresponding to the
given combination of -m, -b, -c and options is already configured,
and returns 0 if no such driver is present.

-g This option is used to add or remove graphics input (GIN) device
handlers. Devices such as mice, bitpads, and keyboards may have
handlers to turn their input data into 'events.' The -g flag may be
given one argument that is interpreted as a device name. That GIN
device is removed from the configuration files. If the -g flag has
two arguments, the second is a handler for that device, and the
device is added to the files. If it was already present, its handler is
updated and the user is informed. Multiple devices may be added
or removed by specifying \texttt{-g} multiple times.

\textbf{Setting Command-line Parameters}

Any number of arguments can be given on the command line of the
form \texttt{resource=value}. These arguments can be given at the same
time as an add or delete driver request, but must follow all the driver-
configuration arguments on the command line.

Some resources have values that are character strings. In this case
their values must be enclosed within the characters \texttt{	extbackslash"}. The quotes are
syntactically necessary for them to be used as C-language strings, and
the backslashes protect the quotes from being removed by the shell.

\textbf{Examples}

Print out the current value of NCLIST:

\begin{verbatim}
configure -y NCLIST
\end{verbatim}

Return 1 if character major device 7 and vector 3 are available:

\begin{verbatim}
configure -t -v 7 -m 3 -c
\end{verbatim}

Add a clock-time polling and initialization routine to the already
configured "foo" driver, a hypothetical character driver at major
device #17:

\begin{verbatim}
configure -a foopoll fooinit -c -m 17
\end{verbatim}

Delete the "foo" driver:

\begin{verbatim}
configure -m 17 -d -c
\end{verbatim}

Add a new "hypo" driver, a block driver with a character interface. It
absorbs 3 different interrupt vectors, at priority 6:

\begin{verbatim}
configure -a hypoopen hypoclose hyporead hypowrite hypoioctl\hypostrategy hypotab hypointr -b -c -1 6 -v 17 42 49
\end{verbatim}

\textbf{Notes}

\textbf{Kernel Data Space Restrictions (286 only)}

If the total size of all the allocated resources grows too large, the
group will not fit within the kernel's 64k near data segment. You will
not see messages about excessive size from \texttt{configure}, but you may
see them from the linker when you attempt to link the kernel.
Files

/usr/sys/conf/master
/usr/sys/conf/xenixconf
/usr/sys/conf/config

See Also

master(F), config(ADM), event(M), hdinstall(ADM)
Name

consoleprint - print /usr/adm/messages or any file to a serial printer attached to the printer port of a serial console

Syntax

consoleprint [ file ]

Description

console(C) prints the file /usr/adm/messages to a printer attached to the printer port of a serial console. If a filename is specified, it is printed instead. consoleprint is normally run by a system administrator to get a hardcopy version of the system console messages.

This command uses the file /etc/termcap.

Files

/etc/termcap

See Also

lprint(C)

Notes

The only terminals currently supported with entries in /etc/termcap are the Tandy DT-100 and DT-1, and the Hewlett-Packard HP-92.

Terminal communications parameters (such as baud rate and parity) must be set up on the terminal by the user.
Name

custom - Installs specific portions of the XENIX System

Syntax


Description

With custom you can create a custom installation by selectively installing or deleting portions of the XENIX system. custom is executable only by the super-user and is either interactive or can be invoked from the command line with several options.

Files are extracted or deleted in packages. A package is a collection of individual files. Packages are grouped together in sets.

Three default sets are always available:

- Operating System
- Development System
- Text Processing System

You can also install additional sets. You can list the available packages by using the custom command as described next.

Usage

To use custom interactively, enter:

    custom

You see a list of sets. For example:

    1. Operating System
    2. Development System
    3. Text Processing System
    4. Add a Supported Product

The program prompts you to choose a set from which to work. If the data files for that set are not already installed on the hard disk, custom prompts you for the floppy which contains these data files and installs them. You may also see menu items for each product that has been previously added using the "Add a Supported Product" option. If you are adding a new product, you will be prompted for volume 1 of the new product distribution and custom will extract the product information necessary to support it.
When you select a valid set, you see a menu like this:

1. Install one or more packages
2. Remove one or more packages
3. List the files in a package
4. Install a single file
5. Select a new set to customize
6. Display current disk usage
7. Help

When you enter a menu option, you are prompted for further information. This is what the options prompt, and what action occurs:

1. Install
   Prompts for one or more package names.
   Calculates which installation volumes (distribution media) are needed, then prompts for the correct volume numbers. If multiple packages are specified, the names should be separated by spaces on the command line.

   This option, as well as "2" and "3," displays a list of all available packages in the currently selected set. Each line describes the package name, whether the package is fully installed, not installed or partially installed, the size of the package (in 512 byte blocks), and a one line description of the package contents.

2. Remove
   Prompts for one or more package names.
   Deletes the correct files in the specified package. If multiple packages are specified the names should be separated by spaces on the command line.

   Displays available packages (see option "1").

3. List files in a package
   Lists all files in the specified package.
   Prompts for one or more package names. Enter the name of the desired package(s).

   Displays available packages (see option "1").
4. Install a single file
   Extract the specified file from the distribution set.
   
   Filename should be a full pathname relative to the root directory "/".

5. Select a new set
   Allows you to work from a different set than the current one.

6. Display current disk usage
   Tells you your current disk usage.

7. Help
   Prints a page of instructions to help you use custom.

Options

Three arguments are required for a completely non-interactive use of custom:

   A set identifier
   (-o, -d, or -t),

   A command
   (-i, -r, -l, or -f),

   And either one or more package names, or a file name

If any information is missing from the command line, custom prompts for the missing data.

Only one of -o, -d, or -t may be specified. These stand for:

-o Operating System

-d Development System

-t Text Processing System

Only one of -i, -r, -l, or -f may be specified, followed by an argument of the appropriate type (one or more package names, or a file name). These options perform the following:
-i  Install the specified package(s)
-r  Remove the specified package(s)
-l  List the files in the specified package(s).
-f  Install the specified file.

The -m flag allows the media device to be specified. The default is /dev/install (which is always the 0 device, as in /dev/fd0). This is very useful if the system has a 5.25-inch drive on /dev/fd0 and a 3.5-inch floppy on /dev/fd1, and it is necessary to install 3.5-inch media. For example:

    custom -m /dev/rfd196ds9

this will override the default device and use the one supplied with the -m flag.

Files

/etc/base.perms
/etc/soft.perms
/etc/text.perms
/etc/perms/*

See Also

fixperm(ADM), df(C), du(C), install(ADM)

Notes

If you upgrade any part of your system, custom detects if you have a different release and prompts you to insert the floppy volume that updates the custom data files. Likewise, if you insert an invalid product or a volume out of order, you will be prompted to reinsert the correct volume.
Name

dial, uuchat - Dials a modem.

Syntax

/usr/lib/uucp/dialX ttynname telno speed
/usr/lib/uucp/dialX -h ttynname speed
/usr/lib/uucp/uuchat ttynname speed chat-script

Description

/usr/lib/uucp/dialX dials a modem attached to ttynname. (X is a dialer name, such as HA1200.) The -h option is used to hang up the modem.

uucico(ADM), ct(C), and cu(C) use /usr/lib/uucp/dialX. Four dialer programs are distributed. dialHA12 is for the Hayes® Smartmodem 1200 and 1200B (and compatibles). dialHA24 is for the Hayes® Smartmodem 2400 (and compatibles). dialVA3450 is for the Racal-Vadic VA3450-Series dialers. dialTBIT is for the Telebit Trailblazer. Source for these is provided in their respective .c files.

uucico(ADM) invokes dial, with a ttynname, telno (phone number), and speed. dial attempts to dial the phone number on the specified line at the given speed. When using the dialHA12 or dialHA24 speed can be a range of baud rates. The range is specified with the form:

lowrate - highrate

where lowrate is the minimum acceptable connection baud rate and highrate is the maximum. The dial program returns the status of the attempt through the following dial return codes:

bit 0x80 = 1
The connection attempt failed.

bits 0x0f =
If bit 0x80 is a 1, then these bits are the dialer error code:

0 general or unknown error code.
1 line is being used.
2 a signal has aborted the dialer.
3 dialer arguments are invalid.
4 the phone number is invalid.
5 the baud rate is invalid or the dialer could not connect at the requested baud rate.
6 can’t open the line.
7 ioctl error on the line.
8 timeout waiting for connection.
9 no dialtone was detected.
10 unused.
11 unused.
12 unused.
13 phone is busy.
14 no carrier is detected.
15 remote system did not answer.

Error codes 12-15 are used to indicate that the problem is at the remote end.

If bit 0x80 is a 0, then these bits are used to indicate the actual connection baud rate. If 0, the baud rate is the same as the baud rate used to dial the phone number or the highest baud rate if a range was specified. Otherwise, these four bits are the CBAUD bits in the struct termio e_flag and the struct sgttyb sg_ispeed and sg_ospeed tty ioctl structures.

You can copy and modify one of the files /usr/lib/uucp/dialHA12.c etc., to use a different modem. There is a makefile in /usr/lib/uucp which should be modified for the new dialer, and can be used to compile the new program.

If you create a dial program for another modem, send us the source. User generated dial programs will be considered for inclusion in future releases.

The dial program to be used on a particular line is specified in the fifth field of the entry for that line in /usr/lib/uucp/Devices. If there is no dial program of that name, then uucico, ct, and cu use a built-in dialer, together with the chat-script of that name in /usr/lib/uucp/Dialers.
**dial** -h is executed by **getty** when it is respawned on a line shared between dial-in and dial-out. If there is no **dial** program, then **getty** uses **/usr/lib/uucp/uuchat**, passing it the & chat-script from **/usr/lib/uucp/Dialers**.

**Files**

- **/usr/lib/uucp/Devices**
- **/usr/lib/uucp/dialVA3450**  
  Racal Vadic 3450 dialer
- **/usr/lib/uucp/dialHA12**  
  Hayes Smartmodem 1200/1200B dialer
- **/usr/lib/uucp/dialHA24**  
  Hayes Smartmodem 2400 dialer
- **/usr/lib/uucp/makefile**  
  Makefile to compile new dialer
- **/usr/lib/uucp/dialTBIT**  
  Telebit Trailblazer dialer
- **/usr/lib/uucp/uuchat**

**See Also**

- ct(C), cu(C), uucico(ADM), getty(M)

**Notes**

You must have the XENIX Development System installed in order to compile and install a new **dial** program.
Name

divvy - Disk dividing utility

Syntax

divvy -b block_device -c character_device [-v virtual_drive]
[-p physical_drive] [-i ] [-m ]

Description

divvy divides an fdisk(ADM) partition into a number of separate areas known as “divisions”. A division is identified by unique major and minor device numbers and can be used for a file system, swap area, or for isolating bad spots on the device.

With divvy you can:

- Divide a disk or fdisk partition into separate devices.
- Create new file systems.
- Change the device names of file systems.
- Change the size of file systems.
- Remove file systems.

Options

Options to divvy are:

-b block_device
   Major device number of block interface.

-c character_device
   Major device number of character interface.

-v virtual_device
   For dividing a virtual drive.

-p physical_drive
   For dividing one of several physical disks that share the same controller.

-i Disk being divided will contain a root file system on division 0.

-m Disk being divided should be made into a number of mountable file systems.
Usage

The device being divided must be a block device with a character interface. For example, to use divvy on a device with a block-interface major number 1 and character interface number of 1, enter:

```
divvy -b 1 -c 1
```

The -v option specifies which virtual drive to divide. The default is the active drive. Here, "virtual drive" is the same as an MS-DOS partition. Virtual drive numbers are determined with the fdisk(ADM) utility.

The -p option allows division of one of several physical disks sharing a controller. divvy defaults to the first physical device numbered "0." To access a second physical disk, use the -p 1 option.

The -i option specifies the device being divided will contain a root file system. With this option, device nodes are created relative to the new root, generally a hard disk, instead of the current root, often an installation floppy. A root filesystem and a recover area are created. divvy prompts for the size of the swap area. If the disk is large enough, then divvy prompts for a separate /u (user) filesystem. divvy also prompts for block-by-block control over the layout of the filesystem(s). If the root filesystem is large enough to require a scratch filesystem, (more than 40,000 blocks) then divvy will prompt for whether one should be created. divvy is invoked with the -i option during XENIX installation.

The -m option is used for initial installation on devices that will not be used as the root. It causes the user to be prompted for a number of file systems.

When divvy is invoked from the command line, you see a main menu:

```
name] Name or rename a division.
c[reate] create a new file system on this division.
p[revent] Prevent a new file system from being created on this division.
s[tart] Start a division on a different block.
e[nd] End a division on a different block.
r[estore] Restore the original partition table.
```

Please enter your choice or 'q' to quit:

To choose a command, enter the first letter of the command, then press RETURN.
The `divvy` division table might look something like this:

<table>
<thead>
<tr>
<th>Name</th>
<th>New File System?</th>
<th>#</th>
<th>First Block</th>
<th>Last Block</th>
</tr>
</thead>
<tbody>
<tr>
<td>root</td>
<td>no, exists</td>
<td>0</td>
<td>0</td>
<td>13754</td>
</tr>
<tr>
<td>swap</td>
<td>no, exists</td>
<td>1</td>
<td>13755</td>
<td>15135</td>
</tr>
<tr>
<td>u</td>
<td>no, exists</td>
<td>2</td>
<td>15136</td>
<td>25135</td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>3</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>4</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>no</td>
<td>5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>recover</td>
<td>no, exists</td>
<td>6</td>
<td>25136</td>
<td>25145</td>
</tr>
<tr>
<td>d1057all</td>
<td>no</td>
<td>7</td>
<td></td>
<td>25546</td>
</tr>
</tbody>
</table>


\( x \) blocks for divisions, \( y \) blocks reserved for the system

`divvy` also displays information about block allocation for system tables and bad tracks.

If you select option ‘n’, you can change the name of the device. `divvy` prompts you for the division number (from the `divvy` table displayed above), then for a new name.

Option ‘c’ causes a given division to become a new, empty file system when you exit from `divvy`. After using the ‘c’ option, you will see a ‘yes’ in the ‘New File System?’ column. If you use option ‘p,’ the ‘yes’ in the ‘New File System?’ column will change to a ‘no’, and the contents of the division will not change.

With the ‘s’ or ‘start’ command, you can start a division on a different block number. With the ‘e’ or ‘end’ command, you can end a division on a different block number.

You can use these two commands to change the size of a partition. For example, if your disk is similar to the one in the sample `divvy` table above, and you want to make the root file system larger and the swap area smaller, do this:

Make the swap area smaller with the ‘s’ command.

Use the ‘e’ command to make the root division bigger.

Note that if any of the divisions overlap, `divvy` will complain when you try to exit and put you back in the menus to correct the situation.

The ‘r’ or ‘restore’ command restores the original partition table. This is useful if you make a serious mistake and want to return to where you started.

When you exit from `divvy`, you are prompted whether you want to save any changes you made, or exit without saving the changes. At this time, you can also go back to the `divvy` menu, and may also have the option to reinstall the original, default partition table.
See Also

badtrk(ADM), fdisk(ADM), fsck(ADM), hd(M), mkdev(C), mkfs(C), mknod(C)

Notes

divvy requires kernel level support from the device driver. If divvy lists the size of a disk as "0" blocks, or displays the following error messages, the device may not support dividing:

cannot read division table

or:

cannot get drive parameters

These errors may also occur if the prerequisite programs fdisk and badtrk are not run correctly.

If you change the size of filesystems (such as /u) after you have installed a XENIX filesystem, you will have to run mkfs on the filesystem and reinstall the files that are kept there. This is because the free list for that filesystem has changed. Be sure to backup the files in any filesystem you intend to change, using backup(C), tar(C), or cpio(C), before you run divvy. After XENIX is installed, the bounds of the root filesystem must not be changed.

During installation, if the filesystem on division 0 (generally root) becomes or remains large enough to require a scratch area during fsck, and one does not already exist, divvy prompts for whether one should be created. (The resulting filesystem, /dev/scratch, is used by autoboot if it runs fsck. /dev/scratch should also be entered when fsck prompts for a scratch file name, provided that the filesystem being checked is not larger than the root filesystem.) If all disk divisions have been used up, divvy will not prompt for a scratch filesystem, even if the root filesystem is large enough to require one.

This utility uses BSIZE blocks. Refer to the machine (HW) manual page for the size of filesystem blocks.
Name

dmesg - Displays the system messages on the console.

Syntax

dmesg [- ]

Description

The dmesg command displays all the system messages that have been generated since the last time the system was booted. If the option - is specified, it displays only those messages that have been generated since the last time the dmesg command was performed.

dmesg can be invoked periodically by placing instructions in the file /usr/lib/crontab. It can also be invoked automatically by /etc/rc whenever the system is booted. See "Notes", below.

dmesg logs all error messages it prints in /usr/adm/messages. If dmesg is invoked automatically, the messages file continues to grow and can become very large. The system administrator should occasionally erase its contents.

Files

/etc/dmesg
/usr/adm/messages
/usr/adm/msgbuf

Notes

dmesg is included in this release for backwards compatibility only. The device /dev/error provides a more flexible means of logging error messages, and is recommended over dmesg. See error(М) for more information.

See Also

cron(C), error(M), messages(M)
Name

dparam - Displays/changes hard disk characteristics.

Syntax

dparam [ -w ]
dparam /dev/rhd[01]0 [characteristics]

Description

The dparam command displays or changes the hard disk characteristics currently in effect. These changes go into effect immediately and are also written to the master boot block for subsequent boots. If a non-standard hard disk is used, this utility must be called before accessing the drive.

-w Causes a copy of /etc/masterboot to be copied to disk to ensure that non-standard hard disks are supported for the specified drive. This call must precede a call to write non-standard disk parameters for the desired parameters to be saved correctly in the masterboot block.

When called without options or disk characteristics, dparam prints the current disk characteristics (on the standard output) for the specified hard disk. These values are printed in the same order as the argument list.

When writing characteristics for the specified hard disk, dparam changes the current disk controller status and updates the masterboot block. The argument ordering is critical and must be entered as specified below. All characteristics must be entered when writing disk characteristics, otherwise an error is returned. Hard disk characteristics (in respective order) are:

<table>
<thead>
<tr>
<th>number of cylinders</th>
<th>total number of cylinders on the hard disk</th>
</tr>
</thead>
<tbody>
<tr>
<td>number of heads</td>
<td>number of heads</td>
</tr>
<tr>
<td>write cylinder</td>
<td>hardware specific, consult your hardware manual</td>
</tr>
<tr>
<td>write precompensation cylinder</td>
<td>hardware specific, consult your hardware manual</td>
</tr>
</tbody>
</table>
DPARAM (ADM)

\begin{itemize}
  \item **ecc** \hspace{1cm} number of bits of error correction on I/O transfers, consult your hardware manual
  \item **control** \hspace{1cm} very hardware specific, consult your hardware manual
  \item **landing zone cylinder** \hspace{1cm} where to park heads after shutting down the system
  \item **number of sectors per track** \hspace{1cm} number of sectors per track on the hard disk
\end{itemize}

**Examples**

\begin{itemize}
  \item dparam -w
  \item dparam /dev/rhd10
  \item dparam /dev/rhd00 700 4 256 180 5 0 640 17
\end{itemize}

**Notes**

This utility changes the kernel’s view of the hard disk parameters. It may be subject to restrictions imposed by the hardware configuration.
Name

`fdisk` - Maintain disk partitions.

Syntax

```
fdisk [-p] [-ad partition] [-c partition start size] [-f devicename]
```

Description

`fdisk` displays information about disk partitions. `fdisk` also creates and deletes disk partitions and changes the active partition. `fdisk` functionality is a superset of the MS-DOS command of the same name. `fdisk` is usually used interactively from a menu.

The hard disk has at most four partitions. Only one partition is active at any given time. It is possible to assign a different operating system to each partition. Once a partition is made active, the operating system resident in that partition boots automatically once the current operating system is halted.

To use XENIX, at least one partition must be assigned to XENIX.

The `fdisk` utility does not allocate the first track or the last cylinder on the hard disk when the "Use Entire Disk for XENIX" option is used. The first track on the hard disk is reserved for masterboot and the last cylinder is generally used when running hard disk diagnostics. You should not allocate the last cylinder if you plan to run diagnostics on your hard disk.

For example, if a disk has 2442 tracks, `fdisk` reports these as tracks 0-2441. If your hard disk has 4 heads, `fdisk` will assign (using the "Use Entire Disk for XENIX" option) tracks 1-2437. (Track 0 is reserved for masterboot.) The last cylinder (tracks 2438-2441) is not assigned with the "Use Entire Disk for XENIX" option.

Partitions are defined by a "partition table" at the end of the master boot block. The partition table provides the location and size of the partitions on the disk. The partition table also defines the active partition. Each partition can be assigned to XENIX, DOS, or some other operating system. Once a DOS partition is set up, DOS files and directories resident in the DOS partition may be accessed while running XENIX by means of the `dos(C)` commands. DOS may be booted without the DOS partition being active via the "boot:dos" command. See `boot(HW)`.

Arguments
These flags are used to invoke \texttt{fdisk} non-interactively:

\begin{itemize}
  \item \texttt{-p} prints out the disk partition table.
  \item \texttt{-a \textit{number}} activates the specified partition number.
  \item \texttt{-d \textit{number}} deletes the specified partition number.
  \item \texttt{-c \textit{number start size}} creates partition with specified start and size.
  \item \texttt{-f \textit{name}} Open device \textit{name} and read the partition table associated with that device's partition. The default is \texttt{/dev/rhd00}.
\end{itemize}

\section*{Options}

The \texttt{fdisk} command displays a prompt and a menu of five options. Updates to the disk are not made until you enter "q" from the main menu.

1. Display Partition Table.
   This option displays a table of information about each partition on the hard disk. The \texttt{PARTITION} column gives the partition number. The \texttt{STATUS} column tells whether the partition is active (A) or inactive (I). \texttt{TYPE} tells whether the partition is XENIX, DOS, or "other". The option also displays the starting track, ending track and total number of tracks in each partition.

2. Use Entire Disk for XENIX.
   \texttt{fdisk} creates one partition that includes all the tracks on the disk, except the first track and the last cylinder. This partition is assigned to XENIX and is designated the active partition.

3. Create XENIX Partition
   This option allows the creation of a partition by altering the partition table. \texttt{fdisk} reports the number of tracks available for each partition and the number of tracks in use. \texttt{fdisk} prompts for the partition to create, the starting track and size in tracks. The change is written to the operating system and the hard disk when you enter "q" from the main menu.

4. Activate Partition
   This option activates the specified partition. Only one partition may be active at a time. The change is not effective until you exit. The operating system residing in the newly activated partition boots once the current operating system is halted.

5. Delete Partition
   This option requests which partition you wish to delete. \texttt{fdisk} reports the new available amount of disk space in tracks. The change is not effective until you exit.
Exit the `fdisk` program by typing a `q` at the main `fdisk` menu. Your changes are now written to the operating system and the hard disk.

**Notes**

The minimum recommended size for a XENIX partition is 5 megabytes.

Since `fdisk` is intended for use with DOS, it may not work with all operating system combinations.

**See also**

dos(C), hd(HW).
Name

fdswap - swaps default boot floppy drive.

Syntax

fdswap [onl off]

Description

*fdswap* tells the CMOS to swap the default floppy drive used to read boot information at boot time. For example, if your computer defaults to read boot information on drive A, *fdswap on* changes the default drive to drive B.

*fdswap* with no arguments reports the current *fdswap* state, on or off. *fdswap off* switches the drive setting back to the default configuration. Changing the drives take effect on the next boot of the system.

Notes

This utility is not applicable to all hardware/software configurations and may not be included in your distribution.

Support for this functionality is only available on a small number of machines. The ROMs must recognize and interpret the CMOS flag that specifies that the floppy drives are swapped.
Name

fixperm - Correct or initialize file permissions and ownership.

Syntax

fixperm [ -cfgilnsvwDS [ -d package] ] specfile

Description

For each line in the specification file specfile, fixperm makes the listed pathname conform to a specification. fixperm is typically used to configure a XENIX system upon installation. Non-superusers can only use fixperm with the -n, -f, -D or -I flags. To use any other flags, you must be superuser.

The specification file has the following format: Each non-blank line consists of either a comment or an item specification. A comment is any text from a pound sign "#" up to the end of the line. There is one item specification per line. User and group id numbers must be specified at the top of the specification file for each user and group mentioned in the file. The syntax for the definition section is simple: the first field indicates the type of id (either uid or gid), the second contains the name reference for the id, and the third is the corresponding numeric id. Example:

```
uid   root   0
```

An item specification consists of a package specifier, a permission specification, owner and group specifications, the number of links on the file, the file name, and an optional volume number.

The package specifier is an arbitrary string which is the name of a package within a distribution set. A package is a set of files.

After the package specifier is a permission specification. The permission specification consists of a file type, followed by a numeric permission specification. The item specification is one of the following characters:

- x  Executable.
- a  Archive.
- e  Empty file (create if -c option given).
- b  Block device.
c Character device.

d Directory.

f Text file.

p Named pipe.

If the item specification is used as an upper-case letter, then the file associated with it is optional, and `fixperm` will not return an error message if it does not exist.

The numeric permission conforms to the scheme described in `chmod(C)`. The owner and group permissions are in the third column separated by a slash: e.g., "`bin/bin`". The fourth column indicates the number of links. If there are links to the file, the next line contains the linked filename with no other information. The fifth column is a pathname. The pathname must be relative, i.e., not preceded by a slash "`/`". The sixth column is only used for special files, giving the major and minor device numbers, or volume numbers.

**Options**

The following options are available from the command line:

-c Create empty files and missing directories. Also or creates (or modifies) device files.

-g Instructs `fixperm` to list devices as specified in the permlist (similar to the `--flag`, which lists files on standard output). No changes are made as a result of this flag.

-d package
   Process input lines beginning with given package specifier string (see above). For instance, `--dBASE` processes only items specified as belonging to the Basic utilities set. The default action is to process all lines.

-u package
   Like `--u`, but processes items that are not part of the given package.

-f List files only on standard output. Does not modify target files.

-i Check only if the selected packages are installed. Return values are:

<table>
<thead>
<tr>
<th>Return Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>package completely installed</td>
</tr>
<tr>
<td>4</td>
<td>package not installed</td>
</tr>
<tr>
<td>5</td>
<td>package partially installed</td>
</tr>
</tbody>
</table>
-l List files and directories on standard output. Does not modify target files.

-n Report errors only. Does not modify target files.

-D List directories only on standard output. Does not modify target files.

-v Verbose, in particular, issues a complaint if executable files are word swapped, not fixed stack, not separate I and D, or not stripped.

-s Modify special device files in addition to the rest of the permlist.

-w Lists where (what volume) the specified files or directories are located.

-S Issues a complaint if files are not in x.out format.

The following two lines make a distribution and invoke tar(C) to archive only the files in perms.inst on /dev/sample:

```
/etc/fixperm -f /etc/perms/inst > list
tar cfF /dev/sample list
```

This example reports BASE package errors:

```
/etc/fixperm -nd BASE
```

Notes

Usually fixperm is only run by a shell script at installation.

See Also

custom (ADM)
Name

fsave - Interactive, error-checking filesystem backup

Synopsis

`fsave` filesystem [ dumpinfo ] [ mediainfo ] [ sitename ]

Description

`fsave` is used by `fsphoto` (ADM) to provide a semi-automated interface to `backup` (C) for backing-up XENIX filesystems. Human intervention is required to mount and dismount tapes or floppies at the appropriate times, but is kept to a minimum to reduce the potential for error.

The operator is prompted each time some action is required, such as mounting or unmounting a tape or floppy. These prompts, and their possible selections, are described below.

For all prompts, an answer of `h`, `H`, or `?` will display a short summary of the possible answers.

Filesystem dump (backup)

The following prompt displays the defaults (gleaned from the `schedule` database file) and presents options to alter them:

```
Level dumplevel dump of filesystem filesystem, date
   media size: size feet [or Kb]  media drive: drive
   This media will be saved for howlong, and is howvital.
```

`M`ounted volume, `P`ostpone, `C`heck or `F`ormat volumes, `R`etension or `H`elp:

The values displayed dictate the following instructions: `filesystem` is to be backed-up using `size`-foot long magtapes (or `size`-kilobyte big floppies) mounted on drive `drive`. The `media` will be saved for `howlong` ("1 year," "2 months," etc.), and being a level `dumplevel` dump, is `howvital` ("critical," "precautionary," etc.).

The menu options are:

`m` A volume of the asked for `size` has been mounted (write-enabled), so begin the dump.

`mnewsize` Insufficient volumes of the originally asked for `size` are available, so a `newsize` big volume has been mounted instead. If the dump extends across more than one volume, each volume must be of the same `size`. 

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Postpone this backup until later (fsphoto will automatically retry this filesystem next time it is run).

Recheck the volumes used to backup filesystem for errors. This answer is useful when a dump mysteriously fails and fsave is starting over from the beginning, but the operator doesn’t believe there really is a problem (for example, the tape drive was accidentally left offline or the floppy door was left open), and wants to check the volumes again.

Format the currently mounted volume (useful mainly for floppies).

Format check

The format of ‘‘critical’’ volumes are checked using dumpdir(C):

Check vital volumes for format errors
M)ounted first volume, S)kip format check, or H)elp:

The menu options are:

m The first volume has been (or still is) mounted, and dumpdir can now check the volume format.

s Skip checking the volume format, and continue on to the read error check (below).

The format is not always checked, but when it is, the first volume written must be mounted.

Read error check

All volumes are read using restor(C), which checks for errors during reading. If an error occurs, the dump is declared unsuccessful and is retried from the beginning.

Check vital volumes for read errors
M)ounted which volume, E)rror on previous volume, D)one, S)kip checks, or H)elp:

The menu options are:

m The which (‘‘first’’ or ‘‘next’’) volume has been mounted on the drive and is ready to be checked for read errors.
e An error occurred on the last volume checked, and the dump should be retried.

d All volumes have been checked and no errors occurred, so the filesystem has been successfully backed-up; This backup is done.

s Don't bother (skip) checking the rest of the volumes for read errors.

Every volume should be checked for read errors; restor requires the volumes to be checked in first-to-last order. Volumes that produce read errors should be marked "suspect," discarded and the dump run once again.

After the backup has been successfully performed, instructions are given on how to label the volumes.

Arguments

fsave is normally run by fsphoto, which passes all the proper arguments based on the schedule (ADM) database.

filesystem
The filesystem to be backed-up.

dumpinfo
A set of blank-separated strings that give some optional information about this backup:

dumplevel size savetime importance marker

Each of these component strings may be quoted and can thus contain spaces.

dumplevel The level of the dump to be performed. This is a single digit from 0 to 9 (passed to dump), or the letter x (which means no dump is to be done). The default is to perform a level 0 dump.

size The size of the media volumes that should be used. This should be in feet for tapes and kilobytes for floppies. A size of - means to use the first size listed in mediainfo. This is the default.

savetime How long this backup is to be saved (for example, "3 months"). Default is "1 year."

importance How important is this backup? (For example, "critical" or "precautionary.") Those which are "critical" have their format checked by dumpdir. Default is
Either "none" (the default) or an additional label to place on each volume (for example, "a pink sticker").

A typical dumpinfo might look like:

9 1200 "2 weeks" useful "a blue X"

which specifies that a level 9 dump is to be done on a 1200 foot tape (or 1200 kilobyte floppy) which will be saved for 2 weeks and is to be marked with a blue cross (in addition to a more descriptive label). This backup is merely considered "useful" and thus will not be checked by dumpdir.

mediainfo
A set of blank-separated strings that give some optional information about this the media to be used:

\[\text{drive} \  d \ \text{density sizes} \ldots \ [\text{format}]\]
\[\text{drive} \  k \ \text{sizes} \ldots \ [\text{format}]\]

drive The name of backup device to use. The default is /dev/rmt0.

k sizes... If k is specified, drive is assumed to be a floppy, and the list of sizes which follow define the allowable capacities of the floppies that can be used (in kilobytes).

d density sizes...
Otherwise, d must be specified. In this case, drive is assumed to be a magtape at density BPI, in one of the possible sizes (in feet).

format The XENIX command used to format the tape or floppy so described.

A mediainfo describing 9-track magtape would be:

\[\text{media} /dev/rmt0 \ d \ 1600 \ 2400 \ 1200 \ 600\]
\[\text{media} /dev/rmt2 \ d \ 800 \ 1400 \ 1200 \ 600\]

which specifies that /dev/rmt0 is a 1600 BPI magtape capable of handling 2400, 1200, and 600 foot reels, and that /dev/rmt2 is the 800 BPI device.

A floppy might be described with:

\[\text{media} /dev/fd0 \ k \ 1024 \ \text{format} /dev/fd0\]
which describes device /dev/fd0 as a megabyte (1024 kilobytes)
floppy formatted by the command:

    format /dev/fd0

sitename
Where this backup was made (for example, the name of the company or which building). Note that the uucp(C) nodename from
/etc/systemid is automatically placed on the volume labels.

Only the super-user can execute the fsave command.

Files

/etc/systemid
Name of this machine.

/etc/ddate
Dump-maintained record of last time each filesystem was backed-up.

/dev/tty
Always-existent character-special device.

See Also

fsphoto(ADM), schedule(ADM), backup(C), dumpdir(C), restor(C), basename(C),

Diagnostics

A successful backup exits successfully (0), but errors generate a complaint and an exit status of 1. fsave complains about illegal or incorrect arguments, and exits with a status of 2.

If the backup of filesystem is postponed, fsave exits with a status of 3.
Name

fsck - Checks and repairs filesystems.

Syntax

/bin/fsck [ options ] [ filesystem ] ...

Description

fsck audits and interactively repairs inconsistent conditions for XENIX System V filesystems. If the filesystem is consistent, the number of files, number of blocks used, and number of blocks free are reported. If the filesystem is inconsistent, the operator is prompted for concurrence before each correction is attempted. It should be noted that most corrective actions result in some loss of data. The amount and severity of the loss may be determined from the diagnostic output. (An experienced operator can resolve discrepancies manually using fsdb(ADM), the filesystem debugger.) The default action for each consistency correction is to wait for the operator to respond "yes" or "no". If the operator does not have write permission fsck defaults to the action of the -n option.

The following flags are interpreted by fsck:

-\(y\) Assumes a yes response to all questions asked by fsck.

-\(n\) Assumes a no response to all questions asked by fsck; do not open the filesystem for writing.

-\(sb:c\) Ignores the actual free list and (unconditionally) reconstructs a new one by rewriting the super-block of the filesystem. The filesystem must be unmounted while this is done.

The -\(sb:c\) option allows for creating an optimal free-list organization. The following forms are supported:

-\(s\)

-\(sB\) Blocks-per-cylinder:Blocks-to-skip (filesystem interleave)

(for anything else)

If \(b:c\) is not given, then the values used when the filesystem was created are used. If these values were not specified, then a reasonable default value is used.

-\(S\) Conditionally reconstructs the free list. This option is like -\(sb:c\) above except that the free list is rebuilt only if there are no discrepancies discovered in the filesystem. Using -\(S\) forces a "no" response to all questions asked by fsck. This option is useful for forcing free list reorganization on uncontaminated
If `fsck` cannot obtain enough memory to keep its tables, it uses a scratch file. If the `-t` option is specified, the file named in the next argument is used as the scratch file, if needed. Make certain you leave a space between the `-t` and the filename, or `fsck` will use the entire filesystem as a scratch file and erase the entire disk. If you created a scratch filesystem during installation then you can use `/dev/scratch` as the filename, provided that the filesystem being checked is no larger than the root filesystem. Without the `-t` flag, `fsck` prompts the operator for the name of the scratch file. The file chosen should not be on the filesystem being checked, and if it is not a special file or did not already exist, it is removed when `fsck` completes. If the system has a large hard disk there may not be enough space on another filesystem for the scratch file. In such cases, if the system has a floppy drive, use a blank, formatted floppy in the floppy drive with (for example) `/dev/fd0` specified as the scratch file.

Quiet `fsck`. Do not print size-check messages in Phase 1. Unreferenced fifoS files will selectively be removed. If `fsck` requires it, counts in the superblock will be automatically fixed and the free list salvaged.

Directories are checked for bad blocks. Useful after system crashes.

Fast check. Check block and sizes (Phase 1) and check the free list (Phase 5). The free list will be reconstructed (Phase 6) if it is necessary.

Recovers the root filesystem. The required `filesystem` argument must refer to the root filesystem, and preferably to the block device (normally `/dev/root`). This switch implies `-y` and overrides `-n`. If any modifications to the filesystem are required, the system will be automatically shutdown to ensure the integrity of the filesystem.

Causes any supported filesystem to be converted to the type of the current filesystem. The user is prompted to verify the request for each filesystem that requires conversion unless the `-y` option is specified. It is recommended that every filesystem be checked with this option `while unmounted` if it is to be used with the current version of XENIX. To update the active root filesystem, it should be checked with:

```
fsck -c -rr /dev/root
```

If no `filesystems` are specified, `fsck` reads a list of default filesystems from the file `/etc/checklist`. 

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Inconsistencies checked are as follows:

- Blocks claimed by more than one inode or the free list
- Blocks claimed by an inode or the free list outside the range of the filesystem
- Incorrect link counts
- Size checks:
  - Incorrect number of blocks
  - Directory size not 16-byte aligned
- Bad inode format
- Blocks not accounted for anywhere
- Directory checks:
  - File pointing to unallocated inode
  - Inode number out of range
- Super block checks:
  - More than 65536 inodes
  - More blocks for inodes than there are in the filesystem
- Bad free block list format
- Total free block or free inode count incorrect

Orphaned files and directories (allocated but unreferenced) are, with the operator's concurrence, reconnected by placing them in the lost+found directory. The name assigned is the inode number. The only restriction is that the directory lost+found must preexist in the root of the filesystem being checked and must have empty slots in which entries can be made. This is accomplished by making lost+found, copying a number of files to the directory, and then removing them (before fsck is executed).

Files

/etc/checklist Contains default list of filesystems to check
/etc/default/boot Automatic boot control

See Also

autoboot(ADM), fsdb(ADM), checklist(F), filesystem(F), init(M)
Notes

*fsck* will not run on a mounted non-raw filesystem unless the filesystem is the root filesystem or unless the -n option is specified and no writing out of the filesystem will take place. If any such attempt is made, a warning is displayed and no further processing of the filesystem is done for the specified device.

Although checking a raw device is almost always faster, there is no way to tell if the filesystem is mounted. And cleaning a mounted filesystem will almost certainly result in an inconsistent superblock.

Warning

File systems created under XENIX-86 version 3.0 are not supported under XENIX System V because the word ordering in type *long* variables has changed. *fsck* is capable of auditing and repairing XENIX version 3.0 file systems if the word ordering is correct.

For the root filesystem, "*fsck -rr /dev/root*" should be run. For all other filesystems, "*fsck /dev/??*" on the unmounted block device should be used.

Diagnostics

Initialization Phase

Command syntax is checked. Before the filesystem check can be performed, *fsck* sets up certain tables and opens some files. The *fsck* terminates on initialization errors.

General Errors

Three error messages may appear in any phase. While they seem to offer the option to continue, it is generally best to regard them as fatal, end the run, and investigate what may have caused the problem.

**CAN NOT SEEK: BLK B (CONTINUE?)**

The request to move to a specified block number $B$ in the filesystem failed. The occurrence of this error condition indicates a serious problem (probably a hardware failure) that may require additional help.

**CAN NOT READ: BLK B (CONTINUE?)**

The request for reading a specified block number $B$ in the filesystem failed. The occurrence of this error condition indicates a serious problem (probably a hardware failure) that may require additional help.
CANNOT WRITE: BLK B (CONTINUE?)
The request for writing a specified block number $B$ in the filesystem failed. The disk may be write-protected.

**Meaning of Yes/No Responses**

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTINUE?</td>
<td>Terminates program.</td>
<td>Attempts to continue to run filesystem check. Often, however, the problem persists. The error condition does not allow a complete check of the filesystem. A second run of \textit{fsck} should be made to recheck this filesystem.</td>
</tr>
<tr>
<td></td>
<td>(This is the recom-</td>
<td></td>
</tr>
<tr>
<td></td>
<td>mended response.)</td>
<td></td>
</tr>
</tbody>
</table>

Phase 1: Check Blocks and Sizes

This phase checks the inode list.

**Meaning of Yes/No Responses—Phase 1**

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTINUE?</td>
<td>Terminates the pro-</td>
<td>Continues with the program.</td>
</tr>
<tr>
<td></td>
<td>gram.</td>
<td>This error condition means that a complete check of the filesystem is not possible. A second run of \textit{fsck} should be made to recheck this filesystem.</td>
</tr>
<tr>
<td></td>
<td>(Recommended response.)</td>
<td></td>
</tr>
<tr>
<td>CLEAR?</td>
<td>Ignores the error condi-</td>
<td>Deallocates i-node $I$ by zeroing its contents. This may invoke the UNALLOCATED error condition in Phase 2 for each directory entry pointing to this i-node.</td>
</tr>
<tr>
<td></td>
<td>tion.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A NO response is only</td>
<td></td>
</tr>
<tr>
<td></td>
<td>appropriate if the user</td>
<td></td>
</tr>
<tr>
<td></td>
<td>intends to take other</td>
<td></td>
</tr>
<tr>
<td></td>
<td>measures to fix the</td>
<td></td>
</tr>
<tr>
<td></td>
<td>problem.</td>
<td></td>
</tr>
</tbody>
</table>

**Phase 1 Error Messages**

UNKNOWN FILE TYPE I=I (CLEAR?)
The mode word of the i-node $I$ suggests that the i-node is not
a pipe, special character i-node, regular i-node, or directory i-node.

**LINK COUNT TABLE OVERFLOW (CONTINUE?)**
An internal table for *fsck* containing allocated i-nodes with a link count of zero has no more room.

**B BAD I=I**
I-node *I* contains block number *B* with a number lower than the number of the first data block in the filesystem or greater than the number of the last block in the filesystem. This error condition may invoke the EXCESSIVE BAD BLKS error condition in Phase 1 if i-node *I* has too many block numbers outside the filesystem range. This error condition invokes the BAD/DUP error condition in Phase 2 and Phase 4.

**EXCESSIVE BAD BLOCKS I=I (CONTINUE?)**
There is more than a tolerable number (usually 10) of blocks with a number lower than the number of the first data block in the filesystem or greater than the number of the last block in the filesystem associated with i-node *I*.

**B DUP I=I**
I-node *I* contains block number *B*, which is already claimed by another i-node. This error condition may invoke the EXCESSIVE DUP BLKS error condition in Phase 1 if i-node *I* has too many block numbers claimed by other i-nodes. This error condition invokes Phase 1B and the BAD/DUP error condition in Phase 2 and Phase 4.

**EXCESSIVE DUP BLKS I=I (CONTINUE?)**
There is more than a tolerable number (usually 10) of blocks claimed by other i-nodes.

**DUP TABLE OVERFLOW (CONTINUE?)**
An internal table in *fsck* containing duplicate block numbers has no more room.

**POSSIBLE FILE SIZE ERROR I=I**
The i-node *I* size does not match the actual number of blocks used by the i-node. This is only a warning. If the -q option is used, this message is not printed.

**DIRECTORY MISALIGNED I=I**
The size of a directory i-node is not a multiple of 16. This is only a warning. If the -q option is used, this message is not printed.
PARTIALLY ALLOCATED INODE $I=I$ (CLEAR?)
I-node $I$ is neither allocated nor unallocated.

Phase 1B: Rescan for More DUPS

When a duplicate block is found in the filesystem, the filesystem is rescanned to find the i-node that previously claimed that block. When the duplicate block is found, the following information message is printed:

\[
\text{B DUP } I=I \\
\text{I-node } I \text{ contains block number } B, \text{ which is already claimed by another i-node. This error condition invokes the BAD/DUP error condition in Phase 2. I-nodes with overlapping blocks may be determined by examining this error condition and the DUP error condition in Phase 1.}
\]

Phase 2: Check Path Names

This phase removes directory entries pointing to bad inodes found in Phase 1 and phase 1B.

**Meaning of Yes/No Responses—Phase 2**

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FIX?</td>
<td>Terminates the program since <code>fsck</code> will be unable to continue.</td>
<td>In Phase 2, a <code>y(yes)</code> response to the FIX? prompt says: Change the root i-node type to &quot;directory.&quot; If the root i-node data blocks are not directory blocks, a very large number of error conditions are produced.</td>
</tr>
</tbody>
</table>

(Continued)
<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTINUE?</td>
<td>Terminates the program.</td>
<td>Ignores the DUPS/BAD error condition in root i-node and attempt to continue to run the filesystem check. If root i-node is not correct, then this may result in a large number of other error conditions.</td>
</tr>
<tr>
<td>REMOVE?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Removes duplicate or unallocated blocks.</td>
</tr>
</tbody>
</table>

**Phase 2 Error Messages**

**ROOT INODE UNALLOCATED. TERMINATING**
The root i-node (always i-node number 2) has no allocate mode bits. The occurrence of this error condition indicates a serious problem. The program stops.

**ROOT INODE NOT DIRECTORY (FIX?)**
The root i-node (usually i-node number 2) is not directory i-node type.

**DUPS/BAD IN ROOT INODE (CONTINUE?)**
Phase 1 or Phase 1B found duplicate blocks or bad blocks in the root i-node (usually i-node number 2) for the filesystem.

**I OUT OF RANGE I=I NAME=F (REMOVE?)**
A directory entry $F$ has an i-node number $I$ that is greater than the end of the i-node list.

**UNALLOCATED I=I OWNER=O MODE=M SIZE=S MTIME=T NAME=F (REMOVE?)**
A directory entry $F$ has an i-node $I$ without allocate mode bits. The owner $O$, mode $M$, size $S$, modify time $T$, and filename $F$ are printed. If the filesystem is not mounted and the `-n` option was not specified, the entry is removed automatically if the i-node it points to is character size 0.

**DUP/BAD I=I OWNER=O MODE=M SIZE=S MTIME=T**

May 16, 1988
DIR=F (REMOVE?)
Phase 1 or Phase 1B found duplicate blocks or bad blocks associated with directory entry F, directory i-node I. The owner O, mode M, size S, modify time T, and directory name F are printed.

DUP/BAD I=I OWNER=O MODE=M SIZE=S MTIME=T FILE=F (REMOVE?)
Phase 1 or Phase 1B found duplicate blocks or bad blocks associated with file entry F, i-node I. The owner O, mode M, size S, modify time T, and filename F are printed.

BAD BLK B IN DIR I=I OWNER=O MODE=M SIZE=S MTIME=T
This message only occurs when the -D option is used. A bad block was found in DIR i-node I. Error conditions looked for in directory blocks are nonzero padded entries, inconsistent "." and ".." entries, and embedded slashes in the name field. This error message means that the user should at a later time either remove the directory i-node if the entire block looks bad or change (or remove) those directory entries that look bad.

Phase 3: Check Connectivity

This phase is concerned with the directory connectivity seen in Phase 2.

Meaning of Yes/No Responses—Phase 3

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>RECONNECT?</td>
<td>Ignores the error condition. This invokes the UNREF error condition in Phase 4. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Reconnects directory i-node I to the filesystem in directory for lost files (usually lost+found). This may invoke a lost+found error condition if there are problems connecting directory i-node I to lost+found. This invokes CONNECTED information message if link was successful.</td>
</tr>
</tbody>
</table>
Phase 3 Error Messages

UNREF DIR I=I OWNER=O MODE=M SIZE=S MTIME=T (RECONNECT?)
   The directory i-node I was not connected to a directory entry when the filesystem was traversed. The owner O, mode M, size S, and modify time T of directory i-node I are printed. The fsck program forces the reconnection of a nonempty directory.

SORRY. NO lost+found DIRECTORY
   There is no lost+found directory in the root directory of the filesystem; fsck ignores the request to link a directory in lost+found. This invokes the UNREF error condition in Phase 4. Possible problem with access modes of lost+found.

SORRY. NO SPACE IN lost+found DIRECTORY
   There is no space to add another entry to the lost+found directory in the root directory of the filesystem; fsck ignores the request to link a directory in lost+found. This invokes the UNREF error condition in Phase 4. Clean out unnecessary entries in lost+found or make lost+found larger (see Procedure 5.2).

DIR I=I1 CONNECTED. PARENT WAS I=I2
   This is an advisory message indicating a directory i-node I1 was successfully connected to the lost+found directory. The parent i-node I2 of the directory i-node I1 is replaced by the i-node number of the lost+found directory.
Phase 4: Check Reference Counts

This phase checks the link count information seen in Phases 2 and 3.

*Meaning of Yes/No Responses—Phase 4*

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>RECONNECT?</td>
<td>Ignores this error condition.</td>
<td>Reconnect i-node $I$ to filesystem in the directory for lost files (usually <em>lost+found</em>). This can cause a <em>lost+found</em> error condition in this phase if there are problems connecting i-node $I$ to <em>lost+found</em>.</td>
</tr>
<tr>
<td>CLEAR?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Deallocates the i-node by zeroing its contents.</td>
</tr>
<tr>
<td>ADJUST?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Replaces link count of file i-node $I$ with $Y$.</td>
</tr>
<tr>
<td>FIX?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Replaces count in super-block by actual count.</td>
</tr>
</tbody>
</table>

*Phase 4 Error Messages*

UNREF FILE I=$I$ OWNER=$O$ MODE=$M$ SIZE=$S$ MTIME=$T$
(RECONNECT?)

I-node $I$ was not connected to a directory entry when the filesystem was traversed. The owner $O$, mode $M$, size $S$, and
modify time $T$ of i-node $I$ are printed. If the -n option is omitted and the filesystem is not mounted, empty files are cleared automatically. Nonempty files are not cleared.

**SORRY. NO lost+found DIRECTORY**

There is no lost+found directory in the root directory of the filesystem; fsck ignores the request to link a file in lost+found. This invokes the CLEAR error condition later in Phase 4. Possible problem with access modes of lost+found.

**SORRY. NO SPACE IN lost+found DIRECTORY**

There is no space to add another entry to the lost+found directory in the root directory of the filesystem; fsck ignores the request to link a file in lost+found. This invokes the CLEAR error condition later in Phase 4. Check size and contents of lost+found.

(CLEAR)

The i-node mentioned in the immediately previous UNREF error condition cannot be reconnected.

**LINK COUNT FILE I=I OWNER=O MODE=M SIZE=S MTIME=T COUNT=X SHOULD BE Y (ADJUST?)**

The link count for i-node $I$, which is a file, is $X$ but should be $Y$. The owner $O$, mode $M$, size $S$, and modify time $T$ are printed.

**LINK COUNT DIR I=I OWNER=O MODE=M SIZE=S MTIME=T COUNT=X SHOULD BE Y (ADJUST?)**

The link count for i-node $I$, which is a directory, is $X$ but should be $Y$. The owner $O$, mode $M$, size $S$, and modify time $T$ of directory i-node $I$ are printed.

**LINK COUNT F I=I OWNER=O MODE=M SIZE=S MTIME=T COUNT=X SHOULD BE Y (ADJUST?)**

The link count for $F$ i-node $I$ is $X$ but should be $Y$. The filename $F$, owner $O$, mode $M$, size $S$, and modify time $T$ are printed.

**UNREF FILE I=I OWNER=O MODE=M SIZE=S MTIME=T (CLEAR?)**

I-node $I$, which is a file, was not connected to a directory entry when the filesystem was traversed. The owner $O$, mode $M$, size $S$, and modify time $T$ of i-node $I$ are printed. If the -n option is omitted and the filesystem is not mounted, empty files are cleared automatically. Nonempty directories are not cleared.
FSCK (ADM)

UNREF DIR  I=I  OWNER=O  MODE=M  SIZE=S  MTIME=T (CLEAR?)
I-node I, which is a directory, was not connected to a directory entry when the filesystem was traversed. The owner O, mode M, size S, and modify time T of i-node I are printed. If the -n option is omitted and the filesystem is not mounted, empty directories are cleared automatically. Nonempty directories are not cleared.

BAD/DUP FILE I=I  OWNER=O  MODE=M  SIZE=S  MTIME=T (CLEAR?)
Phase 1 or Phase 1B found duplicate blocks or bad blocks associated with file i-node I. The owner O, mode M, size S, and modify time T of i-node I are printed.

BAD/DUP DIR I=I  OWNER=O  MODE=M  SIZE=S  MTIME=T (CLEAR?)
Phase 1 or Phase 1B found duplicate blocks or bad blocks associated with directory i-node I. The owner O, mode M, size S, and modify time T of i-node I are printed.

FREE INODE COUNT WRONG IN SUPERBLK (FIX?)
The actual count of the free i-nodes does not match the count in the super-block of the filesystem. If the -q option is specified, the count will be fixed automatically in the super-block.

Phase 5: Check Free List

This phase checks the free-block list.

Meaning of Yes/No Responses—Phase 5

<table>
<thead>
<tr>
<th>Prompt</th>
<th>n (no)</th>
<th>y (yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTINUE?</td>
<td>Terminates the program.</td>
<td>Ignores rest of the free-block list and continue execution of fsck. This error condition will always invoke BAD BLKS IN FREE LIST error condition later in Phase 5.</td>
</tr>
</tbody>
</table>

(Continued)
<table>
<thead>
<tr>
<th>Prompt</th>
<th>n(no)</th>
<th>y(yes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FIX?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Replaces count in super-block by actual count.</td>
</tr>
<tr>
<td>SALVAGE?</td>
<td>Ignores the error condition. A NO response is only appropriate if the user intends to take other measures to fix the problem.</td>
<td>Replaces actual free-block list with a new free-block list. The new free-block list will be ordered according to the gap and cylinder specs of the -s or -S option to reduce time spent waiting for the disk to rotate into position.</td>
</tr>
</tbody>
</table>

**Phase 5 Error Messages**

**EXCESSIVE BAD BLKS IN FREE LIST (CONTINUE?)**
The free-block list contains more than a tolerable number (usually 10) of blocks with a value less than the first data block in the filesystem or greater than the last block in the filesystem.

**EXCESSIVE DUP BLKS IN FREE LIST (CONTINUE?)**
The free-block list contains more than a tolerable number (usually 10) of blocks claimed by i-nodes or earlier parts of the free-block list.

**BAD FREEBLK COUNT**
The count of free blocks in a free-list block is greater than 50 or less than 0. This error condition will always invoke the BAD FREE LIST condition later in Phase 5.

**X BAD BLKS IN FREE LIST**
X blocks in the free-block list have a block number lower than the first data block in the filesystem or greater than the last block in the filesystem. This error condition will always invoke the BAD FREE LIST condition later in Phase 5.
X DUP BLKS IN FREE LIST
X blocks claimed by i-nodes or earlier parts of the free-list block were found in the free-block list. This error condition will always invoke the BAD FREE LIST condition later in Phase 5.

X BLK(S) MISSING
X blocks unused by the filesystem were not found in the free-block list. This error condition will always invoke the BAD FREE LIST condition later in Phase 5.

FREE BLK COUNT WRONG IN SUPERBLOCK (FIX?)
The actual count of free blocks does not match the count in the super-block of the filesystem.

BAD FREE LIST (SALVAGE?)
This message is always preceded by one or more of the Phase 5 information messages. If the -q option is specified, the free-block list will be salvaged automatically.

Phase 6: Salvage Free List
This phase reconstructs the free-block list. It has one possible error condition that results from bad blocks-per-cylinder and gap values.

Phase 6 Error Messages

DEFAULT FREE-BLOCK LIST SPACING ASSUMED
This is an advisory message indicating the blocks-to-skip (gap) is greater than the blocks-per-cylinder, the blocks-to-skip is less than 1, the blocks-per-cylinder is less than 1, or the blocks-per-cylinder is greater than 500. The values of 7 blocks-to-skip and 400 blocks-per-cylinder are used.

Cleanup Phase
Once a filesystem has been checked, a few cleanup functions are performed. The cleanup phase displays advisory messages about the filesystem and status of the filesystem.

Cleanup Phase Messages

X files Y blocks Z free
This is an advisory message indicating that the filesystem checked contained X files using Y blocks leaving Z blocks free in the filesystem.

***** BOOT XENIX (NO SYNC!) *****
This is an advisory message indicating that a mounted filesystem or the root filesystem has been modified by fsck. If the XENIX system is not rebooted immediately without sync, the work done by fsck may be undone by the in-core copies of tables the UNIX system keeps. If the -b option of the fsck command was specified and the filesystem is root, a reboot is automatically done.

***** FILE SYSTEM WAS MODIFIED *****

This is an advisory message indicating that the current filesystem was modified by fsck.
**Name**

fsdb - File system debugger.

**Syntax**

`/etc/fsdb` special [ - ]

**Description**

`fsdb` can be used to patch up a damaged file system after a crash. It has conversions to translate block and i-numbers into their corresponding disk addresses. Also included are mnemonic offsets to access different parts of an i-node. These greatly simplify the process of correcting control block entries or descending the file system tree.

`fsdb` contains several error-checking routines to verify i-node and block addresses. These can be disabled if necessary by invoking `fsdb` with the optional - argument or by the use of the O symbol. (`fsdb` reads the i-size and f-size entries from the superblock of the file system as the basis for these checks.)

Numbers are considered decimal by default. Octal numbers must be prefixed with a zero. During any assignment operation, numbers are checked for a possible truncation error due to a size mismatch between source and destination.

`fsdb` reads a block at a time and will therefore work with raw as well as block I/O. A buffer management routine is used to retain commonly used blocks of data in order to reduce the number of read system calls. All assignment operations result in an immediate write-through of the corresponding block.

The symbols recognized by `fsdb` are:

- `#` absolute address
- `i` convert from i-number to i-node address
- `b` convert to block address
- `d` directory slot offset
- `+,-` address arithmetic
- `q` quit
- `>`,`<` save, restore an address
- `=` numerical assignment
- `=+` incremental assignment
- `=-` decremental assignment
- `="` character string assignment
- `O` error checking flip flop
- `p` general print facilities
The print facilities generate a formatted output in various styles. The current address is normalized to an appropriate boundary before printing begins. It advances with the printing and is left at the address of the last item printed. The output can be terminated at any time by typing the delete character. If a number follows the p symbol, that many entries are printed. A check is made to detect block boundary overflows since logically sequential blocks are generally not physically sequential. If a count of zero is used, all entries to the end of the current block are printed. The print options available are:

- `i` print as i-nodes
- `d` print as directories
- `o` print as octal words
- `e` print as decimal words
- `c` print as characters
- `b` print as octal bytes

The `f` symbol is used to print data blocks associated with the current i-node. If followed by a number, that block of the file is printed. (Blocks are numbered from zero.) The desired print option letter follows the block number, if present, or the `f` symbol. This print facility works for small as well as large files. It checks for special devices and that the block pointers used to find the data are not zero.

Dots, tabs, and spaces may be used as function delimiters but are not necessary. A line with just a new-line character will increment the current address by the size of the data type last printed. That is, the address is set to the next byte, word, double word, directory entry or i-node, allowing the user to step through a region of a file system. Information is printed in a format appropriate to the data type. Bytes, words and double words are displayed with the octal address followed by the value in octal and decimal. A `.B` or `.D` is appended to the address for byte and double word values, respectively. Directories are printed as a directory slot offset followed by the decimal i-number and the character representation of the entry name. I-nodes are printed with labeled fields describing each element.

The following mnemonics are used for i-node examination and refer to the current working i-node:

- `md` mode
- `ln` link count
- `uid` user ID number
- `gid` group ID number
Examples

386i     prints i-number 386 in an i-node format. This now becomes the current working i-node.

ln=4     changes the link count for the working i-node to 4.

ln+=1    increments the link count by 1.

fc       prints, in ASCII, block zero of the file associated with the working i-node.

2i.fd    prints the first 32 directory entries for the root i-node of this file system.

d5i.fc   changes the current i-node to that associated with the 5th directory entry (numbered from zero) found from the above command. The first logical block of the file is then printed in ASCII.

512B.p0o prints the superblock of this file system in octal.

2i.a0b.d7=3 changes the i-number for the seventh directory slot in the root directory to 3. This example also shows how several operations can be combined on one command line.

d7.nm="name" changes the name field in the directory slot to the given string. Quotes are optional when used with nm if the first character is alphabetic.

a2b.p0d   prints the third block of the current i-node as directory entries.

See Also

fsck(ADM), dir(F), filesystem(F).
Name

fsname-  Prints or changes the name of a file system.

Syntax

fsname [-p] [-s name ] /dev/device

Description

The /etc/fsname utility is used to print or change the name of a filesystem. The options are:

-p  Select the "pack" name field instead of the filesystem name field.

-s name  Changes the specified field in the superblock.

The default action is to print the name of the filesystem.

See Also

mkfs(C), ustat(S), filesystem (F)
Name

fsphoto - Performs periodic semi-automated system backups

Syntax

fsphoto [-i] schedule [ drive ]

Description

fsphoto, in conjunction with fsave (ADM), provides a semi-automated interface to backup (C) for backing-up XENIX filesystems. A human operator is required to mount and dismount tapes or floppies at the appropriate times, so some interaction is necessary, but all such interaction is kept to a minimum to reduce the potential for human error.

The selection and timing of backups for all filesystems is governed by the schedule (ADM) database. The system administrator must set up this file, and make arrangements to run fsphoto on the implicitly defined schedule (normally once per weekday). fsphoto can be invoked most easily from the sysadmin (ADM) menu. fsphoto interprets schedule, and for each filesystem that should be backed-up on that day, runs fsave to interact with the operator and backup the filesystem without error.

The optional argument drive specifies the magtape or floppy device to use; the default is specified in the schedule file.

Backups may be postponed (via fsave ) or interrupted. The resulting "partial" backups are automatically resumed the next time fsphoto is run: Any missed filesystems are backed-up as if the original backup had not been delayed. The -i flag ignores any pending partial backups.

If there is a pending partial backup, the normally scheduled backups are not done. This means that if a partial backup is resumed, and the normally scheduled backups are to be done, fsphoto must be run twice.

You must be the super-user to use this program.

Files

/usr/lib/sysadmin/schedule
  Database describing which filesystems are to be backed-up when, and at what dump level.

/dev/tty
  Source of interactive input.
Record of filesystems successfully backed-up in the pending partial backup.

Temporary file for recording successfully backed-up filesystems.

See Also

fsave(ADM), schedule(ADM), backup(C), basename(C)

Diagnostics

fsphoto complains of syntax errors in schedule, and exits with a status of 1.

fsphoto complains about illegal or incorrect arguments, and exits with a status of 1.

An interrupt will cause an exit status of 2.

Notes

If a drive is explicitly given, the "raw" (/dev/r*) form of the device should be used.
Name

haltsys, reboot - Closes out the file systems and shuts down the system.

Syntax

/etc/haltsys
/etc/reboot

Description

The haltsys utility performs a uadmin( ) system call (see uadmin(S)) to flush out pending disk I/O, mark the file systems clean, and halt the processor. haltsys takes effect immediately, so user processes should be killed beforehand. shutdown(ADM) is recommended for normal system shutdown, since it warns users, terminates processes, then calls haltsys. Use haltsys directly only if you cannot run shutdown; for example, because of some system problem.

The reboot command performs the same function as haltsys, except the system is rebooted automatically afterwards.

Only the super-user can execute haltsys or reboot.

Notes

haltsys locks hard disk heads.

See Also

shutdn(S), uadmin(S), shutdown(ADM)
Name

hdinstall - places newly-created kernel in default location.

Syntax

hdinstall

Description

When a new kernel is created with the Link Kit, hdinstall must be invoked to place the new kernel in /xenix. hdinstall moves the "old" /xenix to a file called /xenix.old and copies /usr/sys/conf/xenix to /xenix, the default location.

Files

/usr/sys/conf/xenix /xenix /xenix.old

See Also

configure(ADM), config(ADM)
Name

dleout - Logs out idle users.

Syntax

idleout [ minutes | hours:minutes ]

Description

The idleout command monitors line activity and logs out users whose terminal remains idle longer than a specified period of time.

The utility uses a default file, /etc/default/idleout, to indicate the number of hours a user's terminal may remain idle before being logged out. This file has one entry:

   IDLETIME=time

The time format is identical to that used on the command line. The time specified in the default file is overridden by idletime if idletime is specified on the command line. Note that, if idletime is zero, no monitoring takes place and idle users are not logged out.

Files

/etc/default/idleout
/etc/utmp
/etc/wtmp

See Also

who(C), getut(S), kill(S)

Notes

Only the superuser can run this program.
Name

install - Installation shell script.

Syntax

/etc/install [ device ]

Description

/etc/install is the sh(C) script used to install XENIX distribution (or application program) floppies. It performs the following tasks:

- Prompts for insertion of floppies.
- Extracts files using the tar(C) utility.
- Executes /once/init.* programs on each floppy after they have been extracted.
- Removes any /once/init.* programs when the installation is finished.

The optional argument to the command specifies the device used. The default device is /dev/install and is normally linked to /dev/rfd0.

Files

/etc/install

/once/init.*
Name

ipcrm - Removes a message queue, semaphore set or shared memory ID.

Syntax

\texttt{ipcrm [ options ]}

Description

\texttt{ipcrm} removes one or more specified messages, a semaphore or shared memory identifiers. The identifiers are specified by the following options:

- \texttt{-q msqid} removes the message queue identifier \texttt{msqid} from the system and destroys the message queue and data structure associated with it.

- \texttt{-m shmid} removes the shared memory identifier \texttt{shmid} from the system. The shared memory segment and data structure associated with it are destroyed after the last detach.

- \texttt{-s semid} removes the semaphore identifier \texttt{semid} from the system and destroys the set of semaphores and data structure associated with it.

- \texttt{-Q msgkey} removes the message queue identifier, created with key \texttt{msgkey}, from the system and destroys the message queue and data structure associated with it.

- \texttt{-M shmkey} removes the shared memory identifier, created with key \texttt{shmkey}, from the system. The shared memory segment and data structure associated with it are destroyed after the last detach.

- \texttt{-S semkey} removes the semaphore identifier, created with key \texttt{semkey}, from the system and destroys the set of semaphores and data structure associated with it.

The details of the removes are described in \texttt{msgctl(5)}, \texttt{shmctl(5)}, and \texttt{semctl(5)}. The identifiers and keys may be found by using \texttt{ipcs(ADM)}.

See Also


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Note

*ipcrm* cannot be used to remove semaphores created using *creatsem*(S) or to remove shared memory created using *sdget*(S).
Name

ipcs - Reports the status of inter-process communication facilities.

Syntax

ipcs [ options ]

Description

`ipcs` prints certain information about active inter-process communication facilities. Without `options`, information is printed in short format for message queues, shared memory, and semaphores that are currently active in the system. Otherwise, the information that is displayed is controlled by the following `options`:

- `-q` Print information about active message queues.
- `-m` Print information about active shared memory segments.
- `-s` Print information about active semaphores.

If any of the options `-q`, `-m`, or `-s` are specified, information about only those indicated are displayed. If none of the three options are specified, information about all three are displayed.

- `-b` Print biggest allowable size information (maximum number of bytes in messages on queue for message queues, size of segments for shared memory, and number of semaphores in each set for semaphores). See below, for the meaning of columns in a listing.
- `-c` Print creator's login name and group name. See below.
- `-o` Display information on outstanding usage (number of messages on queue, total number of bytes in messages on queue, and the number of processes attached to shared memory segments).
- `-p` Display process number information. (Process ID of last process to send a message and process ID of last process to receive a message on message queues. It displays the process ID of the creating process and the process ID of the last process to attach or detach on shared memory segments.) See below.
- `-t` Print time information. (Time of the last control operation that changed the access permissions for all facilities. Time of last `msgsnd` and last `msgrcv` on message queues, last `shmat` and last `shmdt` on shared memory, and last `semop(S)` on semaphores.) See below.
- `-a` Use all print `options`. (This is a shorthand notation for `-b`, `-c`, `-o`, `-p`, and `-t`.)
- `-C corefile` Use the file `corefile` in place of `/dev/kmem`.
- `-N namelist` The argument will be taken as the name of an alternate `namelist` (`/xenix` is the default).
The column headings and the meaning of the columns in an *ipcs* listing are given below; the letters in parentheses indicate the *options* that cause the corresponding heading to appear; **all** means that the heading always appears. Note that these *options* only determine what information is provided for each facility; they do not determine which facilities will be listed.

### T (all)
Type of the facility:
- **q** message queue;
- **m** shared memory segment;
- **s** semaphore.

### ID (all)
The identifier for the facility entry. Note that ID is "X" for facilities created using *creatsem* (S) or *sdget* (S).

### KEY (all)
The key used as an argument to *msgget*, *semget*, or *shmget* to create the facility entry. (Note: The key of a shared memory segment is changed to *IPC_PRIVATE* from when the segment has been removed until all processes attached to the segment detach it.)

### MODE (all)
The facility access modes and flags: The mode consists of 11 characters that are interpreted as follows:

The first two characters are:
- **R** if a process is waiting on a *msgrcv*;
- **S** if a process is waiting on a *msgsnd*;
- **D** if the associated shared memory segment has been removed. It will disappear when the last process attached to the segment detaches it;
- **C** if the associated shared memory segment is to be cleared when the first attach is executed;
- **-** if the corresponding special flag is not set.

The next 9 characters are interpreted as three sets of three bits each. The first set refers to the owner's permissions; the next to permissions of others in the user-group of the facility entry; and the last to all others. Within each set, the first character indicates permission to read, the second character indicates permission to write or alter the facility entry, and the last character is currently unused.

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The permissions are indicated as follows:

- **r** if read permission is granted;
- **w** if write permission is granted;
- **a** if alter permission is granted;
- **-** if the indicated permission is *not* granted.

**OWNER** (all)  The login name of the owner of the facility entry.

**GROUP** (all)  The group name of the group of the owner of the facility entry.

**CREATOR**(a,c)  The login name of the creator of the facility entry.

**CGROUP**(a,c)  The group name of the group of the creator of the facility entry.

**CBYTES**(a,o)  The number of bytes in messages currently outstanding on the associated message queue.

**QNUM**(a,o)  The number of messages currently outstanding on the associated message queue.

**QBYTES**(a,b)  The maximum number of bytes allowed in messages outstanding on the associated message queue.

**LSPID**(a,p)  The process ID of the last process to send a message to the associated queue.

**LRPID**(a,p)  The process ID of the last process to receive a message from the associated queue.

**STIME**(a,t)  The time the last message was sent to the associated queue.

**RTIME**(a,t)  The time the last message was received from the associated queue.

**CTIME**(a,t)  The time when the associated entry was created or changed.

**NATTCH**(a,o)  The number of processes attached to the associated shared memory segment.

**SEGSZ**(a,b)  The size of the associated shared memory segment.

**CPID**(a,p)  The process ID of the creator of the shared memory entry.

**LPID**(a,p)  The process ID of the last process to attach or detach the shared memory segment.

**ATIME**(a,t)  The time the last attach was completed to the associated shared memory segment.

**DTIME**(a,t)  The time the last detach was completed on the associated shared memory segment.

**NSEMS**(a,b)  The number of semaphores in the set associated with the semaphore entry.

**OTIME**(a,t)  The time the last semaphore operation was completed on the set associated with the semaphore entry.
Files

/xenix system namelist
/dev/kmem memory
/etc/passwd user names
/etc/group group names

See Also

creatsem(S), msgop(S), sdget(S), semop(S), shmop(S)

Notes

Things can change while *ipcs* is running; the picture it gives is only a close approximation.
Name

ips, isbs, ipbs - IMAGEN protocol handlers.

Syntax

/usr/lib/ips [ options ] [ file ]
/usr/lib/isbs [ options ] [ file ]
/usr/lib/isps [ options ] [ file ]

Description

ips, isbs, and ipbs are the lowest level of IMAGEN printer software. Each handles a different form of communications. They present a very similar view to higher-level software, allowing such software to be relatively independent of communications method.

ips sends files to the IMAGEN printer using the “sequence packet protocol” over RS-232C serial communication lines. This protocol provides for error detection, retransmission, status reporting, detection of unrecoverable errors, and printer usage accounting. The IMAGEN printer must be configured for “sequenced packet (V1)” at the desired baud rate.

isbs supports the “serial byte stream” communications method over RS-232C serial communication lines. This protocol provides for flow control, but no error detection or correction. The IMAGEN printer must be configured for the “serial byte stream” protocol at the desired baud rate, should use an “EOF” character of 0x04, a “quote” character of 0x02, an 8-bit-wide data path, XON/XOFF flow control, and should not ignore unprintable characters.

ipbs supports the “parallel byte stream” communications method, which is essentially similar to isbs but works on parallel rather than serial ports. The IMAGEN printer must be configured for the parallel interface, should use an “EOF” character of 0x04, a “quote” character of 0x02, and should not ignore unprintable characters.

Neither isbs nor ipbs provides printer-usage accounting. The following information is common to all these programs.

If no file name is given, the standard input is read.

The following options are recognized:

-D string
Imbed string into the document control language of the file being sent. If an unrecoverable failure occurs during transmission and the file can be resent, this string will be resent as well.
-astfile
   Save the current printer status in file stsfie.

-i device
   The IMAGEN printer is connected to XENIX special file device. The default device is the value of DEVICE in the file /etc/default/imagen.

-logfile
   Save information on the communications needed to send the input in the file logfile.

-r The standard input is rewritable. Normally, the standard input is not assumed to be rewritable. Or, if an explicit file was named, that file is not rewritable. Normally, an explicitly named file is assumed to be rewritable.

-s Regardless of what other indications may have been given, use the standard output as the printer.

-pdebug
   Sets various debugging values.

The following options are recognized by all three programs, but only used by ips and isbs; ipbs ignores them:

-o The line characteristics need to be set up if the output is being sent to the standard output. Normally, the characteristics of the standard output are not changed. Or they do not need to be set up if an explicit device was given with the -i option. Normally, the characteristics of named devices are changed.

-B speed
   The baud rate of the serial communications lines is speed. It is assumed that the IMAGEN printer is capable of running at the specified speed, and that it has been configured to do so. The default speed is the value of SPEED in the /etc/default/imagen file.

The following options are recognized by all three programs, but only used by ips; both isbs and ipbs ignore them:

-A acctfile
   Turns on accounting, and places the accounting information in file acctfile. This file should be read by imacct(C). There should be a separate acctfile for each IMAGEN printer.

-nuser
   Names the user or account to be credited with this printing job. Since these programs are normally run by the spooling system, there is no reasonable default username. Therefore, if accounting is enabled by use of the -A option, this option should also be
specified. If it is not, all printing is charged to user "????

-h host
Names the machine to be credited with originating this printing job. If not specified, first uname(S) and then /etc/systemid are used to determine the name of the local system. If the name of the system cannot be determined, "LOCAL" is used.

The following option is not supported, and the -n option should be used instead:

-uuid
The user identification number of the person to be credited with this printing job.

ips, isbs, and ipbs all read /etc/default/imagen to obtain various default settings. The values obtained, and the default values, are:

DEVICE=/dev/imagen
The name of the XENIX special file connected to the IMAGEN printer. This can be overridden with the -i or -s options.

SPEED=9600
The baud rate of the IMAGEN printer. This is meaningful only for ips and isbs, and can be overridden with the -B option.

The values of the default settings can be changed to reflect the local system configuration. If /etc/default/imagen does not exist or cannot be read, the above default values are used.

Files

/dev/imagen
Default name of the XENIX special file connected to the IMAGEN printer.

/dev/null
Default stsfie. See the -a option.

imagen.log
Default logfile. See the -l option.

See Also

imagen(M), ipr(C)

Author

IMAGEN Corporation.
Name

kbmode - Set keyboard mode or test keyboard support

Syntax

kbmode command [ file ]

Description

This command can be used to determine if your system keyboard supports AT mode. If it does, this utility can change the keyboard mode in between AT mode and PC/XT compatibility mode.

If the file argument is specified, it should be a tty device of one of the multiscreens of the keyboard’s group.

Valid commands are:

- test - determine if keyboard supports AT mode
- at - set keyboard to AT mode
- xt - set keyboard to PC/XT compatibility mode

Notes

Some keyboards look like AT keyboard but do not support AT mode. Setting such a keyboard to AT mode will render it useless, unless it can be set to XT mode from another (serial) terminal.

See Also

keyboard(HW)
Name

lpadmin - Configures the lineprinter spooling system.

Syntax

/usr/lib/lpadmin -p printer [ options... ]
/usr/lib/lpadmin -x dest
/usr/lib/lpadmin -d [ dest ]

Description

lpadmin configures the lineprinter spooling system to describe printers, classes, and devices. It is used to add and remove destinations, change membership in classes, change devices for printers, change printer interface programs, and to change the system default destination. System managers may also use lpinit (ADM) to add new printing destinations to the system. lpadmin may not be used when the lineprinter scheduler, lpsched (ADM), is running, except where noted below.

Exactly one of the -p, -d, or -x options must be present for every legal invocation of lpadmin.

-d [ dest ] Makes dest, an existing destination, the new system default destination. If dest is not supplied, then there is no system default destination. This option may be used when lpsched (ADM) is running. No other options are allowed with -d.

-x dest Removes destination dest from the LP system. If dest is a printer and is the only member of a class, then the class will be deleted, too. No other options are allowed with -x.

-p printer Names a printer to which all of the options below refer. If printer does not exist then it will be created.

The following options are only useful with -p and may appear in any order. For ease of discussion, the printer will be referred to as p below.

-c class Inserts printer p into the specified class. Class will be created if it does not already exist.

-e eprinter Copies an existing printer’s interface program to be the new interface program for p.
-h Indicates that the device associated with p is hardwired. This option is assumed when creating a new printer unless the -l option is supplied.

-interface Establishes a new interface program for p. Interface is the pathname of the new program.

-l Indicates that the device associated with p is a login terminal. The lineprinter scheduler, lpsched(ADM), disables all login terminals automatically each time it is started. Before re-enabling p, its current device should be established using lpadmin.

-mmodel The model printer interface program, dumb, is supplied with XENIX lineprinter software. It is a shell procedure which interfaces lpsched(ADM) and print devices. It can be found in the directory /usr/spool/lp/model and may be used as is with lpadmin -m or lpinit(ADM). This program is an interface for a line printer without special functions and protocol. Form feeds are assumed. System managers may modify copies of dumb and then use lpadmin -i to associate the copies with printers.

-rclass Removes printer p from the specified class. If p is the last member of the class, then the class will be removed.

-vdevice Associates a new device with printer p. Device is the pathname of a file that is writable by the system manager, lp. Note that there is nothing to stop a system manager from associating the same device with more than one printer. If only the -p and -v options are supplied, then lpadmin may be used while the scheduler is running.

Restrictions

When creating a new printer, the -v option and one of the -e, -i, or -m options must be supplied. Only one of the -e, -i, or -m options may be supplied. The -h and -l keyletters are mutually exclusive. Printer and class names may be no longer than 14 characters and must consist entirely of the characters A-Z, a-z, 0-9 and _ (underscore).

Models

Model printer interface programs are shell procedures which interface between lpsched(ADM) and devices. Models reside in the directory /usr/spool/lp/model and may be used as is with lpadmin -m. Models should have 644 permission if owned by lp & bin, or 664 permission if owned by bin & bin. System managers may modify copies of models and then use lpadmin -i to associate them with printers. If printers have special options, these can be included in the interface program.
Users can then choose an option with the \texttt{lp -o} command.

One model interface program is supplied with XENIX lineprinter software: \textit{dumb}. This is an interface program for a lineprinter without special functions and protocol. Form feeds are assumed. This is a good model for system managers to copy and modify.

Serial printers that need delays or other special \texttt{stty(C)} options (such as mapping CR to newline) should have this string included in the model interface program:

\begin{verbatim}
stty [ options ... ] 0<&1
\end{verbatim}

Files

\texttt{/usr/spool/lp/*}

See Also

\begin{itemize}
\item accept(C), enable(C), lp(C), lpinit(ADM), lpsched(ADM), lpstat(C)
\end{itemize}
Name

lpinit - Adds, reconfigures and maintains lineprinters.

Syntax

/etc/lpinit

Description

lpinit is a shell script for configuring and adding new lineprinters to a system, and for maintaining and reconfiguring existing printers. It should only be executed by the system manager.

lpinit asks a series of questions for which the default answers are displayed. You can press RETURN to accept the default value or type in a new value.

lpinit displays a menu with the following options:

1) Add a new printer
2) Remove a printer
3) Reconfigure an existing printer
4) Assign a system default printer
5) Print lp status information

When reconfiguring an existing printer the following options are given:

1) Insert a printer into a class
2) Remove a printer from a class
3) Install a new interface program for a printer
4) Associate a new device with a printer

Information which the system manager may be asked to supply includes:

- The printer device (e.g. /dev/lp0).
- The printer character mode. (The default value is non-interprettive. See "Notes" below for more information.)
- The printer name (default is printer).
- The pathname of the interface program (several example programs are supported).
- The name of a class into which to insert or remove a printer.
- Whether the printer being added or reconfigured is a parallel, serial, or remote printer.
- Whether the printer being added or reconfigured requires special handling for carriage returns and line feeds.

The printer name can be any combination of up to 14 alphanumeric characters or underscores. A printer interface program can be a shell script, C program, or any executable program; or the model interface
The `lpinit` program, `/usr/spool/lp/model/dumb`, can be copied and modified. (See the "Models" section of the `lpadmin(ADM)` manual page.)

When adding a new printer, `lpinit` changes the acceptance status of the new lineprinter to "accept," and enables it to print files. `/etc/lpinit` then asks if the new printer will be the default printing destination. All nonspecific print requests are routed to the default destination (see `lp(C)`).

If the line printer scheduler is running when `lpinit` is invoked, the user is reminded that any jobs which are printing may be interrupted and the user is asked if he wants to continue. The scheduler is restarted when `lpinit` exits only if it was running when `lpinit` was invoked or if a new printer was added.

The steps to configure a new printer can be taken separately, (see `lpadmin(ADM)`, `accept(C)`, `enable(C)`, and `lpsched(ADM)` for more information).

**Files**

`/etc/lpinit` `/usr/lib/mkdev/lp`

**Notes**

Some printers require conversions for line-feeds, tabs and form-feeds. In *interpretive* mode, the system sends line-feeds as carriage-returns, tabs as the appropriate number of spaces, and form-feeds as the appropriate number of carriage-returns. In *non-interpretive* mode (the default value), the system sends every character to the printer unmodified.

If you are adding a parallel printer you are asked, after the menu of interface scripts, if the printer requires conversions for line-feed, tab and form-feed. If the printer does not, press RETURN. If the printer does, press `y`. This selects *interpretive* mode and assigns the device `/dev/lp[012][f]` to the printer.

If you choose *interpretive* mode, note the following:

You must be sure that the printer's actual top-of-form corresponds to top-of-form as interpreted by the printer driver.

If you run a program that does any non-standard line spacing, such as half-line feeds or 8 lines per inch, the printer's top-of-form will be out of place in subsequent output.

If your output contains characters that are not uniformly spaced, the tab translation may not work properly.
Note that if your printer can be set (for example, with dip switches) to treat line-feed as newline and carriage-return as carriage-return (without a line-feed), and if the printer can do its own tabs and formfeeds, you should select non-interpretive mode. If your printer cannot automatically do tabs, you can still use non-interpretive mode by using the -e option of the pr(C) command when printing files that contain tabs.

See Also

accept(C), enable(C), lp(C), lpadmin(ADM), lpsched(ADM), pr(C)
Name

lpsched, lpshut, lpmove - Starts/stops the lineprinter request scheduler and moves requests.

Syntax

/usr/lib/lpsched
/usr/lib/lpshut
/usr/lib/lpmove requests destinations
/usr/lib/lpmove dest1 dest2

Description

lpsched schedules requests taken by $lp(C)$ for printing on lineprinters.

lpshut shuts down the lineprinter scheduler. All printers that are printing at the time lpshut is invoked will stop printing. Requests that were printing at the time a printer was shut down will be reprinted in their entirety after lpsched is started again. All lineprinter commands perform their functions even when lpsched is not running.

lpmove moves requests that were queued by $lp(C)$ between lineprinter destinations. This command may be used only when lpsched is not running. The first form of the command moves the named requests to the lineprinter destinations, dest. Requests are request IDs as returned by $lp(C)$. The second form moves all requests for destination dest1 to destination dest2. As a side effect, $lp(C)$ will reject requests for dest1.

Note that lpmove never checks the acceptance status for the new destination when moving requests (see accept($C$)).

Files

/usr/spool/lp/*

See Also

accept($C$), enable($C$), $lp(C)$, lpadmin(ADM), lpinit(ADM), lpstat($C$)
Name

makekey - Generates an encryption key.

Syntax

/usr/lib/makekey

Description

makekey improves the usefulness of encryption schemes by increasing the amount of time required to search the key space. It reads 10 bytes from its standard input, and writes 13 bytes on its standard output. The output depends on the input in a way that is intended to be difficult to compute (i.e., to require a substantial fraction of a second).

The first 8 input bytes (the input key) can be arbitrary ASCII characters. The last 2 input bytes (the salt) are best chosen from the set of digits, dot (.), slash (/), and uppercase and lowercase letters. The salt characters are repeated as the first 2 characters of the output. The remaining 11 output characters are chosen from the same set as the salt and constitute the output key.

The transformation performed is essentially the following: the salt is used to select one of 4,096 cryptographic machines all based on the National Bureau of Standards DES algorithm, but broken in 4,096 different ways. Using the input key as the key, a constant string is fed into the machine and recirculated. The 64 bits that come out are distributed into the 66 output key bits in the result.

See Also

passwd(F)
Name

mkdev - Calls scripts to add peripheral devices.

Syntax

/etc/mkdev lp
/etc/mkdev hd
/etc/mkdev serial
/etc/mkdev fs [ device file ]
/etc/mkdev fd
/etc/mkdev tape
/etc/mkdev shl
/etc/mkdev mouse

Description

mkdev calls the scripts to create the requested type of device file(s). mkdev may call lpinit(ADM), or any other script found in the directory /usr/lib/mkdev. If no arguments are listed, mkdev prints a usage message.

/etc/mkdev lp creates device files for use with line printers. (See lpinit(ADM).)

/etc/mkdev hd creates device files for use with a peripheral hard disk. The device files for an internal hard disk already exist. hdinit invokes the following utilities: dparam(ADM), badtrk(ADM), fdisk(ADM), and divvy(ADM).

/etc/mkdev serial creates device files for use with serial cards. The device files for the first and second ports already exist. Additional device files must be created for the ports added when expansion cards are added to the system. The /etc/ttys and /etc/ttytype files are updated.

/etc/mkdev fs performs the system maintenance tasks required to add a new filesystem to the system once the device is created (mknod(\(C\))) and the filesystem is made (mkfs(ADM)). It creates the /file and /file/lost+found directories, reserves slots in the lost+found directory, (if either already exist, they are used unmodified) and modifies /etc/checklist, /etc/default/filesys and /etc/default to check (fsck(ADM)) and mount (mount(ADM),mnt(\(C\)),rc(\(C\))) the filesystem as appropriate. It is usually used in conjunction with mkdev hd when adding a second hard disk to the system or with mkdev fd when creating a mountable filesystem on a floppy, but can be used on any additional filesystem (for example, on a large internal hard disk).
/etc/mkdev fd creates bootable and root file system floppy disks. The three basic options are: boot and root on a single disk (96 or 135 tpi only), boot and root pair (48 tpi) or filesystem only. Use with mkdev fs when creating a filesystem-only floppy.

Several boot and/or root floppies can be created during a single mkdev fd session, but mkdev does not display a prompt to remove the first floppy and insert the next one. Insert the next floppy when mkdev prompts "Would you like to format the floppy first? (y/n)."

/etc/mkdev tape configures the tape driver in preparation for linking a new kernel that includes tape support. It adds a standard quarter-inch cartridge tape driver and/or a mini-cartridge tape driver.

The current driver configurations can be displayed, and changed if necessary. A zero in any of the fields means the driver automatically detects the type of tape device installed and uses the built-in values for that device. If the autoconfiguration values are not correct for your drive, refer to your hardware manual for the correct values, configure the driver and relink the new kernel. mkdev tape can also be used to remove a tape driver from the existing kernel.

/etc/mkdev shl initializes necessary devices and configures kernel parameters associated with the number of shell layers sessions available on the system.

/etc/mkdev mouse initializes necessary devices and configures the system to use any supported mouse.

Once the driver is configured, you are prompted for re-linking the kernel. The appropriate devices in /dev are created.

The various init scripts prompt for the information necessary to create the devices.

Files

/usr/lib/mkdev/*

See Also

badtrk(ADM), divvy(ADM), dparam(ADM), fd(HW), fdisk(ADM), filesys(F), format(C), hd(HW), lp(HW), lpinit(ADM), mkfs(ADM), mknod(C), mount(ADM), serial(HW), usemouse(C), tape(HW).

Notes

Note that /etc/mkdev tape does not add a tape driver for SCSI tape systems. The appropriate drivers already exist in the SCSI kernel.
Name

mkfs - Constructs a file system.

Syntax

/etc/mkfs [ -y ] [ -n ] special blocks[ : inodes] [gap inblocks]
/etc/mkfs [ -y ] [ -n ] special proto [gap inblocks]
[-s blocks [ : inodes]]

Description

mkfs constructs a file system by writing on the special file special, according to the directions found in the remainder of the command line.

If it appears that the special file contains a file system, operator confirmation is requested before overwriting the data. The -y "yes" option overrides this, and writes over any existing data without question. The -n option causes mkfs to terminate without question if the target contains an existing file system. The check used is to read block one from the target device (block one is the super-block) and see whether the bytes are the same. If they are not, this is taken to be meaningful data and confirmation is requested.

If the second argument is given as a string of digits, mkfs builds a file system with a single empty directory on it. The size of the file system is the value of blocks interpreted as a decimal number. The boot program is left uninitialized. If the number of inodes is specified, then this number should be the same as the estimated number of files in the file system. If the optional number of inodes is not given, the number of inodes is calculated as a function of the system file size.

If the second argument is a file name that can be opened, mkfs assumes it to be a prototype file, proto, and takes its directions from that file. The prototype file contains tokens separated by spaces or newlines. The first token is the name of a file to be copied onto block zero as the bootstrap program. The bootstrap program specified should already be stripped of the header (see strip(CP)). If the header has not been stripped from the bootstrap program, then mkfs issues a warning. The second token is a number specifying the size of the created file system. Typically, it will have been the number of blocks on the device, perhaps diminished by space for swapping. The next token is the i-list size in blocks. The next set of tokens comprise the specification for the root file. File specifications consist of tokens giving the mode, the user ID, the group ID, and the initial contents of the file. The syntax of the contents field depends on the mode.
The mode token for a file is a 6 character string. The first character specifies the type of the file. (The characters -bcd specify regular, block special, character special and directory files respectively.) The second character of the type is either u or - to specify set-user-ID mode or not. The third is g or - for the set-group-ID mode. The rest of the mode is a three digit octal number giving the owner, group, and other read, write, execute permissions; see chmod(C).

Two decimal number tokens come after the mode; they specify the user and group ID's of the owner of the file.

If the file is a regular file, the next token is a pathname whose contents and size are copied. If the file is a block or character special file, two decimal number tokens follow which give the major and minor device numbers. If the file is a directory, mkfs makes the entries . and .. and then reads a list of names and (recursively) file specifications for the entries in the directory. The scan is terminated with the token $.

A sample prototype specification follows:

```
/stand/diskboot
4872 110
d--777 3 1
usr d--777 3 1
sh ---755 3 1 /bin/sh
ken d--755 6 1
$
b0 b--644 3 1 0 0
c0 c--644 3 1 0 0
$
```

In the second version of the command the -s option is a command-line override of the size and number of inodes in the proto file.

In both commands, the disk interleaving factors, gap and inblocks, can be specified. The interleaving factors are a disk hardware function and are described in detail in the XENIX System Administrator's Guide.

See Also

chmod(C), filesystem(F), dir(F), strip(CP)

Notes

There is no way to specify links when using a prototype file. If the number of inodes is specified on the command line, then the maximum number of inodes in the file system is 65500.
This utility uses BSIZE blocks. Refer to the *machine (HW)* manual page for the size of filesystem blocks.
Name

mkuser - Adds a login ID to the system.

Syntax

/etc/mkuser

Description

mkuser is used to add more user login IDs to the system. It is the preferred method for adding new users to the system, since it handles all directory creation and password file updating. To add a new user to the system, mkuser requires six pieces of information:

- login name
- user ID
- group ID
- user's login shell
- initial password
- comment string for the /etc/passwd file (optional).

The login name is checked against certain criteria (i.e., it must be at least three characters and begin with a lowercase letter). The password must follow standard XENIX conventions (see passwd(F)). The password file comment field can be up to 35 characters of information.

mkuser prompts for the shell type to assign to the new user. The selection of shells is determined by the number of shells installed on the system. The shells included in the Run Time System are the standard (Bourne) shell, sh, and the restricted shell, rsh. Each installed shell is represented by a subdirectory /usr/lib/mkuser/shell, which is installed along with the given shell package (see custom(ADM)). The shell subdirectory contains the files needed to set up the user's environment to use that shell. These files are mkuser.defs and mkuser.init, plus any additional files that are specific to a given shell. (For example, /usr/lib/mkuser/csh/cshrc and /usr/lib/mkuser/csh/login are the standard .cshrc and .login files used by the csh and are copied to the user's home directory when mkuser is run.)

mkuser takes some of its parameters from a default file, /etc/default/mkuser. An example default file is:
HOME=/usr
HOMEMODE=0755
PROFMODE=0640
MAILMODE=0640

The HOME entry is the user's home directory, the HOMEMODE entry is the permissions for the user's home directory, the PROFMODE entry is the permissions for the .login, .profile and .cshrc files or other shell-specific files, and the MAILMODE entry specifies the permissions of the user's mailbox.

This file can be edited by the super-user to change these defaults. These defaults can also be defined on a per-shell basis by adding similar entries to the appropriate /usr/lib/mkuser/shell/mkuser.def file. In addition, there are other files in /usr/lib/mkuser that can be customized. These include /usr/lib/mkuser/lib/mail, which is the standard mail message sent to new users, /usr/lib/mkuser/lib/help, which is the explanation displayed by mkuser at startup, /usr/lib/mkuser/shell/mkuser.init, and any of the shell related files.

mkuser allocates user IDs starting at 200, or the largest number used in the password file. (The operator can also assign a specific user ID to a new user. It must be greater than or equal to 200 and must not already exist.) The default group ID for new users is 50. The minimum group ID allowed for user accounts is 50. The operator is given the choice of assigning the user to the default group or another existing group (only those groups with IDs greater than or equal to 50 are displayed, but any group can be selected). In addition, a new group can be created, in which case the operator may specify the name or ID (or both). If only the name is specified, the next available number is assigned.

mkuser can only be executed by the super-user.

The minimum length of a legal password, and the minimum and maximum number of weeks used in password aging are specified in /etc/default/passwd by the variables PASSLENGTH, MINWEEKS and MAXWEEKS. For example, these variables might be set as follows:

    PASSLENGTH=6
    MINWEEKS=2
    MAXWEEKS=6

Files

/etc/passwd
/usr/spool/mail/username
/etc/default/mkuser

May 16, 1988
/etc/default/passwd
/usr/lib/mkuser/mkuser/lib/help
/usr/lib/mkuser/mkuser/lib/mail
/usr/lib/mkuser/shell/mkuser.defs
/usr/lib/mkuser/shell/mkuser.init
/usr/lib/mkuser/shell/shellfiles

See Also
chmod(С), custom(ADM), sh(С), csh(С), rsh(С), vsh(С), group(F), passwd(F), pwadmin(ADM), rmuser(ADM)
Name

mount - Mounts a file structure.

Syntax

/etc/mount [ special-device directory [ -r ]]

Description

`mount` announces to the system that a removable file structure is present on `special-device`. The file structure is mounted on `directory`. The `directory` must already exist; it becomes the name of the root of the newly mounted file structure. `directory` should be empty. If `directory` contains files, they will appear to have been removed while the `directory` is mounted and reappear when the `directory` is unmounted.

The `mount` and `umount` commands maintain a table of mounted devices. If each special device is invoked without any arguments, `mount` displays the name of the device, and the directory name of the mounted file structure, whether the file structure is read-only, and the date it was mounted.

The optional last argument indicates that the file is to be mounted read-only. Physically write-protected file structures must be mounted in this way or errors occur when access times are updated, whether or not any explicit write is attempted.

`umount` removes the removable file structure previously mounted on device `special-device`.

Files

/etc/mnttab Mount table
/etc/default/filesys Filesystem data

See Also

`umount(ADM), mnt(C), mount(S), mnttab(F), default(F)`

Diagnostics

`mount` issues a warning if the file structure to be mounted is currently mounted under another name.
Busy file structures cannot be dismounted with `umount`. A file structure is busy if it contains an open file or some user’s working directory.

Notes

Only the super-user can use the `mount` command.

Some degree of validation is done on the file structure, however it is generally unwise to mount corrupt file structures.

Be warned that when in single-user mode, the commands that look in `/etc/mnttab` for default arguments (for example `df`, `ncheck`, `quot`, `mount`, and `umount`) give either incorrect results (due to a corrupt `/etc/mnttab` from a non-shutdown stoppage) or no results (due to an empty mnttab from a `shutdown` stoppage).

When multi-user, this is not a problem; `/etc/rc` initializes `/etc/mnttab` to contain only `/dev/root` and subsequent mounts update it appropriately.

The `mount(ADM)` and `umount(ADM)` commands use a lock file to guarantee exclusive access to `/etc/mnttab`. The commands which just read it (those mentioned above) do not, so it is possible that they may hit a window, which is corrupt. This is not a problem in practice since `mount` and `umount` are not frequent operations.

When mounting a file system on a floppy disk you need not use the same directory each time. However, if you do, the full pathnames for the files are consistent with each use.

Floppy disks must be unprotected (no write-protect tab) to be mounted as a filesystem. Always `umount` filesystems on floppy disks before removing them from the floppy drive. Failure to do so requires running `fsck` the next time the disk is mounted.
Name

mvdir - Moves a directory.

Syntax

/etc/mvdir dirname name

Description

mvdir moves directories within a file system. The directory (dirname) must be a directory. If there is already a directory or file with the same name as name, mvdir fails.

Neither name may be a sub-set of the other. For example, you cannot move a directory named /x/y to /x/y/z, and vice versa.

Notes

You must be root to use mvdir.

See Also

mkdir(C)
Name

ncheck - Generates names from inode numbers.

Syntax

ncheck [ -i numbers ] [ -a ] [ -s ] [ filesystem ]

Description

ncheck with no argument generates a pathname and inode number list of all files on the set of file systems specified in /etc/mnttab. The two characters "/." are appended to the names of directory files. The -i option reduces the report to only those files whose inode numbers follow. The -a option allows printing of the names . and .., which are ordinarily suppressed. The -s option reduces the report to special files and files with set-user-ID mode; it is intended to discover concealed violations of security policy. A single filesystem may be specified rather than the default list of mounted file systems.

Files

/etc/mnttab

See Also

fsck(ADM), sort(C)

Diagnostics

When the file system structure is improper, ?? denotes the "parent" of a parentless file and a pathname beginning with ... denotes a loop.

Notes

See Notes under mount(ADM).
Name

netutil - Administers the XENIX network.

Syntax

netutil [option] [-x] [-e]

Description

The netutil command allows the user to create and maintain a network of XENIX machines. A Micnet network is a link through serial lines of two or more XENIX systems. It is used to send mail between systems with the mail(C) command, transfer files between systems with the rcp(C) command, and execute commands from a remote system with the remote(C) command.

The netutil command is used to create and distribute the data files needed to implement the network. It is also used to start and stop the network. The option argument may be any one of install, save, restore, start, stop, or the numbers 1 through 5 respectively. The -x option logs transmissions and the -e options logs errors. The -x and -e options work only when they are used in conjunction with start, stop or their decimal equivalents (4 and 5).

The install option interactively creates the data files needed to run the network. The save option saves these files on floppy or hard disks, allowing them to be distributed to the other systems in the network. If you save the micnet files to the hard disk, you can then use uucp(C) to transfer the files to the other machines. This option specifies the name of the backup device and prompts for whether this is the desired device to use. The user can specify an alternate device, including a file on the hard disk. The name of the default backup device is located in the file /etc/default/micnet. This can be changed depending on system configuration. The restore option copies the data files from floppy disk back to a system. The start option starts the network. The stop option stops the network. An option may also be any decimal digit in the range 1 to 5. If invoked without an option, the command displays a menu from which to choose one. Once an option is selected, it prompts for additional information if needed.
A network must be installed before it can be started. Installation consists of creating appropriate configuration files with the **install** option. This option requires the name of each machine in the network, the serial lines to be used to connect the machines, the speed of transmission for each line, and the names of the users on each machine. Once created, the files must be distributed to each computer in the network with the **save** and **restore** options. The network is started by using the **start** option on each machine in the network. Once started, mail and remote commands can be passed along the network. A record of the transmissions between computers in a network can be kept in the network log files. Installation of the network is described in the XENIX *System Administrator’s Guide*.

**Files**

/bin/netutil
/etc/default/micnet

**See Also**

aliases(M), aliashash(ADM), mail(C), micnet(F), remote(C), rcp(C), systemid(F), top(F).
Name

pwadmin - Performs password aging administration.

Syntax

pwadmin [ -min weeks -max weeks ] options

Description

pwadmin is used to examine and modify the password aging information in the password file. The options one can specify are as follows:

- `d user` Displays the password aging information.
- `f user` Forces the user to change his password at the next login.
- `c user` Prevents the user from changing his password.
- `a user` Enables password aging for the given user. This option sets the minimum number of weeks that the user must wait before changing his password and the maximum number of weeks that a user can keep his current password for the values defined by the MINWEEKS and MAXWEEKS variables in the `/etc/default/passwd` file. If the file is not found or the defined values are not in the range 0 to 63, the default values 2 and 4 are used.
- `n user` Disables the password aging feature.
- `min weeks` Enables password aging and sets the minimum number of weeks before the user can change his password to `weeks`. (This prevents him from changing his password back to the old one).
- `max weeks` Enables password aging and sets the number of weeks so the user can keep his current password set for `weeks`.

Files

/etc/passwd

/etc/default/passwd

See Also

passwd(C), passwd(F)
Notes

The user must not attempt to force a new password by setting both the -min and -max values to zero. To force a password, use the -f option.

The user must not attempt to prevent further password changes by setting the -min value greater than the -max value. To prevent changes, use the -c option.
Name

rmuser - Removes a user account from the system.

Syntax

/etc/rmuser

Description

rmuser removes users from the system. It begins by prompting for a user name; after receiving a valid user name as a response, it then deletes the named user's entry in the password file, and removes the user's mailbox file, the .profile file, and the entire home directory. It will also remove the users group entry in /etc/group if the user was the only remaining member of that group, and the group ID was greater than 50.

Before removing a user ID from the system, make sure its mailbox is empty and that all files belonging to that user ID have been saved or deleted as required.

The rmuser program will refuse to remove a user ID or any of its files if one or more of the following checks fails:

- The user name given is one of the 'system' user names such as root, sys, sysinfo, cron, or uucp. All user IDs less than 200 are considered reserved for system use, and cannot be removed using rmuser. Likewise, all group IDs less than 50 are not removable using rmuser.

- The user's mailbox exists and is not empty.

- The user's home directory contains files other than .profile.

rmuser can only be executed by the super-user.

Files

/etc/passwd

/usr/spool/mail/username

$HOME

See Also

mkuser(ADM), backup(C)
Name

runbig - Runs a command that may require more memory than normal.

Syntax

runbig command [ arguments ]

Description

runbig executes commands that may require more memory than is normally available to a user process. While runbig is executing the specified command, it ignores the restriction on the default of memory available to the user process. The command will run normally until it grows to be larger than the amount of memory available to a user process. It is then locked in core memory and not swapped until it either exits or shrinks to a size less than or equal to the size of a default user process.

The removal of the process size restriction during execution of runbig will be preserved during an exec(S) system call, but not for a fork(S) system call.

See Also

exec(S), fork(S)

Notes

Running programs greater than the default process size, and therefore, possibly greater than the size of the disk swap area, may severely impact system performance.

runbig has no effect on systems whose memory size is much less than the size of the disk swap area.
Name

schedule - Database for automated system backups

Description

The schedule database is used in conjunction with fsphoto(ADM) to partially automate system-wide backups. For each filesystem to be backed-up, a cyclical schedule of backup(C) levels is specified.

This cyclical schedule (or cycle) is a list of dump levels to perform (including no dump at all) and a pointer to the last-used element of that list. The pointer is advanced to the next element of the list on a regular basis (each time fsphoto is run, usually once per day), starting over at the beginning each time it falls off the end. It is advanced, however, only on success - the desired dump must have been successful.

Each entry in the file is on a separate line. Blank and comment lines (beginning with ""#""") may be placed anywhere. Several keywords are recognized:

**site sitename**

*Sitename* is passed to fsave as a description to place on each tape label. Usually, *sitename* is the name of the company or a building number.

**media drive k sizes... [format]**

Device *drive* is a floppy capable of handling volumes with any of the listed *sizes* (in kilobytes). If specified, *format* is the XENIX command used to format the described floppies.

**media drive d density sizes... [format]**

Device *drive* is a *density* BPI magtape capable of handling tapes of any of the indicated *sizes* (in feet). Like floppies, *format* is the optional XENIX command used to format the described tape.

**[0-9] size savetime importance marker**

Description of each dump level, as described in fsave(ADM). The defaults are:

<table>
<thead>
<tr>
<th>Level</th>
<th>Size</th>
<th>Savetime</th>
<th>Importance</th>
<th>Marker</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>-</td>
<td>&quot;1 year&quot;</td>
<td>critical</td>
<td>none</td>
</tr>
<tr>
<td>1</td>
<td>-</td>
<td>&quot;3 months&quot;</td>
<td>necessary</td>
<td>none</td>
</tr>
<tr>
<td>2...7</td>
<td>-</td>
<td>&quot;1 month&quot;</td>
<td>important</td>
<td>none</td>
</tr>
<tr>
<td>8</td>
<td>-</td>
<td>&quot;2 weeks&quot;</td>
<td>useful</td>
<td>none</td>
</tr>
<tr>
<td>9</td>
<td>-</td>
<td>&quot;1 week&quot;</td>
<td>precautionary</td>
<td>none</td>
</tr>
</tbody>
</table>

All four fields must be specified. A *size* of - means to use the first size listed in the appropriate **media sizes** list.
Keywords should be placed before any filesystem dump schedules. A filesystem dump schedule is of the form:

/dev/rfilesys cycle

The filesystem resident on device /dev/filesys is to be backed-up according to cycle, which is a space-separated list of dump levels (the digits 0 to 9, passed to dump), or the letter x, meaning no dump should occur.

A dump cycle must have at least one member, but it may be of any length. Different filesystems may have cycles of different lengths.

Here is a sample schedule file:

# SYSTEM BACKUP SCHEDULE
site mymachine

# Media Entries
# 96 tpi 1.2 MB floppy 0
# media /dev/rfd096ds15 k 1200 format /dev/rfd096ds15
# 96 tpi 1.2 MB floppy 1
# media /dev/rfd196ds15 k 1200 format /dev/rfd196ds15
# Cartridge tape 0
# media /dev/rct0 d 20000 300 450 600 tape erase
# 9-track tape drive
# media /dev/rmt0 d 1600 2400 1200 600

# Backup Descriptor Table
# Backup Vol. Save for Vitality Label
# level size how long (importance) marker
0 - "1 year" critical "a red sticker"
1 - "4 months" necessary "a yellow sticker"
8 - "3 weeks" useful "a blue sticker"
9 - "1 week" precautionary none

# Schedule Table
# Filesystem MTWTF MTWTF MTWTF MTWTF
/dev/rroot 0 x 9 x 9 8 x 9 x 9 1 x 9 x 9 8 x 9 x 9
/dev/ru 9 0 9 9 9 9 1 9 9 9 8 9 9 9

In the example above, filesystem /dev/rroot is dumped using a level 0 dump the first time fsphoto is run (on a Monday), and if that dump is successful, the next (second) time it runs (Tuesday), no dump is performed. If doing nothing is successful, the third time run (Wednesday) a level 9 dump occurs. If that dump succeeds, no dump occurs the fourth time (Thursday), but the fifth time fsphoto is run (Friday), a level 9 dump is made.

Each time a successful dump at the specified level happens, the pointer advances so that the next run of fsphoto (on the next weekday) will do the next dump scheduled for that filesystem. If however, a dump fails (or is interrupted or postponed by the operator) the pointer...
is not advanced; hence, the next time \textit{fsphoto} is attempted, the same level dump will again be tried so the sequence will not be broken (but the timing may be off).

Continuing the example, the nineteenth time \textit{fsphoto} runs, a level 9 dump of /dev/rroot is done, no dump is performed the next (twentieth) time, but the twenty-first time (Monday of every fifth week) the cycle starts over again at the beginning with a level 0 dump.

The larger and more rapidly changing filesystems /dev/ru is dumped more frequently (each time \textit{fsphoto} is run - once a day - instead of every other time), and the levels used are staggered to prevent having to perform two full-scale dumps (like levels 0 or 1) of the large filesystems on the same day. The backup cycle period is also shorter, two weeks instead of four.

\textbf{See Also}

\textit{fsphoto(ADM)}, \textit{fsave(ADM)}, \textit{backup(C)}

\textbf{Notes}

Keywords and filesystem names must not be preceded by any spaces or tabs.

It is not necessary to specify the name of the ‘‘raw’’ (/dev/r*) device for each filesystem, but the backups are faster if this is done.
Name

setclock - Sets the system real-time (time of day) clock.

Syntax

setclock [ time ]

Description

The `setclock` file sets the battery-powered, real-time time of day clock to the given time. If `time` is not given, the current contents of the battery-powered clock are displayed. The `time` must be a combination of digits with the form:

MMddhhmmyy

where `MM` is the month, `dd` is the day, `hh` is the hour, `mm` is the minute, and `yy` is the last two digits of the year. If `yy` is not given, it is taken from the current system time. For example, the command:

082615035

sets the time of day clock to 15:03 on August 26, 1985.

Files

/etc/setclock

See Also

clock(F)

Notes

Not all computers have battery-powered real-time time of day clocks. Refer to your computer's hardware reference manual.
**setmnt - Establishes /etc/mnttab table.**

### Syntax

```
/etc/setmnt
```

### Description

`setmnt` creates the `/etc/mnttab` table (see `mnttab(F)`), which is needed for both the `mount(ADM)` and `umount(ADM)` commands. `setmnt` reads the standard input and creates a `mnttab` entry for each line. Input lines have the format:

```
filesys node
```

where `filesys` is the name of the file system's `special file` (e.g., "hd0") and `node` is the root name of that file system. Thus `filesys` and `node` become the first two strings in the `mnttab(F)` entry.

### Files

```
/etc/mnttab
```

### See Also

`mnttab(F)`

### Notes

If `filesys` or `node` are longer than 128 characters, errors can occur.

`setmnt` silently enforces an upper limit on the maximum number of `mnttab` entries.

`setmnt` is normally invoked by `/etc/rc` when the system boots up.
**Name**

settime - Changes the access and modification dates of files.

**Syntax**

```bash
settime mmddhhmm [ yy ] [ -f fname ] name ...
```

**Description**

Sets the access and modification dates for one or more files. The dates are set to the specified date, or to the access and modification dates of the file specified via `-f`. Exactly one of these methods must be used to specify the new date(s). The first `mm` is the month number; `dd` is the day number in the month; `hh` is the hour number (24 hour system); the second `mm` is the minute number; `yy` is the last two digits of the year and is optional. For example:

```
settime 1008004583 ralph pete
```

sets the access and modification dates of files `ralph` and `pete` to Oct 8, 12:45 AM, 1983. Another example:

```
settime -f ralph john
```

This sets the access and modification dates of the file `john` to those of the file `ralph`.

**Notes**

Use of `touch` in place of `settime` is encouraged.
Name

shutdown - Terminates all processing.

Syntax

/etc/shutdown [ time ] [ su ]

Description

shutdown is part of the XENIX operation procedures. Its primary function is to terminate all currently running processes in an orderly and cautious manner. The time argument is the number of minutes before a shutdown will occur. The optional su argument lets the user go single-user, without completely shutting down the system. However, the system is shut down for multi-user use. shutdown goes through the following steps. First, all users logged on the system are notified to log off the system by a broadcasted message. All file system super-blocks are updated before the system is stopped (see sync(ADM)). This must be done before rebooting the system, to ensure file system integrity.

You must be super-user to execute the shutdown command.

See Also

sync(ADM), umount(ADM), wall(ADM), boot(HW)

Diagnostics

The most common error diagnostic that will occur is device busy. This diagnostic appears when a particular file system could not be unmounted. See umount(ADM).

Notes

Once shutdown has been invoked, it must be allowed to run to completion and must not be interrupted by pressing BREAK or DEL.

shutdown does not work when executed from within a shell layer.

shutdown locks the hard disk heads.
Name

sync - Updates the super-block.

Syntax

sync

Description

sync executes the sync system primitive. If the system is to be stopped, sync must be called to ensure file system integrity. Note that shutdown(ADM) automatically calls sync before shutting down the system.

See Also

sync(S)
Name

sysadmin - Performs file system backups and restores files.

Syntax

/etc/sysadmin

Description

sysadmin is a utility for performing filesystem backups and for restoring files from backup volumes, and includes several options. Its main function is to act as a front-end for the fsphoto(ADM) utility, which performs backups according to an established schedule. Depending on the day of the week, a daily incremental backup (level 9), or a periodic full backup (level 0) is automatically selected. sysadmin can also be invoked to do an unscheduled backup. It can provide a listing of the files backed up and also has facilities for restoring individual files and complete filesystems from backups.

The main sysadmin menu appears as follows:

Filesystem Maintenance Options

1. Perform a scheduled backup
2. Perform an unscheduled backup
3. List the contents of an archive
4. Restore backed up file(s)
5. Restore an entire filesystem
6. Check backup archive integrity

Enter an option or enter q to quit:

Any supported archive medium may be used to create backups. Any filesystem may be backed up. Menus of these devices are created for each option from the files /tmp/backup.list, /etc/default/archive, and /etc/default/filesys.

You must be the super-user to use this program.

Files

/tmp/backup.list
/etc/default/archive
/etc/default/filesys
See Also

fsphoto(ADM), mkfs(ADM), backup(C), dumpdir(C), restore(C), archive(F), filesys(F)

Notes

/tmp/backup.list, /etc/default/archive and /etc/default/filesys may be edited to add devices, or to delete entries for devices that are no longer used.

Warning

You should never backup more than one filesystem to the tape devices /dev/nrct0 and /dev/nrct2. This is because, although backup can write more than one filesystem to /dev/nrct0 or /dev/nrct2, restore may not be able to restore more than one filesystem from these devices.

You must also be sure to close the floppy door when inserting floppy disks during a backup. If you fail to do so in a multi-floppy backup, the entire backup will fail and you will have to begin again.
Name

sysadmsh - Menu driven system administration utility

Syntax

sysadmsh

Description

sysadmsh is an easy-to-use menu interface designed to provide novice users with the tools needed for day-to-day system administration of the XENIX system.

WARNING: sysadmsh does not replace the XENIX documentation. It provides an overview of available system administration features and a reminder of tasks which need to be performed regularly. An understanding of the XENIX Installation Guide, the XENIX System Administrator's Guide, and the XENIX User's Guide is necessary to use sysadmsh.

Usage

To use this utility enter:

sysadm

at the login prompt. This sets your login shell to be the sysadmsh menu hierarchy. You may access many useful commands and sub-menus, all presented in simple, descriptive terms.

Alternately, sysadmsh menus may also be invoked by logging in as the super-user (root) and entering:

sysadmsh

at the shell prompt.

Once you are in sysadmsh, on-line instructions for its use may be obtained by selecting the <F1> key.

Some sysadmsh options must be run from the system console device. Some options must be run while in single user (system maintenance) mode. Check the documentation manual page referenced by the menu selection for more information.
**Files**

**See Also**

XENIX System Administrator's Guide  
XENIX User's Guide  
XENIX Installation Guide

acctcom(ADM), accton(ADM), alias(M), asktime(ADM), at(C), badtrk(ADM), checklist(F), chgrp(C), chmod(S), chown(C), configure(ADM) copy(C), cron(C), csh(C), custom(ADM), df(C), diff(C), dircmp(C), disable(C), diskcmp(C), diskcp(C), dmesg(ADM), dos(C), dtype(C), du(C), enable(C), fdisk(ADM), find(C), finger(C), fixperm(ADM), format(C), fsck(ADM), fstab(F), grpcheck(C), init(M), kill(C), login(M), lp(C), lpadmin(ADM), lpinit(ADM), lpsstat(C), mail(C), mkdev(ADM), mkuser(ADM), more(C), mount(ADM), netutil(ADM), ps(C), pwdadmin(ADM), pwcck(C), quot(C), rmuser(ADM), shutdown(ADM), sysadmin(ADM), systemid(F), tar(C), ttys(F), umount(ADM), uuinstall(ADM), vi(C), wall(ADM), who(C), write(C)

**Notes**

A knowledge of vi(C) is assumed for file edit selections, although the SCO Lyrix® editor is used when available.

**Acknowledgements**

This utility takes its design from the SCO Lyrix Word Processing System.
Name

telinit, mkinittab - Alternative method of turning terminals on and off.

Syntax

telinit state
mkinittab [ttysfile]...

Description

telinit directs the actions of init(M). It is an alternative to using enable(C) and disable(C) to allow and disallow logins on terminals.

telinit generates a new /etc/ttys file from the /etc/inittab file. Only those lines from inittab(F) which apply in state are converted to their ttys(F) equivalent. init is then signaled to allow or disallow logins on terminals according to /etc/ttys.

The recognized state arguments are:

0-6
Generate /etc/ttys using the lines in /etc/inittab which apply to the specified state.

q, Q
Do not generate a new /etc/ttys file, but signal init to examine the existing /etc/ttys file.

s, S
Signal init to enter System Maintenance (single-user) mode.

Only the superuser can run telinit. Users currently logged onto terminals that are disabled are abruptly killed. Logins are not allowed on terminals not listed in /etc/ttys.

mkinittab writes on the standard output an inittab-format file generated from the specified ttysfiles. Each ttysfile must be in ttys format. If no ttysfile is specified, the standard input is read.

Files

/etc/ttys
/etc/inittab
See Also

disable(C), enable(C), getty(M), init(M), inittab(F), login(M), ttys(F)

Notes

inittab is provided for users more familiar with the telinit approach to terminal administration, as opposed to the standard XENIX enable and disable approach. It is intended that a full integration of these two approaches will be provided in a future version of XENIX.
Name

umount - Dismounts a file structure.

Syntax

/etc/umount special-device

Description

umount announces to the system that the removable file structure previously mounted on device special-device is to be removed. Any pending I/O for the file system is completed, and the file structure is flagged clean. For a detailed explanation of the mounting process, see mount(ADM).

Files

/etc/mnttab Mount table

See Also

mount(ADM), mount(S), mnttab(F)

Diagnostics

device busy An executing process is using a file on the named file system

May 16, 1988
Name

uucheck - Checks the uucp directories and permissions file.

Syntax

/usr/lib/uucp/uucheck [ -v ] [ -x debug_level ]

Description

uucheck checks for the presence of the uucp system required files and directories. It also checks for some obvious errors in the Permissions file (/usr/lib/uucp/Permissions). When executed with the -v option, it gives a detailed explanation of how the uucp programs will interpret the Permissions file. The -x option is used for debugging. debug-option is a single digit in the range 1-9; the higher the value, the greater the detail.

Note that uucheck can only be used by the super-user or uucp.

Files

/usr/lib/uucp/Systems
/usr/lib/uucp/Permissions
/usr/lib/uucp/Devices
/usr/lib/uucp/Maxuuscheds
/usr/lib/uucp/Maxuxqts
/usr/spool/uucp/*
/usr/spool/uucppublic/*

See Also

uucico(ADM), uuschec(ADM), uucp(C), uustat(C), uux(C)

Notes

The program does not check file/directory modes or some errors in the Permissions file such as duplicate login or machine name.
**Name**

`uucico` - File transport program for the `uucp` system.

**Syntax**

```
/usr/lib/uucp/uucico [ -r role_number ] [ -x debug_level ]
[ -i interface ] [ -d spool_directory ] [ -s ] [ -S ] system_name
```

**Description**

`uucico` is the file transport program for `uucp` work file transfers. Role numbers for the `-r` are the digit 1 for master mode or 0 for slave mode (default). The `-r` option should be specified as the digit 1 for master mode when `uucico` is started by a program or `cron`. `uux` and `uucp` both queue jobs that will be transferred by `uucico`. It is normally started by the scheduler, `uusched`, but can be started manually; this is done for debugging. For example, the shell `uutry` starts `uucico` with debugging turned on. A single digit must be used for the `-x` option with higher numbers for more debugging.

The `-i` option defines the interface used with `uucico`. This interface only affects slave mode. Known interfaces are UNIX (default), TLI (basic Transport Layer Interface), and TLIS (Transport Layer Interface with Streams modules, read/write); only the default, UNIX, is applicable in this release.

The `-d` option can be used to specify the `spool` directory: the default is `/usr/spool/uucp`.

If `-s` is specified, a call to the specified site is made even if there is no work for site `sitename` in the spool directory, but call only when times in the `Systems` file permit it. This is useful for polling sites that do not have the hardware to initiate a connection.

The `-S` option can be used to specify the system name, overriding the call schedule given in the `Systems` file. For example, `-S` can be used to call a system which is said to be ‘‘Never’’ called in the `Systems` file.

**Files**

- `/usr/lib/uucp/Systems`
- `/usr/lib/uucp/Permissions`
- `/usr/lib/uucp/Devices`
- `/usr/lib/uucp/Maxuuxqts`
- `/usr/lib/uucp/Maxuuscheds`
- `/usr/spool/uucp/*`
- `/usr/spool/uucppublic/*`

May 16, 1988
See Also

uusched(ADM), uutry(ADM), cron(C), uucp(C), uustat(C), uux(C).
Name

uuclean - uucp spool directory clean-up.

Syntax

/usr/lib/uucp/uuclean [ -Ctime ] [ -Dtime ] [ -Wtime ] [ -Xtime ] [ -mstring ] [ -otime ] [ -ssystem ] [ -xdebug_level ]

Description

uuclean will scan the spool directories for old files and take appropriate action to remove them in a useful way:

Inform the requestor of send/receive requests for systems that can not be reached.

Return mail, which cannot be delivered, to the sender.

Delete or execute mews for mews type files (depending on where the news originated--locally or remotely).

Remove all other files.

In addition, there is provision to warn users of requests that have been waiting for a given number of days (default 1). Note that uuclean will process as if all option times were specified to the default values unless time is specifically set.

The following options are available.

-Ctime Any C. files greater or equal to time days old will be removed with appropriate information to the requestor. (default 7 days)

-Dtime Any D. files greater or equal to time days old will be removed. An attempt will be made to deliver mail messages and execute mews when appropriate. (default 7 days)

-Wtime Any C. files equal to time days old will cause a mail message to be sent to the requestor warning about the delay in contacting the remote. The message includes the JOBID, and in the case of mail, the mail message. The administrator may include a message line telling whom to call to check the problem (-m option). (default 1 day)

-Xtime Any X. files greater or equal to time days old will be removed. The D. files are probably not present (if they were, the X. could get executed). But if there are D. files,
they will be taken care of by D. processing. (default 2 days)

-mstring This line will be included in the warning message generated by the -W option.

-otime Other files whose age is more than time days will be deleted. (default 2 days) The default line is "See your local administrator to locate the problem".

-system Execute for system spool directory only.

-xdebug_level
The -x debug level is a single digit between 0 and 9; higher numbers give more detailed debugging information.

This program is typically started by the shell uudemon.clean, which should be started by cron(C). uuclean can only be executed by the super user or uucp.

Files

/usr/lib/uucp directory with commands used by uuclean internally

/usr/spool/uucp spool directory

See Also

cron(C), uucp(C), uux(C).
Name

uuinstall - Administers UUCP control files.

Syntax

/etc/uuinstall [-r]

Description

The uuinstall program is used to manage the content of the control files used by the uucp communications system. It allows the user to change the contents of these files without using a text editor. The user need not know the detailed format of each of the control files, although he must be familiar with the function of the various fields within the files. These details are explained in the XENIX System Administrator's Guide.

The uuinstall program can only be executed by the super-user. When invoked with the optional -r flag, uuinstall will not allow any of the files to be modified whether or not the user has made changes to the files.

If uuinstall finds any of the required uucp control files missing from the system, it will create them with the correct access permissions and ownership.

Files

/etc/systemid
/usr/lib/uucp/Systems
/usr/lib/uucp/Permissions
/usr/lib/uucp/Devices

See Also

mkuser(ADM)
Name

uusched - The scheduler for the uucp file transport program.

Syntax

/usr/lib/uucp/uusched [ -x debug_level ] [ -u debug_level ]

Description

uusched is the uucp file transport scheduler. It is usually started by the daemon uudemond.hour that is started by cron(C) from an entry in /usr/spool/cron/crontabs/root:

39,9 * * * * /bin/su uucp -c "/usr/lib/uucp/uudemond.hour" > /dev/null

The two options are for debugging purposes only; -x debug_level will output debugging messages from uusched and -u debug_level will be passed as -x debug_level to uucico. The debug_level is a number between 0 and 9; higher numbers give more detailed information.

Files

/usr/lib/uucp/Systems
/usr/lib/uucp/Permissions
/usr/lib/uucp/Devices
/usr/lib/uucp/Maxuuscheds
/usr/spool/uucp/*
/usr/spool/uucppublic/*

See Also

uucico(ADM), cron(C), uucp(C), uustat(C), uux(C).
**Name**

uutry - Tries to contact remote system with debugging on.

**Syntax**

```
/usr/lib/uucp/uutry [-x debug_level] [-r] system_name
```

**Description**

The uutry program is a shell that invokes uucico to call a remote site. Debugging is automatically enabled at default level 5; -x overrides this value. If uutry successfully connects to the remote system, uutry stores the debugging output in the file `tmp/system`, where system is the name of the remote system. In addition, uutry uses `tail -f` to print the last 10 lines of the debugging output to the standard output.

To break out of the shell created by uutry, press DELETE or BREAK. This returns control to the terminal while uucico continues to run, sending the output to `/tmp/system_name`.

The -r option overrides the retry time in `/usr/spool/uucp/status`.

**Files**

```
/usr/lib/uucp/Systems
/usr/lib/uucp/Permissions
/usr/lib/uucp/Devices
/usr/lib/uucp/Maxuuscheds
/usr/lib/uucp/Maxuuxqts
/usr/spool/uucp/*
/usr/spool/uucppublic/*
/tmp/system_name
```

**See Also**

uucico(ADM), uucp(C), uux(C).
Name

uuxqt - Executes remote command requests.

Syntax

/usr/lib/uucp/uuxqt [ -s system ] [ -x debug_level ]

Description

*uuxqt* is the program that executes remote job requests from remote systems generated by the use of the *uux* command. (Mail uses *uux* for remote mail requests). *uuxqt* searches the spool directories looking for X. files. For each X. file, *uuxqt* checks to see if all the required data files are available and accessible, and file commands are permitted for the requesting system. The *Permissions* file is used to validate file accessibility and command execution permission.

There are two environment variables that are set before the *uuxqt* command is executed:

UU_MACHINE is the machine that sent the job (the previous one).

UU_USER is the user that sent the job.

These can be used in writing commands that remote systems can execute to provide information, auditing, or restrictions.

The *-x debug_level* is a single digit between 0 and 9. Higher numbers give more detailed debugging information.

Files

/usr/lib/uucp/Permissions
/usr/lib/uucp/Maxuuxqts
/usr/spool/uucp/*

See Also

uucico(ADM), uucp(C), uustat(C), uux(C), mail(C).
Name

wall - Writes to all users.

Syntax

/etc/wall

Description

wall reads a message from the standard input until an end-of-file. It then sends this message to all users currently logged in preceded by "Broadcast Message from ...". wall is used to warn all users, for example, prior to shutting down the system.

The sender should be super-user to override any protections the users may have invoked.

Files

/dev/tty*

See Also

mesg(C), write(C)

Diagnostics

Cannot send to ... The open on a user’s tty file has failed.
This page intentionally left blank.
Contents

Hardware Dependent (HW)

intro  Introduction to miscellaneous features and files.
8087  Math co-processor for Intel family CPUs.
boot  XENIX boot program.
cmos  Displays and sets the configuration data base.
fd    Floppy devices.
hd    Internal fixed disk drive.
keyboard Name and function of special keyboard keys.
lp, lp0, lp1, lp2 Line printer device interfaces..
machine Description of host machine.
mouse  Mouse or other graphic input device.
parallel Interface to parallel ports.
ramdisk Memory block device.
screen, tty[01-n], Display adapter and video monitor.
  color,
  monochrome,
ega, pga Small computer systems interface.
scsi
serial, tty1[a-h], Interfaces to serial ports.
tty1[A-H],
tty2[a-h],
tty2[A-H] tape  Cartridge tape device.
terminal Login terminal.
Name

intro - Introduction to machine related miscellaneous features and files.

Description

The hardware-dependent section (HW) contains information useful in maintaining the system. Included are descriptions of files, devices, tables and programs that are important in maintaining the entire system that are directly related to the kind of computer on which the system runs. This section is intended for use with the 86 family of Intel CPUs, specifically 8086, 8088, 80186, 80286 and 80386 based computers.
Name

8087

Syntax

8087
80287

Description

The 8087 is the INTEL math co-processor for the 8086. The 80287 is the INTEL math co-processor for the 80286. The kernel tests for the presence of an 8087 or 80287 at startup.

If your system has an 8087 or 80287, you must turn off a switch on the main system board in order to enable 8087 interrupts. Check your hardware manual to determine the proper switch and setting. If your system does not have an 8087, or the switch is on, the kernel will run a set of emulator routines which are much slower.

The C compiler available with the program development package generates the appropriate 8087 (or 80287) opcodes. C routines compiled with this compiler have run as much as 200 times as fast as the emulated code. In particular, the standard math library routines run considerably faster if you have an 8087 (or 80287).

The overflow, division by zero, and invalid operand exceptions return a SIGFPE signal. This signal can be caught. The rest of the 8087 and 80287 floating point exceptions (underflow, denormalized operand, and precision error) are masked.

Notes

The emulator returns meaningless information on divide by zero.

There is no obvious way to tell which 8087 (or 80287) exception generated the SIGFPE.
Name

`boot` - XENIX boot program.

Description

`boot` is an interactive program used to load and execute standalone XENIX programs. It is used primarily for loading and executing the XENIX kernel, but can load and execute any other programs that are linked for standalone execution. `boot` is a required part of the XENIX Operating System and must be present in the root directory of the root file system to ensure successful loading of the XENIX kernel.

The `boot` program is invoked by the system each time the computer is started. To restart the system without going through lengthy shutdown procedures, you can use the `reboot` command. This causes the system to reboot after shutting down without waiting for keyboard input. See `haltsys (ADM)` for more information.

For diskette boot, the procedure has three stages:

1. The ROMs load the boot block from sector 0 of the floppy, where sector 0 of the disk is the same as sector 0 of the filesystem.
2. The boot block-loads `/boot` from the floppy filesystem.
3. `/boot` executes and prompts the user.

For fixed disk boot, the procedure has five stages:

1. The ROMs load in the `masterboot` block from sector 0 on the hard disk.
2. The `masterboot` block then loads the partition boot block (`boot0`) from sector 0 of the active partition (see `fdisk(ADM)`).
3. Then, assuming the XENIX partition is active, `boot1` is loaded from 1K into the active partition in a 2.2 or later XENIX installation. If the disk was installed with a pre-2.2 XENIX release, then `boot1` is assumed to begin at 3K into the active partition. `Bootl` spans 20 physically contiguous 1K blocks on the disk.
4. `boot1` loads `/boot` from the XENIX file system.
5. `/boot` executes and prompts the user.

`/boot` and `/xenix` may lie on tracks that have been mapped by `badtrk(ADM)`. `masterboot`, `boot0`, and `boot1` cannot lie on bad tracks.
The fixed disk boot procedure is invoked if the diskette drive is empty.

When first invoked, boot prompts for the location of a program to load by displaying the message:

XENIX System V

Boot:

To specify the location of a program, a device and filename must be given. The filename must include the full pathname of the file containing the standalone program. You can display a list of the current allowable device names by typing a question mark (?)

The format for the device and pathname is as follows:

xx(m,o)filename
or
xx(m)filename

where:
xx = device name
   ('hd' for the hard disk or 'fd' for diskette device)
m = minor device number
   (40 for the root filesystem on the hard disk)
o = offset in the partition (usually 0). This is optional.
filename = standard XENIX pathname. Must start with a slash if the program is not in the root directory.

All numbers are in decimal. See the manual pages for hd(HW) and fd(HW) for minor device numbers of these devices. Specifying the offset is optional. The location of the program to be loaded must always be entered first on the command line and be present if other boot options are specified either on the command line or in /etc/default/boot.

If you want boot to pause and wait for a <RETURN> before executing the program that it loads, enter the word "prompt" on the command line. For example, if you enter "prompt" and press <RETURN>, boot prints the following message and waits for you to press the return key again:

   Loaded, press <RETURN>.

The prompt can be changed to another string as in this example:

   prompt="change diskettes now"

boot loads xenix from the diskette, prints the message "change diskettes now", and waits for <RETURN> to be pressed. No other characters can appear between prompt, the "=" sign and the prompt
string, although string may contain spaces. When you press <RETURN>, xenix will begin execution. "Prompt" can be set either on the command line or in /etc/default/boot. If a prompt is not specified, boot executes the loaded program without pausing.

If you have just loaded the boot program from the distribution diskette, simply press <RETURN> and boot defaults to the correct values.

To load XENIX from a hard disk, enter:

    hd(40,0)xenix

To use the default boot string specified in /etc/default/boot, simply press <RETURN> when the system displays the boot prompt, and boot uses the values specified by DEFBOOTSTR in /etc/default/boot.

If nothing is typed after a short while and LOADXENIX is set to YES in the default root file system's /etc/default/boot file, boot times out and behaves as though a <RETURN> had been pressed, except that an "auto" is added to the boot string. (If, in addition to LOADXENIX=YES, TIMEOUT=n is defined, boot waits n seconds before timing out.) boot proceeds through the boot procedure, and init(M) is passed a -a flag with no "prompt".

It is recommended that you install DOS on the hard disk before XENIX. See the manual page for dos(C). However, once you install DOS you can boot it at the XENIX "Boot" prompt by entering "dos".

During XENIX installation, a custom masterboot is placed on the hard disk. If a non-standard disk is specified, its parameters are stored and enabled in this masterboot.

**Configuring The Kernel**

boot passes any boot string typed at the boot prompt to the kernel, except for the "prompt" string.

The kernel reads the boot string to determine which peripherals are the root, pipe and swap devices. If no devices are specified in either the /etc/default/boot description or on the command line, the default devices compiled into the kernel are used.
Additional arguments in the boot string can alter this default action. These arguments have the form:

\[
\text{dev}=xx(m,o) \\
\text{or} \\
\text{dev}=xx(m) \\
\text{where:} \\
\begin{align*}
\text{dev} & = \text{The desired system device} \,(\text{root[dev]}, \text{pipe[dev]}, \text{or swap[dev]}) \\
xx, m, o & = \text{same as for the boot device}
\end{align*}
\]

If any combination of \text{root}, \text{pipe} or \text{swap} is specified, then those system devices will reside on that device, with the unspecified system devices using the defaults compiled in the kernel. Setting one device does not affect the default values for the other system devices.

Selecting The System Console

You can select the system console at boot time either by entering the command \text{systty=x} at the boot prompt, or by placing the keywords \text{SYSTTY=x} in the file /etc/default/boot. The letter \text{x} represents either a number or a string parameter.

If you use the \text{systty=x} command at boot time, \text{boot} uses the string parameter \text{x} to pass the selected console device to the kernel. The values of the boot string parameter \text{systty} are:

\[
\begin{align*}
\text{sio} & \quad \text{Serial port COM1} \\
\text{scrn} & \quad \text{Display adapter}
\end{align*}
\]

For example, to assign the system console to the serial port at COM1, enter this command at the boot prompt:

\[
\text{systty=sio}
\]

If you do not specifically set the system console at boot time, the \text{boot} program follows these steps to determine the system console:

- \text{boot} reads /etc/default/boot and looks for the keywords \text{SYSTTY=x} where \text{x} is a number that specifies the system console device.

\[
\begin{align*}
1 & \quad \text{indicates the serial adapter at COM1.} \\
0 & \quad \text{indicates the display adapter.}
\end{align*}
\]

- If \text{SYSTTY} is not found or /etc/default/boot is unreadable, \text{boot} checks for a display adapter and assigns it as the system console.
If no display adapter is found, boot looks for COM1, sets the serial port to 9600 baud, 8 data bits, 1 stop bit, and no parity, and uses it as the system console.

Thus, to have boot automatically set the system console to the serial port at COM1, enter this line in /etc/default/boot:

SYSTTY=1

Aliasing

A set of system devices can be aliased to a single keyword by defining the keyword in the file /etc/default/boot. This keyword can then be entered on the "Boot" command line and the boot program then reads the corresponding system devices from /etc/default/boot and pass them to the kernel. An alias has the following form:

key=file [root=xx(m) pipe=xx(m) swap=xx(m) prompt[="string"]]

In all cases, the device specification can also have the format dev=xx(m,o), where o is the offset.

For example, if you have a root file system on a second hard disk and want to use it, but want to boot using the xenix located on the first hard disk, enter the following line into the /etc/default/boot description:

disk2=hd(40,0)xenix root=hd(104,0) prompt="Using second disk"

The next time you boot the system from the first hard disk, enter "disk2" in response to the "Boot" prompt. xenix will be loaded from the first hard disk, and when you see the message, "Using second disk", press <RETURN> . xenix will now boot and use the root file system on the second hard disk. Note that you must edit the /etc/default/boot file in the root file system on the device from which boot will be read, in this case the first hard disk.

Another example: Suppose you want to boot off the second drive (hd10) and use the root filesystem and swap space of the second drive. At the boot prompt, use the following bootstring:

hd(104)xenix root=hd(104) pipe=hd(104) swap=hd(105)

Once booted, you must create the device nodes for the second drive for use by the utilities:

fixperm -c -dHD1 /etc/perms/inst

Boot options

Boot options can be changed via keywords in /etc/default/boot. The following keywords are recognized by boot:
LOADXENIX=YES If YES, boot automatically loads XENIX after a delay time specified by the TIMEOUT parameter. The default value is 60 seconds.

DEFBOOTSTR=string string is used as the default boot string for timeouts and for no input on the command line. There can be no white space between DEFBOOTSTR, the "=" sign and string.

SYSTTY=x If x is one (1), the system console device is set to the serial adapter at COM1. If x is zero (0), the system console is set to the main display adapter.

ONLYROOT=NO Whether or not the root filesystem is to be mounted readonly. This should only be set to "yes" during installation.

FSCKFIX=YES or NO Whether or not fsck(ADM) fixes any root system problems by itself. If the variable is set at YES, then fsck(ADM) is run on the root filesystem with the -rr flag.

MULTIUSER=YES or NO Whether or not init(M) invokes sulogin or proceeds to multiuser mode.

PANICBOOT=YES or NO Whether or not the system reboots after a panic(). This variable is read from /etc/default/boot by init.

TIMEOUT=n n is the number of seconds to wait at boot, before timing out (if LOADXENIX is set to YES).

Diagnostics

If an error occurs, masterboot displays an error message, and locks the system. The following is a list of the most common messages and their meanings:

**IO ERR**
An error occurred when masterboot tried to read in the partition boot of the active operating system.

**BAD TBL**
The bootable partition indicator of at least one of the operating systems in the fdisk table contains an unrecognizable code.
NO OS

There was an unrecoverable error that prevented the active operating system's partition boot from executing.

When boot displays error messages, it returns to the “Boot” prompt. The following is a list of the most common messages and their meanings:

bad magic number

The given file is not an executable program.

can't open <pathname>

The supplied pathname does not correspond to an existing file, or the device is unknown.

Stage 1 boot failure

The bootstrap loader cannot find or read the boot file. You must restart the computer and supply a file system disk with the boot file in the root directory.

not a directory

The specified area on the device does not contain a valid XENIX filesystem.

zero length directory

Although an otherwise valid filesystem was found, it contains a directory of apparently zero length. This most often occurs when a pre-System V XENIX filesystem (with incorrect, or incompatible word ordering) is in the specified area.

fload:read(x)=y

An attempted read of x bytes of the file returned only y bytes. This is probably due to a premature end-of-file. It could also be caused by a corrupted file, or incorrect word ordering in the header.

Files

/boot
/etc/default/boot
/etc/masterboot
/etc/hdboot0
/etc/hdboot1

See Also

autoboot(ADM), badtrak(ADM), fd(HW), fdisk(ADM), haltsys(ADM), hd(HW), init(M), sulogin(M)
Notes

The computer tries to boot off any diskette in the drive. If the diskette does not contain a valid bootstrap program, errors occur.

The *boot* program cannot be used to load programs that have not been linked for standalone execution. To create standalone programs, the `-A` option of the XENIX linker (`ld(CP)`) and special standalone libraries must be used.

Standalone programs can operate in real or protected mode, but they must not be large or huge models. Programs in real mode can use the input/output routines of the computer's startup ROM.

RONLYROOT should only be set to "yes" for installation. If it is set to "yes" during day-to-day operations, it will prevent you making changes to the root filesystem. You will then be required to boot from the floppy drive, edit the `/etc/default/boot` file and reboot.
Name

cmos - Displays and sets the configuration data base.

Syntax

cmos [ address [ value ] ]

Description

The `cmos` command displays and/or sets the values in the CMOS configuration data base. This battery-powered data base stores configuration information about the computer that is used at power up to define the system hardware configuration and to direct boot procedures. The data base is 64 bytes long and is reserved for system operation. Refer to your computer hardware manual for more information.

The `cmos` command is typically used to alter the current hardware configuration when new devices are added to the system. When only `address` is given, the command displays the value at that address. If both `address` and a `value` are given, the command assigns the value to that address. If no arguments are given, the command displays the entire contents of the data base.

The CMOS configuration data base may also be examined and modified by reading from and writing to `/dev/cmos` file. Because successful system operation depends on correct configuration information, the data base should be modified by experienced system administrators only.

The computer manufacturer’s diagnostic diskette should be run before setting the CMOS data base.

Files

/etc/cmos
/dev/cmos

Notes

Not all computers have a CMOS configuration data base. Some computers use switches on the main system board to configure the system. Refer to your computer hardware reference manual to determine whether you have a configuration data base.
Name

fd - floppy devices

Description

The fd devices implement the XENIX interface with floppy disk drives. Typically, the tar(C), cpio(C) or dd(C) commands are used to read or write floppy disks. For instance,

```
tar tvf /dev/fd0
```

tabulates the contents of the floppy disk in drive 0 (zero).

The block special fd devices are also block-buffered. The floppy driver can read or write 1K bytes at a time using raw i/o. Note that block transfers are always a multiple of the 1K disk block size.

The floppy devices are named /dev/fd0 and /dev/fd1 (see Notes, below, for more information about device naming procedure).

The corresponding character special (raw) devices, /dev/rfd0 and /dev/rfd1, afford direct, unbuffered transmission between the floppy and the user’s read or write transfer address in the user’s program.

For information about formatting, see format(C).

The minor device number determines what kind of physical device is attached to each device file (see Notes).

Files

```
/dev/fd0 /dev/rfd048ds8 /dev/rfd096ds15 /dev/rfd0135ds9
/dev/fd1 /dev/rfd148ds8 /dev/rfd196ds15 /dev/rfd1135ds9
/dev/rfd0 /dev/rfd048ds9 /dev/rfd096ds9 /dev/rfd0135ds18
/dev/rfd1 /dev/rfd148ds9 /dev/rfd196ds9 /dev/rfd1135ds18
           /dev/rfd048ss8
           /dev/rfd148ss9
```

Notes

When accessing the character special floppy devices, the user’s buffer must begin on a word boundary. The count in a read(S), write(S), or lseek(S) call to a character special floppy device must be a multiple of 1K bytes.

Device names determine the particular drive and media configuration. The device names have the form: fd048ds9 Where: fd0 = drive number (0, 1, 2 or 3) 48 = number of disk tracks per inch (48 or 96) ds = single or double sided floppy (ss or ds) 9 = number of sectors on
the floppy (8 or 9)

For instance, /dev/fd048ss9 indicates a 48 track per inch, single sided, 9 sector floppy disk device in drive 0.

The minor device numbers for floppy drives depend on the drive and media configuration. The most common are:

<table>
<thead>
<tr>
<th>Drive</th>
<th>Minor Device Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>12 4 8 0 52 44 36 60</td>
</tr>
<tr>
<td>1</td>
<td>13 5 9 1 53 45 37 61</td>
</tr>
<tr>
<td>2</td>
<td>14 6 10 2 54 46 38 62</td>
</tr>
</tbody>
</table>
| 3*    | reserved for special, non-floppy devices connected to the floppy controller as unit #3.

The scheme for creating minor device numbers is as follows. When interpreted as a binary number, each bit of the minor device number represents some aspect of the device/media configuration.

For example, the minor device number for /dev/fd048ss8 is “8.” Interpreted as a binary number, 8 is:

```
00001000
```

This is how each bit, or binary digit, is significant:

<table>
<thead>
<tr>
<th>48tpi - 0</th>
<th>Sectors per Track</th>
<th>ss - 0</th>
<th>Drive</th>
</tr>
</thead>
<tbody>
<tr>
<td>96tpi - 1</td>
<td>16 8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>135tpi - 1</td>
<td>32</td>
<td>4</td>
<td>2 1</td>
</tr>
</tbody>
</table>

0 0 1 0 0

May 16, 1988
Only the last six digits of the number are used in minor device identification. The first significant digit is the third from the left. In this example, the third digit from the left is zero, thus the device is 48tpi. The next two digits mean:

<table>
<thead>
<tr>
<th>Bits</th>
<th>Sectors per Track</th>
</tr>
</thead>
<tbody>
<tr>
<td>16</td>
<td>8</td>
</tr>
</tbody>
</table>
| 0    | 0                 | 9
| 0    | 1                 | 8
| 1    | 0                 | 15
| 1    | 1                 | 18

The fourth digit tells whether the floppy is single sided (ss - 0) or double sided (ds - 1). The last two signify the drive number:

<table>
<thead>
<tr>
<th>Bits</th>
<th>Drive Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>1</td>
</tr>
</tbody>
</table>
| 0    | 0            | 0
| 0    | 1            | 1
| 1    | 0            | 2
| 1    | 1            | 3*

* reserved for special, non-floppy devices connected to the floppy controller as unit #3.

Using this information, you can construct any minor device numbers you need.

It is not advisable to format a low density (48tpi) diskette on a high density (96tpi or 135tpi) floppy drive. Low density diskettes written on a high density drive should be read on high density drives. They may or may not be readable on a low density drive.

Use error-free floppy disks for best results on reading and writing.
Name

hd - Internal hard disk drive

Description

Block-buffered access to the primary hard disk is provided through the following block special files: hd00, hd01 through hd04, hd0a and hd0d, root, and swap. Block-buffered access to the secondary hard disk is provided through the following block special files: hd10, hd11 through hd14, hd1a.

hd00 refers to the entire physical disk; hd01 through hd04 refer to the fdisk partitions. root refers to the root file system; swap refers to the swap area. The block special files access the disks via the system's normal buffering mechanism and may be read and written without regard to the size of physical disk records.

Character special files follow the same naming convention as the block special files except that the character special file is prefaced with an "r". For example, the character special file referring to the entire physical disk is /dev/rhd00.

The following are the names of the fixed disk partitions. Each partition can be accessed through a block interface, for example /dev/hd01, or through a character (raw) interface, for example /dev/rhd01.
Device File Names for Fixed Disks

<table>
<thead>
<tr>
<th>Disk 1</th>
<th>Disk 2</th>
<th>Partition</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/hd00</td>
<td>/dev/hd10</td>
<td>entire disk</td>
</tr>
<tr>
<td>/dev/rhd00</td>
<td>/dev/rhd10</td>
<td></td>
</tr>
<tr>
<td>/dev/hd01</td>
<td>/dev/hd11</td>
<td>first partition</td>
</tr>
<tr>
<td>/dev/rhd01</td>
<td>/dev/rhd11</td>
<td></td>
</tr>
<tr>
<td>/dev/hd02</td>
<td>/dev/hd12</td>
<td>second partition</td>
</tr>
<tr>
<td>/dev/rhd02</td>
<td>/dev/rhd12</td>
<td></td>
</tr>
<tr>
<td>/dev/hd03</td>
<td>/dev/hd13</td>
<td>third partition</td>
</tr>
<tr>
<td>/dev/rhd03</td>
<td>/dev/rhd13</td>
<td></td>
</tr>
<tr>
<td>/dev/hd04</td>
<td>/dev/hd14</td>
<td>fourth partition</td>
</tr>
<tr>
<td>/dev/rhd04</td>
<td>/dev/rhd14</td>
<td></td>
</tr>
<tr>
<td>/dev/hd0a</td>
<td>/dev/hd1a</td>
<td>active partition</td>
</tr>
<tr>
<td>/dev/rhd0a</td>
<td>/dev/rhd1a</td>
<td></td>
</tr>
<tr>
<td>/dev/hd0d</td>
<td>/dev/hd1d</td>
<td>DOS partition</td>
</tr>
<tr>
<td>/dev/rhd0d</td>
<td>/dev/rhd1d</td>
<td></td>
</tr>
<tr>
<td>/dev/root</td>
<td>/dev/rroot</td>
<td>root file system</td>
</tr>
<tr>
<td>/dev/swap</td>
<td>/dev/swap</td>
<td>swap area</td>
</tr>
</tbody>
</table>

Note that the root and swap file names do not exist for a second disk.

To access DOS partitions, specify letters such as "C:" or "D:" to indicate first or second partitions. The file /etc/default/msdos contains lines that assign a letter abbreviation for the DOS device name. Refer to dos(C).

The following table lists the minor device number definitions for the hard disk special files, along with examples. Note that the block and character special devices share the same minor device definition. The minor device number definition is as follows: bits 7 and 6 denote physical drive, bits 5-3 denote virtual(fdisk) partition and bits 2-0 denote divvy partition.
## Minor Device Bits

<table>
<thead>
<tr>
<th>Phys.</th>
<th>Virtual</th>
<th>Divvy</th>
<th>Device special</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>0 0</td>
<td>0 0</td>
<td>/dev/hd00</td>
<td>whole PD 0</td>
</tr>
<tr>
<td>0 1</td>
<td>0 0</td>
<td>0 0</td>
<td>/dev/hd10</td>
<td>whole PD 1</td>
</tr>
<tr>
<td>1 0</td>
<td>0 0</td>
<td>0 0</td>
<td>/dev/hd20</td>
<td>whole PD 2</td>
</tr>
<tr>
<td>1 1</td>
<td>0 0</td>
<td>0 0</td>
<td>/dev/hd30</td>
<td>whole PD 3</td>
</tr>
<tr>
<td>0 0</td>
<td>0 0 1</td>
<td>1 1 1</td>
<td>/dev/hd01</td>
<td>PD 0, whole VD 1</td>
</tr>
<tr>
<td>0 0</td>
<td>0 1 0</td>
<td>1 1 1</td>
<td>/dev/hd02</td>
<td>PD 0, whole VD 2</td>
</tr>
<tr>
<td>0 0</td>
<td>0 1 1</td>
<td>1 1 1</td>
<td>/dev/hd03</td>
<td>PD 0, whole VD 3</td>
</tr>
<tr>
<td>0 0</td>
<td>1 0 0</td>
<td>1 1 1</td>
<td>/dev/hd04</td>
<td>PD 0, whole VD 4</td>
</tr>
<tr>
<td>0 0</td>
<td>1 0 1</td>
<td>1 1 1</td>
<td>/dev/hd0a</td>
<td>PD 0, whole active VD</td>
</tr>
<tr>
<td>0 0</td>
<td>1 1 0</td>
<td>1 1 1</td>
<td>/dev/hd0d</td>
<td>PD 0, whole DOS VD</td>
</tr>
<tr>
<td>0 0</td>
<td>1 0 1</td>
<td>0 0 0</td>
<td>/dev/root</td>
<td>PD 0, active virtual, DP 0</td>
</tr>
<tr>
<td>0 0</td>
<td>1 0 1</td>
<td>0 0 1</td>
<td>/dev/swap</td>
<td>PD 0, active virtual, DP 1</td>
</tr>
<tr>
<td>0 0</td>
<td>0 0 1</td>
<td>0 1 0</td>
<td>/dev/usr</td>
<td>PD 0, active virtual, DP 2</td>
</tr>
<tr>
<td>0 0</td>
<td>0 1 0</td>
<td>0 1 0</td>
<td>/dev/recover</td>
<td>PD 0, active virtual, DP 6</td>
</tr>
<tr>
<td>0 1</td>
<td>0 0 1</td>
<td>1 1 1</td>
<td>/dev/hd11</td>
<td>PD 1, whole VD 1</td>
</tr>
<tr>
<td>0 1</td>
<td>0 1 0</td>
<td>1 1 1</td>
<td>/dev/hd12</td>
<td>PD 1, whole VD 2</td>
</tr>
<tr>
<td>0 1</td>
<td>0 1 1</td>
<td>1 1 1</td>
<td>/dev/hd13</td>
<td>PD 1, whole VD 3</td>
</tr>
<tr>
<td>0 1</td>
<td>1 0 0</td>
<td>1 1 1</td>
<td>/dev/hd14</td>
<td>PD 1, whole VD 4</td>
</tr>
<tr>
<td>0 1</td>
<td>1 0 1</td>
<td>1 1 1</td>
<td>/dev/hd1a</td>
<td>PD 1, whole active VD</td>
</tr>
<tr>
<td>0 1</td>
<td>1 1 0</td>
<td>1 1 1</td>
<td>/dev/hd1d</td>
<td>PD 1, whole DOS VD</td>
</tr>
<tr>
<td>0 1</td>
<td>1 0 1</td>
<td>0 0 0</td>
<td>/dev/u0</td>
<td>PD 1, active virtual, DP 0</td>
</tr>
<tr>
<td>0 1</td>
<td>1 0 1</td>
<td>0 0 1</td>
<td>/dev/u1</td>
<td>PD 1, active virtual, DP 1</td>
</tr>
<tr>
<td>0 1</td>
<td>1 0 1</td>
<td>0 1 0</td>
<td>/dev/u2</td>
<td>PD 1, active virtual, DP 2</td>
</tr>
</tbody>
</table>

**KEY**

| VD = virtual drive | PD = physical drive | DP = divvy partition | t = user-defined name |

The device files **usr** and **u[0-2]** are optional filesystem names; these nodes are not present unless created by the system administrator.

### Files

- `/dev/hd0a`
- `/dev/rhd0a`
- `/dev/hd0[0-4]`
- `/dev/rhd0[0-4]`
- `/dev/hd0d`
- `/dev/rhd0d`
- `/dev/hd1a`
- `/dev/rhd1a`
- `/dev/hd1[0-4]`
- `/dev/rhd1[0-4]`
- `/dev/hd1d`
- `/dev/rhd1d`
- `/dev/root`
- `/dev/rroot`
- `/dev/swap`
- `/dev/rswap`

### See Also

- `fdisk(ADM)`
- `badtrk(ADM)`
- `divvy(ADM)`
- `dos(C)`
- `mkdev(ADM)`

May 16, 1988
Diagnostics

The following messages are among those that may be printed on the console:

invalid fixed disk parameter table

and:

error on fixed disk (minor n), block = nnnnn,
cmd=nnnnn, status=nnnn,
Sector = nnnnn, Cylinder/head = nnnnn

Possible reasons for the first error include:

- The kernel is unable to get drive specifications, such as number of heads, cylinders, and sectors per track, from the disk controller ROM.

- Improper configuration.

- The disk is not turned on.

- The disk is not supported.

The second error specifies the following information:

- \texttt{block} : The XENIX block number within the device.

- \texttt{cmd} : The last command sent to the disk controller.

- \texttt{status} : The error status from the disk controller.

- \texttt{Sector} and \texttt{Cylinder/head} specify the location of a possible flaw. This information is used with \texttt{badtrk(ADM)}.

Notes

On the first disk, \texttt{hd00} denotes the entire disk and is used to access the master boot block which includes the fdisk partition table. For the second disk, \texttt{hd10} denotes the entire disk and is used to access its fdisk partition table. Do not write to \texttt{hd10} and \texttt{hd00}. 
Name

keyboard - The PC keyboard.

Description

The PC keyboard is used to enter data, switch screens, and send certain control signals to the computer. XENIX performs terminal emulation on the PC screen and keyboard, and, in doing so, makes use of several particular keys and key combinations. These keys and key combinations have special names that are unique to the XENIX system, and may or may not correspond to the keytop labels on your keyboard. These keys are described later.

When you press a key, one of the following happens:

- An ASCII value is entered
- A string is sent to the computer.
- A function is initiated.
- The meaning of another key, or keys, is changed.

When a key is pressed (a keystroke), the keyboard sends a scancode to the computer, it is interpreted by the keyboard driver. The interpretation of key codes may be modified so that keys can function differently from their default actions.

There are three special occurrences, or keystrokes:

- Switch screens.
- Send signals.
- Change the value of previous character, characters or string.

Switching Screens (Multiscreen)

To get to the next consecutive screen, enter Ctrl-PrtSc using the Ctrl key, and the PrtSc key. Any active screen may be selected by entering alt-Fn, where Fn is one of the function keys. F1 refers to the PC display (/dev/tty01).
Signals

A signal affects some process or processes. Examples of signals are Ctrl-d (end of input, exits from shell), Ctrl-\ (quits a process), Ctrl-s (stop output to the screen), and Ctrl-q (resume sending output).

Typically, characters are mapped to signals using stty(C). The only way to map signals is using stty.

Altering Values

The actual code sent to the keyboard driver can be changed by using certain keys in combination. For example, the SHIFT key changes the ASCII values of the alphanumeric keys. Holding down the Ctrl key while pressing another key sends a control code (Ctrl-d, Ctrl-s, Ctrl-q, etc.).

Special Keys

To help you find the special keys, the following table shows which keys on a typical console correspond to XENIX system keys. In this table, a hyphen (-) between keys means ‘hold down the first key while pressing the second.’

<table>
<thead>
<tr>
<th>XENIX Name</th>
<th>Keytop</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>INTR</td>
<td>Del</td>
<td>Stops current action and returns to the shell. This key is also called the RUB OUT or INTERRUPT key.</td>
</tr>
<tr>
<td>BACKSPACE</td>
<td>←</td>
<td>Deletes the first character to the left of the cursor. Note that the “cursor left” key also has a left arrow (←) on its keytop, but you cannot backspace using that key.</td>
</tr>
<tr>
<td>Ctrl-d</td>
<td>Ctrl-d</td>
<td>Signals the end of input from the keyboard; also exits current shell.</td>
</tr>
<tr>
<td>Ctrl-h</td>
<td>Ctrl-h</td>
<td>Deletes the first character to the left of the cursor. Also called the ERASE key.</td>
</tr>
<tr>
<td>Ctrl-q</td>
<td>Ctrl-q</td>
<td>Restarts printing after it has been stopped with Ctrl-s.</td>
</tr>
</tbody>
</table>
KEYBOARD (HW)

Ctrl-s Ctrl-s
Suspends printing on the screen (does not stop the program).

Ctrl-u Ctrl-u
Deletes all characters on the current line. Also called the KILL key.

Ctrl-\ Ctrl-\ 
Quits current command and creates a core file, if allowed. (Recommended for debugging only.)

ESCAPE Esc
Special code for some programs. For example, changes from insert mode to command mode in the vi(C) text editor.

RETURN (down-left arrow or ENTER)
Terminates a command line and initiates an action from the shell.

Fn Fn
Function key n. F1-F12 are unshifted, F13-F24 are shifted F1-F12, F25-F36 are Ctrl-F1 through F12, and F37-F48 are Ctrl-Shift-F1 through F12.

The next Fn keys (F49-F60) are on the number pad (unshifted):

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>F49</td>
<td>'7'</td>
</tr>
<tr>
<td>F50</td>
<td>'8'</td>
</tr>
<tr>
<td>F51</td>
<td>'9'</td>
</tr>
<tr>
<td>F52</td>
<td>'-'</td>
</tr>
<tr>
<td>F53</td>
<td>'4'</td>
</tr>
<tr>
<td>F54</td>
<td>'5'</td>
</tr>
<tr>
<td>F55</td>
<td>'6'</td>
</tr>
<tr>
<td>F56</td>
<td>'+'</td>
</tr>
<tr>
<td>F57</td>
<td>'1'</td>
</tr>
<tr>
<td>F58</td>
<td>'2'</td>
</tr>
<tr>
<td>F59</td>
<td>'3'</td>
</tr>
<tr>
<td>F60</td>
<td>'0'</td>
</tr>
</tbody>
</table>

For keys F61 through F96, see /usr/lib/keyboard/strings. These function keys are not available on all keyboards, but you can map other keys to represent them.

The keyboard mapping is performed through a structure defined in /usr/include/sys/keyboard.h. Each key can have ten states. The first eight are:

- Base - Ctrl-Shift
- Shift - Alt-Shift
- Ctrl - Alt-Ctrl
- Alt - Alt-Ctrl-Shift

There are two additional states indicated by two special bytes. The
first is a "special state" byte whose bits indicate whether the key is "special" in one or more of the first eight states.

The second is one of four characters (C, N, B, O) which indicate how the lock keys affect the particular key. This is discussed further in the next section, "Scan Codes."

Keyboard Mode

Most keyboards normally are in a PC compatibility mode, though some can be put into a native AT keyboard mode. The XENIX utility `kbmode(ADM)` can be used to determine if a keyboard supports AT mode, and can also be used to put the keyboard into AT mode until the next time the system is rebooted. A system can also be configured to boot with the keyboard in AT mode with the `configure(ADM)` utility.

Enhanced keyboards are more fully programmable in AT mode. Also, it recognizes two control keys and an alt key.

Scan Codes

The following table describes the default contents of `/usr/lib/keyboard/keys`. The column headings are:

| SCAN CODE | The scan code generated by the keyboard hardware when a key is pressed. There is no user access to the scan code generated by releasing a key. |
| BASE | The normal value of a key press. |
| SHIFT | The value of a key press when the SHIFT is also being held down. |
| LOCK | Indicates which lock keys affect that particular key: |
| - C indicates Capslock |
| - N indicates Numlock |
| - B indicates both |
| - O indicates locking is off |

Keys affected by the lock keys C, B, or N, send the shifted value (scan code) of current state when that lock key is on. When the shift key is depressed while a lock key is also on, the key reverts (toggles) to its original state.

The other columns are the values of key presses when combinations of the CTRL, ALT and SHIFT keys are also held down.

All values, except for keywords, are ASCII character values. The keywords refer to the special function keys.
<table>
<thead>
<tr>
<th>SCAN CODE</th>
<th>BASE</th>
<th>SHIFT</th>
<th>CTRL</th>
<th>CTRL</th>
<th>ALT</th>
<th>ALT</th>
<th>ALT</th>
<th>ALT</th>
<th>LOCK</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>1</td>
<td>esc</td>
<td>esc</td>
<td>nop</td>
<td>nop</td>
<td>esc</td>
<td>esc</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>2</td>
<td>'1'</td>
<td>'1'</td>
<td>nop</td>
<td>nop</td>
<td>'1'</td>
<td>'1'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>3</td>
<td>'2'</td>
<td>'@'</td>
<td>nop</td>
<td>nop</td>
<td>'2'</td>
<td>'@'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>4</td>
<td>'3'</td>
<td>'#'</td>
<td>nop</td>
<td>nop</td>
<td>'3'</td>
<td>'#'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>5</td>
<td>'4'</td>
<td>'$'</td>
<td>nop</td>
<td>nop</td>
<td>'4'</td>
<td>'$'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>6</td>
<td>'5'</td>
<td>'%'</td>
<td>nop</td>
<td>nop</td>
<td>'5'</td>
<td>'%'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>7</td>
<td>'6'</td>
<td>'5s'</td>
<td>rs</td>
<td>rs</td>
<td>'6'</td>
<td>'5s'</td>
<td>rs</td>
<td>rs</td>
<td>O</td>
</tr>
<tr>
<td>8</td>
<td>'7'</td>
<td>'&amp;'</td>
<td>nop</td>
<td>nop</td>
<td>'7'</td>
<td>'&amp;'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>9</td>
<td>'8'</td>
<td>'*'</td>
<td>nop</td>
<td>nop</td>
<td>'8'</td>
<td>'*'</td>
<td>nop</td>
<td>nop</td>
<td>O</td>
</tr>
<tr>
<td>10</td>
<td>'9'</td>
<td>'('</td>
<td>nop</td>
<td>nop</td>
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May 16, 1988
Page 5
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<th>Description</th>
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The following scan codes exist only for keyboards which support, and are in, native AT mode rather than PC compatibility mode.

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<tr>
<th>SCAN CODE</th>
<th>BASE 87-95</th>
<th>SCAN CODE</th>
<th>BASE 96-127</th>
<th>SCAN CODE</th>
<th>BASE 128-137</th>
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<td>87</td>
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<td>fkey47</td>
<td>88</td>
<td>fkey48</td>
<td>89</td>
<td>nop</td>
</tr>
</tbody>
</table>

May 16, 1988
The next table lists the "value" of each of the special keywords used in `/usr/lib/keyboard/keys` (and the preceding table). `mapkey(ADM)` places a "value" in the `ioctl` buffer during key mapping. The keywords are only used in the scan code file (`/usr/lib/keyboard/keys`) for readability.

<table>
<thead>
<tr>
<th>Name</th>
<th>Value</th>
<th>Meaning</th>
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<tbody>
<tr>
<td>nop</td>
<td>0</td>
<td>No operation - no action from keypress</td>
</tr>
<tr>
<td>lshift</td>
<td>2</td>
<td>Left hand shift</td>
</tr>
<tr>
<td>rshift</td>
<td>3</td>
<td>Right hand shift</td>
</tr>
<tr>
<td>clock</td>
<td>4</td>
<td>Caps lock</td>
</tr>
<tr>
<td>nlock</td>
<td>5</td>
<td>Numeric lock</td>
</tr>
<tr>
<td>clock</td>
<td>6</td>
<td>Scroll lock</td>
</tr>
<tr>
<td>alt</td>
<td>7</td>
<td>Alt key</td>
</tr>
<tr>
<td>btab</td>
<td>8</td>
<td>Back tab key - generates fixed sequence (esc [ Z)</td>
</tr>
<tr>
<td>ctrl</td>
<td>9</td>
<td>Control key</td>
</tr>
<tr>
<td>nsr</td>
<td>10</td>
<td>Switch to the next screen</td>
</tr>
<tr>
<td>scr16</td>
<td>26</td>
<td>Switch to screen #16</td>
</tr>
<tr>
<td>fkey1</td>
<td>27</td>
<td>Function key #1</td>
</tr>
<tr>
<td>fkey96</td>
<td>122</td>
<td>Function key #96</td>
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<td>rctl</td>
<td>128*</td>
<td>Right Control Key</td>
</tr>
<tr>
<td>ralt</td>
<td>129*</td>
<td>Right Alt Key</td>
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</tbody>
</table>

* AT mode keyboard only.
This table lists names and decimal values that are interchangeable in the `mapkey` file. Names are used in place of numeric constants to make it easier to read the scan code table. Again, only the decimal values are placed in the `ioctl` buffer. These are taken from `ascii(M)`.

<table>
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<th>Value</th>
<th>Name</th>
<th>Value</th>
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</thead>
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<tr>
<td>stx</td>
<td>2</td>
<td>dc3</td>
<td>19</td>
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<td>etx</td>
<td>3</td>
<td>dc4</td>
<td>20</td>
</tr>
<tr>
<td>eot</td>
<td>4</td>
<td>nak</td>
<td>21</td>
</tr>
<tr>
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<td>5</td>
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</table>

**Keyboard Mapping**

The PC keyboard is mapped as part of terminal emulation. This kind of mapping is performed only on the computer keyboard, not on remote terminals. Use `mapkey` to change keyboard mapping. To change the mapping for individual channels (multiscreens), use `mapchan(M)`.

Keyboard mapping can also be performed using `ioctl`. The syntax is the same as for string key mapping (see previous section).

For keyboard mapping, `cmd` is GIO_KEYMAP to display the current map, and PIO_KEYMAP puts the prepared buffer into place.

**String Key Mapping**

To map string (function) keys, use the `mapstr` (see `mapkey(ADM)`) utility. `mapstr` modifies the string mapping table where function keys are defined.

The string mapping table is an array of 512 bytes (typedef `strmap_t`) containing null terminated strings that redefine the function keys. The first null terminated string is assigned to the first string key, the second string to the second string key, and so on.
There is no limit to the length of any particular string as long as the whole table does not exceed 512 bytes, including nulls. Strings are made null by the introduction of extra null characters.

The following is a list of default function key values:

<table>
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<tr>
<th>Key #</th>
<th>Function</th>
<th>Shift Function</th>
<th>Ctrl Function</th>
<th>Ctrl Shift Function</th>
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</thead>
<tbody>
<tr>
<td>1</td>
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<td>ESC[w]</td>
</tr>
<tr>
<td>2</td>
<td>ESC[N</td>
<td>ESC[Z]</td>
<td>ESC[l]</td>
<td>ESC[x]</td>
</tr>
<tr>
<td>3</td>
<td>ESC[O</td>
<td>ESC[a]</td>
<td>ESC[m]</td>
<td>ESC[y]</td>
</tr>
<tr>
<td>4</td>
<td>ESC[P</td>
<td>ESC[b]</td>
<td>ESC[n]</td>
<td>ESC[z]</td>
</tr>
<tr>
<td>5</td>
<td>ESC[Q</td>
<td>ESC[c]</td>
<td>ESC[o]</td>
<td>ESC[@]</td>
</tr>
<tr>
<td>6</td>
<td>ESC[R</td>
<td>ESC[d]</td>
<td>ESC[p]</td>
<td>ESC[ ]</td>
</tr>
<tr>
<td>7</td>
<td>ESC[S</td>
<td>ESC[e]</td>
<td>ESC[q]</td>
<td>ESC[]</td>
</tr>
<tr>
<td>8</td>
<td>ESC[T</td>
<td>ESC[f]</td>
<td>ESC[r]</td>
<td>ESC[ ]</td>
</tr>
<tr>
<td>9</td>
<td>ESC[U</td>
<td>ESC[g]</td>
<td>ESC[s]</td>
<td>ESC[~]</td>
</tr>
<tr>
<td>10</td>
<td>ESC[V</td>
<td>ESC[h]</td>
<td>ESC[t]</td>
<td>ESC[ ]</td>
</tr>
<tr>
<td>11</td>
<td>ESC[W</td>
<td>ESC[i]</td>
<td>ESC[u]</td>
<td>ESC[ ]</td>
</tr>
<tr>
<td>12</td>
<td>ESC[X</td>
<td>ESC[j]</td>
<td>ESC[v]</td>
<td>ESC[ ]</td>
</tr>
</tbody>
</table>

You can also map string keys using `ioctl(S)`. The syntax is:

```c
#include <sys/keyboard.h>
ioctl(fd,cmd,buf)
int fd, cmd;
char *buf;
...
```

For string key mapping where `cmd` is GIO_STRMAP to display the string mapping table and PIO_STRMAP to put the new string mapping table in place.
Files

/usr/lib/keyboard/keys
/usr/lib/keyboard/strings

See Also

mapchan(F), mapchan(M), mapkey(ADM), multiscreen(M), screen(HW), setkey(C), stty(C), kbmode(ADM), configure(ADM)
Name

lp, lp0, lp1, lp2 - Line printer device interfaces.

Description

The \texttt{lp0}, \texttt{lp1}, and \texttt{lp2} files provide access to the optional parallel ports of the computer. The \texttt{lp0} and \texttt{lp2} files provide access to parallel ports 1 and 2, respectively. The \texttt{lp1} file provides access to the parallel port on the monochrome adaptor.

Only one of \texttt{lp0} and \texttt{lp1} may be used on a given system. To access two parallel printers on a system, use either \texttt{lp0} or \texttt{lp1}, and \texttt{lp2}.

Files

\begin{verbatim}
/dev/lp0
/dev/lp1
/dev/lp2
\end{verbatim}

See Also

lp(C), lpadmin(ADM), lpsched(ADM), lpinit(ADM)

Notes

The standard \texttt{lp} ports, \texttt{lp0}, \texttt{lp1}, and \texttt{lp2} send a printer initialization string the first time the file is opened after the system is \textit{booted}.

Not all computers have an alternate parallel port slot.
Name

Machine - Description of host machine.

Description

This page lists the internal characteristics of personal computers which use the Intel 8086 processor family and its associated hardware. The information is intended for software developers who wish to transfer relocatable object or executable files from other XENIX machines to a personal computer then prepare the files for execution on the personal computer.

Central Processing Unit Intel 8086, 8088, 80186, 80286, 80386

Disk Block Size (BSIZE) 1024 bytes

Memory Management Scheme Unmapped (8086, 8088, 80186)
Segmented (80286)
Segmented and paged (80386)

Split Instruction and Data Supported

Variable Stack Size Supported (8086, 80386 only)
(8086, 80386 default configuration)

Fixed Stack Size Supported
(80286 default configuration)

Clock Ticks .05 second (8086, 8088, 80186)
.02 second (80286, 80386)

Binary Compatibility

The small and middle model binary programs created by the C compiler cc(CP) run on many processors. The following chart shows which XENIX systems running on which processors produce code executable on other machines. It is assumed that system specific system calls are not used to produce portable code. cc(CP) produces code by default, but can also be used as a cross development compiler, by using the appropriate flags.

SCO-nn is XENIX distributed by The Santa Cruz Operation, Inc. MS-nn is XENIX distributed by Microsoft Corporation. Intel XENIX is distributed by Intel Corporation. Altos XENIX is distributed by Altos Computer Systems. nn designates the machine processor. System designates the version of XENIX, either 2.3, 3.0, or System V.
<table>
<thead>
<tr>
<th>Processor</th>
<th>Default compiler produces programs which run on System/Processor</th>
<th>Runs default programs created on System/Processor</th>
<th>Compiles (cross development) programs for System/Processor</th>
</tr>
</thead>
<tbody>
<tr>
<td>SCO-86 3.0</td>
<td>SCO-86 [3.0, Sys V] SCO-186 [3.0, Sys V] SCO-286 SysV</td>
<td>SCO-86 3.0 SCO-186 3.0 Intel, Altos-86 2.3, 3.0</td>
<td>DOS*</td>
</tr>
<tr>
<td>SCO-286 3.0</td>
<td>SCO-286 [3.0, Sys V] MS-286 [3.0†, Sys V]</td>
<td>SCO-286 3.0 MS-286 3.0†</td>
<td>DOS*</td>
</tr>
<tr>
<td>MS-286 3.0†</td>
<td>MS-286 [3.0†, Sys V] SCO-286 Sys V</td>
<td>SCO-286 3.0</td>
<td>DOS*</td>
</tr>
<tr>
<td>MS-386 System V</td>
<td>MS-386 Sys V SCO-386 Sys V</td>
<td>SCO-86 [3.0, Sys V]† SCO-186 [3.0, Sys V]† SCO-286 [3.0, Sys V]†</td>
<td>DOS*</td>
</tr>
</tbody>
</table>

* MS-DOS for i8086/8088, i80186 and i80286 processors.
† MS-286 3.0 XENIX is equivalent to Intel 286 3.0 XENIX.
‡ untested, pending release of this product.
See also

clockrate(HW), cc(CP), ld(CP), a.out(F).
Name

mouse - System mouse.

Description

Mouse usage under XENIX is provided through the following special device files:

<table>
<thead>
<tr>
<th>Device Path</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/mouse</td>
<td>Directory for mouse-related special device files.</td>
</tr>
<tr>
<td>/dev/mouse/bus[0-1]</td>
<td>Bus mouse device files.</td>
</tr>
<tr>
<td>/dev/mouse/vpim[0-1]</td>
<td>vpix-mouse device files.</td>
</tr>
<tr>
<td>/dev/mouse/microsoft_ser</td>
<td>Microsoft serial mouse device files.</td>
</tr>
<tr>
<td>/dev/mouse/logitech_ser</td>
<td>Logitech serial mouse device files.</td>
</tr>
<tr>
<td>/dev/mouse/mousesys_ser</td>
<td>Mousesys serial mouse device files.</td>
</tr>
<tr>
<td>/dev/mouse/ttyp[0-7]</td>
<td>Special pseudo-tty files for mouse input.</td>
</tr>
<tr>
<td>/etc/default/usemouse</td>
<td>Default map file for mouse-generated characters.</td>
</tr>
<tr>
<td>/usr/lib/event/devices</td>
<td>File containing device information for mice.</td>
</tr>
<tr>
<td>/usr/lib/event/ttys</td>
<td>File listing ttys eligible to use mice.</td>
</tr>
<tr>
<td>/usr/lib/mouse/*</td>
<td>Alternate map files for mice.</td>
</tr>
</tbody>
</table>

XENIX supports mice attached directly to controller cards on the bus and mice attached to standard serial ports. The command:

**mkdev mouse**

is used to configure a new mouse or to reconfigure an existing mouse.

See Also

mkdev(ADM), usemouse(C)
Name

parallel - Parallel interface devices.

Description

There are several parallel devices:

/dev/lp0 Main parallel adapter.
/dev/lp1 Adapter on monochrome video card.
/dev/lp2 Alternate parallel adapter (on appropriate machines).

It is not possible to have all three parallel devices on one system. XT computers only allow the use of /dev/lp0. Some AT computers allow the use of two parallel devices, /dev/lp2, and either /dev/lp0 or /dev/lp1. However, available devices vary from machine to machine, and may instead allow either /dev/lp0, or and either /dev/lp1, and /dev/lp2.

If a parallel device fails to interrupt properly, the parallel driver enters "poll mode." Once interrupts are received from the device, the driver returns to its original mode.

The parallel driver delays a certain amount of time when a parallel device is closed. The amount of delay can affect printer performance, but is necessary to compensate for different sizes of printer buffers and printer speeds. For example, this command sets the delay on close to 1 second, specified in 10ths of a second:

```
stty time 10< /dev/lp0
```

When given from a prompt, this command will only work if the port is open. It is recommended that a variation of this command be placed in the interface script used with the parallel device to achieve the same results:

```
stty time 10 0< &1
```

Notes

Parallel adapters on add-on cards will function, but switches must be set correctly. Some compatible computers have ports lp0 and lp1 reversed.

The stty (C) command for output processing is supported on a parallel device. stty options that have no effect on a parallel device are ignored and no error messages are displayed.
Usage

Usually invoked by through `lp(C)`, but can be written to directly.

Files

/dev/lp0
/dev/lp1
/dev/lp2

See Also

`lp(C)`, `lp(HW)`, `lpadmin(ADM)`, `lpinit(ADM)`, `lpsched(ADM)`, `serial(HW)`
Name

ramdisk - Memory block device

Description

The *ramdisk* device driver provides a block interface to memory. A *ramdisk* can be used like any other block device, including making it into a file systems using `mkfs(ADM)`. There are eight *ramdisks* available.

The characteristics of a *ramdisk* file are determined by its minor device number. The bits in the minor device number encode its size, longevity, and which of the eight possible *ramdisks* it is.

The three low-order bits of the minor device number determine which of the eight *ramdisks* is being accessed.

The next four bits of the minor device number determine the size of the *ramdisk*. The size of a *ramdisk* must be a power of 2, and must be at least 16K. Since 4 bits are available, there are 16 possible sizes, starting at 16K and doubling every time the size indicator is incremented, to produce possible sizes of 16K, 32K, 64K, and up.

The high-order bit is a longevity indicator. If set, memory is permanently allocated to that *ramdisk*, and can be deallocated only by rebooting the system. Permanent *ramdisks* can only be allocated by the superuser. However, once a permanent *ramdisk* is allocated (by opening it), it can be read and written by anyone having the appropriate permissions on the *ramdisk* inode.

If clear, the *ramdisk* is deallocated when no processes have it open. To create an easily removable, but semi-permanent *ramdisk*, use a separate process to keep the device open for as long as necessary.
Since a complete set of *ramdisks* (8) would consume 256 inodes, only one example 16K *ramdisk* (/dev/ram00) is created when the system is installed. The system administrator can check this existing file to determine the major device number for any other required *ramdisks*. All *ramdisks* will use the same major device number.

The following table shows how the minor device number is constructed:

<table>
<thead>
<tr>
<th>Description</th>
<th>Longevity</th>
<th>Size (see next table)</th>
<th>Ram Disk No.</th>
<th>Minor Device Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>16K (#1) (Temporary)</td>
<td>0 0 0 0 0 0 0 1</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>16K (#1) (Permanent)</td>
<td>1 0 0 0 0 0 0 1</td>
<td>129</td>
<td></td>
<td></td>
</tr>
<tr>
<td>64K (#0) (Temporary)</td>
<td>0 0 0 1 0 0 0 1</td>
<td>16</td>
<td></td>
<td></td>
</tr>
<tr>
<td>512K (#7) (Permanent)</td>
<td>1 0 1 0 1 1 1 1</td>
<td>175</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The contents of the size field and the corresponding *ramdisk* size is shown in the next table.

<table>
<thead>
<tr>
<th>Size Bits</th>
<th>Ramdisk Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>16K</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>32K</td>
</tr>
<tr>
<td>0 0 1 0</td>
<td>64K</td>
</tr>
<tr>
<td>0 0 1 1</td>
<td>128K</td>
</tr>
<tr>
<td>0 1 0 0</td>
<td>256K</td>
</tr>
<tr>
<td>0 1 0 1</td>
<td>512K</td>
</tr>
<tr>
<td>0 1 1 0</td>
<td>1M</td>
</tr>
<tr>
<td>0 1 1 1</td>
<td>2M</td>
</tr>
<tr>
<td>1 0 0 0</td>
<td>4M</td>
</tr>
<tr>
<td>1 0 0 1</td>
<td>8M</td>
</tr>
<tr>
<td>1 0 1 0</td>
<td>16M</td>
</tr>
<tr>
<td>1 0 1 1</td>
<td>32M</td>
</tr>
<tr>
<td>1 1 0 0</td>
<td>64M</td>
</tr>
<tr>
<td>1 1 0 1</td>
<td>128M</td>
</tr>
<tr>
<td>1 1 1 0</td>
<td>256M</td>
</tr>
<tr>
<td>1 1 1 1</td>
<td>512M</td>
</tr>
</tbody>
</table>

To create a ramdisk, follow these steps:
1. Create the device node.

You must first create the device that the ramdisk will reside on. It has the form:

```
mknod  device_name  b_or_c  major_device_number  minor_device_number
```

where `b_or_c` "b" or "c". "b" is for blocked devices and is the one you will use. The major number will always be 31. The minor number is derived from the table above. The minor number is the sum of the three attribute columns.

Longevity:
- permanent = 128
- non-permanent = 0

Size:
- 16K = 0
- 128K = 24
- 32K = 8
- 256K = 32
- 64K = 16
- 512K = 40
- 1 Meg = 48
- 2 Meg = 56
- 16 Meg = 80
- 4 Meg = 64
- 32 Meg = 88

Ram Disk number: 0 through 7
Note: There are only 8 devices available. Two different size devices may not share the same number.

For example, to create a 64K permanent ramdisk, the minor number could vary from 144 to 151. If the disk number was 1 the mknod command would be:

```
mknod  /dev/ram64  b  31  145
```

2. Make a file system.

This creates a file system on the ramdisk. In this example `mkfs` has the form:

```
mkfs  device_name  size_of_file_in_Bsize_blocks
```

In this example, the command to create a 64K file system would be:

```
mkfs  /dev/ram64  64
```

3. Mount the filesystem.

This mounts the selected device on the specified mount point. It has the form:

```
mount  device_name  mount_point
```

In order to mount the example 64K ramdisk on /mnt the command would be:

```
mount  /dev/ram64  /mnt
```

To make a file system on a non-permanent ramdisk, the device file
must be held open between the *mkfs* and the *mount*(ADM) operations. Otherwise, the *ramdisk* is allocated at the start of the *mkfs* command, and deallocated at its end. Once the *ramdisk* is mounted, it is open until it is unmounted.

The following shell fragment shows one way to use *mkfs* on a non-permanent 512K *ramdisk*, then mount it:

```
( /etc/mkfs /dev/ram40 512 
 /etc/mount /dev/ram40 /mnt 
 ) < /dev/ram40
```

Notes

*ramdisks* must occupy contiguous memory. If free memory is fragmented, opening a *ramdisk* may fail even though there is enough total memory available. Ideally, all *ramdisks* should be allocated at system startup. This helps prevent the *ramdisks* themselves from fragmenting memory.

*ramdisks* are geared towards use in specialized applications. In many cases, you will notice a *decrease in system performance* when *ramdisks* are used, because XENIX can generally put the memory to better use elsewhere.

Files

/dev/ram00

See Also

*mkfs*(ADM), *mount*(ADM), mknod(C)
**Name**

screen - tty[01-n], color, monochrome, ega, vga
- Display adapter and video monitor.

**Description**

The tty[01-n] device files provide character I/O between the system and the video display monitor and keyboard. Each file corresponds to a separate teletype device. Although there is a maximum of 12 screens, the exact number available (n) depends upon the amount of memory in the computer. The screens are modeled after a 25 line, 80 column ASCII terminal, unless specified otherwise.

System error messages from the kernel are written to /dev/console, which is normally the current multiscreen. If the /dev/console is the default output device for system error messages, and the display being used is switched to graphics mode, console messages are not displayed. When the video device returns to text mode, a notice message is displayed and the text of the kernel error can be recovered from usr/adm/messages.

Although all tty[01-n] devices may be open concurrently, only one of the corresponding devices can be active at any given time. The active device displays its own screen and takes sole possession of the keyboard. It is an error to attempt to access the color, monochrome, or ega file when no corresponding adapter exists or no multiscreens are associated with it.

To get to the next consecutive screen, enter Ctrl-PrtSc using the Ctrl key, and the PrtSc key. Any active screen may be selected by entering alt-Fn, where Fn is one of the function keys. For example, F1 refers to the tty01 device.

**Control Modes**

To change the display mode used for the video monitor, open the device file associated with that mode. For example, to switch to display output on an installed CGA, a program should open /dev/color and use the selector mapping ioctl s on the file descriptor that is returned from the open call. Using device files helps ensure future compatibility.
Multiscreens can be reassigned to different adapters (in multi-adapter systems) with these *ioctl*s:

- **SWAPMONO**: Selects the monochrome display as the output device for the video monitor.
- **SWAPCGA**: Selects the regular color display as the output device for the video monitor.
- **SWAPEGA**: Selects the enhanced color display as the output device for the video monitor.
- **SWAPVGA**: Selects the video graphics array color display as the output device for the video monitor.

To find out which display adapter type is currently attached to the video monitor, you can use *ioctl(S)* with the following request:

- **CONS_CURRENT**: Returns the display adapter type currently attached to the video monitor. The return value can be one of: MONO, CGA, EGA, or VGA.

**Display Modes**

The following *ioctl*s can be used to change the video display mode:

- **SW_B80x25**: Selects 80x25 black and white text display mode. (MONO, CGA, EGA, VGA)
- **SW_C80x25**: Selects 80x25 color text display mode. (CGA, EGA, VGA)
- **SW_BG320**: Selects 320x200 black and white graphics display mode. (CGA, EGA, VGA)
- **SW_CG320**: Selects 320x200 color graphics display mode. (CGA, EGA, VGA)
- **SW_BG640**: Selects 640x200 black and white graphics display mode. (CGA, EGA, VGA)
SCREEN (HW)

SW_EGAMONO80x25 Selects EGA (Enhanced Graphics Adapter) mode 7 - emulates support provided by the monochrome display. (EGA, VGA)

SW_EGAMONOAPA Selects EGA support for 640x350 graphics display mode (EGA mode F). (EGA with mono monitor)

SW_ENHMONOAPA2 Selects EGA mode F*. (EGA with mono monitor)

SW_ENHB40x25 Selects enhanced EGA support for 40x25 black and white text display mode. (EGA, VGA)

SW_ENHC40x25 Selects enhanced EGA support for the 40x25 color text display mode. (EGA, VGA)

SW_ENHB80x25 Selects enhanced EGA support for 80x25 black and white text display mode. (EGA, VGA)

SW_ENHC80x25 Selects enhanced EGA support for 80x25 color text display mode. (EGA, VGA)

SW_CG320_D Selects EGA support for 320x200 graphics display mode. (EGA mode D.) (EGA, VGA)

SW_CG640_E Selects EGA support for 640x200 graphics display mode (EGA mode E). (EGA, VGA)

SW_CG640x350 Selects EGA support for 640x350 graphics display mode (EGA mode 10). (EGA, VGA)

SW_ENH_CG640 Selects EGA mode 10*. (EGA, VGA)

SW_MCAMODE Reinitializes the monochrome adapter. (MONO)

SW_VGA40x25 Selects VGA support for the 40x25 color text display mode (VGA mode 1+). (VGA)

SW_VGA80x25 Selects VGA support for the 80x25 black and white text display mode (VGA mode 2+). (VGA)

SW_VGAM80x25 Selects VGA mode 7+ - emulates support provided by the monochrome display. (VGA with mono monitor)

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SCREEN (HW)

SW_VGA11 Selects VGA support for the 640x480 graphics display mode (VGA mode 11). (VGA)

SW_VGA12 Selects VGA support for the 640x480 graphics display mode (VGA mode 12). (VGA)

SW_VGA13 Selects VGA support for the 320x200 graphics display mode (VGA mode 13). (VGA)

Switching to an invalid display mode for a display device will result in an error.

Getting Display Modes

The following ioctl() requests are provided to obtain information about the current display modes:

CONS_GET Returns the current display mode setting for current display adapter. (All)

CGA_GET Returns the current display mode setting of the color graphics adapter. (CGA only)

EGA_GET Returns the current display mode setting of the enhanced graphics adapter. (EGA only)

MCA_GET Returns the current display mode setting of the monochrome adapter. (MONO only)

VGA_GET Returns the current display mode of the video graphics array adapter. (VGA only)

Memory Mapping Modes

The ioctl(S) routine is used to map the display memory of the various devices into the user's data space. On the 80286, ioctl() returns a selector for the display memory. The macro sotofar is used to create a far pointer from this selector so the display memory can be accessed. The sotofar macro is located in /usr/include/sys/sysmacros.h. On the 80386, ioctl() returns a (char *).

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Refer to your hardware manual for details on various displays, adapters, and controllers.

These `ioctl()` requests can be used to map the display memory:

**MAPCONS**  
Maps the display memory of the adapter currently being used into the user's data space.  
(All)

**MAPMONO**  
Maps the monochrome adapter's display memory into the user's data space.  (MONO only)

**MAPCGA**  
Maps the color adapter's display memory into the user's data space.  (CGA only)

**MAPEGA**  
Maps the enhanced graphics adapter's display memory into the user's data space.  (EGA only)

**MAPVGA**  
Maps the video graphics array adapter display memory into the user's data space.  (VGA only)

For example, the following code can be used to acquire a pointer to the start of the user data space associated with the color graphics adapter display memory:

```c
char far *dp;  
int selector;  

fd=open("/dev/color", O_WRONLY);  
selector=ioctl(fd, MAPCGA, 0);  
dp = sotofar(selector, 0);  
```

Note that when the display memory is mapped into the user space, the adapter's start address registers are not set. The start address can be reset in two ways, so that the start address of the display memory corresponds to the upper left hand corner of the screen:

1. Switch modes with an `ioctl()` (the "switch" can be to the present mode). See the "Display Modes" section of this manual page.
2. Change the start address high and low address with the
in-on-port/out-on-port ioctl().

The in-on-port/out-on-port ioctl()’s can also be used to determine the
current value in the start address register, and then set up a pointer to
point to the offset in the mapped-in data space.

Graphics Adapter Port I/O

You can use ioctl(S) to read or write a byte from or to the graphics
adapter port. The arg parameter of the ioctl call uses the io_arg data
structure:

    struct port_io_arg {
        struct port_io_struct args[4];
    };

As shown above, the io_arg structure points to an array of four port_io
data structures. The port_io structure has the following format:

    struct port_io_struct {
        char    dir;    /* direction flag (in vs. out) */
        unsigned_int  port;  /* port address */
        char        data;  /* byte of data */
    };

You may specify one, two, three, or four of the port_io_struct struc-
tures in the array for one ioctl call. The value of dir can be either
IN_ON_PORT to specify a byte being input to the graphics adapter
port or OUT_ON_PORT to specify a byte being output to the graphics
adapter port. Port is an integer specifying the port address of the
desired graphics adapter port. Data is the byte of data being input or
output as specified by the call.

If you are not using any of the port_io structures, load the port with 0,
and leave the unused structures at the end of the array. Refer to the
hardware manuals for port addresses and functions for the various
adapters.

You can use the following ioctl(S) commands to input or output a byte
on the graphics adapter port:

MGAIO     Inputs or outputs a byte on the monochrome
           adapter port as specified. (MONO only)

CGAIO     Inputs or outputs a byte on the color graphics
           adapter port as specified. (CGA only)
EGAIO
Inputs or outputs a byte on the enhanced graphics adapter port as specified. (EGA only)

VGAIO
Inputs or outputs a byte on the video graphics array adapter port as specified. (VGA only)

CONSIO
Inputs or outputs a byte on the current graphics adapter port as specified. (Any)

To input a byte on any of the graphics adapter ports, load dir with IN_ON_PORT and load port with the port address of the graphics adapter. The byte input from the graphics adapter port will be returned in data.

To output a byte, load dir with OUT_ON_PORT, load port with the port address of the graphics adapter, and load data with the byte you want output to the graphics adapter port.

Function Keys

ioctl(S) can be used to define or obtain the current definition of a function key. The arg parameter of the ioctl call uses the fkeyarg data structure:

```
struct fkeyarg {
    unassigned int keynum;
    char keydef [MAXFK];
    /* Comes from char flen; ioctl.h via comcrt.h */
    char flen; ioctl.h via comcrt.h */
}
```

You can use the following ioctl(S) requests to obtain or assign function key definitions:

GETFKEY Obtains the current definition of a function key. The function key number must be passed in keynum. The string currently assigned to the key will be returned in keydef and the length of the string will be returned in flen when the ioctl is performed.

SETFKEY Assigns a given string to a function key. The function key number must be passed in keydef and the length of the string (number of characters) must be passed in flen.

Screen Attribute Sequences
The following character sequences are defined by ANSI X3.64-1979 and may be used to control and modify the screen display. Each \texttt{Pn} is replaced by the appropriate ASCII number (decimal) to produce the desired effect. The last column is for \textit{termcap} (M) codes, where \textquoteleft{n/a}\textquoteright{} means not applicable.

The use of 7 or 8 bit characters in the escape sequence is a valid invocation for each action defined. For example the ANSI ED command can be invoked via the \textquoteleft\texttt{ESC [ Pn J}\textquoteright{} (0x1b-0x5b-Pn-0x4a, 7 bit chars) sequence or the \textquoteleft\texttt{CSI Pn J}\textquoteright{} (0x9b-Pn-0x4n, 8 bit chars) sequence.

<table>
<thead>
<tr>
<th>ISO</th>
<th>Sequence</th>
<th>Action</th>
<th>Termcap Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>ED</td>
<td>CSI Pn J</td>
<td>Erases all or part of a display. \texttt{Pn=0}: erases from active position to end of display. \texttt{Pn=1}: erases from the beginning of display to active position. \texttt{Pn=2}: erases entire display.</td>
<td>cd</td>
</tr>
<tr>
<td>EL</td>
<td>CSI Pn K</td>
<td>Erases all or part of a line. \texttt{Pn=0}: erases from active position to end of line. \texttt{Pn=1}: erases from beginning of line to active position. \texttt{Pn=2}: erases entire line.</td>
<td>ce</td>
</tr>
<tr>
<td>ECH</td>
<td>CSI Pn X</td>
<td>Erases \texttt{Pn} characters</td>
<td>n/a</td>
</tr>
<tr>
<td>CBT</td>
<td>CSI Pn Z</td>
<td>Moves active position back \texttt{Pn} tab stops.</td>
<td>bt</td>
</tr>
<tr>
<td>Command</td>
<td>Explanation</td>
<td>Page 9</td>
<td></td>
</tr>
<tr>
<td>----------</td>
<td>-------------</td>
<td>--------</td>
<td></td>
</tr>
<tr>
<td><strong>SU</strong></td>
<td>Scroll screen up <em>Pn</em> lines, introducing new blank lines at bottom.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>SD</strong></td>
<td>Scrolls screen down <em>Pn</em> lines, introducing new blank lines at top.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CUP</strong></td>
<td>Moves active position to location <em>P1</em> (vertical) and <em>P2</em> (horizontal).</td>
<td>cm</td>
<td></td>
</tr>
<tr>
<td><strong>HVP</strong></td>
<td>Moves active position to location <em>P1</em> (vertical) and <em>P2</em> (horizontal).</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CUU</strong></td>
<td>Moves active position up <em>Pn</em> number of lines.</td>
<td>up (ku)</td>
<td></td>
</tr>
<tr>
<td><strong>CUD</strong></td>
<td>Moves active position down <em>Pn</em> number of lines.</td>
<td>do (kd)</td>
<td></td>
</tr>
<tr>
<td><strong>CUF</strong></td>
<td>Moves active position <em>Pn</em> spaces to the right.</td>
<td>nd (kr)</td>
<td></td>
</tr>
<tr>
<td><strong>CUB</strong></td>
<td>Moves active position <em>Pn</em> spaces backward.</td>
<td>bs (kl)</td>
<td></td>
</tr>
<tr>
<td><strong>HPA</strong></td>
<td>Moves active position to column given by <em>Pn</em>.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>HPR</strong></td>
<td>Moves active position <em>Pn</em> characters to the right.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>VPA</strong></td>
<td>Moves active position to line given by <em>Pn</em>.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command</td>
<td>Action Description</td>
<td></td>
<td></td>
</tr>
<tr>
<td>----------</td>
<td>------------------------------------------------------------------------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td>VPR</td>
<td>Moves active position down by ( Pn ) lines.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IL</td>
<td>Inserts ( Pn ) new, blank lines.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ICH</td>
<td>Inserts ( Pn ) blank places for ( Pn ) characters.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DL</td>
<td>Deletes ( Pn ) lines.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DCH</td>
<td>Deletes ( Pn ) number of characters.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CPL</td>
<td>Moves active position to beginning of line, ( Pn ) lines up.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CNL</td>
<td>Moves active position to beginning of line, ( Pn ) lines down.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SGR</td>
<td>Resets bold, blink, blank, underscore, and reverse. Color: Restores normal selected colors.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SGR</td>
<td>Sets bold. Color: Sets intensity (changes color to lt_color).</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SGR</td>
<td>Sets underscore. Color: No effect.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SGR</td>
<td>Changes background from lt_color to color; foreground blinks.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
SCREEN (HW)

SGR CSI 7 m  Sets reverse video. **Color:** so
     Uses reverse selected colors.

SGR CSI 10 m  Select primary font.  GE

SGR CSI 11 m  Select first alternate font. Allows ASCII characters
     less than 32 to be displayed as ROM characters.  n/a

SGR CSI 12 m  Select second alternate font. Toggles high bit of extended
     ASCII code before displaying as ROM characters.  GS

SGR ESC[ 4 m  Underscores. **Color:** No effect  n/a

SGR CSI 3 C m  **Color:** Selects foreground color $C$ (see Table 1 below).  n/a

SGR CSI 4 C m  **Color:** Selects background color $C$ (see Table 1).  n/a

SGR CSI 8 m  Sets blank (non-display).  n/a

The following color codes and sequences are defined by International Organization for Standardization ISO DP 6429.

<table>
<thead>
<tr>
<th>Table 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C$</td>
</tr>
<tr>
<td>0</td>
</tr>
<tr>
<td>1</td>
</tr>
<tr>
<td>2</td>
</tr>
<tr>
<td>3</td>
</tr>
<tr>
<td>4</td>
</tr>
<tr>
<td>5</td>
</tr>
<tr>
<td>6</td>
</tr>
<tr>
<td>7</td>
</tr>
</tbody>
</table>
SM (Set Mode)  ESC \[2\ h\]  Lock keyboard. Ignores keyboard input until unlocked. Characters are not saved.  n/a

MC (Media Copy)  ESC \[2\ i\]  Send screen to host. Current screen contents are sent to the application.  n/a

RM (Reset Mode)  ESC \[2\ l\]  Unlock keyboard. Re-enable keyboard input.  n/a

The following color codes and sequences are additional control sequences.

<table>
<thead>
<tr>
<th>Cn</th>
<th>Color</th>
<th>Cn</th>
<th>Color</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Black</td>
<td>8</td>
<td>Grey</td>
</tr>
<tr>
<td>1</td>
<td>Blue</td>
<td>9</td>
<td>Lt. Blue</td>
</tr>
<tr>
<td>2</td>
<td>Green</td>
<td>10</td>
<td>Lt. Green</td>
</tr>
<tr>
<td>3</td>
<td>Cyan</td>
<td>11</td>
<td>Lt. Cyan</td>
</tr>
<tr>
<td>4</td>
<td>Red</td>
<td>12</td>
<td>Lt. Red</td>
</tr>
<tr>
<td>5</td>
<td>Magenta</td>
<td>13</td>
<td>Lt. Magenta</td>
</tr>
<tr>
<td>6</td>
<td>Brown</td>
<td>14</td>
<td>Yellow</td>
</tr>
<tr>
<td>7</td>
<td>White</td>
<td>15</td>
<td>Lt. White</td>
</tr>
</tbody>
</table>

n/a  CSI=c A  Set overscan color to color c. c is a decimal value taken from Table 2 above. (This sequence may not be supported on all hardware.)  n/a

n/a  CSI=p;dB  Set the bell parameter to the decimal values of p and d. p is the period of the bell tone in units of 840.3 nanoseconds, and d is the duration of the tone in units of 100 milliseconds.  n/a
n/a  CSI = $;eC  Set the cursor to start on scanline $ and end on scanline e.
n/a  CSI = xD  Turn on or off ($x=1$ or $0$) the intensity of the background color.
n/a  CSI = xE  Set or clear ($x=1$ or $0$) the Blink vs. Bold background bit in the 6845 crt controller.
n/a  CSI = cF  Set normal foreground color to c. (c is a decimal parameter taken from Table 2.)
n/a  CSI = c G  Set normal background. (See Table 2.)
n/a  CSI = c H  Set reverse foreground. (See Table 2.)
n/a  CSI = c I  Set reverse background. (See Table 2.)
n/a  CSI = c J  Set graphic foreground. (See Table 2.)
n/a  CSI = c K  Set graphic background. (See Table 2.)

n/a  ESC [ Pn g  Accesses alternate graphics set. Not the same as "graphics mode." Refer to your owner's manual for decimal/character codes ($Pn$) and possible output characters.

n/a  ESC Q Fn 'string'  Define function key $Fn$ with $string$. String delimiters ’ and ’ may be any character not in $string$. Function keys are numbered 0 through 9 ($F1 = 0$, $F2 = 1$, etc.).

n/a  ESC [ Pnz  $CSI Pnz$  $Pn$ should be equal to the number of the screen to switch to. Will only work if screen was configured for at boot, else no action will take place.
Files

/dev/console
/dev/tty [02 -n]
/dev/color
/dev/monochrome
/dev/ega
/dev/vga

See Also

console(M), ioctl(S), keyboard(HW), keymap(M), mapkey(ADM), mapchan(M), multiscreen(M), setcolor(C), stty(C), systty(M), vidi(C), termcap(M), tty(M)
Name

scsi - small computer systems interface.

Description

SCSI provides a standard interface for peripherals such as hard disks, printers, tape drives and others. SCSI is run via a host adapter card that can support up to 8 controllers, each supporting up to 8 devices. Note that only 4 hard disks can be attached to a controller.

The minor device numbering scheme for SCSI devices (for example, a hard disk) is the same as the standard minor device number scheme for non-SCSI devices.

Each SCSI controller has its own major device number.

Notes

This utility is not applicable to all hardware/software configurations and may not be included in your distribution.

Currently, the only SCSI host adapter card supported is the Adaptec AHA-1540 controlling 1 or 2 hard disks and 1 tape drive.

See Also

hd(HW), tape(HW)
Name

tty1[a-h], tty1[A-H], tty2[a-h], tty2[A-H] - Interface to serial ports

Description

The tty1[a-h], tty1[A-H], tty2[a-h] and tty2[A-H] files provide access to the standard and optional serial ports of the computer. Each file corresponds to one of the serial ports (with or without modem control). Files are named according to the following conventions:

- The first number in the file name corresponds to the COM expansion slot.

- Lower case letters indicate no modem control.

- Upper case letters indicate the line has modem control.

tty1a and tty1A both refer to COM 1, whereas tty2a and tty2A both refer to COM 2.

For example, with a four port expansion board installed at COM 1 and a single port board installed at COM 2, you can access:

  tty1a  tty1A
  tty1b  tty1B
  tty1c  tty1C
  tty1d  tty1D
  tty2a  tty2A

Each serial port has modem and non-modem invocations. The device names in the following table refer to the serial ports, with and without modem control. The first section of the table describes boards at COM 1 and the second section describes boards installed at COM 2. “Minor” is the minor device number for the port (see mknod(C)).
<table>
<thead>
<tr>
<th>Board Type</th>
<th>Non-Modem Control</th>
<th>Modem Control</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Minor</td>
<td>Name</td>
</tr>
<tr>
<td>1 Port</td>
<td>0</td>
<td>tty1a</td>
</tr>
<tr>
<td>4 Port</td>
<td>1</td>
<td>tty1b</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>tty1c</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>tty1d</td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>tty1e</td>
</tr>
<tr>
<td></td>
<td>5</td>
<td>tty1f</td>
</tr>
<tr>
<td>8 Port</td>
<td>6</td>
<td>tty1g</td>
</tr>
<tr>
<td></td>
<td>7</td>
<td>tty1h</td>
</tr>
<tr>
<td>1 Port</td>
<td>8</td>
<td>tty2a</td>
</tr>
<tr>
<td>4 Port</td>
<td>9</td>
<td>tty2b</td>
</tr>
<tr>
<td></td>
<td>10</td>
<td>tty2c</td>
</tr>
<tr>
<td></td>
<td>11</td>
<td>tty2d</td>
</tr>
<tr>
<td></td>
<td>12</td>
<td>tty2e</td>
</tr>
<tr>
<td></td>
<td>13</td>
<td>tty2f</td>
</tr>
<tr>
<td></td>
<td>14</td>
<td>tty2g</td>
</tr>
<tr>
<td></td>
<td>15</td>
<td>tty2h</td>
</tr>
</tbody>
</table>

Interrupt Vectors:

All board(s) installed at COM 1 - 4
All board(s) installed at COM 2 - 3

For a list of I/O addresses, see the Release Notes furnished with your distribution.

Access

The files may only be accessed if the corresponding serial interface card is installed and its jumper I/O address correctly set. Also, for multi-port expansion cards, you must use the mkdev(ADM) program to create more than the default number of files.

The serial ports must also be defined in the system configuration. Check your hardware manual to determine how your system is configured, via a CMOS database or by switch settings on the main system board. If your system is configured using a CMOS database, the ports are defined in the database (see cmos(HW)). Otherwise, define the ports by setting the proper switches on the main system board. Refer to your computer hardware manual for switch settings.
It is an error to attempt to access a serial port that has not been installed and defined.

The serial ports can be used for a variety of serial communication purposes such as connecting login terminals to the computer, attaching printers, or forming a serial network with other computers. Note that a serial port may operate at most of the standard XENIX baud rates, and that the ports (on most computers) have a DTE (Data Terminal Equipment) configuration. The following table defines how each pin is used for 25-pin and 9-pin connections:

<table>
<thead>
<tr>
<th>25-Pin</th>
<th>9-Pin</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>2</td>
<td>Transmit Data</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>Receive Data</td>
</tr>
<tr>
<td>4</td>
<td>7</td>
<td>Request to Send</td>
</tr>
<tr>
<td>5</td>
<td>8</td>
<td>Clear to Send</td>
</tr>
<tr>
<td>7</td>
<td>5</td>
<td>Signal Ground</td>
</tr>
<tr>
<td>8</td>
<td>1</td>
<td>Carrier Detect (Data Set Ready)</td>
</tr>
<tr>
<td>20</td>
<td>4</td>
<td>Data Terminal Ready</td>
</tr>
</tbody>
</table>

Only pins 2, 3, and 7 (2,3 and 5 for 9-pin) are necessary for a terminal (or direct) connection.

A modem control device (port) uses pins 2, 3, and 7 in the same way as a non-modem control device: send on pin 2 and receive on pin 3. Pin 7 is data ground. On a non-modem control device the state of the other pins are not set or read. On a modem control device, pins 4 and 20 (RTS & DTR) are asserted and the port will not open until pin 8 (CXD) is asserted. That is, no signal travels from pin 2 until pin 8 is asserted from another source. The modem control device monitors the status of pin 8.

See tty(M) and termio(M) for the details of serial line operation in the XENIX system.

Files

/dev/tty1[a-h]
/dev/tty1[A-H]
/dev/tty2[a-h]
/dev/tty2[A-H]

See Also

cmos(HW), csh(C), cu(C), getty(ADM), mkdev(ADM), mknod(C), nohup(C), open(S), termio(M), tty(M), uucp(C)
Notes

If you login via a modem control serial line, hanging up logs that line out and kills your background processes. See *nohup*(C) and *csh*(C).

You cannot use the same serial port with both modem and non-modem control at the same time. For example, you cannot use tty1a and tty1A simultaneously.

Use a modem cable to connect your modem to a computer.
Name

tape - Cartridge tape device.

Description

The tape device implements the XENIX interface with a tape drive. Typically, the tar(C), cpio(C), dd(C), backup(C), dump(C), or restore(C) commands are used to access a tape drive.

A single tape drive with a raw (character, non-blocking) interface is supported. There are three standard tape device types. Devices beginning with the "r" prefix (for "raw device"), should be used for most normal tape work, while devices with the "n" prefix, ("for no rewind on hold"), should be used for storing and restoring multiple files. Devices beginning with the "e" prefix (for ECC device) support a 2/64 error recovery scheme. Thus two 512-byte blocks out of every 64 blocks can be bad and the driver will correct the errors. This software ECC support provides a high degree of error recovery.

The following table summarizes the base naming conventions for the tape drives supported:

<table>
<thead>
<tr>
<th>Drive</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ct0,1</td>
<td>QIC24 unit 0,1</td>
</tr>
<tr>
<td>ct2,3</td>
<td>QIC11 unit 0,1</td>
</tr>
<tr>
<td>ctmini</td>
<td>floppy controller-based cartridge tape</td>
</tr>
<tr>
<td>mt0,1</td>
<td>reel to reel unit 0,1 1600 bpi</td>
</tr>
<tr>
<td>mt2,3</td>
<td>reel to reel unit 0,1 800 bpi</td>
</tr>
<tr>
<td>mt4,5</td>
<td>reel to reel unit 0,1 6250 bpi</td>
</tr>
</tbody>
</table>

tape(C) describes the commands used to access tape drives.

Files

/dev/rct0
/dev/nrct0
/dev/rct2
/dev/nrct2
/dev/erct0
/dev/rctmini

Notes

After certain tape operations are executed, the system returns a prompt before the tape controller has finished its operation. If the user enters another tape command too quickly, a "device busy" error is returned until the tape device is finished with its previous operation.
Periodic tape cartridge retensioning and tape head cleaning are necessary for continued error-free operation of the tape subsystem. Use `tape(C)`, to retension the tape.

**See Also**

`backup(C)`, `cpio(C)`, `dd(C)`, `dump(C)`, `format(C)`, `tape(C)`, `tar(C)`, `restore(C)`.
Name

terminal - Login terminal.

Description

A terminal is any device used to enter and display data. It may be connected to the computer:

- By a serial wire, either direct or dialup
- As a virtual terminal, for example with emulator software
- Through a display adapter

A terminal has an associated device file /dev/tty*.

Files

/dev/tty*

See Also

console(M), disable(C), enable(C), mkdev(ADM), serial(HW), stty(C), vidi(C), termcap(M), term(F), terminals(M)

May 16, 1988